MELSEC Communication Protocol
Reference Manual

-RJ71C24
-RJ71C24-R2
-RJ71C24-R4
-LJ71C24
-LJ71C24-R2
-LJ71E71-100
-QJ71C24N
-QJ71C24N-R2
-QJ71C24N-R4
-QJ71C24
-QJ71C24-R2
-QJ71E71-100
-QJ71E71-B5
-QJ71E71-B2
SAFETY PRECAUTIONS

(Read these precautions before using this product.)

Before using this product, please read this manual and the relevant manuals carefully and pay full attention to safety to handle the product correctly.

Note that these precautions apply only to this product. For the safety precautions of the programmable controller system, please read the User's Manual for the CPU module used.

In this manual, the safety precautions are classified into two levels: "WARNING" and "CAUTION".

[Design precautions]

WARNING

● When connecting an external device with a CPU module or intelligent function module to modify data of a running programmable controller, configure an interlock circuit in the program to ensure that the entire system will always operate safely. For other forms of control (such as program modification, parameter change, forced output, or operating status change) of a running programmable controller, read the relevant manuals carefully and ensure that the operation is safe before proceeding. Improper operation may damage machines or cause accidents.

● Especially, when a remote programmable controller is controlled by an external device, immediate action cannot be taken if a problem occurs in the programmable controller due to a communication failure. To prevent this, configure an interlock circuit in the program, and determine corrective actions to be taken between the external device and CPU module in case of a communication failure.

● Do not write any data to the "system area" and "write-protect area" of the buffer memory in the module. Also, do not use any "use prohibited" signals as an output signal from the CPU module to each module. Doing so may cause malfunction of the programmable controller system. For the "system area", "write-protect area", and the "use prohibited" signals, refer to the user's manual for the module used.
[Operating precautions]

⚠️ CAUTION

- When changing data and operating status, and modifying program of the running programmable controller from an external device such as a personal computer connected to an intelligent function module, read relevant manuals carefully and ensure the safety before operation. Incorrect change or modification may cause system malfunction, damage to the machines, or accidents.
- Do not power off the programmable controller or reset the CPU module while the setting values in the buffer memory are being written to the flash ROM in the module. Doing so will make the data in the flash ROM undefined. The values need to be set in the buffer memory and written to the flash ROM again. Doing so also can cause malfunction or failure of the module.
(1) Mitsubishi programmable controller ("the PRODUCT") shall be used in conditions;
   i) where any problem, fault or failure occurring in the PRODUCT, if any, shall not lead to any major or serious accident;
      and
   ii) where the backup and fail-safe function are systematically or automatically provided outside of the PRODUCT for the case of any problem, fault or failure occurring in the PRODUCT.

(2) The PRODUCT has been designed and manufactured for the purpose of being used in general industries.

MITSUBISHI SHALL HAVE NO RESPONSIBILITY OR LIABILITY (INCLUDING, BUT NOT LIMITED TO ANY AND ALL RESPONSIBILITY OR LIABILITY BASED ON CONTRACT, WARRANTY, TORT, PRODUCT LIABILITY) FOR ANY INJURY OR DEATH TO PERSONS OR LOSS OR DAMAGE TO PROPERTY CAUSED BY the PRODUCT THAT ARE OPERATED OR USED IN APPLICATION NOT INTENDED OR EXCLUDED BY INSTRUCTIONS, PRECAUTIONS, OR WARNING CONTAINED IN MITSUBISHI'S USER, INSTRUCTION AND/OR SAFETY MANUALS, TECHNICAL BULLETINS AND GUIDELINES FOR the PRODUCT.

("Prohibited Application")

Prohibited Applications include, but not limited to, the use of the PRODUCT in:

- Nuclear Power Plants and any other power plants operated by Power companies, and/or any other cases in which the public could be affected if any problem or fault occurs in the PRODUCT.
- Railway companies or Public service purposes, and/or any other cases in which establishment of a special quality assurance system is required by the Purchaser or End User.
- Aircraft or Aerospace, Medical applications, Train equipment, transport equipment such as Elevator and Escalator, Incineration and Fuel devices, Vehicles, Manned transportation, Equipment for Recreation and Amusement, and Safety devices, handling of Nuclear or Hazardous Materials or Chemicals, Mining and Drilling, and/or other applications where there is a significant risk of injury to the public or property.

Notwithstanding the above, restrictions Mitsubishi may in its sole discretion, authorize use of the PRODUCT in one or more of the Prohibited Applications, provided that the usage of the PRODUCT is limited only for the specific applications agreed to by Mitsubishi and provided further that no special quality assurance or fail-safe, redundant or other safety features which exceed the general specifications of the PRODUCTs are required. For details, please contact the Mitsubishi representative in your region.
INTRODUCTION

Thank you for purchasing the Mitsubishi programmable controller.
This manual describes the supported devices, access range, communication procedure, and message format required for using MELSEC communication protocols listed below.
Before using this product, thoroughly read this manual and the related manuals to develop full familiarity with the functions and performance of the programmable controller to ensure correct use.
Make sure that the end users read this manual and then keep the manual in a safe place for future reference.

Relevant products
RJ71C24, RJ71C24-R2, RJ71C24-R4,
LJ71C24, LJ71C24-R2, LJ71E71-100,
QJ71C24N, QJ71C24N-R2, QJ71C24N-R4, QJ71C24, QJ71C24-R2, QJ71E71-100, QJ71E71-B5, QJ71E71-B2
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Appendix 4 Applicable Commands for Online Program Change

18.4 Read and Write Device Memory

Considerations

Data to be specified in command

Batch read in bit units (command: 00)

Batch read in word units (command: 01)

Batch write in bit units (command: 02)

Batch write in word units (command: 03)

Test in bit units (random write) (command: 04)

Test in word units (random write) (command: 05)

Monitor device memory (command: 06, 07, 08, 09)

18.5 Read and Write Extended File Register

Data to be specified in command

Batch read (command: 17)

Batch write (command: 18)

Test (random write) (command: 19)

Monitor extended file registers (command: 1A, 1B)

Direct read (command: 3B)

Direct write (command: 3C)

18.6 Read and Write Buffer Memory of Special Function Module

Data to be specified in command

Accessible modules

Batch read (command: 0E)

Batch write (command: 0F)

APPENDIX

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Accessing module access devices

Accessing CPU buffer memory access device

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Number of scans required for processing

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When RCPU is configured in the multiple CPU system

When QCPU is configured in the multiple CPU system

Appendix 4 Applicable Commands for Online Program Change

Commands that cannot be executed during RUN

Commands that enable/disable online change

Setting method for writing data to CPU during RUN

Appendix 5 Number of Processing per One Communication

Commands for 4C/3C/4E/3E frame
**RELEVANT MANUALS**

<table>
<thead>
<tr>
<th>Manual name [manual number]</th>
<th>Description</th>
<th>Available form</th>
</tr>
</thead>
</table>

**e-Manual** refers to the Mitsubishi FA electronic book manuals that can be browsed using a dedicated tool. e-Manual has the following features:

- Required information can be cross-searched in multiple manuals.
- Other manuals can be accessed from the links in the manual.
- The hardware specifications of each part can be found from the product figures.
- Pages that users often browse can be bookmarked.

**User’s manuals for the module**

**Serial communication module**

<table>
<thead>
<tr>
<th>Manual name [manual number]</th>
<th>Description</th>
<th>Available form</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC iQ-R Serial Communication Module User's Manual(Startup) [SH-081250ENG]</td>
<td>Explains the specifications, functions, procedures prior to operation, system configurations, wiring, and data communication examples of serial communication module.</td>
<td>Print book e-Manual EPUB PDF</td>
</tr>
<tr>
<td>MELSEC-L Serial Communication Module User's Manual (Basic) [SH-080894ENG]</td>
<td>Explains the overview of the module and describes the applicable system configuration, the specifications, the procedures prior to operations, the basic methods of communicating with the external device, maintenance and inspection, and the troubleshooting of serial communication module.</td>
<td>Print book e-Manual EPUB PDF</td>
</tr>
<tr>
<td>Q Corresponding Serial Communication Module User's Manual (Basic) [SH-080006]</td>
<td>Explains the overview of the module and describes the applicable system configuration, the specifications, the procedures prior to operations, the basic methods of communicating with the external device, maintenance and inspection, and the troubleshooting of serial communication module.</td>
<td>Print book PDF</td>
</tr>
</tbody>
</table>

**Ethernet interface module**

<table>
<thead>
<tr>
<th>Manual name [manual number]</th>
<th>Description</th>
<th>Available form</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC-L Ethernet Interface Module User's Manual (Basic) [SH-081105ENG]</td>
<td>Explains the information on the specifications of Ethernet interface module, the procedures for data communications with external devices, circuit connection (open/close), fixed buffer exchange, random access buffer exchange, and the troubleshooting.</td>
<td>Print book e-Manual EPUB PDF</td>
</tr>
<tr>
<td>Q Corresponding Ethernet Interface Module User's Manual (Basic) [SH-080009]</td>
<td>Explains the information on the specifications of Ethernet interface module, the procedures for data communications with external devices, circuit connection (open/close), fixed buffer exchange, random access buffer exchange, and the troubleshooting.</td>
<td>Print book PDF</td>
</tr>
</tbody>
</table>
## TERMS

This manual uses the terms listed in the following table unless otherwise noted.

<table>
<thead>
<tr>
<th>Terms</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACPU</td>
<td>A generic term for MELSEC-A series CPU modules</td>
</tr>
<tr>
<td>Buffer memory</td>
<td>Memory for intelligent function modules to store setting values and monitor values.</td>
</tr>
<tr>
<td>Built-in Ethernet port CPU</td>
<td>A generic term for MELSEC-Q series and MELSEC-L series with built-in Ethernet port</td>
</tr>
<tr>
<td>C24</td>
<td>Another term for serial communication modules</td>
</tr>
<tr>
<td>CC-Link IE</td>
<td>A generic term for CC-Link IE Controller Network and CC-Link IE Field Network</td>
</tr>
<tr>
<td>Connected station (host station)</td>
<td>Connected station (host station) indicates a station directly connected to external devices</td>
</tr>
<tr>
<td>Control CPU</td>
<td>A CPU module that controls each module. In a multiple CPU system, a control CPU can be set for each module.</td>
</tr>
<tr>
<td>CPU module</td>
<td>A generic term for MELSEC programmable controller CPU</td>
</tr>
<tr>
<td>Device</td>
<td>Supported devices and internal devices (X, Y, W, etc.) of the CPU modules</td>
</tr>
<tr>
<td>E71</td>
<td>Another term for Ethernet interface modules</td>
</tr>
<tr>
<td>Engineering tool</td>
<td>A tool for setting, programming, debugging, and maintaining programmable controllers. The tool indicates GX Developer, GX Works2, and GX Works3 etc. For the supported tools, refer to the following manual. The user's manual for the module used or the MELSEC iQ-R Module Configuration Manual</td>
</tr>
<tr>
<td>External device</td>
<td>A device which sends request message to the supported devices (such as a personal computer, HIM, measuring instrument, ID units, barcode readers, regulators, and C24s)</td>
</tr>
<tr>
<td>Intelligent function module</td>
<td>A generic term for MELSEC iQ-R series modules, MELSEC-Q series modules, and MELSEC-L series modules that have functions other than input or output, such as A/D or D/A converter modules</td>
</tr>
<tr>
<td>LCPU</td>
<td>A generic term for MELSEC-L series CPU modules</td>
</tr>
<tr>
<td>Link device</td>
<td>Internal devices (LX/LY/LB/LW/RX/RY/RW/RRw) of the network modules</td>
</tr>
<tr>
<td>MC protocol</td>
<td>An abbreviation for MELSEC communication protocol. Protocols to access supported devices or programmable controller connected to supported devices from external devices.</td>
</tr>
<tr>
<td>Module access device</td>
<td>A generic term for module device access of MELSEC iQ-R series and intelligent function module devices of MELSEC-Q/L series</td>
</tr>
<tr>
<td>Multidrop connection</td>
<td>A connection when connecting a personal computer and multiple external devices or C24s in 1:n or m:n basis using RS-422/485 interface</td>
</tr>
<tr>
<td>Network module</td>
<td>A generic term for MELSEC programmable controller which can be connected to Ethernet, CC-Link IE Field Network, CC-Link IE Controller Network, MELSECNET/H, and MELSECNET/10.</td>
</tr>
<tr>
<td>Other station</td>
<td>Other station indicates a station connected to the connected station (host station) on the network.</td>
</tr>
<tr>
<td>QCPU</td>
<td>A generic term for MELSEC-Q series CPU modules</td>
</tr>
<tr>
<td>QnACPU</td>
<td>A generic term for MELSEC-QnA series CPU modules</td>
</tr>
<tr>
<td>RCPU</td>
<td>A generic term for MELSEC iQ-R series CPU module</td>
</tr>
<tr>
<td>Relay station</td>
<td>A station that relays data link to other station with mounting more than one network modules on one programmable controller.</td>
</tr>
<tr>
<td>Response message</td>
<td>A processing result message sent from SLMP compatible devices in response to the request message</td>
</tr>
<tr>
<td>Request message</td>
<td>A processing request message sent from external devices to the supported devices</td>
</tr>
<tr>
<td>Special function module</td>
<td>A generic term for MELSEC A series modules and MELSEC-QnA series modules that have functions other than input or output, such as A/D or D/A converter modules</td>
</tr>
<tr>
<td>Supported device</td>
<td>A generic term for devices which receive MC protocol messages</td>
</tr>
<tr>
<td>User frame</td>
<td>A data name used when registering the fixed format part in a message to be transmitted between an external device and a serial communication module, and using it for data transmission and reception. (The content of data in a user frame must be the same as the specifications of the external device.) Register the order (transmission control code, C24 station No., sum check, fixed data, etc.) of the head and end part of a message to be transmitted to serial communication module. This function is used for the on-demand function of MC protocol and the data send/receive function by nonprocedural protocol.</td>
</tr>
</tbody>
</table>
MELSEC communication protocol (hereinafter abbreviated as MC protocol) is a communication protocol for MELSEC programmable controller used when accessing programmable controller from an external device via C24 or E71. This part explains the overview and basic operations of MC protocol.

1 ABILITY OF MC PROTOCOL

2 SUPPORTED DEVICES AND ACCESS RANGES

3 COMMUNICATION PROCEDURE
1 ABILITY OF MC PROTOCOL

This chapter explains the purposes and features of the MC protocol.

1.1 Purposes

MC protocol performs data communication to control a programmable controller system on the external devices (such as a personal computer, GOT).

**Reading and writing data**

By reading/writing data to/from the device memory of the CPU module and buffer memory of the intelligent function modules, the following operations can be performed:

- **Reading data**
  Operation monitoring, data analysis, production control, etc. of the CPU module can be performed on the external device.

- **Writing data**
  Production instructions can be issued from the external device.

**Reading and writing files**

By reading/writing files such as programs and parameters stored in the CPU module, the following operations can be performed:

- **Reading files**
  File management for the CPU modules of the connected station (host station) and other station can be performed on the external device.

- **Writing files**
  Execution programs can be modified (replaced) by writing file data stored in the external device to the programmable controller CPU as necessary.

**Remote control of CPU module**

The CPU module can be remotely controlled from the external device by performing remote RUN/STOP/PAUSE/Latch Clear/RESET operations.

**Monitoring CPU module**

The status of CPU module and data in the device memory can be sent to an external device at constant intervals, upon the occurrence of a mechanical error, or when certain conditions are satisfied.

**Data transmission from CPU module to external device (On-demand function)**

The emergency data that is required to notify to external devices can be sent from the CPU module.
1.2 Features

Communication from external device without using sequential programs

The programmable controller transmits data in accordance with the commands from an external device. Thus, a program for data communication is not required for CPU module. (When using on-demand functions with C24, a sequence program for data communication from CPU module is required.)

Communication protocols of C24/E71

The message formats and control procedures for an external device to access a programmable controller are defined for each supported device.

Accessible via various network

By using MC protocol, accessing other station via various network can be performed seamlessly.
This chapter explains the supported modules and accessible modules.

## 2.1 Supported Devices

Communications using the MC protocol can be performed as an external device if a device can incorporate application programs and send/receive data using the control procedures of the MC protocol.

This manual explains MC protocol communication when connecting the devices shown below and external devices.

<table>
<thead>
<tr>
<th>Type</th>
<th>Series</th>
<th>Model name</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Serial communication module</td>
<td>MELSEC iQ-R series</td>
<td>RJ71C24, RJ71C24-R2, RJ71C24-R4</td>
<td>Page 26 MESSAGES OF SERIAL COMMUNICATION MODULE</td>
</tr>
<tr>
<td></td>
<td>MELSEC-L series</td>
<td>LJ71C24, LJ71C24-R2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>MELSEC-Q series</td>
<td>QJ71C24N, QJ71C24N-R2, QJ71C24N-R4, QJ71C24, QJ71C24-R2</td>
<td></td>
</tr>
<tr>
<td>Ethernet interface module</td>
<td>MELSEC-L series</td>
<td>LJ71E71-100</td>
<td>Page 37 MESSAGES OF ETHERNET INTERFACE MODULE</td>
</tr>
<tr>
<td></td>
<td>MELSEC-Q series</td>
<td>QJ71E71-100, QJ71E71-B5, QJ71E71-B2</td>
<td></td>
</tr>
</tbody>
</table>

## 2.2 Accessible Range and Accessible Modules

A CPU module and other station on the network can be accessed via a supported device.

**Accessible range**

The following devices are accessible.

- Supported devices that are connected to the external device directly (connected station)
- Other stations on the same network with the supported devices \(^*1\)
- Other stations on the other network that are connected to other station in the same network with the supported device \(^*1\)

\(^*1\) Other station on which network No. and station No. is set, and a multidrop connection station can be accessed.

The accessible range differs in types (frames) of a message format.

The following figure shows the maximum range that can be accessed.

![Diagram of Accessible Range](image)

For the accessible range of each message, refer to the following sections.

<table>
<thead>
<tr>
<th>Message formats of serial communication modules</th>
<th>Message formats of Ethernet interface modules</th>
</tr>
</thead>
<tbody>
<tr>
<td>• Page 43 Accessible range of 4C frame</td>
<td>• Page 46 Accessible range of 4E frame, 3E frame</td>
</tr>
<tr>
<td>• Page 44 Accessible range of 3C frame</td>
<td>• Page 47 Accessible range of 1E frame</td>
</tr>
<tr>
<td>• Page 44 Accessible range of 2C frame</td>
<td></td>
</tr>
<tr>
<td>• Page 45 Accessible range of 1C frame</td>
<td></td>
</tr>
</tbody>
</table>

For details on the accessible range of programmable controllers of other stations on a network system, refer to the manual for the network system used.

The multiple CPU system is supported. For details on the multiple CPU system, refer to the following section.

\[^*\] Page 455 Compatibility with Multiple CPU Systems
Accessible modules

The following modules in the access range can be accessed however, the commands that can be used have some restrictions. (Page 465 Accessible Modules for Each Command)
For the access to A series and QnA series modules, refer to the following sections.
- For QnA series: Page 280 MELSEC-QnA SERIES SUPPORTED SPECIFICATIONS
- For A series: Page 336 MELSEC-A SERIES SUPPORTED SPECIFICATIONS
For the restrictions for model name and version of the supported module, refer to the manual of each module.

Connectable modules

The following modules can be connected from an external device with the serial communication.
- Serial communication module
- CPU modules that have serial communication function
For the serial communication functions, refer to the user's manual of the CPU module used.
- QnUCPU User's Manual (Function Explanation, Program Fundamentals)

The following modules can be connected from an external device with the Ethernet communication.
- Ethernet interface module
- Built-in Ethernet CPU module
For Ethernet built-in CPU modules, refer to the user's manual of the CPU module used.
- MELSEC-L CPU Module User's Manual (Built-In Ethernet Function)
- QnUCPU User's Manual (Communication via Built-in Ethernet Port)

Accessible modules via supported device

The following modules are accessible from the connected station (host station) or other station.
- CPU module
- MELSECNET/H remote I/O station
- CC-Link IE Field Network head module
- Intelligent function module

Modules that can be relayed between networks

The networks that can be relayed by setting the network No. and station No., and the devices that can be relayed are shown below.

<table>
<thead>
<tr>
<th>Network</th>
<th>Module type</th>
<th>Model name</th>
</tr>
</thead>
<tbody>
<tr>
<td>CC-Link IE Field Network</td>
<td>CC-Link IE Field Network master/local-equipped module</td>
<td>RJ71GF11-T2, RJ71EN71 (when using the CC-Link IE Field Network function)</td>
</tr>
<tr>
<td></td>
<td>CC-Link IE Field Network master/local module</td>
<td>LJ71GF11-T2, QJ71GF11-T2, QS0J71GF11-T2</td>
</tr>
<tr>
<td>CC-Link IE Controller Network</td>
<td>CC-Link IE Controller Network-equipped module</td>
<td>RJ71GP21-SX</td>
</tr>
<tr>
<td></td>
<td>CC-Link IE Controller Network module</td>
<td>QJ71GP21-SX, QJ71GP21S-SX</td>
</tr>
<tr>
<td>MELSECNET/H</td>
<td>MELSECNET/H module</td>
<td>QJ71LP21, QJ71LP21-25, QJ71LP21S-25, QJ71LP21G, QJ71BR11, QJ71NT11B</td>
</tr>
<tr>
<td>Ethernet</td>
<td>Ethernet interface module</td>
<td>RJ71EN71, LJT1E71-100, QJ71E71-100, QJ71E71-B5, QJ71E71-B2, QJ71E71</td>
</tr>
</tbody>
</table>

In the circumstances that multiple network modules with the same network No. are mounted on the station with C24/E71, the access to other stations is performed via the network module mounted on the slot that has the lowest base unit number when the network No. is specified.

The following networks are accessible.
- Ethernet (Setting the network No. and station No. are required.)
- CC-Link IE Controller Network
- CC-Link IE Field Network
- MELSECNET/H

Up to 8 connection targets (relay stations: 7 stations) can be accessed.
This chapter explains the considerations when performing communication from an external devices to the programmable controller system using MC protocol.

### 3.1 Features of Communication Process

The following shows the features of data communication using MC protocol.

#### Request messages and response messages

There are two types of messages in MC protocol; request message and response message. The request message sent from the external device is processed in the CPU module via MC protocol supported devices. The processing result is returned as a response message to the external device.

**Half-duplex communication**

Data communication by MC protocol is performed with half-duplex communication.¹

When accessing CPU module, send the next command message after receiving the response message against the previously sent command message from the CPU module. (The command messages cannot be sent until the reception of the response message is completed.)

When the system between external devices and CPU module is configured with an m:n connection, the next command message cannot be sent until data communication between either of the external devices and CPU modules is completed.

¹ When using the on-demand function using C24, full-duplex communication can be performed.
3.2 Considerations

The following are the considerations when performing data communication.

When accessing CPU module

The following are the considerations when accessing a CPU module from an external device via a supported device.

■ Processing timing of CPU module

Processing for a request message is performed during an END processing of CPU module.

1. Send a request message from the external device to a supported device.
2. When the request message is received from the external device to the target device, a data read request or write request is issued to the CPU module.
3. In accordance with the request issued from the external device during END processing from the external device, CPU modules reads/writes data and then sends the processing result back to the supported device.
4. Once the supported device receives a processing result from the CPU module, send a response message including the processing result to the external device.

■ Read or write data while CPU module is in RUN

• Due to process the request from the external device, scan time of the CPU module will be extended. If the extension of the scan time affects the control, access the CPU module several times with less number of points.
• Before writing, check whether the online change is enabled (such as whether the system protection is unlocked or not) on the CPU module side.

■ When the access target CPU module is protected by system protection

An error occurs at the access target, and an abnormal response is sent back to the external device. Unlock the system protection of the CPU module side, and resend the request message.

■ When access requests are sent to one station from several external devices at the same time

Depending on the request timing, the processing requested from the external device may be on hold until several END processing take place. By using either of the following methods, multiple requests can be processed in one scan.
• Execute COM instruction by program.
• Ensure 1 to 100 ms of service processing time using "Service Processing Setting" of Engineering tool.
When accessing MELSECNET/H or MELSECNET/10 remote I/O station

The following are the considerations when accessing a MELSECNET/H remote I/O station or MELSECNET/10 remote I/O station from external devices.

■ Considerations for supported frames

1E frame cannot be used for communication.

■ Functions that can be used

The functions that can be used for remote I/O station are as follows:

<table>
<thead>
<tr>
<th>Function</th>
<th>MELSECNET/H remote I/O station</th>
<th>MELSECNET/10 remote I/O station</th>
</tr>
</thead>
<tbody>
<tr>
<td>Read/write device memory</td>
<td>☐</td>
<td>—</td>
</tr>
<tr>
<td>Read/write buffer memory</td>
<td>☐</td>
<td>—</td>
</tr>
<tr>
<td>Read/write intelligent function module</td>
<td>☐</td>
<td>☐</td>
</tr>
<tr>
<td>Programmable controller CPU monitoring function (only when C24 is mounted) *1</td>
<td>☐</td>
<td>—</td>
</tr>
</tbody>
</table>

*1  The monitoring target devices can be registered within the device range of MELSECNET/H remote I/O station. Only reading from/writing to the buffer memory of intelligent function module is available for MELSECNET/10 remote I/O stations supported by QnA/A series.

■ When writing data

When writing data to the devices of the remote I/O station or intelligent function module mounted on the remote I/O station, set the setting of online program change to allow with Engineering tool.

(☞ Page 458 Setting method for writing data to CPU during RUN)

■ Accessible range of other station

Accessing MELSECNET/H remote master station and MELSECNET/H remote I/O station can be performed from E71 with MELSECNET/H remote I/O station mounted.

Other station cannot be accessed via a remote I/O station. (A remote I/O station does not work as a relay station.)
Considerations when connecting C24

The following shows the considerations when performing data communication between C24.

### Conditions that C24 transmission sequence becomes initial status

The transmission sequence of C24 becomes initial status under the following conditions.
- When turning the power ON, changing the status of reset switch on the front of the CPU, and switching modes.
- When the transmission of a response message for the command message reception is completed.
- When a transmission sequence initialization request is received.
- When the CD signal turns OFF while performing data communication by setting the "CD terminal check enable" in the full-duplex communication of RS-232.

### Abnormal response from C24

An abnormal response to the external device using MC protocol is issued when an error is detected in the request sent to the connected station (host station). Therefore, an abnormal response may be issued while sending request from the external device in the full-duplex communication.

### Replacement of other station CPU modules to communicate with

C24 imports and retains the information of other station CPU modules after started up.
When replacing the other station CPU module to perform data communication after starting up C24, reboot the C24 if the model name of the CPU module is changed. (Reset the programmable controller of the connected station (host station)/CPU reset).

### Framing error on external device

A framing error may occur on the external device when nothing is sent from C24 to the external device via RS-422/485.

- Q Corresponding Serial Communication Module User's Manual (Basic)
- MELSEC-L Serial Communication Module User's Manual (Basic)
- MELSEC iQ-R Serial Communication Module User's Manual (Application)

Skip reading data until C24 sends either STX, ACK, or NAK on the external device.
Before the data communication, check the C24 interface specification written in the following manuals.

- Q Corresponding Serial Communication Module User's Manual (Basic)
- MELSEC-L Serial Communication Module User's Manual (Basic)
- MELSEC iQ-R Serial Communication Module User's Manual (Startup)

### Installation of multiple C24s

When multiple external devices that are connected to each C24 request access to the CPU module at the same time, the CPU module decides the order of access.
The access priority order cannot be set by user.
Considerations when connection E71

Send of request message
Before sending a request message, check that the supported device is ready to receive the request message.

When sending multiple request messages
For 4E frame, send the request message with appending "Serial No." to the subheader on the external device. By appending "Serial No.", the send source can be identified when multiple request messages have been sent.

When sending request message continuously
When sending request messages consecutively without waiting for the reception of the response message using 4E frame, make sure that the number of command messages shown below are not exceeded.

<table>
<thead>
<tr>
<th>Name</th>
<th>Model name</th>
<th>TCP/UDP</th>
<th>Applicable number of commands for processing per one connection(^1)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ethernet interface module</td>
<td>QJ71E71-100, LJ71E71-100</td>
<td>TCP</td>
<td>(6144 - Message size (byte))</td>
</tr>
<tr>
<td></td>
<td></td>
<td>UDP</td>
<td>1 * (57 - Number of connections to be used)</td>
</tr>
<tr>
<td>Ethernet interface module</td>
<td>QJ71E71-B2, QJ71E71-B5</td>
<td>TCP</td>
<td>(5120 - Message size (byte))</td>
</tr>
<tr>
<td></td>
<td></td>
<td>UDP</td>
<td>1 * (10 - Number of connections to be used)</td>
</tr>
</tbody>
</table>

\(^1\) If the calculation result became decimal, the number after the decimal points will be rounded off to positive number.

Any of the following symptoms occurs when the exceeded number of commands are sent. In such case, decrease the frequency of request message transmission.

- For TCP/IP, the receive buffer memory of supported device will be full. Since the window size becomes '0', the transmission of request messages will be stopped temporarily until enough receive buffer space becomes available.
- For UDP/IP, an error may occur in the supported device, or response messages may not be returned from the supported device.

When the response message corresponding to the request message does not return
If the response message is not returned from the supported device, resend the request message from the external device after the specified time set with "Monitoring timer" of the request message is elapsed.

Replacement of devices
After replacing a device on Ethernet due to failure, the devices may not communicate properly because of the change of the MAC address. (When replaced with the device that has the same IP address)

When a device in the Ethernet network is replaced, restart all devices in the network.
This part explains the message format of MC protocol.

4 MESSAGES OF SERIAL COMMUNICATION MODULE

5 MESSAGES OF ETHERNET INTERFACE MODULE

6 ACCESS ROUTE SETTINGS
4 MESSAGES OF SERIAL COMMUNICATION MODULE

This section explains the specifications of the messages of MC protocol and access range when connecting with serial communication from an external device.

4.1 Types and Purposes of Messages

The messages of MC protocol can be classified as shown in the following table depending on the supported device and its intended purpose.

**Formats and codes**

There are five formats for the message that can be used for serial communication module.

<table>
<thead>
<tr>
<th>Setting value</th>
<th>Format</th>
<th>Code of communication data</th>
<th>Remarks</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Format 1</td>
<td>ASCII code</td>
<td>—</td>
<td>Page 27 Format 1</td>
</tr>
<tr>
<td>2</td>
<td>Format 2</td>
<td>ASCII code</td>
<td>Format with block number appended</td>
<td>Page 28 Format 2</td>
</tr>
<tr>
<td>3</td>
<td>Format 3</td>
<td>ASCII code</td>
<td>Format enclosed with STX and ETX</td>
<td>Page 29 Format 3</td>
</tr>
<tr>
<td>4</td>
<td>Format 4</td>
<td>ASCII code</td>
<td>Format with CR and LF appended at the end</td>
<td>Page 30 Format 4</td>
</tr>
<tr>
<td>5</td>
<td>Format 5</td>
<td>Binary code</td>
<td>Can be used by 4C frame.</td>
<td>Page 31 Format 5</td>
</tr>
</tbody>
</table>

Set the format with the communication protocol setting of Engineering tool.

---

Communication using binary code shorten the communication time since the amount of communication data is reduced by approximately half as compared to the one using ASCII code.

**Frame**

This section explains the types and purposes of the frames (data communication messages) used by the external device to access the supported devices using MC protocol.

The frames for serial communication modules are as follows:

<table>
<thead>
<tr>
<th>Frame</th>
<th>Features and purposes</th>
<th>Compatible message format</th>
<th>Format</th>
</tr>
</thead>
<tbody>
<tr>
<td>4C frame</td>
<td>Accessible from external devices with the maximum access range.</td>
<td>Dedicated protocols for MELSEC-QnA series serial communication modules (QnA extension frame).</td>
<td>Formats 1 to 5</td>
</tr>
<tr>
<td>3C frame</td>
<td>These message formats are simplified compared to the 4C frame. Data communication software for MELSEC-QnA series programmable controllers can be used.</td>
<td>Dedicated protocols for MELSEC-QnA series serial communication modules (QnA frame).</td>
<td>Formats 1 to 4</td>
</tr>
<tr>
<td>2C frame</td>
<td></td>
<td>Dedicated protocols for MELSEC-QnA series serial communication modules (QnA simplified frame).</td>
<td></td>
</tr>
<tr>
<td>1C frame</td>
<td>These frames have the same message structures as when accessing the CPU module using an MELSEC-A series computer link module. Data communication software for MELSEC-A series programmable controllers can be used.</td>
<td>Dedicated protocols for MELSEC-A series computer link modules</td>
<td></td>
</tr>
</tbody>
</table>

---
4.2 Message Formats of Each Protocol

This section explains the message format and setting data per each format.

Format 1

Message format

- **Request message**

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Request data</th>
<th>Sum check code</th>
</tr>
</thead>
</table>

- **Response message (Normal completion: Response data)**

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Response data</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
</table>

- **Response message (Normal completion: No response data)**

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
</tr>
</thead>
</table>

- **Response message (Abnormal completion)**

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Error code</th>
</tr>
</thead>
</table>

Setting data

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control code</td>
<td>A code is defined for control.</td>
<td>Page 32 Control code</td>
</tr>
<tr>
<td>(ENQ, STX, ACK, NAK, ETX)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Frame ID No.</td>
<td>Specify the frame to be used.</td>
<td>Page 34 Frame ID No.</td>
</tr>
<tr>
<td>Access route</td>
<td>Specify the access route.</td>
<td>Page 43 ACCESS ROUTE SETTINGS</td>
</tr>
<tr>
<td>Request data</td>
<td>Set the command that indicates the request content. Refer to &quot;Request data&quot; rows of each command.</td>
<td>Page 58 COMMANDS AND FUNCTIONS</td>
</tr>
<tr>
<td>Response data</td>
<td>Store the read data for the command. Refer to &quot;Response data&quot; rows of each command.</td>
<td></td>
</tr>
<tr>
<td>Sum check code</td>
<td>The value of the lower one byte (8 bits) of the additional result regarding the data in the sum check target range as a binary data.</td>
<td>Page 34 Sum check code</td>
</tr>
<tr>
<td>Error code</td>
<td>Error code indicates the content of occurred error.</td>
<td>Page 36 Error code</td>
</tr>
</tbody>
</table>
Format 2

Message format

<table>
<thead>
<tr>
<th>Request message</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control code</td>
</tr>
<tr>
<td>ENQ</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Response message (Normal completion: Response data)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control code</td>
</tr>
<tr>
<td>STX</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Response message (Normal completion: No response data)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control code</td>
</tr>
<tr>
<td>ACK</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Response message (Abnormal completion)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control code</td>
</tr>
<tr>
<td>NAK</td>
</tr>
</tbody>
</table>

Setting data

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control code</td>
<td>A code is defined for control.</td>
<td>Page 32 Control code</td>
</tr>
<tr>
<td>(ENQ, STX, ACK, NAK, ETX)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Block number</td>
<td>This can set arbitrarily in the range of '00H' to 'FFH'. It is used for data defragmentation.</td>
<td>Page 34 Block number</td>
</tr>
<tr>
<td>Frame ID No.</td>
<td>Specify the frame to be used.</td>
<td>Page 34 Frame ID No.</td>
</tr>
<tr>
<td>Access route</td>
<td>Specify the access route.</td>
<td>Page 43 ACCESS ROUTE SETTINGS</td>
</tr>
<tr>
<td>Request data</td>
<td>Set the command that indicates the request content. Refer to &quot;Request data&quot; rows of each command.</td>
<td>Page 58 COMMANDS AND FUNCTIONS</td>
</tr>
<tr>
<td>Response data</td>
<td>Store the read data for the command. Refer to &quot;Response data&quot; rows of each command.</td>
<td></td>
</tr>
<tr>
<td>Sum check code</td>
<td>The value of the lower one byte (8 bits) of the additional result regarding the data in the sum check target range as a binary data.</td>
<td>Page 34 Sum check code</td>
</tr>
<tr>
<td>Error code</td>
<td>Error code indicates the content of occurred error.</td>
<td>Page 36 Error code</td>
</tr>
</tbody>
</table>
Format 3

Message format

■ Request message

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Request data</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
<tbody>
<tr>
<td>STX/ETX</td>
<td></td>
<td></td>
<td></td>
<td>STX/ETX</td>
<td></td>
</tr>
</tbody>
</table>

■ Response message (Normal completion: Response data)

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>End code</th>
<th>Response data</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
<tbody>
<tr>
<td>STX/ETX</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>STX/ETX</td>
<td></td>
</tr>
</tbody>
</table>

■ Response message (Normal completion: No response data)

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>End code</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
<tbody>
<tr>
<td>STX/ETX</td>
<td></td>
<td></td>
<td></td>
<td>STX/ETX</td>
<td></td>
</tr>
</tbody>
</table>

■ Response message (Abnormal completion)

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>End code</th>
<th>Error code</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
<tbody>
<tr>
<td>STX/ETX</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>STX/ETX</td>
<td></td>
</tr>
</tbody>
</table>

Setting data

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control code</td>
<td>A code is defined for control.</td>
<td>Page 32 Control code</td>
</tr>
<tr>
<td>Frame ID No.</td>
<td>Specify the frame to be used.</td>
<td>Page 34 Frame ID No.</td>
</tr>
<tr>
<td>Access route</td>
<td>Specify the access route.</td>
<td>Page 43 ACCESS ROUTE SETTINGS</td>
</tr>
<tr>
<td>Request data</td>
<td>Set the command that indicates the request content. Refer to &quot;Request data&quot; rows of each command.</td>
<td>Page 58 COMMANDS AND FUNCTIONS</td>
</tr>
<tr>
<td>Response data</td>
<td>Store the read data for the command. Refer to &quot;Response data&quot; rows of each command.</td>
<td></td>
</tr>
<tr>
<td>Sum check code</td>
<td>The value of the lower one byte (8 bits) of the additional result regarding the data in the sum check target range as a binary data.</td>
<td>Page 34 Sum check code</td>
</tr>
</tbody>
</table>
| End code        | Indicates that the processing result is a normal completion or abnormal completion.  
                  • 4C/3C/2C frame: QACK (normal), QNAK (abnormal)  
                  • 1C frame: GG (normal completion), NN (abnormal completion) | Page 36 End code |
| Error code      | Error code indicates the content of occurred error.                         | Page 36 Error code |
Format 4

Message format

■ Request message

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Request data</th>
<th>Sum check code</th>
<th>Control code</th>
</tr>
</thead>
<tbody>
<tr>
<td>ENQ, STX, ACK, NAK, ETX, CR, LF</td>
<td>06h</td>
<td></td>
<td></td>
<td>CR</td>
<td>0Dh, LF</td>
</tr>
</tbody>
</table>

■ Response message (Normal completion: Response data)

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Response data</th>
<th>Control code</th>
<th>Sum check code</th>
<th>Control code</th>
</tr>
</thead>
<tbody>
<tr>
<td>STX, 02h</td>
<td></td>
<td></td>
<td>ETX, 03h</td>
<td>CR</td>
<td>0Dh, LF</td>
<td></td>
</tr>
</tbody>
</table>

■ Response message (Normal completion: No response data)

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Control code</th>
<th>Sum check code</th>
<th>Control code</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACK, 06h</td>
<td></td>
<td></td>
<td>CR, LF</td>
<td>0Dh, 0Ah</td>
<td></td>
</tr>
</tbody>
</table>

■ Response message (Abnormal completion)

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Error code</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
<tbody>
<tr>
<td>NAK, 15h</td>
<td></td>
<td></td>
<td>CR, LF</td>
<td>0Dh, 0Ah</td>
<td></td>
</tr>
</tbody>
</table>

Setting data

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control code (ENQ, STX, ACK, NAK, ETX, CR, LF)</td>
<td>A code is defined for control.</td>
<td>Page 32 Control code</td>
</tr>
<tr>
<td>Frame ID No.</td>
<td>Specify the frame to be used.</td>
<td>Page 34 Frame ID No.</td>
</tr>
<tr>
<td>Access route</td>
<td>Specify the access route.</td>
<td>Page 43 ACCESS ROUTE SETTINGS</td>
</tr>
<tr>
<td>Request data</td>
<td>Set the command that indicates the request content. Refer to &quot;Request data&quot; rows of each command.</td>
<td>Page 56 COMMANDS AND FUNCTIONS</td>
</tr>
<tr>
<td>Response data</td>
<td>Store the read data for the command. Refer to &quot;Response data&quot; rows of each command.</td>
<td></td>
</tr>
<tr>
<td>Sum check code</td>
<td>The value of the lower one byte (8 bits) of the additional result regarding the data in the sum check target range as a binary data.</td>
<td>Page 34 Sum check code</td>
</tr>
<tr>
<td>Error code</td>
<td>Error code indicates the content of occurred error.</td>
<td>Page 36 Error code</td>
</tr>
</tbody>
</table>
Format 5

Message format

■ Request message

<table>
<thead>
<tr>
<th>Control code</th>
<th>Number of data bytes</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Request data</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
<tbody>
<tr>
<td>DLE 10H</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>STX 02H</td>
<td></td>
</tr>
</tbody>
</table>

■ Response message (Normal completion: Response data)

<table>
<thead>
<tr>
<th>Control code</th>
<th>Number of data bytes</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Response ID code</th>
<th>Normal completion code</th>
<th>Response data</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
<tbody>
<tr>
<td>DLE 10H</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>STX 02H</td>
<td></td>
</tr>
</tbody>
</table>

■ Response message (Normal completion: No response data)

<table>
<thead>
<tr>
<th>Control code</th>
<th>Number of data bytes</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Response ID code</th>
<th>Normal completion code</th>
<th>Response data</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
<tbody>
<tr>
<td>DLE 10H</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>STX 02H</td>
<td></td>
</tr>
</tbody>
</table>

■ Response message (Abnormal completion)

<table>
<thead>
<tr>
<th>Control code</th>
<th>Number of data bytes</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Response ID code</th>
<th>Error codes</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
<tbody>
<tr>
<td>DLE 10H</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>STX 02H</td>
<td></td>
</tr>
</tbody>
</table>

Setting data

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control code</td>
<td>A code is defined for control.</td>
<td>Page 32 Control code</td>
</tr>
<tr>
<td>Number of data bytes</td>
<td>A number of bytes from a frame ID No. to control code (DLE, ETX).</td>
<td>Page 33 Number of data bytes</td>
</tr>
<tr>
<td>Frame ID No.</td>
<td>Specify the frame to be used.</td>
<td>Page 34 Frame ID No.</td>
</tr>
<tr>
<td>Access route</td>
<td>Specify the access route.</td>
<td>Page 43 ACCESS ROUTE SETTINGS</td>
</tr>
<tr>
<td>Request data</td>
<td>Set the command that indicates the request content. Refer to “Request data” rows of each command.</td>
<td>Page 56 COMMANDS AND FUNCTIONS</td>
</tr>
<tr>
<td>Response data</td>
<td>Store the read data for the command. Refer to “Response data” rows of each command.</td>
<td></td>
</tr>
<tr>
<td>Sum check code</td>
<td>The value of the lower one byte (8 bits) of the additional result regarding the data in the sum check target range as a binary data.</td>
<td>Page 34 Sum check code</td>
</tr>
<tr>
<td>Response ID code</td>
<td>This indicates a response message. The 2-byte numerical value, ‘FFFFH’ is stored.</td>
<td></td>
</tr>
<tr>
<td>Normal completion code</td>
<td>This indicates the processing is completed normally. The 2-byte value, ‘0000H’ is stored.</td>
<td></td>
</tr>
<tr>
<td>Error code</td>
<td>Error code indicates the content of occurred error.</td>
<td>Page 36 Error code</td>
</tr>
</tbody>
</table>
4.3 Details of Setting Data

This section explains how to specify the common data items and their content in each message.

Control code

Control code is a data that has special meaning (such as head data of a message) for C24 transmission control.

Control code used in a message (format 1 to format 4) in ASCII code

The control code used for a message in ASCII code (format 1 to format 4) is shown in the following table.

<table>
<thead>
<tr>
<th>Symbol name</th>
<th>Description</th>
<th>Code (hexadecimal)</th>
</tr>
</thead>
<tbody>
<tr>
<td>STX</td>
<td>Start of Text</td>
<td>02H</td>
</tr>
<tr>
<td>ETX</td>
<td>End of Text</td>
<td>03H</td>
</tr>
<tr>
<td>EOT</td>
<td>End of Transmission</td>
<td>04H</td>
</tr>
<tr>
<td>ENQ</td>
<td>Enquiry</td>
<td>05H</td>
</tr>
<tr>
<td>ACK</td>
<td>Acknowledge</td>
<td>06H</td>
</tr>
<tr>
<td>LF</td>
<td>Line Feed</td>
<td>0AH</td>
</tr>
<tr>
<td>CL</td>
<td>Clear</td>
<td>0CH</td>
</tr>
<tr>
<td>CR</td>
<td>Carriage Return</td>
<td>0DH</td>
</tr>
<tr>
<td>NAK</td>
<td>Negative Acknowledge</td>
<td>15H</td>
</tr>
</tbody>
</table>

■ EOT (04H), CL (0CH)

EOT and CL are codes for initializing the transmission sequence for data communications in ASCII code using the MC protocol and for placing C24 into wait state to receive commands from an external device.

The transmission sequence is initialized with the command (command code: 1615) when binary code (format 5) is used. When performing the following at an external device, send the EOT/CL to the C24 depending on the format used.

- Canceling a read/write request by command previously sent. (If a write request is issued, the write request cannot be canceled when the data has already written to the CPU module.)
- Placing C24 into the wait state to receive commands before commands are sent.
- Placing C24 into the state where it has been started up when data communication cannot be performed normally.

The message structure when sending EOT, CL is shown below.

Only the following data is sent. The station No. and PC No. are not required.

When C24 receives EOT or CL, it proceeds as follows.

- C24 terminates any read/write processing performed to the CPU module upon request from the external device. In this case, C24 does not send a response message to the command previously received.
- C24 initializes the transmission sequence using the MC protocol on the interface side and placing C24 into wait state to receive commands from an external device.
- C24 does not send a response message to the EOT or CL reception. (It does not send anything to external devices.)
- When it receives EOT or CL while the on-demand function (data transmission function from the CPU module to external devices) is being performed, C24 terminates to transmit the on-demand data to external devices. (Page 274 On-demand function)
Control code used in a message (format 5) in binary code

The control code used for a message in binary code (format 5) is shown in the table below.

<table>
<thead>
<tr>
<th>Symbol name</th>
<th>Description</th>
<th>Code (hexadecimal)</th>
</tr>
</thead>
<tbody>
<tr>
<td>STX</td>
<td>Start of Text</td>
<td>02H</td>
</tr>
<tr>
<td>ETX</td>
<td>End of Text</td>
<td>03H</td>
</tr>
<tr>
<td>DLE</td>
<td>Data Link Escape</td>
<td>10H</td>
</tr>
</tbody>
</table>

■ Additional code (10H)

The additional code is added to distinguish the data when the control code DLE (10H) is the same as the setting data in the frame 5.

When '10H' is included in the data from "Number of data bytes" and "Request data" in the request message, the additional code '10H' is added in front of the data.

When '10H' is included in the data from "Number of data bytes" and "Response data" in the response message, the additional code '10H' is added.

('10H' is transmitted as '10H' + '10H'.)

Calculate the following value except for the additional code.
- Number of data bytes (setting item of format 5)
- Sum check code

Number of data bytes

A number of data bytes indicates the total number of bytes from the frame ID No. to control code.

Range

Calculate the data in the range from frame ID No. before DLE (10H) except for the additional code. (Page 33 Additional code (10H))

Setting method

Set the data in binary code (format 5) at data communication.

Send 2-byte numerical value from the lower byte (L: bits 0 to 7).

Ex.

Response message (Normal completion: Response data)
- Frame ID No.: 1 byte
- Access route: 7 byte
- Response ID code, normal completion code: 4 bytes
- Response data: 2 bytes + additional code (10H) 1 byte

Number of data bytes = 1 + 7 + 4 + 2 = 14 (0EH)
Block number

Block number is an arbitrary number defined by an external device and used for data defragmentation. Block number converts data to 2-digit (hexadecimal) ASCII code within the range of ‘00H’ to ‘FFH’ and sent them from the upper digits. C24 only checks if the block number is specified within the correct range. It does not check whether the block numbers are sent in order.

Frame ID No.

Specify the frame to be used.

<table>
<thead>
<tr>
<th>Type</th>
<th>Setting value</th>
</tr>
</thead>
<tbody>
<tr>
<td>4C frame</td>
<td>F8</td>
</tr>
<tr>
<td>3C frame</td>
<td>F9</td>
</tr>
<tr>
<td>2C frame</td>
<td>FB</td>
</tr>
<tr>
<td>1C frame</td>
<td>— (Not required)</td>
</tr>
</tbody>
</table>

Setting method

■ Data communication in ASCII code
Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■ Data communication in binary code
Send 1-byte numerical value.

Ex.
For 4C frame (F8)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>F 8</td>
<td>F8</td>
</tr>
</tbody>
</table>

Sum check code

Set the sum check code when performing sum check. For sum check code, set the value to be calculated from the data with the range of sum check for error detection.

Sum check

Sum check is a function for detecting error when data changes while data transmission. Set the sum check existence by Engineering tool.

■ When sum check code is set to "Exist"
Attach a sum check code to the request message. C24 checks the sum check code. The sum check code is added to the response message.

■ When sum check code is set to "None"
The sum check code is not required for the request message. C24 does not check the sum check code. The sum check code is not added to the response message.
Sum check range

The sum check range of each message format is as follows:

<table>
<thead>
<tr>
<th>Format</th>
<th>Message structure</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Format 1 to format 3</td>
<td>Control code</td>
<td>Sum check code</td>
</tr>
<tr>
<td>Format 4</td>
<td>Control code</td>
<td>Sum check code</td>
</tr>
<tr>
<td>Format 5</td>
<td>Control code</td>
<td>Sum check code</td>
</tr>
</tbody>
</table>

**Calculation of a sum check code**

For sum check code, set the numerical values of the lower 1 byte (8 bits) of the added result (sum) as binary data within the sum check range.

Calculate sum check code except for the additional code. (Page 33 Additional code (10H))

**Ex**

In the following case of 1C frame format 1, the sum check code will be 'C0'.

Formula: 30H + 30H + 46H + 46H + 42H + 52H + 33H + 4DH + 30H + 30H + 30H + 30H = 2C0H

Sum check code: 'C0' (ASCII code 43H, 30H)

In the following case of 4C frame format 5, the sum check code will be '05'.

Formula: 12H + 00H + F8H + 05H + 07H + 03H + 04H + 00H + 01H + 00H + 01H + 04H + 01H + 00H + 40H + 00H + 00H + 40H + 00H + 00H + 9CH + 05H + 00H = 205H

Sum check code: '05' (ASCII code 30H, 35H)
Setting method

■ Data communication in ASCII code
Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■ Data communication in binary code
The same as the data communication in ASCII code, use the numerical value converted to the 2 digit ASCII code (hexadecimal).
Send 2-byte numerical value from the upper byte (H: bits 8 to 15).

Ex
Sum check code: ’05’ (ASCII code 30H, 35H)

End code

Indicates that the processing result is a normal completion or abnormal completion.
The following fixed value is stored.

<table>
<thead>
<tr>
<th>Processing result</th>
<th>4C frame, 3C frame, 2C frame</th>
<th>1C frame</th>
</tr>
</thead>
<tbody>
<tr>
<td>Normal completion</td>
<td>Q A C K 51H 41H 43H 48H</td>
<td>G G 40H 4EH</td>
</tr>
<tr>
<td>Abnormal completion</td>
<td>Q N A K 51H 46H 41H 48H</td>
<td>N N 46H 4EH</td>
</tr>
</tbody>
</table>

Error code

Error code indicates the content of occurred error.
If more than one error occurs at the same time, the error code detected first is returned.
For the content of error code and its corrective action, refer to the user's manual of the module used.

Q Corresponding Serial Communication Module User's Manual (Basic)
MELSEC-L Serial Communication Module User's Manual (Basic)
MELSEC iQ-R Serial Communication Module User's Manual (Application)

Setting method

■ Data communication in ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

■ Data communication in binary code
Send 2-byte numerical value from the lower byte (L: bits 0 to 7).

Ex
When error code 7151H is returned

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>7 1 5 1</td>
<td>51H 21H</td>
</tr>
</tbody>
</table>

For the error code of 1C frame, refer to the following section.
Page 342 Error code

36 4 MESSAGES OF SERIAL COMMUNICATION MODULE
4.3 Details of Setting Data
5  MESSAGES OF ETHERNET INTERFACE MODULE

This section explains the specifications of the messages and access range of MC protocol when connecting with Ethernet communication from an external device.

5.1 Types and Purposes of Messages

The messages of MC protocol can be classified as shown in the following table depending on the supported device and its intended purpose.

**Code**

ASCII code and binary code are available.

Set the operation settings with Engineering tool.

Communication using binary code shorten the communication time since the amount of communication data is reduced by approximately half as compared to the one using ASCII code.

**Data storage order**

The data size and the storing order of values for data in each item vary between ASCII code and binary code.

- **Data communication using ASCII code**
  Data is stored in order from the upper byte to the lower byte.

- **Data communication using binary code**
  Data is stored in order from the lower byte to the upper byte.

**Ex.**

Subheader of 4E frame request message (serial No. is ‘1234’)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Serial number</td>
<td>Serial number</td>
</tr>
<tr>
<td>5 4 0 0</td>
<td>5 0 0 0</td>
</tr>
<tr>
<td>35h 34h 30h 30h</td>
<td>30h 30h</td>
</tr>
</tbody>
</table>
### Frame

This section explains the types and purposes of the frames (data communication messages) used by the external device to access the supported devices using MC protocol.

The frames for Ethernet interface modules are as follows:

<table>
<thead>
<tr>
<th>Frame</th>
<th>Features and purposes</th>
<th>Compatible message format</th>
<th>Correspondence code</th>
</tr>
</thead>
<tbody>
<tr>
<td>4E frame</td>
<td>A message format that a &quot;Serial No.&quot; (arbitrary number for message identification) is added to 3E frame. By appending a &quot;Serial No.&quot;, the send source can be identified when multiple request messages have been sent.</td>
<td>Message formats for SLMP</td>
<td>ASCII code Binary code</td>
</tr>
<tr>
<td>3E frame</td>
<td>These frames have the same message structures as when accessing the CPU module using MELSEC-QnA series Ethernet interface module. Data communication software for MELSEC-QnA series programmable controllers can be used.</td>
<td>Message formats for SLMP Message formats for MELSEC-QnA series Ethernet interface modules</td>
<td>ASCII code Binary code</td>
</tr>
<tr>
<td>1E frame</td>
<td>These frames have the same message structures as when accessing the CPU module using an MELSEC-A series Ethernet interface module. Data communication software for MELSEC-A series programmable controllers can be used.</td>
<td>Message formats for MELSEC-A series Ethernet interface module</td>
<td>ASCII code Binary code</td>
</tr>
</tbody>
</table>
5.2 Message Format

This section explains the message format and setting data for 4E frame and 3E frames. For the message format for 1E frame, refer to the following section.

Message format

■ Request message

<table>
<thead>
<tr>
<th>Header</th>
<th>Subheader</th>
<th>Access route</th>
<th>Request data length</th>
<th>Monitoring timer</th>
<th>Request data</th>
</tr>
</thead>
</table>

Specify the number of bytes in this range.

■ Response message (At normal completion: Response data)

<table>
<thead>
<tr>
<th>Header</th>
<th>Subheader</th>
<th>Access route</th>
<th>Response data length</th>
<th>End code</th>
<th>Response data</th>
</tr>
</thead>
</table>

Specify the number of bytes in this range.

■ Response message (Normal completion: No response data)

<table>
<thead>
<tr>
<th>Header</th>
<th>Subheader</th>
<th>Access route</th>
<th>Response data length</th>
<th>End code</th>
</tr>
</thead>
</table>

Specify the number of bytes of the end code.

■ Response message (Normal completion: Response data)

<table>
<thead>
<tr>
<th>Header</th>
<th>Subheader</th>
<th>Access route</th>
<th>Response data length</th>
<th>End code</th>
<th>Error information</th>
</tr>
</thead>
</table>

Specify the number of bytes in this range.

Setting data

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Header</td>
<td>A header of Ethernet. Normally, it is added automatically.</td>
<td>Page 40 Header</td>
</tr>
<tr>
<td>Subheader</td>
<td>The value to be set according to type of message is defined.</td>
<td>Page 40 Subheader</td>
</tr>
<tr>
<td>Access route</td>
<td>Specify the access route.</td>
<td>Page 43 ACCESS ROUTE SETTINGS</td>
</tr>
<tr>
<td>Request data length</td>
<td>Specify the data length from the monitoring timer to the request data.</td>
<td>Page 41 Request data length and response data length</td>
</tr>
<tr>
<td>Monitoring timer</td>
<td>Set the wait time up to the completion of reading and writing processing.</td>
<td>Page 41 Monitoring timer</td>
</tr>
<tr>
<td>Request data</td>
<td>For the request data, set the command that indicates the request content. Refer to &quot;Request data&quot; rows of each command.</td>
<td>Page 58 COMMANDS AND FUNCTIONS</td>
</tr>
<tr>
<td>Response data length</td>
<td>The data length from an end code to a response data (at normal completion) or an error information (at abnormal completion) is stored.</td>
<td>Page 41 Request data length and response data length</td>
</tr>
<tr>
<td>Response data</td>
<td>For the response data, store the read data for the command at normal completion. Refer to &quot;Response data&quot; rows of each command.</td>
<td>Page 58 COMMANDS AND FUNCTIONS</td>
</tr>
<tr>
<td>End code</td>
<td>The command processing result is stored.</td>
<td>Page 42 End code</td>
</tr>
<tr>
<td>Error information</td>
<td>Store the information of a station on which an error occurred and information of a command.</td>
<td>Page 42 Error information</td>
</tr>
</tbody>
</table>
5.3 Details of Setting Data

This section explains how to specify the common data items and their content in each message. For the setting data with 1E frame, refer to the following section.

Header

A header for TCP/IP and UDP/IP. A header of a request message is added on the external device side and sent. Normally, it is added automatically by an external device. A header for a response message is set automatically by E71.

Subheader

The value to be set according to type of message is defined.

Setting method for 4E frame

Set the fixed value (request message: ‘5400’, response message: ‘D400’) and a serial No. (0000H to FFFFH).
A serial No. is an arbitrary number that is added on the external device side for message recognition. When a request message is sent with a serial No. added, the same serial No. is added to the response message. Use a serial No. when transmitting more than one request messages from an external device to the same supported device.

Serial No. added on the external device side must be managed at the external device side.

Data communication using ASCII code

It's 12 bytes in total.
A fixed value is set by 4-digit ASCII code.
For the serial No., convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.
The 4-byte '0' (30H) is inserted after the serial No.

Data communication using binary code

It's 6 bytes in total.
A fixed value is set in 2 bytes.
For the serial No., send 2-byte numerical value from the lower byte (L: bits 0 to 7).
The 2-byte '0' (00H) is inserted after the serial No.

Request message (serial No. ‘1234’)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Serial number</td>
<td>Serial number</td>
</tr>
<tr>
<td>5 4 0 0</td>
<td>5 4 0 0</td>
</tr>
<tr>
<td>35H, 34H, 30H, 30H</td>
<td>35H, 00H</td>
</tr>
<tr>
<td>(Fixed value)</td>
<td>(Fixed value)</td>
</tr>
<tr>
<td>1 2 3 4</td>
<td>34H, 12H</td>
</tr>
<tr>
<td>31H, 32H, 33H, 34H</td>
<td>34H, 00H</td>
</tr>
<tr>
<td>0 0 0 0</td>
<td>00H, 00H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 30H</td>
<td>00H, 00H</td>
</tr>
<tr>
<td>(Free)</td>
<td>(Free)</td>
</tr>
</tbody>
</table>

Setting method for 3E frame

Set the fixed value (request message: ‘5000’, response message: ‘D000’).
Request message

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Serial number</td>
<td>Serial number</td>
</tr>
<tr>
<td>5 0 0 0</td>
<td>5 0 0 0</td>
</tr>
<tr>
<td>35H, 30H, 30H, 30H</td>
<td>50H, 00H</td>
</tr>
</tbody>
</table>
Response message

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00h 00h</td>
</tr>
</tbody>
</table>

Request data length and response data length

For the request data length, specify the data length from the monitoring timer to the request data. For the response data length, the data length from an end code to a response data (for normal completion) or an error information (for abnormal completion) is stored.

### Setting method

Specify the data length in hexadecimal. (Unit: byte)

#### Data communication using ASCII code

Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

#### Data communication using binary code

Send 2-byte numerical value from the lower byte (L: bits 0 to 7).

Ex.
The data length is 24 bytes

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 1 8</td>
<td>18h 00h</td>
</tr>
</tbody>
</table>

Monitoring timer

Set the wait time up to the completion of reading and writing processing. Set the wait time from when E71 on the connection station requests processing to the access target to when the response is returned.

- **0000H (0):** Wait infinitely (Waits until a processing is completed.)
- **0001H to FFFFH (1 to 65535):** Waiting time (unit: 250 ms)

To perform normal data communication, using the timer within the setting range in the table below is recommended depending on the communication destination.

<table>
<thead>
<tr>
<th>Access target</th>
<th>Monitoring timer</th>
</tr>
</thead>
<tbody>
<tr>
<td>Connected station (host station)</td>
<td>0001H to 0028H (0.25s to 10s)</td>
</tr>
<tr>
<td>Other station</td>
<td>0002H to 00F0H (0.5s to 60s)</td>
</tr>
</tbody>
</table>

### Setting method

#### Data communication using ASCII code

Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

#### Data communication using binary code

Send 2-byte numerical value from the lower byte (L: bits 0 to 7).

Ex.
When specifying 10H (16 × 250 ms = 4 seconds) for the monitoring timer

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 1 0</td>
<td>10h 00h</td>
</tr>
</tbody>
</table>
End code

The command processing result is stored.
At normal completion, '0' is stored.
At abnormal completion, an error code of the access target is stored.
Error code indicates the content of occurred error.
If more than one error occurs at the same time, the error code detected first is returned.
For the content of error code and its corrective action, refer to the user’s manual of the module used.

- QCPU User’s Manual (Hardware Design, Maintenance and Inspection)
- MELSEC-L CPU Module User’s Manual ( Hardware Design, Maintenance and Inspection)
- Q Corresponding Ethernet Interface Module User’s Manual (Basic)
- MELSEC-L Ethernet Interface Module User’s Manual (Basic)
- MELSEC iQ-R Serial Communication Module User’s Manual (Application)

Setting method

■ Data communication using ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

■ Data communication using binary code
Send 2-byte numerical value from the lower byte (L: bits 0 to 7).

Ex:
Normal completion

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000H</td>
<td>00H</td>
</tr>
</tbody>
</table>

Error code C051H

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>C051H</td>
<td>51H</td>
</tr>
</tbody>
</table>

Error information

Store the information of a station on which an error occurred and information of a command.

<table>
<thead>
<tr>
<th>Access route</th>
<th>Command</th>
<th>Subcommand</th>
</tr>
</thead>
</table>

- Access route: The information of a station which sent an error response is stored. It may differ from the contents of a request message.
- Command, subcommand: The command and the subcommand when an error occurred are stored.
This chapter explains the accessible range of each frame of MC protocol and data to specify the access target.

### 6.1 Accessible Ranges and Settable Data for Each Frame

The accessible range of each frame and the data items to set an access route are as shown below.

#### 4C frame

**Accessible range of 4C frame**

The following ranges can be accessed.

4C frame is supported by multiple CPU system. (Page 455 Compatibility with Multiple CPU Systems)

**Message format (Setting example for accessing connected station (host station))**

- **Data communication in ASCII code (Format 1 to Format 4)**

  ```
  0 0 0 0 0 0 0 0
  30h 30h 30h 30h 46h 46h 30h 30h
  ```

- **Data communication in binary code (Format 5)**

  ```
  0 0 0 0 0 0 0 0
  FFh FFh FFh FFh 00h 00h
  ```

**Data to be set**

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Station No.</td>
<td>Specify the station to be connected from an external device.</td>
<td>Page 48 Station No.</td>
</tr>
<tr>
<td>Network No.</td>
<td>Specify the network No. of an access target.</td>
<td>Page 50 Network No., PC No.</td>
</tr>
<tr>
<td>PC No.</td>
<td>Specify the network module station No. of an access target.</td>
<td></td>
</tr>
<tr>
<td>Request destination module i/O No.</td>
<td>• When accessing a multidrop connection station via network, specify the start input/output number of a multidrop connection source module.</td>
<td>Page 53 Request destination module i/O No., request destination module station No.</td>
</tr>
<tr>
<td></td>
<td>• Specify the CPU module of the multiple CPU system and redundant CPU system.</td>
<td></td>
</tr>
<tr>
<td>Request destination module station No.</td>
<td>When accessing a multidrop connection station via network, specify the station No. of an access target module.</td>
<td></td>
</tr>
<tr>
<td>Self-station No.</td>
<td>At the time of m:n multidrop connection, specify the station No. of a request source external device.</td>
<td>Page 56 Self-station No.</td>
</tr>
</tbody>
</table>
3C frame

Accessible range of 3C frame

The following ranges can be accessed.

![Diagram of 3C frame network connection]

Message format (Setting example for accessing connected station (host station))

<table>
<thead>
<tr>
<th>Station No.</th>
<th>Network No.</th>
<th>PC No.</th>
<th>Self-station No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>F F 0 0</td>
<td>30n 30n 30n 30n</td>
<td></td>
</tr>
</tbody>
</table>

Data to be set

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Station No.</td>
<td>Specify the station to be connected from an external device.</td>
<td>Page 48 Station No.</td>
</tr>
<tr>
<td>Network No.</td>
<td>Specify the network No. of an access target.</td>
<td>Page 50 Network No., PC No.</td>
</tr>
<tr>
<td>PC No.</td>
<td>Specify the network module station No. of an access target.</td>
<td></td>
</tr>
<tr>
<td>Self-station No.</td>
<td>At the time of m:n multidrop connection, specify the station No. of a request source external device.</td>
<td>Page 56 Self-station No.</td>
</tr>
</tbody>
</table>

2C frame

Accessible range of 2C frame

The following ranges can be accessed.

![Diagram of 2C frame network connection]

Message format (Setting example for accessing connected station (host station))

<table>
<thead>
<tr>
<th>Station No.</th>
<th>Self-station No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0</td>
<td>30n</td>
</tr>
</tbody>
</table>

Data to be set

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Station No.</td>
<td>Specify the station to be connected from an external device.</td>
<td>Page 48 Station No.</td>
</tr>
<tr>
<td>Self-station No.</td>
<td>At the time of m:n multidrop connection, specify the station No. of a request source external device.</td>
<td>Page 56 Self-station No.</td>
</tr>
</tbody>
</table>
## 1C frame

### Accessible range of 1C frame

The following ranges can be accessed.

![Diagram of network setup](image)

When accessing a device, only the applicable device range for MELSEC-A series module can be accessed. (Page 346 Accessible device range)

### Message format (Setting example for accessing connected station (host station))

<table>
<thead>
<tr>
<th>Station No.</th>
<th>PC No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>00000000</td>
<td>FFF</td>
</tr>
</tbody>
</table>

### Data to be set

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Station No.</td>
<td>Specify the station to be connected from an external device.</td>
<td>Page 48 Station No.</td>
</tr>
<tr>
<td>PC No.</td>
<td>Specify the network module station No. of an access target.</td>
<td>Page 50 Network No., PC No.</td>
</tr>
</tbody>
</table>
4E frame, 3E frame

Accessible range of 4E frame, 3E frame

The following ranges can be accessed.

- 4C frame is supported by multiple CPU system. (Page 455 Compatibility with Multiple CPU Systems)

Message format (Setting example for accessing connected station (host station))

- **Data communication in ASCII code**
  
  ```
  0 0 FF FF 0 3 FF 0 0
  ...
  ```

- **Data communication in binary code**
  
  ```
  00h FFh FFh 03h 00h
  ```

Data to be set

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Network No.</td>
<td>Specify the network No. of an access target.</td>
<td>Page 50 Network No., PC No.</td>
</tr>
<tr>
<td>PC No.</td>
<td>Specify the network module station No. of an access target.</td>
<td></td>
</tr>
<tr>
<td>Request destination module I/O No.</td>
<td>• When accessing a multidrop connection station, specify the start input/output number of a multidrop connection source module.</td>
<td>Page 53 Request destination module I/O No., request destination module station No.</td>
</tr>
<tr>
<td></td>
<td>• Specify the CPU module of the multiple CPU system and redundant CPU system.</td>
<td></td>
</tr>
<tr>
<td>Request destination module station No.</td>
<td>When accessing a multidrop connection station, specify the station No. of an access target module.</td>
<td></td>
</tr>
</tbody>
</table>
1E Frame

Accessible range of 1E frame
The following ranges can be accessed.

When accessing a device, only the applicable device range for MELSEC-A series module can be accessed. (Page 393 Accessible device range)

Message format (Setting example for accessing connected station (host station))

- Data communication in ASCII code

Data communication in binary code

Data to be set
Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>PC No.</td>
<td>Specify the network module station No. of an access target.</td>
<td>Page 50 Network No., PC No.</td>
</tr>
</tbody>
</table>
6.2 **Detail of data to be set**

This section explains the content and specification method of the data items to set the access route.

- ○: Necessary, —: Unnecessary

<table>
<thead>
<tr>
<th>Item</th>
<th>Frames for C24</th>
<th>Frames for E71</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Station No.</td>
<td>○  ○  ○  ○</td>
<td>—  —  —  —</td>
<td>Page 48 Station No.</td>
</tr>
<tr>
<td>Network No.</td>
<td>○  ○  —  —</td>
<td>○  ○  —  —</td>
<td>Page 50 Network No., PC No.</td>
</tr>
<tr>
<td>PC No.</td>
<td>○  ○  ○  ○</td>
<td>○  ○  ○  ○</td>
<td></td>
</tr>
<tr>
<td>Request destination module I/O No.</td>
<td>○  —  —  —</td>
<td>○  ○  —  —</td>
<td>Page 53 Request destination module I/O No., request destination module station No.</td>
</tr>
<tr>
<td>Request destination module station No.</td>
<td>○  —  —  —</td>
<td>○  ○  —  —</td>
<td></td>
</tr>
<tr>
<td>Self-station No.</td>
<td>○  ○  ○  ○</td>
<td>—  —  —  —</td>
<td>Page 56 Self-station No.</td>
</tr>
</tbody>
</table>

**Station No.**

Specify the station accessed from an external device.

**Accessing connected station (host station)**

Specify '0' when accessing connected station (host station).

**Accessing multidrop connection station**

Specify the station No. of an access target station from '0' to '31' (00H to 1FH) when connecting with the multidrop connection.

- **When accessing all stations connected with the multidrop connection with the global function**

Specify 'FF' (FFH) when turning ON/OFF the global signal to all station connected with the multidrop connection using the global function. By specifying 0 to 31 (00H to 1FH), X1A/X1B turns ON only on the specified station, and does not turn ON on the other stations.

(☞ Page 249 Global Function)
Accessing other stations via network

Specify the station No. from 0 to 31 (00H to 1FH) of a station that relays multidrop connection and network when accessing other stations via network.

Specify '0' when accessing other stations via network without the multidrop connection.

Setting method

■ Data communication in ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■ Data communication in binary code

Send 1-byte numerical value.

Ex.

When the station No. setting for C24 to be accessed is '5'

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 5</td>
<td>05H</td>
</tr>
</tbody>
</table>

When accessing all station connected with the multidrop connection using the global function

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>F F</td>
<td>55H</td>
</tr>
</tbody>
</table>

Point

The station No. of the serial communication module can be checked by using the following parameters of Engineering tool.

・GX Works2: "Station Number Setting" in "Switch Setting"
・GX Works3: "Station Number Settings" in "Module Parameter"
Network No., PC No.

Specify the network No. and station No. that are set with the parameters for the access target network module.
Specify a fixed value when accessing the connection station.

**Point**

Specify the network No. with the value shown below.
Specifying improper value may result in no response returned.

---

### Accessing connected station (host station)

Specify '0' for the network No., and 'FF' for the PC No.

![Diagram of connected station (host station)](image)

**When using the on-demand function**

Specify '0' for the network No., and 'FE' for the PC No.

(→ Page 274 On-demand function)

---

### Accessing multidrop connection station

Specify '0' for the network No., and 'FF' for the PC No.

![Diagram of multidrop connection station](image)

---

### Accessing other stations via network

Specify the network No. and station No. of an access target.

<table>
<thead>
<tr>
<th>Access target</th>
<th>Network No.</th>
<th>PC No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Other station of which station No. is set</td>
<td>01H to EFH (1 to 239)</td>
<td>01H to 78H (1 to 120)</td>
</tr>
<tr>
<td>Specified control station/master station¹</td>
<td>Stations with network No.240 to 255 are not accessible.</td>
<td>7DH</td>
</tr>
<tr>
<td>Current control station/Master station²</td>
<td></td>
<td>7EH</td>
</tr>
</tbody>
</table>

¹ Access the station set as a control station/master station by parameters.
² Access the station which is operating as a control station/master station.

---

* [*1* Accessing the station set as a control station/master station by parameters.]
* [*2* Accessing the station which is operating as a control station/master station.]*
When accessing with the "Valid Module During Other Station Access" setting
1C frame and 1E frame do not have the setting of network No.
When specifying the network of access target is required because more than one network module is mounted on the connection station, set the "Valid Module During Other Station Access" with Engineering tool.

When accessing in accordance with the setting of "Valid Module During Other Station Access" using a frame with the network No. set is desired, specify 'FEH' (254) to the network No.
When accessing other station via C24/E71 mounted on MELSECNET/H remote I/O station, the access to the other station specified with the PC No. of MELSECNET/H remote I/O station is available by specifying 'FEH' to the network No.

Accessing multidrop connection station via network
Specify the network No. and station No. of a station relaying the network routed through and multidrop connection station.

<table>
<thead>
<tr>
<th>Access target</th>
<th>Network No.</th>
<th>PC No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Multidrop connection station via network</td>
<td>01H to EFH (1 to 239)</td>
<td>01H to 78H (1 to 120)</td>
</tr>
<tr>
<td></td>
<td>Stations with network No.240 to 255 are not accessible.</td>
<td></td>
</tr>
</tbody>
</table>

![Diagram of network connections](image)
Setting method

■ Data communication in ASCII code
Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■ Data communication in binary code
Send 1-byte numerical value.

Ex.
Accessing connected station (host station) or multidrop connection station

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Network No.</td>
<td>PC No.</td>
</tr>
<tr>
<td>0 0</td>
<td>FF</td>
</tr>
<tr>
<td>30h, 30h</td>
<td>46h, 46h</td>
</tr>
</tbody>
</table>

When accessing other station of which network No. is '2' and station No. is '3'

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Network No.</td>
<td>PC No.</td>
</tr>
<tr>
<td>0 2</td>
<td>0 3</td>
</tr>
<tr>
<td>30h, 32h</td>
<td>30h, 33h</td>
</tr>
</tbody>
</table>

The network No. and station No. of the network module can be checked by using the following parameters of Engineering tool.

- GX Works2: "Network Parameter"
- GX Works3: "Module Parameter"

The network No. and the station No. of the network module are normally set in decimal. However, the network No. and the PC No. are set in hexadecimal.
Request destination module I/O No., request destination module station No.

Specify these numbers when an access target is as shown below.

- Multidrop connection station
- CPU module on multiple CPU system
- CPU module on redundant system

Specify the fixed value when the access target is other than those listed above.

<table>
<thead>
<tr>
<th>Request destination module I/O No.</th>
<th>Request destination module station No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>03FFH</td>
<td>00H</td>
</tr>
</tbody>
</table>

Accessing multidrop connection station

When connecting to an access target with a direct multidrop connection, it can be accessed by specifying a station No. (Page 48 Station No.).

For the request destination module I/O No. and the request destination module station No., specify the fixed value.

<table>
<thead>
<tr>
<th>Request destination module I/O No.</th>
<th>Request destination module station No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>03FFH</td>
<td>00H</td>
</tr>
</tbody>
</table>

■ For 4E frame and 3E frame

When accessing a multidrop connection station with the frames (4E frame, 3E frame) for Ethernet interface module, specify the start input/output number of a multidrop connection source module (relay station) and the station No. of an access target module.

<table>
<thead>
<tr>
<th>Request destination module I/O No.</th>
<th>Request destination module station No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000H to 01FFH</td>
<td>00H to 1FH (0 to 31): Station No.</td>
</tr>
</tbody>
</table>
Accessing multidrop connection station via network

Specify the start input/output number of a multidrop connection source module (relay station) and the station No. of an access target.

<table>
<thead>
<tr>
<th>Request destination module I/O No.</th>
<th>Request destination module station No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000H to 01FFH: Values obtained by dividing the start input/output number by 16</td>
<td>00H to 1FH (0 to 31): Station No.</td>
</tr>
</tbody>
</table>

Accessing multiple CPU system, redundant system

Specify the access target CPU module with the request destination module I/O No. Specify the fixed value (00H) for the station No.

<table>
<thead>
<tr>
<th>Access target CPU module</th>
<th>Request destination module I/O No.</th>
<th>Request destination module station No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Multiple CPU system</td>
<td>Control CPU</td>
<td>03FFH</td>
</tr>
<tr>
<td></td>
<td>Non-control CPU</td>
<td>03E0H</td>
</tr>
<tr>
<td></td>
<td>Multiple CPU No.1</td>
<td>03E1H</td>
</tr>
<tr>
<td></td>
<td>Multiple CPU No.2</td>
<td>03E2H</td>
</tr>
<tr>
<td></td>
<td>Multiple CPU No.3</td>
<td>03E3H</td>
</tr>
<tr>
<td></td>
<td>Multiple CPU No.4</td>
<td>03E4H</td>
</tr>
<tr>
<td>Redundant system</td>
<td>Control system CPU</td>
<td>03D0H</td>
</tr>
<tr>
<td></td>
<td>Standby system CPU</td>
<td>03D1H</td>
</tr>
<tr>
<td></td>
<td>System A CPU</td>
<td>03D2H</td>
</tr>
<tr>
<td></td>
<td>System B CPU</td>
<td>03D3H</td>
</tr>
</tbody>
</table>
Setting method
For the request destination module I/O No., specify the value obtained by dividing the start input/output number assigned to the module by 16 in 4 digits (hexadecimal).

Data communication in ASCII code
For the request destination module I/O No., convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from the upper digits.
For the request destination module station No., convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Data communication in binary code
For the request destination module I/O No., the 2-byte value is sent from the lower byte (L: bit 0 to 7).
For the request destination module station No., the 1-byte value is sent.

Ex.
Accessing connected station (host station)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>Request destination module I/O No.</td>
<td>Request destination module station No.</td>
</tr>
<tr>
<td>0 3 F F 0 0</td>
<td>FF 03 00</td>
</tr>
</tbody>
</table>

Accessing multidrop connection station via network
- Start input/output number: 0080H (input/output signal: 0080H to 009FH)
- Request destination module I/O No.: 0008H
- Station No.: 5

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>Request destination module I/O No.</td>
<td>Request destination module station No.</td>
</tr>
<tr>
<td>0 0 0 8 0 5</td>
<td>08 00 05</td>
</tr>
</tbody>
</table>

The station No. of the serial communication module can be checked by using the following parameters of Engineering tool.
- GX Works2: "Station Number Setting" in "Switch Setting"
- GX Works3: "Station Number Settings" in "Module Parameter"

When accessing non-control CPU (multiple CPU No.2) on multiple CPU system

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>Request destination module I/O No.</td>
<td>Request destination module station No.</td>
</tr>
<tr>
<td>0 3 E 1 0 0</td>
<td>00 00</td>
</tr>
</tbody>
</table>

6 ACCESS ROUTE SETTINGS
6.2 Detail of data to be set
Self-station No.

Specify this when more than one external device (m stations) and more than one C24s (n stations) are connected with the multidrop connection.

Specify the fixed value (00H) for any cases other than multidrop connection in a m:n basis.

When external devices are connected with the m:n multidrop connection

Specify the station No. of request source external device, 0 to 31 (00H to 1FH).

For the station No. (m stations) of external devices, the value which is not set to C24 (n stations) of the multidrop connection is used.

(The total of 'm' and 'n' is up to 32 stations.)

• Station No. of a request source external device: Specify it to the self-station No.

• Station No. of the connected station C24: Specify it to the station No. (Page 48 Station No.)

Setting method

Data communication in ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Data communication in binary code

Send 1-byte numerical value.

Ex.

For connection other than m:n multidrop connection

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 30H 30H</td>
<td>00H</td>
</tr>
</tbody>
</table>

For accessing with the m:n multidrop connection

Station No. assigned to a request source external device: 31 (1FH)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 F 31H 46H</td>
<td>1FH</td>
</tr>
</tbody>
</table>
This part explains the functions that can be specified by a message of MC protocol and the message format of request data and message data of each command.

7 COMMANDS AND FUNCTIONS

8 DEVICE ACCESS

9 LABEL ACCESS

10 BUFFER MEMORY ACCESS

11 CONTROL MODULE OPERATION

12 FILE CONTROL

13 SERIAL COMMUNICATION MODULE DEDICATED COMMANDS
This chapter explains the commands of MC protocol. The functions of a message are defined by each command. The message format for request data and response data varies with commands. Depending on the type of frame to be used, the specific value is assigned to a command. The value of command is specified at the head of a request data.

### 7.1 Command List

The following shows the list of commands.

<table>
<thead>
<tr>
<th>Control code</th>
<th>Access route</th>
<th>Request data</th>
<th>Command</th>
<th>Response data</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

There are some commands that cannot be executed while the CPU module is in RUN. Refer to the following section.
- Page 457 Applicable Commands for Online Program Change

For details on the number of points processed per communication and modules can be accessed by each command, refer to the following sections.
- Page 459 Number of Processing per One Communication
- Page 465 Accessible Modules for Each Command
# Commands for 4C/3C/4E/3E frame

The following shows the commands for 4C/3C/4E/3E frame. For 4C/3C/4E/3E frame, specify subcommands in the request message as well.

## Device access

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Description</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Batch read and write</td>
<td>Batch read in word units</td>
<td>0401 Read values from devices in word units. Read the values in batch with specifying the consecutive device points.</td>
<td>0000 For MELSEC-Q/L series 0080 For MELSEC-iQ-R series 0002 For MELSEC-Q/L series 0082 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td>Batch read in bit units</td>
<td></td>
<td>Read values from devices in bit units. Read the values in batch with specifying the consecutive device points.</td>
<td>0001 For MELSEC-Q/L series 0081 For MELSEC-iQ-R series 0003 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td>Batch write in word units</td>
<td>1401 Write values to devices in word units. Write the consecutive devices in batch with specifying the consecutive device points.</td>
<td>0000 For MELSEC-Q/L series 0080 For MELSEC-iQ-R series 0002 For MELSEC-iQ-R series</td>
<td></td>
</tr>
<tr>
<td>Batch write in bit units</td>
<td></td>
<td>Write values to devices in bit units. Write the consecutive devices in batch with specifying the consecutive device points.</td>
<td>0001 For MELSEC-Q/L series 0081 For MELSEC-iQ-R series 0003 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td>Random read and write</td>
<td>Random read in word units</td>
<td>0403 Read values from devices in word or double-word units. Read device values with specifying device numbers. Discontinuous device numbers can be specified.</td>
<td>0000 For MELSEC-Q/L series 0080 For MELSEC-iQ-R series 0002 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td>Random write in word units (test)</td>
<td></td>
<td>Read values randomly in word units by specifying the monitor condition. The read timing can be changed.</td>
<td>0040 Monitor condition specified 00C0</td>
</tr>
<tr>
<td>Random write in bit units (test)</td>
<td></td>
<td>Write values to devices in word or double-word units. Write device values with specifying device numbers. Discontinuous device numbers can be specified.</td>
<td>0000 For MELSEC-Q/L series 0080 For MELSEC-iQ-R series 0002 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td>Batch read and write multiple blocks</td>
<td>Batch read multiple blocks</td>
<td>0406 Read values for specified multiple blocks by handling consecutive word devices or bit devices as one block. Each block can be specified with discontinuous device numbers.</td>
<td>0000 For MELSEC-Q/L series 0080 For MELSEC-iQ-R series 0002 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td>Monitor device memory</td>
<td>Register monitor data</td>
<td>0801 Register the devices to be monitored. Perform monitor data registration by specifying monitor conditions. The read timing can be changed.</td>
<td>0000 For MELSEC-Q/L series 0080 For MELSEC-iQ-R series 0002 For MELSEC-iQ-R series 0040 Monitor condition specified 00C0</td>
</tr>
<tr>
<td>Monitor</td>
<td>0802 Read the values of registered devices.</td>
<td>0000 —</td>
<td></td>
</tr>
</tbody>
</table>
### Label access

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Description</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Batch read and write</td>
<td>041A</td>
<td>Read the values from array type labels. Read the values in batch with specifying the consecutive array elements. Specify the array type labels or array type elements of structure type labels.</td>
<td>0000 For MELSEC iQ-R series</td>
</tr>
<tr>
<td>Batch write array type labels</td>
<td>141A</td>
<td>Write the values to array type labels. Write the values in batch with specifying the consecutive array elements. Specify the array type labels or array type elements of structure type labels.</td>
<td>0000 For MELSEC iQ-R series</td>
</tr>
<tr>
<td>Random read and write</td>
<td>041C</td>
<td>Read values with specifying multiple labels.</td>
<td>0000 For MELSEC iQ-R series</td>
</tr>
<tr>
<td>Random write labels</td>
<td>141B</td>
<td>Write values with specifying multiple labels.</td>
<td>0000 For MELSEC iQ-R series</td>
</tr>
</tbody>
</table>

### Buffer memory access

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Description</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Buffer memory</td>
<td>Batch read</td>
<td>0613</td>
<td>Read data from the buffer memory of the host station (supported device).</td>
</tr>
<tr>
<td></td>
<td>Batch write</td>
<td>1613</td>
<td>Write data to the buffer memory of the host station (supported device).</td>
</tr>
<tr>
<td>Intelligent function module</td>
<td>Batch read</td>
<td>0601</td>
<td>Read intelligent function module buffer memory data.</td>
</tr>
<tr>
<td></td>
<td>Batch write</td>
<td>1601</td>
<td>Write intelligent function module buffer memory data.</td>
</tr>
</tbody>
</table>

### Module control

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Description</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Remote control</td>
<td>Remote RUN</td>
<td>1001</td>
<td>Perform remote RUN to the access target module.</td>
</tr>
<tr>
<td></td>
<td>Remote STOP</td>
<td>1002</td>
<td>Perform remote STOP to the access target module.</td>
</tr>
<tr>
<td></td>
<td>Remote PAUSE</td>
<td>1003</td>
<td>Perform remote PAUSE to the access target module.</td>
</tr>
<tr>
<td></td>
<td>Remote latch clear</td>
<td>1005</td>
<td>Perform remote latch clear to the access target module.</td>
</tr>
<tr>
<td></td>
<td>Remote RESET</td>
<td>1006</td>
<td>Perform remote RESET to the access target module.</td>
</tr>
<tr>
<td></td>
<td>Read CPU model name</td>
<td>0101</td>
<td>Read model name and model code from the access target module.</td>
</tr>
<tr>
<td>Remote password</td>
<td>Unlock</td>
<td>1630</td>
<td>Specify a remote password to enable communications with other devices. (Change a device from the locked state to unlocked state.)</td>
</tr>
<tr>
<td></td>
<td>Lock</td>
<td>1631</td>
<td>Specify a remote password to disable communications with other devices. (Change a device from the unlocked state to locked state.)</td>
</tr>
<tr>
<td>Loopback test</td>
<td>0619</td>
<td>Test to check whether communications between external device and connection station operate normally.</td>
<td>0000 —</td>
</tr>
<tr>
<td>Clear error information</td>
<td>Turn indicator LED OFF, initialize communication error information/error code</td>
<td>1617</td>
<td>Turn OFF the error LED, and initialize communication error information and error code.</td>
</tr>
</tbody>
</table>
### File control

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Description</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>File check</strong></td>
<td>1810</td>
<td>For the specified storage destination file, read the file name, file creation date and time (last edit date and time) etc.</td>
<td>0000 For MELSEC-Q/L series 0040 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td><strong>Search directory/file information</strong></td>
<td>1811</td>
<td>Read the file No. of the specified file.</td>
<td>0000 For MELSEC-Q/L series 0040 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td><strong>Create new file</strong></td>
<td>1820</td>
<td>Create a file with specifying its size. (Reserve a storage area for the specified file.)</td>
<td>0000 For MELSEC-Q/L series 0040 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td><strong>Delete file</strong></td>
<td>1822</td>
<td>Delete a file.</td>
<td>0000 For MELSEC-Q series 0004 For MELSEC-L series 0040 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td><strong>Copy file</strong></td>
<td>1824</td>
<td>Copy a file.</td>
<td>0000 For MELSEC-Q series 0004 For MELSEC-L series 0040 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td><strong>Modify file attribute</strong></td>
<td>1825</td>
<td>Change the file attribute.</td>
<td>0000 For MELSEC-Q series 0004 For MELSEC-L series 0040 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td><strong>Modify file creation date and time</strong></td>
<td>1826</td>
<td>Modify the file creation date and time (last edit date and time).</td>
<td>0000 For MELSEC-Q/L series 0040 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td><strong>Open file</strong></td>
<td>1827</td>
<td>Open a file to lock it so that the contents of the file cannot be modified by other devices.</td>
<td>0000 For MELSEC-Q series 0004 For MELSEC-L series 0040 For MELSEC-iQ-R series</td>
</tr>
<tr>
<td><strong>Read file</strong></td>
<td>1828</td>
<td>Read a file content.</td>
<td>0000 ---</td>
</tr>
<tr>
<td><strong>Write to file</strong></td>
<td>1829</td>
<td>Write content to a file.</td>
<td>0000 ---</td>
</tr>
<tr>
<td><strong>Close file</strong></td>
<td>182A</td>
<td>Close a file to unlock it by opening file (command: 1827).</td>
<td>0000 ---</td>
</tr>
</tbody>
</table>

For the QnACPU dedicated commands, refer to the following section.

Page 282 QnACPU Dedicated Commands List
## Serial communication dedicated commands

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Description</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>User frame</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Read registered data</td>
<td>0610</td>
<td>Read the contents of registered user frames.</td>
<td>0000</td>
</tr>
<tr>
<td>Register data</td>
<td>1610</td>
<td>Register user frames to C24.</td>
<td>0000</td>
</tr>
<tr>
<td>Delete registered data</td>
<td></td>
<td>Delete the registered user frame.</td>
<td>0001</td>
</tr>
<tr>
<td>Global</td>
<td>1618</td>
<td>Turn ON/OFF the global signal (X1A/X1B). This can be performed to a connected station and multidrop connection station.</td>
<td>0000</td>
</tr>
<tr>
<td>Initialize transmission sequence</td>
<td>1615</td>
<td>Terminate a current processing request, and place C24 into the wait state to receive commands. This can be performed to a connected station and multidrop connection station.</td>
<td>0000</td>
</tr>
<tr>
<td>Switch mode</td>
<td>1612</td>
<td>Switch the operation mode and transmission specifications of the specified interface. This can be performed to a connected station and multidrop connection station.</td>
<td>0000</td>
</tr>
<tr>
<td>Programmable controller CPU monitoring</td>
<td>0630</td>
<td>Register the conditions to monitor and start the programmable controller CPU monitoring.</td>
<td>0000</td>
</tr>
<tr>
<td>Deregister</td>
<td>0631</td>
<td>End the programmable controller CPU monitoring.</td>
<td>0000</td>
</tr>
<tr>
<td>On-demand</td>
<td>2101</td>
<td>Issue a transmission request to C24 from CPU module, and transmit data to external devices.</td>
<td></td>
</tr>
</tbody>
</table>

### Commands for 2C frame

The following shows the commands for 2C frame.

The commands for 4C/3C frame are equivalent to the following device access commands and subcommands.

<table>
<thead>
<tr>
<th>Function</th>
<th>2C frame command</th>
<th>4C/3C frame command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Batch read and write</td>
<td>1 0401 0001</td>
<td>Read values from devices in bit units. Read the values in batch with specifying the consecutive device points.</td>
<td></td>
</tr>
<tr>
<td>Batch read and write</td>
<td>2 0000</td>
<td>Read values from devices in word units. Read the values in batch with specifying the consecutive device points.</td>
<td></td>
</tr>
<tr>
<td>Batch write in bit units</td>
<td>3 1401 0001</td>
<td>Write values to devices in bit units. Write the consecutive devices in batch with specifying the consecutive device points.</td>
<td></td>
</tr>
<tr>
<td>Batch write in word units</td>
<td>4 0000</td>
<td>Write values to devices in word units. Write the consecutive devices in batch with specifying the consecutive device points.</td>
<td></td>
</tr>
<tr>
<td>Random read and write</td>
<td>5 0403 0000</td>
<td>Read values from devices in word or double-word units. Read device values with specifying device numbers. Discontinuous device numbers can be specified.</td>
<td></td>
</tr>
<tr>
<td>Random read in word units</td>
<td>6 1402 0001</td>
<td>Write values to devices in bit units. Write device values with specifying device numbers. Discontinuous device numbers can be specified.</td>
<td></td>
</tr>
<tr>
<td>Monitor device memory</td>
<td>8 0801 0000</td>
<td>Register the devices to be monitored.</td>
<td></td>
</tr>
<tr>
<td>Monitor</td>
<td>9 0802 0000</td>
<td>Read the values of registered devices.</td>
<td></td>
</tr>
</tbody>
</table>

### Commands for 1C/1E frame

For the commands for 1C/1E frame, refer to the following sections.

- Page 343 Command and Function Lists for 1C Frame
- Page 390 Commands and Function List for 1E Frame
8 DEVICE ACCESS

This chapter explains the commands to read and write devices.

8.1 Data to be Specified in Commands

This section explains the contents and specification methods for data items which are set in each command related to device access.

Devices

Specify the device to be accessed by a device code and a device number.
- The data order differs between ASCII code or binary code.
- The data size to be set differs between MELSEC-Q/L series subcommands (subcommand: 0000, 0001) and MELSEC iQ-R series subcommands (subcommand: 0002, 0003).

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>![Device code](2 digits) ![Device number](6 digits)</td>
<td>![Device number](3 bytes) ![Device code](1 byte)</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>![Device code](4 digits) ![Device number](8 digits)</td>
<td>![Device number](4 bytes) ![Device code](2 bytes)</td>
</tr>
</tbody>
</table>

**Point**

When accessing any of the following devices, use the device extension specification (subcommand: 008□).
- Link direct device
- Module access device
- CPU buffer memory access device

For the message format for device extension specification, refer to the following section.

Page 432 Read/Write by Device Extension Specification
### Device codes

Specify the device name to be accessed.
Specify the device within the range of the access target module.
For the values of each device code, refer to the following section.

Page 66 Device code list

#### Data communication using ASCII code

Convert the numerical value to 2-digit or 4-digit ASCII code (hexadecimal), and send it from the upper digits.
- For MELSEC-Q/L series: 2-digit ASCII code
- For MELSEC iQ-R series: 4-digit ASCII code

The '*' in a device code can also be specified with a space (code: 20H).

#### Data communication using binary code

Send the 1-byte or 2-byte numerical value from the lower byte (L: bits 0 to 7).
- For MELSEC-Q/L series: 1 byte
- For MELSEC iQ-R series: 2 bytes

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>X *</td>
<td>9C, 20H</td>
</tr>
<tr>
<td></td>
<td>58H, 2AH</td>
<td></td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>X * * *</td>
<td>9C, 00H</td>
</tr>
<tr>
<td></td>
<td>58H, 3AH, 2AH, 2AH</td>
<td></td>
</tr>
</tbody>
</table>
### Device number
Specify the number of device to be accessed.
Specify the device number within the range of the access target module.

#### Data communication using ASCII code
Convert the numerical value to 6-digit or 8-digit ASCII code, and sent it from the upper digits.
Specify the device number in decimal or hexadecimal, depending on the device type. (Page 66 Device code list)
- For MELSEC-Q/L series: 6-digit ASCII code
- For MELSEC iQ-R series: 8-digit ASCII code (10 digits at device extension specification)
The ‘0’ in the upper digits can also be specified with a space (code: 20H).

#### Data communication using binary code
Send the 3-byte or 4-byte numerical value in order from the lower byte (L: bit 0 to 7).
For a device of which device number is in decimal, convert it to hexadecimal and specify.
- For MELSEC-Q/L series: 3 bytes*1
- For MELSEC iQ-R series: 4 bytes*1
*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

#### Example
For input (X) 1234 (a device of which device number is in hexadecimal)

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 1 2 3 4</td>
<td>24h 12h 00h</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 0 0 1 2 3 4</td>
<td>24h 12h 00h 00h</td>
</tr>
</tbody>
</table>

For internal relay (M) 1234 (a device of which device number is in decimal)
For binary code, convert the device number to hexadecimal. ‘1234’ (decimal) → ‘4D2’ (hexadecimal)

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 1 2 3 4</td>
<td>02h 04h 00h</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 0 0 1 2 3 4</td>
<td>02h 04h 00h 00h</td>
</tr>
</tbody>
</table>

For internal relay (M) 16 (with additional code)
For C24 binary code, specify ‘10H’ as ‘10H + 10H’. (Page 33 Additional code (10H))

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>Binary code (For C24)</th>
<th>Binary code (For E71)</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>DLE 10h 10h 00h 00h</td>
<td>10h 00h 00h</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>DLE 10h 10h 00h 00h</td>
<td>10h 00h 00h</td>
</tr>
</tbody>
</table>
Device code list

The following shows the device code of each device and the notation of device number (decimal/hexadecimal). The data to be set differs between MELSEC-Q/L series commands (subcommand: 0000, 0001) and MELSEC iQ-R series subcommand (0002, 0003).

- The available device type and device range are in accordance with the device specifications of access target module. Specify the device that can be used for the access target module.
- Accessing a local device is not available.
- Devices not listed in this section cannot be specified by the command for device access of MC protocol.
- When accessing a device that cannot be specified, create a program etc. to copy a value and store the value temporarily in the device that can be specified and access it.
- When a device can be assigned to a standard global label in GX Works3, even the device, to which a device code cannot be specified, can be accessed by specifying the label name. (Page 119 LABEL ACCESS)

<table>
<thead>
<tr>
<th>Device name</th>
<th>Symbol</th>
<th>Type</th>
<th>Notation</th>
<th>For MELSEC-Q/L series</th>
<th>For MELSEC iQ-R series</th>
</tr>
</thead>
<tbody>
<tr>
<td>Special relay</td>
<td>SM</td>
<td>Bit</td>
<td>Decimal</td>
<td>SM 91H</td>
<td>SM** 0091H</td>
</tr>
<tr>
<td>Special register</td>
<td>SD</td>
<td>Word</td>
<td>Decimal</td>
<td>SD 99H</td>
<td>SD** 0099H</td>
</tr>
<tr>
<td>Input X</td>
<td>Y</td>
<td>Bit</td>
<td>Hexadecimal</td>
<td>Y* 99H</td>
<td>Y*** 0099H</td>
</tr>
<tr>
<td>Internal relay</td>
<td>M</td>
<td>Decimal</td>
<td>Hexadecimal</td>
<td>M* 99H</td>
<td>M*** 0099H</td>
</tr>
<tr>
<td>Latch relay L</td>
<td>L</td>
<td>Decimal</td>
<td>Hexadecimal</td>
<td>L* 99H</td>
<td>L*** 0099H</td>
</tr>
<tr>
<td>Annunciator F</td>
<td>F</td>
<td>Decimal</td>
<td>Hexadecimal</td>
<td>F* 99H</td>
<td>F*** 0099H</td>
</tr>
<tr>
<td>Edge relay V</td>
<td>V</td>
<td>Decimal</td>
<td>Hexadecimal</td>
<td>V* 99H</td>
<td>V*** 0099H</td>
</tr>
<tr>
<td>Link relay B</td>
<td>B</td>
<td>Hexadecimal</td>
<td>Decimal</td>
<td>B* 99H</td>
<td>B*** 0099H</td>
</tr>
<tr>
<td>Data register D</td>
<td>D</td>
<td>Word</td>
<td>Decimal</td>
<td>D* 99H</td>
<td>D*** 0099H</td>
</tr>
<tr>
<td>Link register W</td>
<td>W</td>
<td>Hexadecimal</td>
<td>Decimal</td>
<td>W* 99H</td>
<td>W*** 0099H</td>
</tr>
<tr>
<td>Timer Contact TS</td>
<td>TS</td>
<td>Bit</td>
<td>Decimal</td>
<td>TS 99H</td>
<td>TS** 0099H</td>
</tr>
<tr>
<td>Timer Coil TC</td>
<td>TC</td>
<td></td>
<td>Decimal</td>
<td>TC 99H</td>
<td>TC** 0099H</td>
</tr>
<tr>
<td>Timer Current value</td>
<td>TN</td>
<td>Word</td>
<td>Decimal</td>
<td>TN 99H</td>
<td>TN** 0099H</td>
</tr>
<tr>
<td>Retentive timer STS</td>
<td>STS</td>
<td>Bit</td>
<td>Decimal</td>
<td>STS 99H</td>
<td>STS** 0099H</td>
</tr>
<tr>
<td>Retentive timer Coil</td>
<td>STC</td>
<td></td>
<td>Decimal</td>
<td>STC 99H</td>
<td>STC** 0099H</td>
</tr>
<tr>
<td>Retentive timer Current value</td>
<td>STN</td>
<td>Word</td>
<td>Decimal</td>
<td>STN 99H</td>
<td>STN** 0099H</td>
</tr>
<tr>
<td>Counter Contact CS</td>
<td>CS</td>
<td>Bit</td>
<td>Decimal</td>
<td>CS 99H</td>
<td>CS** 0099H</td>
</tr>
<tr>
<td>Counter Coil CC</td>
<td>CC</td>
<td></td>
<td>Decimal</td>
<td>CC 99H</td>
<td>CC** 0099H</td>
</tr>
<tr>
<td>Counter Current value</td>
<td>CN</td>
<td>Word</td>
<td>Decimal</td>
<td>CN 99H</td>
<td>CN** 0099H</td>
</tr>
<tr>
<td>Link special relay SB</td>
<td>SB</td>
<td>Bit</td>
<td>Hexadecimal</td>
<td>SB 99H</td>
<td>SB** 0099H</td>
</tr>
<tr>
<td>Link special register SW</td>
<td>SW</td>
<td>Word</td>
<td>Hexadecimal</td>
<td>SW 99H</td>
<td>SW** 0099H</td>
</tr>
<tr>
<td>Direct access input DX</td>
<td>SX</td>
<td>Bit</td>
<td>Hexadecimal</td>
<td>DX 99H</td>
<td>DX** 0099H</td>
</tr>
<tr>
<td>Direct access output DY</td>
<td>DY</td>
<td>Bit</td>
<td>Hexadecimal</td>
<td>DY 99H</td>
<td>DY** 0099H</td>
</tr>
<tr>
<td>Index register Z</td>
<td>Z</td>
<td>Word</td>
<td>Decimal</td>
<td>Z* 99H</td>
<td>Z*** 0099H</td>
</tr>
<tr>
<td>Long index register LZ</td>
<td>LZ</td>
<td>Double word</td>
<td>—</td>
<td>—</td>
<td>LZ** 0099H</td>
</tr>
<tr>
<td>File register R</td>
<td>R</td>
<td>Word</td>
<td>Decimal</td>
<td>R* 99H</td>
<td>R*** 0099H</td>
</tr>
<tr>
<td>Serial number access method</td>
<td>ZR</td>
<td>Hexadecimal</td>
<td>Decimal</td>
<td>ZR 99H</td>
<td>ZR** 0099H</td>
</tr>
<tr>
<td>Extended data register D</td>
<td>D</td>
<td>Word</td>
<td>Decimal</td>
<td>D* 99H</td>
<td>—</td>
</tr>
<tr>
<td>Extended link register W</td>
<td>W</td>
<td>Word</td>
<td>Hexadecimal</td>
<td>W* 99H</td>
<td>—</td>
</tr>
<tr>
<td>Refresh data register RD</td>
<td>RD</td>
<td>Word</td>
<td>Decimal</td>
<td>RD* 99H</td>
<td>RD** 0099H</td>
</tr>
</tbody>
</table>
### Number of device points

Specify the number of device points to be read or written.

#### Setting method

- **Data communication using ASCII code**
  
  Convert the numerical value to 4-digit ASCII code (hexadecimal), and send it from the upper digits. Use capitalized code for alphabetical letter.

- **Data communication using binary code**
  
  Send the 2-byte numerical value *1 in order from the lower byte (L: bit 0 to 7).

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

#### Example

For 5 points and 20 points

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 points</td>
<td>0 0 0 5</td>
<td>05h 00h</td>
</tr>
<tr>
<td>20 points</td>
<td>0 0 1 4</td>
<td>14h 00h</td>
</tr>
</tbody>
</table>

---

### Device

<table>
<thead>
<tr>
<th>Device name</th>
<th>Symbol</th>
<th>Type</th>
<th>Notation</th>
<th>For MELSEC-Q/L series</th>
<th>For MELSEC iQ-R series</th>
</tr>
</thead>
<tbody>
<tr>
<td>I/O No. specified device</td>
<td>U</td>
<td></td>
<td></td>
<td>Page 436 Accessing module access devices</td>
<td>Page 438 Accessing CPU buffer memory access device</td>
</tr>
<tr>
<td>Module access device</td>
<td>UDIG</td>
<td>Word</td>
<td>Decimal</td>
<td>G</td>
<td>ABH</td>
</tr>
<tr>
<td>CPU buffer memory access device</td>
<td>U3EDIG</td>
<td>Word</td>
<td>Decimal</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>U3EDHG</td>
<td>Word</td>
<td>Decimal</td>
<td>—</td>
<td>—</td>
</tr>
</tbody>
</table>

*1 The file register specified to "Use File Register of Each Program" in "CPU Parameter" or "PLC parameter" of the CPU module cannot be accessed from external devices.

*2 If the file register of the CPU module is consist of multiple blocks, use the device code of the serial number access method. To specify the file register with the serial number access method, refer to the manual of CPU module.

*3 If the access target CPU module does not support the access to the extended data register D65536 or later, and the extended link register W10000 or later, replace the extended data register to the file register (ZR) and specify again. For the replacement method, refer to the manual of Q/LCPU module.
Access points

Specify the number of device points to be accessed in word unit, double word unit, or bit unit.

Setting method

■ Data communication using ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits. Use capitalized code for alphabetical letter.

■ Data communication using binary code

Send the 1-byte*1 numerical value (hexadecimal).

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Ex

For 5 points and 20 points

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 points</td>
<td>0 5</td>
<td>05h</td>
</tr>
<tr>
<td></td>
<td>30h 35h</td>
<td></td>
</tr>
<tr>
<td>20 points</td>
<td>1 4</td>
<td>14h</td>
</tr>
<tr>
<td></td>
<td>31h 34h</td>
<td></td>
</tr>
</tbody>
</table>

Number of bit access points

Specify the number of device points to be accessed in bit units.

Number of word access points, number of double word access points

Specify the number of device points to be accessed in word unit or double word unit.
Number of blocks

Specify the number of blocks of the device to be accessed in hexadecimal.
Set each number of blocks within the following range.
• Number of word device blocks + Number of bit device blocks ≤ 120

In the following case, calculate it as access point × 2.
• When accessing module of MELSEC iQ-R series by setting device extension specification (subcommand: 008□)

Setting method

■ Data communication using ASCII code
Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.
Use capitalized code for alphabetical letter.

■ Data communication using binary code
Send the 1-byte*1 numerical value (hexadecimal).
*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Ex:
For 5 points and 20 points

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 points</td>
<td>0 5</td>
<td>05</td>
</tr>
<tr>
<td></td>
<td>30h, 35h</td>
<td></td>
</tr>
<tr>
<td>20 points</td>
<td>1 4</td>
<td>14c</td>
</tr>
<tr>
<td></td>
<td>31h, 34h</td>
<td></td>
</tr>
</tbody>
</table>

Number of word device blocks
Specify the number of blocks of the word device.

Number of bit device blocks
Specify the number of blocks of the bit device.
Read data, write data

The read device value is stored for reading, and the data to be written is stored for writing.
The data order differs between bit units or word units.

For bit units
The following shows the data to be read and written in bit units.

Data communication using ASCII code
The ON/OFF status of each device are represented with single-digit ASCII code.
• For ON: ‘1’ (31H)
• For OFF: ‘0’ (30H)

Data communication using binary code
Represent the ON/OFF status of each device in 4-bit per 1 point.
• For ON: ‘1’
• For OFF: ‘0’
When the number of points is odd number, the lowest 4 bits are set to ‘0’.

Ex.
When indicating ON/OFF status of five points from M10

<table>
<thead>
<tr>
<th>M10</th>
<th>M11</th>
<th>M12</th>
<th>M13</th>
<th>M14</th>
</tr>
</thead>
<tbody>
<tr>
<td>ON</td>
<td>OFF</td>
<td>ON</td>
<td>OFF</td>
<td>ON</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code (For C24)*1</th>
<th>Binary code (For E71)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 0 1 0 1 0 1</td>
<td>DLE 10H DLE 10H DLE 10H</td>
<td>10H 10H 10H</td>
</tr>
</tbody>
</table>

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))
For word units (16-point unit for bit device)

The following shows the data to be read and written in word units. When handling data other than bit data, refer to the following section.

- Page 75 Considerations for handling real number data and character string data

**Data communication using ASCII code**

Convert the 1-word (16 points of bit device) numerical value to 4-digit ASCII code (hexadecimal), and send it from the upper digits.

Use capitalized code for alphabetical letter.

The ON/OFF status of bit device is a value of hexadecimal 1-digit in 4-point units.

**Ex**

When indicating ON/OFF status of 32 points from M16

- The device point value becomes "0002" in 16-points units.

**Ex**

When indicating the stored data of D350 and D351

- The content of D350 indicates 56ABH (22187 in decimal)
- The content of D351 indicates 170FH (5903 in decimal)
Data communication using binary code

Send the numerical value in order from the lower byte (L: bit 0 to 7) by handling 16 points unit as 2 bytes.

**Ex**

When indicating ON/OFF status of 32 points from M16

The device point value becomes "02" in 16-points units.

**Ex**

When indicating the stored data of D350 and D351

The content of D350 indicates 56ABH (22187 in decimal)

The content of D351 indicates 170FH (5903 in decimal)
### Data communication using ASCII code

Convert the 2-word numerical value (32 points of bit device) to 8-digit ASCII code (hexadecimal), and send it from the upper digits.

Use capitalized code for alphabetical letter.

The ON/OFF status of the bit device is 1-digit hexadecimal value in 4-point units.

#### Ex

When indicating ON/OFF status of 32 points from M16

<table>
<thead>
<tr>
<th>Device code</th>
<th>Device number</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>M0</td>
<td>0 0 0 1 6</td>
<td>A B 1 2 3 4 C D</td>
</tr>
</tbody>
</table>

#### Ex

When indicating the stored data of D350 (D351)

<table>
<thead>
<tr>
<th>Device code</th>
<th>Device number</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>D0</td>
<td>0 0 3 5 0</td>
<td>17 0 F 5 6 A 8</td>
</tr>
</tbody>
</table>

The content of D351 indicates 170FH (5903 in decimal)
The content of D350 indicates 56ABH (22187 in decimal)
Data communication using binary code

Send the numerical value in order from the lower byte (L: bit 0 to 7) by handling 32 points unit as 4 bytes.

Ex

When indicating ON/OFF status of 32 points from M16

Ex

When indicating the stored data of D350 (D351)

The stored value of the request data or the response data.

The value to read or write.

The content of D350 indicates 56ABH
(22187 in decimal)

The content of D351 indicates 170FH
(5903 in decimal)
Considerations for handling real number data and character string data

The word data and double word data are handled as integer value (16-bit data or 32-bit data).

When data other than integer (real number, character string) is stored in a device, the stored value is read as integer value.

- When real number (0.75) is stored in D0 and D1: D0 = 0000H, D1 = 3F40H
- When character string ('12AB') is stored in D2 and D3: D2 = 3231H, D3 = 4241H

For data to be used as real number or character string data in the instructions of the programmable controller, write it to the device/label according to the defined data specification method. For more details on how to specify data used in instructions, refer to the programming manual of the CPU module used.

For character string data

The following shows the images how character string data is stored.

<table>
<thead>
<tr>
<th>Item</th>
<th>For ASCII code character string</th>
<th>For Unicode character string</th>
</tr>
</thead>
<tbody>
<tr>
<td>Character string to be stored</td>
<td>'ABC'</td>
<td>'ABCD'</td>
</tr>
<tr>
<td>Character code</td>
<td>'41H', '42H', '43H'</td>
<td>'41H', '42H', '43H', '44H'</td>
</tr>
<tr>
<td>NULL indicates 00H.</td>
<td>NULL indicates 00H.</td>
<td>NULL indicates 0000H.</td>
</tr>
</tbody>
</table>

**Ex**

Write ASCII code character string data used in the instructions which handle character strings to word device.

Store the character string ('ABCD') to D0 and D1: D0 = 4241H ('BA'), D1 = 4443H ('DC')

Specify the following data for write data.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>B</td>
</tr>
<tr>
<td>34H</td>
<td>32H</td>
</tr>
<tr>
<td>D0</td>
<td>D1</td>
</tr>
</tbody>
</table>

A | B | C | D | NULL | NULL | 41H | 42H | 43H | 44H | 00H | 00H |
| 34H | 34H | 34H | 34H | 33H | 30H | 30H | 30H | 30H |
| D0 | D1 | D2 |

When communicating ASCII code character string data in ASCII code, data is rearranged every two characters and stored.
## Set/reset

Specify the ON/OFF status of bit device.

- For ON: ‘1’

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 1 30h 31h</td>
<td>01h</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 0 1 30h 30h 30h 31h</td>
<td>01h 00h</td>
</tr>
</tbody>
</table>

- For OFF: ‘0’

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 30h 30h</td>
<td>00h</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 0 0 30h 30h 30h 30h</td>
<td>00h 00h</td>
</tr>
</tbody>
</table>
Monitor condition specification

The following explains the data to be used when specifying monitor conditions by the following commands.

- Random read in word units (command: 0403)
- Register monitor data (command: 0801)

The monitor conditions can be specified by following QCPUs.
- Basic model QCPU
- High Performance model QCPU
- Process CPU

To access a module which does not support this function, select the subcommand that does not specify monitor conditions. For more information on the supported modules, refer to the following section.

Page 465 Accessible Modules for Each Command

When the subcommands which do not specify monitor conditions are selected, each data for specifying the monitor conditions are not necessary.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step No. specification</td>
<td>File specification</td>
<td></td>
</tr>
<tr>
<td></td>
<td>File No.</td>
<td>Page 80 Step No. specification</td>
</tr>
<tr>
<td></td>
<td>File name</td>
<td>Page 292 File No.</td>
</tr>
<tr>
<td></td>
<td>Extension</td>
<td>Page 293 File name, extension, and attribute</td>
</tr>
<tr>
<td></td>
<td>Attribute</td>
<td></td>
</tr>
<tr>
<td></td>
<td>SFC specification</td>
<td></td>
</tr>
<tr>
<td></td>
<td>SFC pattern</td>
<td>Page 82 SFC specification</td>
</tr>
<tr>
<td></td>
<td>SFC block I/O No.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>SFC step No.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Step No.</td>
<td>Page 82 Step No.</td>
</tr>
<tr>
<td></td>
<td>Specify the step No., pointer (P) No., or interrupt pointer (I) No. for a program to be the condition.</td>
<td></td>
</tr>
<tr>
<td>Device specification</td>
<td>Word device value specification</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Device</td>
<td>Page 83 Mask value, monitor conditions when word device value is specified</td>
</tr>
<tr>
<td></td>
<td>Mask value</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Monitor condition value</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Bit device value specification</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Device</td>
<td>Page 83 Monitor conditions when bit device value is specified</td>
</tr>
<tr>
<td></td>
<td>Monitor condition value</td>
<td></td>
</tr>
</tbody>
</table>
Specification of read timing by monitor condition

The read timing can be changed by specifying monitor conditions according to the selection of subcommand.

**When do not specify monitor condition**
Data is read by the END processing after a read request.

**When monitor condition is specified**
Data is read by the END processing after the specified monitor conditions are satisfied.

---

**Point**
Monitoring with multiple conditions to the device memory of the same CPU module cannot be performed at the same time. When this command, to which a monitor condition is specified, is executed while monitor with other conditions is being performed, the command is completed abnormally.
## Monitor condition

Following conditions can be specified as “Monitor condition” for read timing.

<table>
<thead>
<tr>
<th>Conditions that can be specified</th>
<th>Condition satisfaction timing</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step No. specification</td>
<td>When specified program step is executed</td>
</tr>
<tr>
<td>Device specification</td>
<td>Word device value specification</td>
</tr>
<tr>
<td></td>
<td>When specified word device value reached the specified value</td>
</tr>
<tr>
<td></td>
<td>Bit device value specification</td>
</tr>
<tr>
<td></td>
<td>When specified bit device turned ON/OFF</td>
</tr>
</tbody>
</table>

When the step No. specification and device specification are specified together, the read processing is performed when both of the conditions are satisfied.

Specify the following values according to the conditions.

○: Specified, —: Not specified

<table>
<thead>
<tr>
<th>Step No. specification</th>
<th>Device specification</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>○</td>
<td>—</td>
<td>0 1 0 F</td>
<td>01 0 F</td>
</tr>
<tr>
<td>—</td>
<td>○</td>
<td>0 2 0 F</td>
<td>02 0 F</td>
</tr>
<tr>
<td>—</td>
<td>○</td>
<td>0 3 0 F</td>
<td>03 0 F</td>
</tr>
<tr>
<td>—</td>
<td>○</td>
<td>0 4 0 F</td>
<td>04 0 F</td>
</tr>
<tr>
<td>—</td>
<td>○</td>
<td>0 5 0 F</td>
<td>05 0 F</td>
</tr>
</tbody>
</table>
## Step No. specification

Specify a condition using a step No. of program.

Data is read at the END processing immediately after a step of the specified program is executed.

**When step No. is specified**

Specify the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Step No. specification</td>
<td>Specify the registration number of file which includes a program to be the conditions in a module. The number for specification can be obtained from the file control command.</td>
<td>Page 292 File No.</td>
</tr>
<tr>
<td>File specification</td>
<td>Specify the file name, extension, attribute of a file which includes a program to be the conditions.</td>
<td>Page 293 File name, extension, and attribute</td>
</tr>
<tr>
<td>SFC specification</td>
<td>Specify this when a program is SFC.</td>
<td>Page 82 SFC specification</td>
</tr>
<tr>
<td>SFC block I/O No.</td>
<td>Specify the SFC block No. and SFC step No. which include a step to be the conditions.</td>
<td></td>
</tr>
<tr>
<td>SFC step No.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Step No.</td>
<td>Specify the step No., pointer (P) No., or interrupt pointer (I) No. for a program to be the condition.</td>
<td>Page 82 Step No.</td>
</tr>
</tbody>
</table>

*1 When ‘FFFFH’ is specified to the file, the specified file is searched with the file name and extension. In this case, a read and write request from a supported device to the CPU module may be delayed more than one sequence scan time.

**When step No. is not specified**

Set the following when a monitor condition without step No. specification is selected.

- File No.: 0
- File name, extension, attribute: Space (20H)
- SFC specification, step No.: 0

### ASCII code

```
|----------|-----------|-----------|-----------|-------------|-----------|----------|----------|
| 0 0 0 0  | 00 00 20  | 20 20 20  | 20 20 20  | 20 20 20  | 20 20 20  | 20 20 20  | 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 ...
```

File specification

SFC specification

(8 digits)

### Binary code

```
<table>
<thead>
<tr>
<th>File No.</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
<th>Step No.</th>
<th>Step No.</th>
<th>Block No.</th>
<th>SFC pattern</th>
</tr>
</thead>
<tbody>
<tr>
<td>00 00 20</td>
<td>00 00 20</td>
<td>00 00 20</td>
<td>00 00 20</td>
<td>00 00 20</td>
<td>00 00 20</td>
<td>00 00 20</td>
<td>00 00 20</td>
</tr>
</tbody>
</table>
```

File specification

SFC specification
Device specification
Specify a condition using a device and its value.
Data is read at the END processing immediately after the specified device reached the specified value.

### When word device value is specified
Set the following when a monitor condition which specifies word device value is selected.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device specification</td>
<td>Device specification</td>
<td></td>
</tr>
<tr>
<td>Word device value</td>
<td>Word device value specification</td>
<td></td>
</tr>
<tr>
<td>speciﬁcation</td>
<td>Device</td>
<td>Specify the device to be a</td>
</tr>
<tr>
<td></td>
<td>Mask value</td>
<td>condition.</td>
</tr>
<tr>
<td></td>
<td>Monitor condition value</td>
<td>Specify this when detecting</td>
</tr>
<tr>
<td></td>
<td></td>
<td>arbitrary bit range of      conditions when word device value is specified</td>
</tr>
<tr>
<td>Bit device value</td>
<td>Bit device value specification</td>
<td></td>
</tr>
<tr>
<td>speciﬁcation</td>
<td>Device</td>
<td>Specify an arbitrary device.</td>
</tr>
<tr>
<td></td>
<td>Monitor condition value</td>
<td>Specify the fixed value (0).</td>
</tr>
</tbody>
</table>

#### ASCII code

<table>
<thead>
<tr>
<th>Device code</th>
<th>Device number</th>
<th>Mask value</th>
<th>Monitor condition value</th>
<th>Device specification</th>
<th>Monitor condition value</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

#### Binary code

<table>
<thead>
<tr>
<th>Device number</th>
<th>Device code</th>
<th>Mask value</th>
<th>Monitor condition value</th>
<th>Device specification</th>
<th>Monitor condition value</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### When bit device value is specified
Set the following when a monitor condition which specifies bit device value is selected.

#### ASCII code

<table>
<thead>
<tr>
<th>Device code</th>
<th>Device number</th>
<th>Mask value</th>
<th>Monitor condition value</th>
<th>Device specification</th>
<th>Monitor condition value</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

#### Binary code

<table>
<thead>
<tr>
<th>Device number</th>
<th>Device code</th>
<th>Mask value</th>
<th>Monitor condition value</th>
<th>Device specification</th>
<th>Monitor condition value</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
When no device is specified
Set the following when monitor condition without device specification is selected.

### ASCII code

<table>
<thead>
<tr>
<th>Condition</th>
<th>SFC pattern</th>
<th>SFC block No.</th>
<th>SFC step No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Specify an SFC program.</td>
<td>0003H</td>
<td>0000H to 013FH (0 to 319)</td>
<td>0000H to 01FFH (0 to 511)</td>
</tr>
<tr>
<td>Do not specify SFC program.</td>
<td>0000H</td>
<td>0000H</td>
<td>0000H</td>
</tr>
</tbody>
</table>

### SFC specification

The block No. and step No. of SFC (MELSSAP3) program can be specified as a monitor condition.
Specify the following values.

- **Data communication using ASCII code**
  - Convert the numerical value to 4-digit ASCII code (hexadecimal), and send it from the upper digits.

- **Data communication using binary code**
  - Send the 2-byte numerical value in order from the lower byte (L: bit 0 to 7).
  - 
  
  *1 For C24, the additional code may be added. (Page 33 Additional code (10H))

**Ex**

For 0003H

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>00003</td>
<td>030000</td>
</tr>
</tbody>
</table>

### Step No.

Specify the step No., pointer (P) No., or interrupt pointer (I) No. of the sequence program.
Specify a following 4-byte value.

<table>
<thead>
<tr>
<th>Condition</th>
<th>b31</th>
<th>b30</th>
<th>b29 to b0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Specify the step No. of a sequence program</td>
<td>0</td>
<td>0</td>
<td>(Step No. of the arbitrary sequence program)</td>
</tr>
<tr>
<td>Specify pointer No.</td>
<td>0</td>
<td>1</td>
<td>(Arbitrary pointer No.)</td>
</tr>
<tr>
<td>Specify an interrupt pointer No.</td>
<td>1</td>
<td>0</td>
<td>(Arbitrary interrupt pointer No.)</td>
</tr>
<tr>
<td>Do not specify</td>
<td></td>
<td></td>
<td>00000000H</td>
</tr>
</tbody>
</table>

### Data communication using ASCII code

Convert the numerical value to 8-digit ASCII code (hexadecimal), and send it from the upper digits.

### Data communication using binary code

Send the 4-byte numerical value in order from the lower byte (L: bit 0 to 7).

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

**Ex**

When specifying the interrupt pointer I28 (8000001CH)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>80000001C</td>
<td>1C00000000</td>
</tr>
</tbody>
</table>
Mask value, monitor conditions when word device value is specified
Specify the value of word device to be set as a monitor condition. Arbitrary bit range of word devices can only be specified by specifying mask value. (Logical AND by each bit of the specified word device data and the designated mask value is compared with the monitor condition value.)

Data communication using ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal), and send it from the upper digits.

Data communication using binary code
Send the 2-byte numerical value*1 in order from the lower byte (L: bit 0 to 7).
*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Ex.
Specifying when bit 0 to 14 of D0 reaches 1000 (3E8H) as a condition
• Mask value: 7FFFH

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>7 F F F</td>
<td>E8</td>
</tr>
</tbody>
</table>

• Monitor condition value: 03E8H

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 3 E 8</td>
<td>3E</td>
</tr>
</tbody>
</table>

Monitor conditions when bit device value is specified
Specify a bit device status change as the monitor condition from either rising (OFF → ON) or falling (ON → OFF).

<table>
<thead>
<tr>
<th>Condition</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Rising (OFF → ON)</td>
<td>0 2 30 32</td>
<td>02</td>
</tr>
<tr>
<td>Falling (ON → OFF)</td>
<td>0 4 30 34</td>
<td>04</td>
</tr>
</tbody>
</table>
8.2 Batch Read and Write

Read or write the values of consecutive devices in batch by specifying the number of device points.

Batch read in word units (command: 0401)

Read values from devices in word units.

**Point**

When accessing any of the following devices, use the device extension specification (subcommand: 008).  
- Link direct device  
- Module access device  
- CPU buffer memory access device  

For the message format for device extension specification, refer to the following section.  
Page 432 Read/Write by Device Extension Specification

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

The value of read device is stored in word units. The data order differs between ASCII code or binary code. (Page 70 Read data, write data)

**Response data**

The following shows the message format of the request data and response data of the command.

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>Frame</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>4C/3C/4E/3E frame</td>
<td>0 4 0 1</td>
<td>01 04</td>
</tr>
<tr>
<td>2C frame</td>
<td>2</td>
<td></td>
</tr>
</tbody>
</table>

**Subcommand**

<table>
<thead>
<tr>
<th>Type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
<tr>
<td>For MELSEC IQ-R series</td>
<td>0 0 0 2</td>
<td>02 00</td>
</tr>
</tbody>
</table>

For 2C frame, the specification is not required. Functions and specification methods are equivalent to the subcommands for MELSEC-Q/L series.

**Head device**

Specify the head device of the consecutive devices. (Page 63 Devices)

**Restriction**

Long index register (LZ) cannot be specified.
### Number of device points

Specify the number of device points to be read within the following range in word units. (Page 67 Number of device points)

<table>
<thead>
<tr>
<th>Access target</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC-Q/R series module</td>
<td>1 to 960 points</td>
</tr>
<tr>
<td>MELSEC-Q/L series module</td>
<td>1 to 960 points (1 to 15360 points)</td>
</tr>
<tr>
<td>MELSEC-QnA series module</td>
<td>1 to 480 points</td>
</tr>
<tr>
<td>Module on other station via MELSEC-QnA series network module</td>
<td>1 to 480 words (1 to 7680 points)</td>
</tr>
<tr>
<td>MELSEC-A series module</td>
<td>1 to 64 points</td>
</tr>
<tr>
<td>MELSEC-A series module</td>
<td>1 to 32 words (1 to 512 points)</td>
</tr>
</tbody>
</table>

Read 16-point bit device by specifying one point of "Number of device points".
Set the head device number for MELSEC-A series module with a multiple of 16.

### Communication example (Reading bit device)

Read the value of M100 to M131 (for 2 words). (Subcommand: for MELSEC-Q/L series)

#### Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>00 00 00 0</td>
<td>00 00 00 0</td>
<td>00 00 00 0</td>
<td>00 00 00 0</td>
</tr>
</tbody>
</table>

(Response data)

#### Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>00 00 00 0</td>
<td>00 00 00 0</td>
<td>00 00 00 0</td>
<td>00 00 00 0</td>
</tr>
</tbody>
</table>

(Response data)
Communication example (Reading word device)

Read values of T100 to T102. (Subcommand: for MELSEC-Q/L series)
T100 = 4660 (1234H), T101 = 2 (2H), T102 = 7663 (1DEFH) are stored.

■ Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Device code</th>
<th>Device code</th>
<th>Device code</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 4 0 1</td>
<td>30 34 30 31</td>
<td>10 0 0 0</td>
<td>T N</td>
<td>0 0 0 1 0 0</td>
<td>0 0 0 3</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

■ Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Device code</th>
<th>Device code</th>
<th>Device code</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 3 4</td>
<td>31 32 33 34</td>
<td>0 0 0 2</td>
<td>1 D E F</td>
<td>31 44 45 46</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(Response data)
### Batch read in bit units (command: 0401)

Read values from devices in bit units.

When accessing any of the following devices, use the device extension specification (subcommand: 008).
- Link direct device
- Module access device
- CPU buffer memory access device

For the message format for device extension specification, refer to the following section.
Page 432 Read/Write by Device Extension Specification

---

#### Message format

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Head device</th>
<th>Number of device points</th>
</tr>
</thead>
</table>

**Response data**

The value of read device is stored in bit units. The data order differs between ASCII code or binary code. (Page 70 Read data, write data)

---

#### Data specified by request data

**Command**

<table>
<thead>
<tr>
<th>Frame</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>4C/3C/4E/3E frame</td>
<td>04001</td>
<td>0104</td>
</tr>
<tr>
<td>2C frame</td>
<td>1</td>
<td></td>
</tr>
</tbody>
</table>

**Subcommand**

<table>
<thead>
<tr>
<th>Type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0001</td>
<td>0100</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0003</td>
<td>0300</td>
</tr>
</tbody>
</table>

For 2C frame, the specification is not required. Functions and specification methods are equivalent to the subcommands for MELSEC-Q/L series.

**Head device**

Specify the head device of the consecutive devices. (Page 63 Devices)

**Restriction**

Long index register (LZ) cannot be specified.
### Number of device points

Specify the number of device points to be read within the following range. (Page 67 Number of device points)

<table>
<thead>
<tr>
<th>Access target</th>
<th>C24</th>
<th>E71</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC-Q/R series module</td>
<td>1 to 7904</td>
<td>1 to 3584</td>
</tr>
<tr>
<td>MELSEC-Q/L series module</td>
<td>1 to 7168</td>
<td>1 to 3584</td>
</tr>
<tr>
<td>MELSEC-QnA series module</td>
<td>1 to 3952</td>
<td>1 to 1792</td>
</tr>
<tr>
<td>Module on other station via MELSEC-QnA series network module</td>
<td>1 to 7168</td>
<td>1 to 3584</td>
</tr>
<tr>
<td>MELSEC-QnA series module</td>
<td>1 to 256</td>
<td></td>
</tr>
</tbody>
</table>

#### Communication example

Read values of M100 to M107. (Subcommand: for MELSEC-Q/L series)

#### Data communication using ASCII code

(Request data)

```
<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 4 0 1</td>
<td>M</td>
<td>0 0 0 1</td>
<td>0 0 0 8</td>
</tr>
</tbody>
</table>
```

(Response data)

```
0 0 0 1            | 0 0 1 1
```

#### Data communication using binary code

(Request data)

```
<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>01 06</td>
<td>01 00</td>
<td>64 00 00</td>
<td>90 08 00</td>
</tr>
</tbody>
</table>
```

(Response data)

```
00 01 00 11
```

0 = OFF
1 = ON
Batch write in word units (command: 1401)

Write values to devices in word units.

Point

When accessing any of the following devices, use the device extension specification (subcommand: 008□).
- Link direct device
- Module access device
- CPU buffer memory access device

For the message format for device extension specification, refer to the following section.
Page 432 Read/Write by Device Extension Specification

Message format

The following shows the message format of the request data and response data of the command.

- Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Head device</th>
<th>Number of device points</th>
<th>Write data</th>
</tr>
</thead>
</table>

- Response data

There is no response data for this command.

Data specified by request data

- Command

<table>
<thead>
<tr>
<th>Frame</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>4C/3C/4E/3E frame</td>
<td>1 4 0 1</td>
<td>01H, 14H</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Frame</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>2C frame</td>
<td>4</td>
<td>-</td>
</tr>
</tbody>
</table>

- Subcommand

<table>
<thead>
<tr>
<th>Type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 0 0</td>
<td>00H, 00H</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 0 2</td>
<td>02H, 00H</td>
</tr>
</tbody>
</table>

For 2C frame, the specification is not required. Functions and specification methods are equivalent to the subcommands for MELSEC-Q/L series.

- Head device

Specify the head device of the consecutive devices. (Page 63 Devices)

Restriction

Long index register (LZ) cannot be specified.
## Number of device points
Specify the number of device points to be written within the following range in word units. (Page 67 Number of device points)

<table>
<thead>
<tr>
<th>Access target</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC iQ-R series module</td>
<td>1 to 960 points</td>
</tr>
<tr>
<td>MELSEC-Q/L series module</td>
<td>1 to 960 words (1 to 15360 points)</td>
</tr>
<tr>
<td>MELSEC-QnA series module</td>
<td>1 to 480 points</td>
</tr>
<tr>
<td>Module on other station via MELSEC-QnA network module</td>
<td>1 to 480 words (1 to 7680 points)</td>
</tr>
<tr>
<td>MELSEC-A series module</td>
<td>1 to 64 points</td>
</tr>
<tr>
<td></td>
<td>1 to 10 words (1 to 160 points)</td>
</tr>
</tbody>
</table>

For bit device, read 16-point bit device by specifying one point of "Number of device points". Set the head device number for MELSEC-A series module with a multiple of 16.

## Write data
Specify the data to be written for the number of device points in hexadecimal. (Page 70 Read data, write data)

### Communication example (Writing bit device)
Write the values to M100 to M131 (for 2 words). (Subcommand: for MELSEC-Q/L series)

#### Data communication using ASCII code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 4 0 1</td>
<td>M</td>
<td>0 0 0 0</td>
<td>0 2 0</td>
<td>0 0 0 0 1 0</td>
</tr>
<tr>
<td>31h 38h</td>
<td>30h 31h</td>
<td>30h 30h</td>
<td>30h 31h</td>
<td>30h 32h</td>
</tr>
<tr>
<td>0 0 0 0 1 0</td>
<td>0 0 0 0 2 2</td>
<td>A B 9 6</td>
<td>M115 to M100; M131</td>
<td>M116</td>
</tr>
</tbody>
</table>

#### Data communication using binary code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>01h 14h 16h</td>
<td>00h 00h</td>
<td>00h 00h</td>
<td>02h 00h</td>
<td>00h 23h</td>
</tr>
<tr>
<td>00h 00h 00h</td>
<td>90h 00h</td>
<td>00h 00h</td>
<td>00h 00h</td>
<td>00h 00h</td>
</tr>
</tbody>
</table>
| 4 7 2 3 9 6| A B 0 1     | M107 to M100; M115| M108; M123              | M116; M131 | M124
Communication example (Writing word device)

Write '6549' (1995H) to D100, '4610' (1202H) to D101, and '4400' (1130H) to D102. (Subcommand: for MELSEC-Q/L series)

■Data communication using ASCII code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 4 0 1</td>
<td>0 0 0 0</td>
<td>D *</td>
<td>0 0 0 1 0 0</td>
<td>0 0 0 3</td>
</tr>
<tr>
<td>31h 34h</td>
<td>30h 31h</td>
<td>30h 2Ah</td>
<td>30h 30h 30h 31h 30h</td>
<td>31h 39h</td>
</tr>
<tr>
<td>D100</td>
<td>D101</td>
<td>D102</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

■Data communication using binary code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>01h 14h</td>
<td>00h 00h</td>
<td>00h 64h 00h 00h</td>
<td>AAh</td>
<td>03h 00h</td>
</tr>
<tr>
<td></td>
<td></td>
<td>95h 19h 02h 12h 30h</td>
<td></td>
<td>11h</td>
</tr>
<tr>
<td>D100</td>
<td>D101</td>
<td>D102</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
**Batch write in bit units (command: 1401)**

Write values to devices in bit units.

When accessing any of the following devices, use the device extension specification (subcommand: 008).  
- Link direct device  
- Module access device  
- CPU buffer memory access device  

For the message format for device extension specification, refer to the following section.  
Page 432 Read/Write by Device Extension Specification

---

**Message format**

The following shows the message format of the request data and response data of the command.

### Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Head device</th>
<th>Number of device points</th>
<th>Write data</th>
</tr>
</thead>
</table>

### Response data

There is no response data for this command.

---

**Data specified by request data**

### Command

**Frame**

<table>
<thead>
<tr>
<th>Frame</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>4C/3C/4E/3E frame</td>
<td>1 4 0 1</td>
<td>01 14</td>
</tr>
<tr>
<td>2C frame</td>
<td>3</td>
<td>—</td>
</tr>
</tbody>
</table>

### Subcommand

<table>
<thead>
<tr>
<th>Type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 0 1</td>
<td>01 00</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 0 3</td>
<td>03 00</td>
</tr>
</tbody>
</table>

For 2C frame, the specification is not required. Functions and specification methods are equivalent to the subcommands for MELSEC-Q/L series.

### Head device

Specify the head device of the consecutive devices. (Page 63 Devices)

**Restriction**

Long index register (LZ) cannot be specified.
### Number of device points
Specify the number of device points to be written within the following range. (Page 67 Number of device points)

<table>
<thead>
<tr>
<th>Access target</th>
<th>C24</th>
<th>E71</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC-iQ-R series module</td>
<td>1 to 7904 points</td>
<td>1 to 3584 points</td>
<td>1 to 7168 points</td>
<td></td>
</tr>
<tr>
<td>MELSEC-Q/L series module</td>
<td>1 to 3952 points</td>
<td>1 to 1792 points</td>
<td>1 to 3584 points</td>
<td></td>
</tr>
<tr>
<td>MELSEC-QnA series module</td>
<td>1 to 3584 points</td>
<td>1 to 1792 points</td>
<td>1 to 3584 points</td>
<td></td>
</tr>
<tr>
<td>Module on other station via MELSEC-QnA series network module</td>
<td>1 to 160 points</td>
<td>1 to 160 points</td>
<td>1 to 160 points</td>
<td></td>
</tr>
</tbody>
</table>

### Write data
Specify the value to be written to a device for the number equivalent to the specified number of device points. (Page 70 Read data, write data)

### Communication example
Write values to M100 to M107. (Subcommand: for MELSEC-Q/L series)

#### Data communication using ASCII code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 4 0 1</td>
<td>31i  34i  30i  31i</td>
<td>0 0 0 1</td>
<td>M</td>
<td>0 0 0 1 0 0</td>
</tr>
<tr>
<td>0 0 0 1 0 0</td>
<td>30i  30i  30i  31i</td>
<td>0 0 0 1</td>
<td>M</td>
<td>0 0 0 8</td>
</tr>
<tr>
<td>1 1 0 0 1 1 0 0</td>
<td>31i  31i  30i  31i</td>
<td>0 0 0 1</td>
<td>M</td>
<td>0 0 0 8</td>
</tr>
</tbody>
</table>

**M100 to M107**

#### Data communication using binary code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 1 0 0 0</td>
<td>30i  30i  30i  31i</td>
<td>0 0 0 1</td>
<td>M</td>
<td>0 0 0 8</td>
</tr>
<tr>
<td>1 1 0 0 1 1 0 0</td>
<td>31i  31i  30i  31i</td>
<td>0 0 0 1</td>
<td>M</td>
<td>0 0 0 8</td>
</tr>
<tr>
<td>1 1 0 0 1 1 0 0</td>
<td>31i  31i  30i  31i</td>
<td>0 0 0 1</td>
<td>M</td>
<td>0 0 0 8</td>
</tr>
</tbody>
</table>
8.3 Random Read and Write

Read or write device values by specifying the device numbers. It can be specified with discontinuous device numbers.

Random read in word units (command: 0403)

Read values from devices in word units and double word units. It can be specified with discontinuous device number.

When accessing any of the following devices, use the device extension specification (subcommand: 008□).
- Link direct device
- Module access device
- CPU buffer memory access device

For the message format for device extension specification, refer to the following section.

Page 432 Read/Write by Device Extension Specification

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Monitor condition specification designation</th>
<th>Number of word access points (m points)</th>
<th>Number of double word access points (n points)</th>
</tr>
</thead>
</table>

When accessing any of the following devices, use the device extension specification (subcommand: 008□).

Point

When accessing any of the following devices, use the device extension specification (subcommand: 008□).
- Link direct device
- Module access device
- CPU buffer memory access device

For the message format for device extension specification, refer to the following section.

Page 432 Read/Write by Device Extension Specification

Data specified by request data

Command

<table>
<thead>
<tr>
<th>Frame</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>4C/3C/4E/3E frame</td>
<td>0 4 0 3</td>
<td>03H 04H</td>
</tr>
<tr>
<td>2C frame</td>
<td>5</td>
<td>35H</td>
</tr>
</tbody>
</table>

The value of read device is stored in word units and in double word units. The data order differs between ASCII code or binary code. (Page 70 Read data, write data)
Subcommand

The read timing can be changed by specifying monitor conditions according to the selection of subcommand. (Page 77 Monitor condition specification)

For 2C frame, the specification is not required. Functions and specification methods are equivalent to the subcommands that do not specify monitor conditions for MELSEC-Q/L series.

When do not specify monitor condition

<table>
<thead>
<tr>
<th>Type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 0 0</td>
<td>00h, 00h</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 0 2</td>
<td>02h, 00h</td>
</tr>
</tbody>
</table>

When monitoring condition is specified

<table>
<thead>
<tr>
<th>Type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 4 0</td>
<td>04h, 00h</td>
</tr>
</tbody>
</table>

*1 The access targets to which a monitor conditions can be specified have some restrictions. (Page 465 Accessible Modules for Each Command)

At monitor condition specification, use the subcommand 00C0 for the device extension specification. The message format for device extension specification is the same as that of 008. Refer to it by substituting 008 to 00C0. (Page 432 Read/Write by Device Extension Specification)

Monitor condition specification

Specify the conditions for timing to read data. (Page 77 Monitor condition specification)

When do not specify the monitor condition, the specification of this data item is not required.

Number of word access points, number of double word access points

Specify the number of device points to be read within the following range. (Page 68 Access points)

<table>
<thead>
<tr>
<th>Access target</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC iQ-R series module (subcommand: 0000)</td>
<td>1 ≤ Number of word access points + Number of double word access points ≤ 192 points</td>
</tr>
<tr>
<td>MELSEC-Q/L series module (subcommand: 0000)</td>
<td>1 ≤ Number of word access points + Number of double word access points ≤ 192 points</td>
</tr>
<tr>
<td>MELSEC iQ-R series module (subcommand: 0002, 008C)</td>
<td>1 ≤ Number of word access points + Number of double word access points ≤ 96 points</td>
</tr>
<tr>
<td>MELSEC-Q/L series module (subcommand: 0080)</td>
<td>1 ≤ Number of word access points + Number of double word access points ≤ 96 points</td>
</tr>
<tr>
<td>MELSEC-QnA series module</td>
<td>Cannot be used.</td>
</tr>
<tr>
<td>Module on other station via MELSEC-QnA series network module</td>
<td></td>
</tr>
<tr>
<td>MELSEC-A series module</td>
<td></td>
</tr>
</tbody>
</table>

The number of point is specified in the following units depending on device type.

<table>
<thead>
<tr>
<th>Device type</th>
<th>Number of word access points</th>
<th>Number of double word access points</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bit device</td>
<td>16-point units</td>
<td>32-point units</td>
</tr>
<tr>
<td>Word device</td>
<td>1 word units</td>
<td>2 word units</td>
</tr>
</tbody>
</table>

When using subcommand for MELSEC-Q/L series module, calculate it as access points × 2 in the following case.

• When specifying the file register (ZR) of High Performance model QCPU
**Device**
Specify the device to be read. (Page 63 Devices)

---

Point

The number of points equivalent to the specified 'Number of word access points' and 'Number of double word access points' is specified for 'Device', respectively. When '0' is specified for the access points, this specification is not required.
Communication example (Monitor condition is not specified)

Read values of D0, T0, M100 to M115, X20 to X2F with word access. Read values of D1500 to D1501, Y160 to Y17F, M1111 to M1142 with 4 double word access. (Subcommand: for MELSEC-Q/L series)

D0 = 6549 (1995H), T0 = 4610 (1202H), D1500 = 20302 (4F4EH), D1501 = 19540 (4C54H) are stored.

### Data communication using ASCII code

#### (Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Number of word access points</th>
<th>Number of double word access points</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 4 0 3</td>
<td>30h, 34h, 33h, 35h</td>
<td>30h, 34h, 33h</td>
</tr>
<tr>
<td>0 0 0 0</td>
<td>30h, 30h, 30h, 30h</td>
<td>30h, 30h, 30h</td>
</tr>
<tr>
<td>0 4 0 3</td>
<td>30h, 34h, 33h</td>
<td>30h, 30h, 30h</td>
</tr>
</tbody>
</table>

#### Device for word access

<table>
<thead>
<tr>
<th>Device number</th>
<th>Device code</th>
</tr>
</thead>
<tbody>
<tr>
<td>000 00 00 00</td>
<td>T N</td>
</tr>
<tr>
<td>00 00 00 00</td>
<td>M *</td>
</tr>
<tr>
<td>00 01 00 00</td>
<td>X *</td>
</tr>
</tbody>
</table>

#### Device for double word access

<table>
<thead>
<tr>
<th>Device number</th>
<th>Device code</th>
</tr>
</thead>
<tbody>
<tr>
<td>01 01 11 11</td>
<td>M *</td>
</tr>
</tbody>
</table>

#### (Response data)

<table>
<thead>
<tr>
<th>Read data 1 in word units</th>
<th>Read data 2 in word units</th>
<th>Read data 3 in word units</th>
<th>Read data 4 in word units</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 9 9 5</td>
<td>1 2 0 2</td>
<td>2 0 3 0</td>
<td>4 8 4 9</td>
</tr>
<tr>
<td>31h, 39h, 39h, 35h</td>
<td>31h, 32h, 30h, 32h</td>
<td>32h, 30h, 33h, 30h</td>
<td>34h, 38h, 34h, 39h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Read data 1 in double word units</th>
<th>Read data 2 in double word units</th>
<th>Read data 3 in double word units</th>
</tr>
</thead>
<tbody>
<tr>
<td>4 C 5 4 4 F 4 E</td>
<td>C 3 D E B 9 A F</td>
<td>B A D B C B 7</td>
</tr>
<tr>
<td>34h, 33h, 34h, 35h</td>
<td>34h, 33h, 34h, 35h</td>
<td>34h, 33h, 34h, 35h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Read data in word units</th>
<th>Read data in double word units</th>
</tr>
</thead>
<tbody>
<tr>
<td>M115 to M100</td>
<td>D1501 to D1500</td>
</tr>
<tr>
<td>X2F to X20</td>
<td>Y17F to Y160</td>
</tr>
<tr>
<td>M1142 to M1111</td>
<td></td>
</tr>
</tbody>
</table>

Read data 3 in word units

<table>
<thead>
<tr>
<th>Read data 4 in word units</th>
</tr>
</thead>
<tbody>
<tr>
<td>X2F to X20</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>0 = OFF 1 = ON</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1</td>
</tr>
<tr>
<td>0 0</td>
</tr>
<tr>
<td>0 0</td>
</tr>
</tbody>
</table>
Data communication using binary code

(Request data)

Device for word access

<table>
<thead>
<tr>
<th>Device number</th>
<th>Device code</th>
<th>Device number</th>
<th>Device code</th>
<th>Device number</th>
<th>Device code</th>
<th>Device number</th>
<th>Device code</th>
</tr>
</thead>
<tbody>
<tr>
<td>00h-00h</td>
<td>00h</td>
<td>00h-00h</td>
<td>00h</td>
<td>00h-00h</td>
<td>00h</td>
<td>00h-00h</td>
<td>00h</td>
</tr>
</tbody>
</table>

Device for double word access

<table>
<thead>
<tr>
<th>Device number</th>
<th>Device code</th>
<th>Device number</th>
<th>Device code</th>
<th>Device number</th>
<th>Device code</th>
</tr>
</thead>
<tbody>
<tr>
<td>DC0h-00h</td>
<td>00h</td>
<td>00h-00h</td>
<td>00h</td>
<td>00h-00h</td>
<td>00h</td>
</tr>
</tbody>
</table>

(Response data)

Data read 1 in word units

Data read 2 in word units

Data read 3 in word units

Data read 4 in word units

Data read 1 in double word units

Data read 2 in double word units

Data read 3 in double word units

Data read 4 in double word units
Communication example (Monitor condition is specified)

Read values of D0, T0, M100 to M115, X20 to X2F with word access. Read values of D1500 to D1501, Y160 to Y17F, M1111 to M1142 with 4 double word access.

The monitor condition is as follows: When the value of link register (W100) reached '7BH' (123) while the step No.1000 of program file CONB1.QPG is being executed.

Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Monitor condition</th>
<th>File No.</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 4 0 3</td>
<td></td>
<td>0 0 0 4 0</td>
<td>0 3</td>
<td>0 F</td>
<td>C O N B 1</td>
</tr>
<tr>
<td>30x 34x 33x</td>
<td></td>
<td>30x 30x</td>
<td>30x 34x 34x</td>
<td>30x 46x</td>
<td>31x 31x 42x</td>
</tr>
</tbody>
</table>

Communication example (Monitor condition is specified)

Read values of D0, T0, M100 to M115, X20 to X2F with word access. Read values of D1500 to D1501, Y160 to Y17F, M1111 to M1142 with 4 double word access.

The monitor condition is as follows: When the value of link register (W100) reached '7BH' (123) while the step No.1000 of program file CONB1.QPG is being executed.

Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Monitor condition</th>
<th>File No.</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 4 0 3</td>
<td></td>
<td>0 0 0 4 0</td>
<td>0 3</td>
<td>0 F</td>
<td>C O N B 1</td>
</tr>
<tr>
<td>30x 34x 33x</td>
<td></td>
<td>30x 30x</td>
<td>30x 34x 34x</td>
<td>30x 46x</td>
<td>31x 31x 42x</td>
</tr>
</tbody>
</table>

Communication example (Monitor condition is specified)

Read values of D0, T0, M100 to M115, X20 to X2F with word access. Read values of D1500 to D1501, Y160 to Y17F, M1111 to M1142 with 4 double word access.

The monitor condition is as follows: When the value of link register (W100) reached '7BH' (123) while the step No.1000 of program file CONB1.QPG is being executed.

Data communication using ASCII code

(Request data)
Data communication using binary code

(Request data)

It is the same as the communication example when monitor condition is not specified. (Page 98 Data communication using binary code)
Random write in word units (test) (command: 1402)

Write values to devices in word units and double word units. It can be specified with discontinuous device numbers.

When accessing any of the following devices, use the device extension specification (subcommand: 008).  
- Link direct device
- Module access device
- CPU buffer memory access device

For the message format for device extension specification, refer to the following section.
Page 432 Read/Write by Device Extension Specification

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Number of word access points (m points)</th>
<th>Number of double word access points (n points)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device (first point)</td>
<td>Write data (first point)</td>
<td>...</td>
<td>Device (mth point)</td>
</tr>
</tbody>
</table>

Device for word access

| Device (first point) | Write data (first point) | ... | Device (nth point) | Write data (nth point) |

Device for double word access

Response data

There is no response data for this command.

Data specified by request data

Command

Frame | ASCII code | Binary code |
---|---|---|
4C/3C/4E/3E frame | 1 4 0 2 | 02h, 14h |
2C frame | 7 | — |

Subcommand

<table>
<thead>
<tr>
<th>Type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 0 0</td>
<td>00h, 00h</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 0 2</td>
<td>02h, 00h</td>
</tr>
</tbody>
</table>

For 2C frame, the specification is not required. Functions and specification methods are equivalent to the subcommands for MELSEC-Q/L series.
**Number of word access points, number of double word access points**

Specify the number of device points to be written within the following range. (Page 68 Access points)

<table>
<thead>
<tr>
<th>Access target</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC iQ-R series module (subcommand: 0000)</td>
<td>1 ≤ (Number of word access points × 12) + (Number of double word access points × 14) ≤ 1920 points</td>
</tr>
<tr>
<td>MELSEC-Q/L series module (subcommand: 0000)</td>
<td>1 ≤ (Number of word access points × 12) + (Number of double word access points × 14) ≤ 960 points</td>
</tr>
<tr>
<td>MELSEC -Q/R series module (subcommand: 0002, 0080)</td>
<td>1 ≤ Number of word access points ≤ 10 points</td>
</tr>
<tr>
<td>MELSEC-QnA series module Module on other station via MELSEC-QnA series network module</td>
<td></td>
</tr>
</tbody>
</table>

The number of point is specified in the following units depending on device type.

<table>
<thead>
<tr>
<th>Device type</th>
<th>Number of word access points</th>
<th>Number of word access points</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bit device</td>
<td>16-point units</td>
<td>32-point units</td>
</tr>
<tr>
<td>Word device</td>
<td>1 word units</td>
<td>2 word units</td>
</tr>
</tbody>
</table>

**Device**

Specify a device to be written. (Page 63 Devices)

Set the head device number with a multiple of 16 for bit device access of MELSEC-A series module.

**Write data**

Specify the values to be written to device. (Page 70 Read data, write data)

Specify the write data in hexadecimal.

*Point*

Specify 'Device' and 'Write data' with number of points which are specified in 'Number of word access points' and 'Number of double word access points'. When the access point is set to '0', the specification is not required.

**Communication example**

Write values to devices as follows. (Subcommand: for MELSEC-Q/L series)

<table>
<thead>
<tr>
<th>Item</th>
<th>Device to be written</th>
</tr>
</thead>
<tbody>
<tr>
<td>Word access</td>
<td>D0, D1, M100 to M115, X20 to X2F</td>
</tr>
<tr>
<td>Double word access</td>
<td>D1500 to D1501, Y160 to Y17F, M1111 to M1142</td>
</tr>
</tbody>
</table>
Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Device number</th>
<th>Write data 1</th>
<th>Device code</th>
<th>Device number</th>
<th>Write data 2</th>
<th>Device code</th>
<th>Device number</th>
<th>Write data 3</th>
<th>Device code</th>
<th>Device number</th>
<th>Write data 4</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1 4 0 2</td>
<td>0 0 0 0 0</td>
<td>0 4 0 0 0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>31n 34n</td>
<td>30n 32n</td>
<td>30n 30n 30n</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Device for word access

Device for double word access

Write data 1 in word units

0 5 4 0 0
M115 to M100

Write data 2 in word units

0 5 4 0 0
X0F to X20

Write data 3 in double word units

2 3 7 5 2 6 0
Y17F to Y178

Write data 4 in double word units

0 4 7 5
M1142 to M1135

0 7 5
M1118 to M1111

0 = OFF
1 = ON
Data communication using binary code

(Request data)

Device for word access

<table>
<thead>
<tr>
<th>Device number</th>
<th>Device code</th>
<th>Write data 1</th>
</tr>
</thead>
<tbody>
<tr>
<td>00h</td>
<td>00h</td>
<td></td>
</tr>
<tr>
<td>01h</td>
<td>00h</td>
<td></td>
</tr>
<tr>
<td>04h</td>
<td>05h</td>
<td></td>
</tr>
</tbody>
</table>

Device for double word access

<table>
<thead>
<tr>
<th>Device number</th>
<th>Device code</th>
<th>Write data 2</th>
</tr>
</thead>
<tbody>
<tr>
<td>00h</td>
<td>00h</td>
<td></td>
</tr>
<tr>
<td>01h</td>
<td>00h</td>
<td></td>
</tr>
<tr>
<td>04h</td>
<td>05h</td>
<td></td>
</tr>
</tbody>
</table>

Subcommand

- 02h, 14h, 00h, 08h, 04h, 03h

Device access points

- Number of word access points
- Number of double word access points

Write data 1 in word units

- M107 to M108

Write data 2 in word units

- M115 to M108

Write data 3 in double word units

- Y167 to Y160

Write data 4 in double word units

- Y17F to Y178
Random write in bit units (test) (command: 1402)

Write values to devices in bit units. It can be specified with discontinuous device number.

When accessing any of the following devices, use the device extension specification (subcommand: 008).
- Link direct device
- Module access device
- CPU buffer memory access device
For the message format for device extension specification, refer to the following section. Page 432 Read/Write by Device Extension Specification

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Number of bit access points (n points)</th>
<th>Device (first point)</th>
<th>Set/reset (first point)</th>
<th>…</th>
<th>Device (nth point)</th>
<th>Set/reset (nth point)</th>
</tr>
</thead>
</table>

**Response data**

There is no response data for this command.

**Request data**

**Command**

**Frame**

<table>
<thead>
<tr>
<th>Frame</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>4C/3C/4E/3E frame</td>
<td>1 4 0 2 31h 34h 30h 32h</td>
<td>02h 14h</td>
</tr>
<tr>
<td>2C frame</td>
<td>6 36h</td>
<td>---</td>
</tr>
</tbody>
</table>

**Subcommand**

<table>
<thead>
<tr>
<th>Type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 0 1 30h 30h 30h 31h</td>
<td>01h 00h</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 0 3 30h 30h 30h 33h</td>
<td>03h 00h</td>
</tr>
</tbody>
</table>

For 2C frame, the specification is not required. Functions and specification methods are equivalent to the subcommands for MELSEC-Q/L series.

**Number of bit access points**

Specify the number of device points to be written within the following range. (Page 67 Number of device points)

<table>
<thead>
<tr>
<th>Access target</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC iQ-R series module (subcommand: 0001)</td>
<td>1 to 188 points</td>
</tr>
<tr>
<td>MELSEC-Q/L series module (subcommand: 0001)</td>
<td>1 to 188 points</td>
</tr>
<tr>
<td>MELSEC iQ-R series module (subcommand: 0003, 0082)</td>
<td>1 to 94 points</td>
</tr>
<tr>
<td>MELSEC-Q/L series module (subcommand: 0081)</td>
<td>1 to 94 points</td>
</tr>
<tr>
<td>MELSEC-QnA series module</td>
<td>1 to 20 points</td>
</tr>
<tr>
<td>Module on other station via MELSEC-QnA series network module</td>
<td></td>
</tr>
<tr>
<td>MELSEC-A series module</td>
<td>1 to 20 points</td>
</tr>
</tbody>
</table>
Device
Specify a device to be written. (Page 63 Devices)
Specify a bit device.

Set/reset
Specify the ON/OFF status of bit devices. (Page 76 Set/reset)

The number of points equivalent to the specified "Number of bit access points" is specified for "Device" and "Set/reset", respectively.

Communication example
Turn M50 OFF, and turn Y2F ON. (Subcommand: for MELSEC-Q/L series)

Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Number of bit access points</th>
<th>Device code</th>
<th>Device number</th>
<th>Set/reset</th>
<th>Device code</th>
<th>Device number</th>
<th>Set/reset</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>4</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>5</td>
<td>0</td>
</tr>
<tr>
<td>31h</td>
<td>34h</td>
<td>30h</td>
<td>32h</td>
<td>30h</td>
<td>30h</td>
<td>31h</td>
<td>30h</td>
</tr>
</tbody>
</table>

Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Set/reset</th>
<th>Device code</th>
<th>Set/reset</th>
</tr>
</thead>
<tbody>
<tr>
<td>02h</td>
<td>14h</td>
<td>01h</td>
<td>00h</td>
<td>02h</td>
</tr>
<tr>
<td>32h</td>
<td>30h</td>
<td>00h</td>
<td>14h</td>
<td>01h</td>
</tr>
<tr>
<td>2Fh</td>
<td>00h</td>
<td>00h</td>
<td>80h</td>
<td>90h</td>
</tr>
<tr>
<td>90h</td>
<td>00h</td>
<td>01h</td>
<td>01h</td>
<td>01h</td>
</tr>
</tbody>
</table>
8.4 Batch Read and Write Multiple Blocks

Read or write values for specified multiple blocks by handling consecutive devices as one block.

**Batch read multiple blocks (command: 0406)**

Read values for specified multiple blocks by handling consecutive word devices or bit devices as one block. Each block can be specified with discontinuous device numbers.

**Restriction**

When communicating with a Universal model QCPU or an LCPU, if other than "Specify service process execution counts" is selected for "Service Processing Setting" of the CPU module, data separation may occur. To avoid data separation, select "Specify service process execution counts".

**Point**

When accessing any of the following devices, use the device extension specification (subcommand: 008).
- Link direct device
- Module access device
- CPU buffer memory access device

For the message format for device extension specification, refer to the following section.

Page 432 Read/Write by Device Extension Specification

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Number of word device blocks (m points)</th>
<th>Number of bit device blocks (n points)</th>
<th>Block of word device (first point)</th>
<th>…</th>
<th>Block of word device (mth point)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Block of bit device (first point)</td>
<td>… Block of bit device (nth point)</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Response data**

The value of read device is stored in hexadecimal. The data order differs between ASCII code or binary code. (Page 70 Read data, write data)

<table>
<thead>
<tr>
<th>Data for the number of word device blocks</th>
<th>Data for the number of bit device blocks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Word device</td>
<td>Bit device</td>
</tr>
<tr>
<td>Data in the first block</td>
<td>Data in the mth block</td>
</tr>
<tr>
<td>…</td>
<td>…</td>
</tr>
<tr>
<td>Data in the first block</td>
<td>Data in the mth block</td>
</tr>
</tbody>
</table>

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 4 0 6</td>
<td>06 04</td>
</tr>
<tr>
<td>30x 34x</td>
<td>30x 36x</td>
</tr>
</tbody>
</table>
### Subcommand

<table>
<thead>
<tr>
<th>Type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 0 0</td>
<td>00h 00h</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 0 2</td>
<td>02h 00h</td>
</tr>
</tbody>
</table>

### Number of word device blocks, number of bit device blocks

Specify the number of device blocks to be read in hexadecimal. (Page 69 Number of blocks)

Specify the total number of each block within the following range.

<table>
<thead>
<tr>
<th>Access target</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC-Q/L series module (subcommand: 0000)</td>
<td>1: Number of word device blocks + Number of bit device blocks ≤ 120 points</td>
</tr>
<tr>
<td>MELSEC-QnA series module</td>
<td></td>
</tr>
<tr>
<td>MELSEC-Q/L series module (subcommand: 0002, 008)</td>
<td>1: Number of word device blocks + Number of bit device blocks ≤ 60 points</td>
</tr>
<tr>
<td>MELSEC-Q/L series module (subcommand: 0080)</td>
<td></td>
</tr>
</tbody>
</table>

### Block of word device, block of bit device

Specify the device to be read by handling consecutive devices as one block.

Specify the block with the number of points equivalent to the specified "Number of word device blocks" and "Number of bit device blocks", respectively. When '0' is specified, this specification is not required.

Specify the following items for every block.

- **Device**: Specify the head device of the consecutive devices. (Page 63 Devices)
- **Number of device points**: Specify the number of device points to be read. (Page 67 Number of device points)

Specify the total number of device points for each block within the range of 1 to 960.

Word device is 1-word per one point, and bit device is 16-bit for one point.

**Point**

Use a bit device block when the contact and coil for the following devices are specified.

- Timer
- Retentive timer
- Counter

**Restriction**

Long index register (LZ) cannot be specified.
Communication example

Read values from device as follows. (Subcommand: for MELSEC-Q/L series)

<table>
<thead>
<tr>
<th>Item</th>
<th>Content to be read</th>
</tr>
</thead>
<tbody>
<tr>
<td>Word device</td>
<td>Block 1: D0 to D3 (4 points)</td>
</tr>
<tr>
<td></td>
<td>Block 2: W100 to W107 (8 points)</td>
</tr>
<tr>
<td>Bit device</td>
<td>Block 1: M0 to M31 (2 points)</td>
</tr>
<tr>
<td></td>
<td>Block 2: M128 to M159 (2 points)</td>
</tr>
<tr>
<td></td>
<td>Block 3: B100 to B12F (3 points)</td>
</tr>
</tbody>
</table>

Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Device code</th>
<th>Device number</th>
<th>Number of device points</th>
<th>Device code</th>
<th>Device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>D</td>
<td>0000000000</td>
<td>0004</td>
<td>W</td>
<td>00010000</td>
<td>0008</td>
</tr>
<tr>
<td>M</td>
<td>0000000000</td>
<td>0002</td>
<td>M</td>
<td>0000128</td>
<td>0002</td>
</tr>
<tr>
<td>B</td>
<td>0001000000</td>
<td>0003</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(Response data)
## Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device number</th>
<th>Device code</th>
<th>Number of device points</th>
<th>Device number</th>
<th>Device code</th>
<th>Number of device points</th>
<th>Device number</th>
<th>Device code</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>06h, 04h</td>
<td>00h, 00h</td>
<td>04h, 00h</td>
<td>02h, 03h</td>
<td>00h, 00h</td>
<td>00h, 01h</td>
<td>00h, 00h</td>
<td>00h, 00h</td>
<td>00h, 00h</td>
<td>00h, 01h</td>
</tr>
</tbody>
</table>

(Response data)

- **Word device**
  - Data in the first block
  - Data in the second block
  - Data in the third block

- **Bit device**
  - Data in the first block
  - Data in the second block
  - Data in the third block

- **Device number**
  - M15: Bit order of M0
  - M16: Bit order of M0
  - M17: Bit order of M0
  - M18: Bit order of M0

0 = OFF
1 = ON
Batch write multiple blocks (command: 1406)

Write values for specified multiple blocks by handling consecutive word devices or bit devices as one block. Each block can be specified with discontinuous device numbers.

Restriction

When communicating with a Universal model QCPU or an LCPU, if other than "Specify service process execution counts" is selected for "Service Processing Setting" of the CPU module, data separation may occur. To avoid data separation, select "Specify service process execution counts".

Point

When accessing any of the following devices, use the device extension specification (subcommand: 008♭).
- Link direct device
- Module access device
- CPU buffer memory access device

For the message format for device extension specification, refer to the following section.
Page 432 Read/Write by Device Extension Specification

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Number of word device blocks (n points)</th>
<th>Number of bit device blocks (n points)</th>
<th>Block of word device (first point)</th>
<th>...</th>
<th>Block of word device (mth point)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Response data

There is no response data for this command.

Data specified by request data

Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 4 0 6</td>
<td>06 14</td>
</tr>
</tbody>
</table>

Subcommand

<table>
<thead>
<tr>
<th>Type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
<tr>
<td></td>
<td>30 30 30 30</td>
<td></td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>0 0 0 2</td>
<td>02 00</td>
</tr>
<tr>
<td></td>
<td>30 30 30 32</td>
<td></td>
</tr>
</tbody>
</table>

Number of word device blocks, number of bit device blocks

Specify the number of device blocks to be written in hexadecimal. (Page 69 Number of blocks)
Specify the total number of each block within the following range.

<table>
<thead>
<tr>
<th>Access target</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC iQ-R series module (subcommand: 0000)</td>
<td>1 \leq \text{Number of word device blocks} + \text{Number of bit device blocks} \leq 120 points</td>
</tr>
<tr>
<td>MELSEC-Q/L series module (subcommand: 0000)</td>
<td></td>
</tr>
<tr>
<td>MELSEC-QnA series module</td>
<td></td>
</tr>
<tr>
<td>MELSEC iQ-R series module (subcommand: 0002, 0080)</td>
<td>1 \leq \text{Number of word device blocks} + \text{Number of bit device blocks} \leq 60 points</td>
</tr>
<tr>
<td>MELSEC-Q/L series module (subcommand: 0080)</td>
<td></td>
</tr>
</tbody>
</table>

**Block of word device, Block of bit device**

Specify the device to be written by handling consecutive devices as one block.

Specify the block with the number of points equivalent to the specified "Number of word device blocks" and "Number of bit device blocks", respectively. When '0' is specified, this specification is not required.

Specify the following items for each block.

<table>
<thead>
<tr>
<th>Block (1 point)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Head device</td>
</tr>
</tbody>
</table>

- **Device**: Specify the head device of the consecutive devices. ([Page 63 Devices])
- **Number of device points**: Specify the number of device points to be written. ([Page 67 Number of device points])
- **Write data**: Specify the data to be written for the number of device points in hexadecimal. ([Page 70 Read data, write data])

Specify the number of device points within the following range.

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>When using MELSEC-Q/L series (0000, 0080)</td>
<td>1 \leq (Total number of each block \times 4) + (Total number of device) \leq 960 points</td>
</tr>
<tr>
<td>When using MELSEC iQ-R series (0002, 0082)</td>
<td>1 \leq (Total number of each block \times 9) + (Total number of device) \leq 960 points</td>
</tr>
</tbody>
</table>

Word device is 1-word per one point, and bit device is 16-bit for one point.

Use a bit device block when the contact and coil for the following devices are specified.

- **Timer**
- **Retentive timer**
- **Counter**

**Restriction**

Long index register (LZ) cannot be specified.
## Communication example

Write values to devices as follows. (Subcommand: for MELSEC-Q/L series)

### Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Device number</th>
<th>Number of device points</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>D</td>
<td>0</td>
<td>0</td>
<td>0 0 0 0 0 0 0 0 0 0</td>
<td>0 2 0 3</td>
</tr>
<tr>
<td>W</td>
<td>1</td>
<td>0</td>
<td>0 0 0 1 0 0 0 0 8</td>
<td>0 9 7 0</td>
</tr>
<tr>
<td>M</td>
<td>2</td>
<td>0</td>
<td>0 0 0 0 0 0 0 0 0 2</td>
<td>2 0 3 0</td>
</tr>
<tr>
<td>M</td>
<td>3</td>
<td>0</td>
<td>0 0 0 1 2 8 0 0 0 2</td>
<td>2 8 0 0</td>
</tr>
<tr>
<td>B</td>
<td>4</td>
<td>0</td>
<td>0 0 0 1 0 0 0 0 0 3</td>
<td>0 9 7 0</td>
</tr>
</tbody>
</table>

0 = OFF
1 = ON
### Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device code</th>
<th>Device number</th>
<th>Number of device points</th>
<th>Write data</th>
<th>Device code</th>
<th>Device number</th>
<th>Number of device points</th>
<th>Write data</th>
<th>Device code</th>
<th>Device number</th>
<th>Number of device points</th>
<th>Write data</th>
<th>Device code</th>
<th>Device number</th>
<th>Number of device points</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>06h</td>
<td>00h</td>
<td>00h</td>
<td>04h</td>
<td>00h</td>
<td>00h</td>
<td>00h</td>
<td>04h</td>
<td>00h</td>
<td>00h</td>
<td>00h</td>
<td>04h</td>
<td>00h</td>
<td>00h</td>
<td>00h</td>
<td>04h</td>
<td>00h</td>
</tr>
<tr>
<td>D0</td>
<td>D1</td>
<td>D2</td>
<td>D3</td>
<td></td>
<td>W100</td>
<td>W101</td>
<td></td>
<td></td>
<td>W102</td>
<td>W103</td>
<td></td>
<td></td>
<td>W104</td>
<td>W105</td>
<td></td>
<td></td>
</tr>
<tr>
<td>M15</td>
<td>M0</td>
<td>M16</td>
<td>M17</td>
<td></td>
<td>M143</td>
<td>M144</td>
<td></td>
<td></td>
<td>M159</td>
<td>M144</td>
<td></td>
<td></td>
<td>M150</td>
<td>M151</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Device code**

- 00h: Device number
- 04h: Number of device points
- 00h: Write data

8 DEVICE ACCESS

8.4 Batch Read and Write Multiple Blocks
8.5 Device Memory Monitor

Read the registered device data, and monitor it.

Monitoring procedure

The following shows the procedure to monitor devices.

1. Registration of monitor device
   Register a device to be read. (Page 115 Register monitor data (command: 0801))

2. Execution of monitor
   Read values from a registered device. (Page 116 Monitor (command: 0802))

3. Registration of monitor devices
   Reregister a device when a device to be read is changed. (Page 115 Register monitor data (command: 0801))

Point

- Monitoring with multiple conditions to the device memory of the same CPU module cannot be performed at the same time. If monitor (command: 0802) is executed while monitor with other conditions is being performed, the command is completed abnormally.
- Register devices to be read with the 'register monitor data' (command: 0801) before executing the 'monitor' (command: 0802). If the 'monitor' (command: 0802) is executed without the registration, the command is completed abnormally.
- When the access target module is restarted, the registered content is deleted. Register the devices to be read again with the 'register monitor data' (command: 0801).

Register monitor data (command: 0801)

Register devices to be monitored.

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Monitor condition specification designation</th>
<th>Number of word access points (m points)</th>
<th>Number of double word access points (n points)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- Device (first point)  
- Device (mth point)  
- Device (first point)  
- Device (nth point)

There is no response data for this command.
Data specified by request data

**Command**

<table>
<thead>
<tr>
<th>Frame</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>4C/3C/4E/3E frame</td>
<td>0 8 0 1</td>
<td>01h, 08h</td>
</tr>
</tbody>
</table>

2C frame

<table>
<thead>
<tr>
<th></th>
<th>8</th>
<th></th>
</tr>
</thead>
</table>

The data other than commands is the same as the data specified by 'random read in word units' (command: 0403).

> Page 94 Random read in word units (command: 0403)

**Monitor (command: 0802)**

Read value of registered device.

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

**Response data**

The value of read device is stored in word units and in double word units. The data order differs between ASCII code or binary code. (See Page 70 Read data, write data)

Data specified by request data

**Command**

<table>
<thead>
<tr>
<th>Frame</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>4C/3C/4E/3E frame</td>
<td>0 8 0 2</td>
<td>02h, 08h</td>
</tr>
</tbody>
</table>

2C frame

<table>
<thead>
<tr>
<th></th>
<th>9</th>
<th></th>
</tr>
</thead>
</table>

**Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 0</td>
<td>00h, 00h</td>
</tr>
</tbody>
</table>

For 2C frame, the specification is not required. Functions and specification methods are equivalent to the subcommands for MELSEC-Q/L series.
Communication example

Read the following devices registered by the 'register monitor data' (command: 0801).

- Word access: D0, T0, M100 to M115, X20 to X2F
- Double word access: D1500 to D1501, Y160 to Y17F, M1111 to M1142

D0 = 6549 (1995H), T0 = 4610 (1202H), D1500 = 20302 (4F4EH), D1501 = 19540 (4C54H) are stored.

Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>0</th>
<th>8</th>
<th>0</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td>30h</td>
<td>38h</td>
<td>30h</td>
<td>32h</td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>1</th>
<th>9</th>
<th>9</th>
<th>5</th>
</tr>
</thead>
<tbody>
<tr>
<td>31h</td>
<td>30h</td>
<td>39h</td>
<td>35h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>1</th>
<th>2</th>
<th>0</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td>31h</td>
<td>32h</td>
<td>30h</td>
<td>32h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>2</th>
<th>0</th>
<th>3</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>32h</td>
<td>30h</td>
<td>33h</td>
<td>30h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>4</th>
<th>8</th>
<th>4</th>
<th>9</th>
</tr>
</thead>
<tbody>
<tr>
<td>34h</td>
<td>38h</td>
<td>34h</td>
<td>30h</td>
</tr>
</tbody>
</table>

D0 = 6549 (1995H), T0 = 4610 (1202H), D1500 = 20302 (4F4EH), D1501 = 19540 (4C54H)

Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Read data 1 in word units</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 9 9 5</td>
</tr>
<tr>
<td>1 2 0 2</td>
</tr>
<tr>
<td>2 0 3 0</td>
</tr>
<tr>
<td>4 8 4 9</td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>Read data 1 in double word units</th>
</tr>
</thead>
<tbody>
<tr>
<td>4 C 5 4 F 4 E</td>
</tr>
<tr>
<td>4 C 3 D E B 9 A F</td>
</tr>
<tr>
<td>B A D D B C B F</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Read data 2 in double word units</th>
</tr>
</thead>
<tbody>
<tr>
<td>34h 43h 35h 34h 46h 34h 45h</td>
</tr>
<tr>
<td>43h 33h 44h 45h 42h 39h 41h 46h</td>
</tr>
<tr>
<td>42h 43h 44h 46h 42h 43h 42h 37h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Read data 3 in double word units</th>
</tr>
</thead>
<tbody>
<tr>
<td>4 8 4 9 0 0 0 0 0 0 1 1 0 0 0 0 0 0</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Read data 4 in double word units</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 0 1 0 0 0 0 0 1 0 1 0 0 1 1</td>
</tr>
</tbody>
</table>

M115 to M100

<table>
<thead>
<tr>
<th>Y17F to M1142</th>
</tr>
</thead>
<tbody>
<tr>
<td>C F</td>
</tr>
</tbody>
</table>

M1111 to M1142

<table>
<thead>
<tr>
<th>X2F to X20</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 0 1 0 0 0 0 1 0 1 0 0 1 1</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Y160</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 = OFF</td>
</tr>
<tr>
<td>1 = ON</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>M1142 to M1111</th>
</tr>
</thead>
<tbody>
<tr>
<td>B 7</td>
</tr>
</tbody>
</table>

M112 to M100

<table>
<thead>
<tr>
<th>X20</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 0 1 0 0 0 1 0 1 0 0 1 1</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Y160</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 = OFF</td>
</tr>
<tr>
<td>1 = ON</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>M1111</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 = OFF</td>
</tr>
<tr>
<td>1 = ON</td>
</tr>
</tbody>
</table>
### Data communication using binary code

(Request data)

| 02h 08h 00h | 00h |

(Response data)

<table>
<thead>
<tr>
<th>Data read 1 in word units</th>
<th>Data read 2 in word units</th>
<th>Data read 3 in word units</th>
<th>Data read 4 in word units</th>
<th>Data read 1 in double word units</th>
<th>Data read 2 in double word units</th>
<th>Data read 3 in double word units</th>
</tr>
</thead>
<tbody>
<tr>
<td>9Fh 10h</td>
<td>02h 12h</td>
<td>30h 20h</td>
<td>49h 48h</td>
<td>4Eh 4Fh</td>
<td>54h 4Ch</td>
<td>67h 8Ch</td>
</tr>
<tr>
<td>D0</td>
<td>T0</td>
<td>M115 to M100</td>
<td>X2F to X20</td>
<td>D1500</td>
<td>D1501</td>
<td>Y17F to Y160</td>
</tr>
<tr>
<td>M1142 to M1111</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Data read 3 in word units

<table>
<thead>
<tr>
<th>0 = OFF 1 = ON</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 1 1 0 0 0 0 0 1 0 0 0 0</td>
</tr>
<tr>
<td>M107 to M100 ; M115 to M108</td>
</tr>
</tbody>
</table>

Data read 4 in word units

<table>
<thead>
<tr>
<th>0 = OFF 1 = ON</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 0 1 0 1 0 1 0 0 1 0 0 0 0</td>
</tr>
<tr>
<td>X27 to X20 ; X2F to X28</td>
</tr>
</tbody>
</table>

Data read 2 in double word units

<table>
<thead>
<tr>
<th>A</th>
<th>F</th>
<th>---</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 0 1 0 1 1 1 ---</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Y167 to Y160 ; Y17F to Y178</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Data read 3 in double word units

<table>
<thead>
<tr>
<th>B</th>
<th>7</th>
<th>---</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 0 1 1 0 1 1 ---</td>
<td></td>
<td></td>
</tr>
<tr>
<td>M1118 to M1111 ; M1142 to M1135</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Data read 4 in double word units

<table>
<thead>
<tr>
<th>C</th>
<th>3</th>
<th>0 = OFF 1 = ON</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 1 0 0 0 1 1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Y17F to Y178</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
9 LABEL ACCESS

This section explains the commands to read and write devices using the standard global label of GX Works3. The commands can be used when the connected station and request target is MELSEC iQ-R series module.

Restriction

- Local labels cannot be accessed.
- Safety global labels and standard/safety shared global labels cannot be accessed.
- The global labels set with GX Works2 cannot be accessed.
- Enable "Access from External Device" with the global label setting editor of GX Works3 at the time of label access. (Disabled by default.)

9.1 Data to be Specified in Commands

This section explains the contents and specification methods for data items which are set in each command related to label access.

Labels

Specify the global label name to be accessed.
The "Label name" is specified by variable length. Specify the length of character string by "Label name length". (Null is unnecessary at the end of a label name character string.)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name length</td>
<td>Label name</td>
</tr>
<tr>
<td>(4 digits)</td>
<td>(Variable length)</td>
</tr>
<tr>
<td>Label name length</td>
<td>Label name</td>
</tr>
<tr>
<td>(2 bytes)</td>
<td>(Variable length)</td>
</tr>
</tbody>
</table>

Label name length

Specify the number of characters of a label name.

**Data communication using ASCII code**
Convert the numerical value to 4-digit ASCII code (hexadecimal), and send it from upper digits.

**Data communication using binary code**
Send 2-byte*1 numerical values from lower byte (L: bits 0 to 7).

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Ex.
When the number of characters is three.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 3</td>
<td>03h, 00h</td>
</tr>
</tbody>
</table>
Label name
Specify the character string of a label name.

Data communication using ASCII code
Convert the numerical value of UTF-16, which indicates a global label name, to ASCII code (hexadecimal), and send it from the upper digits.

Data communication using binary code
Send the numerical value of UTF-16, which indicates a global label name from lower byte (L: bit 0 to 7).

Ex
When 'A'
(UTF-16: 'A' = 0041)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 4 1</td>
<td>41h, 00h</td>
</tr>
</tbody>
</table>

Labels of the simple data type
Specify the label name as it is.

Bit specification (example: Lbl.3) and digit specification (example: K4Lbl) cannot be used.

Ex
When the label name is 'Lbl'

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name Lbl.3</td>
<td>004C, 0062, 006C</td>
</tr>
<tr>
<td>UTF-16</td>
<td>30303443, 30303632, 30303643</td>
</tr>
<tr>
<td>ASCII code Lbl.3</td>
<td>4C00, 6200, 6C00</td>
</tr>
</tbody>
</table>

Array type label
Specify the element number with square brackets '[ ]' after label name. (UTF-16: '[' = 005B, ']' = 005D)

The element name of array cannot be specified in the square bracket. Specify a numerical value of the element number.

Ex
When the element number of array name 'Lbl' is '20'

- Label name length: 7H
- Label name character string: Lbl[20]

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name Lbl[20]</td>
<td>004C, 0062, 006C, 005B, 0032, 0030, 005D</td>
</tr>
<tr>
<td>UTF-16</td>
<td>30303443, 30303632, 30303643, 30303542, 30303332, 30303330, 30303544</td>
</tr>
<tr>
<td>ASCII code Lbl[20]</td>
<td>4C00, 6200, 6C00, 5B00, 3200, 3000, 5D00</td>
</tr>
</tbody>
</table>

Decimal/hexadecimal notation of element numbers
An element number can be specified in decimal or hexadecimal.

The element numbers can be distinguished by attaching 'k' or 'h' in front of the numerical value. (UTF-16: 'k' = 006B, 'h' = 0068)

When only numerical value is specified, it will be handled as a decimal number.

- Decimal: Numerical value only, or attach 'k' in front of the numerical value. (Example: Lbl[10], Lbl[k10])
- Hexadecimal: Attach 'h' in front of the numerical value. (Example: Lbl[h10])
Two-dimensional array, three-dimensional array,
Up to three-dimensional arrays can be specified.
For two-dimension and three-dimension array, specify an element number by separating with comma (',') in a square bracket.
(UTF-16; ','= 002C)

Ex
When the element numbers are 2, 1, 3 of three-dimensional array of array name 'Lbl'
• Label name length: AH
• Label name character string: Lb[2,1,3]

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>L b l i [ 2 , 1 , 3 ]</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0062 008C 005B 0032 0002 C 0031 002C 0033 005D</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303632 30303643 30303542 30303332 30303243 30303331 30303243 30303333 30303544</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 6200 6C00 5B00 3200 2C00 3100 2C00 3300 5D00</td>
</tr>
</tbody>
</table>

Restriction
Two-dimensional array and three-dimensional array bit type labels cannot be specified with the 'batch read/write array type labels' (command: 041A, 141A).

Structure labels
Specify the structure labels by attaching period '.' as an element name. (UTF-16; '.'= 002E)
Specify the element name for the end member. Only specifying a structure name cannot set the whole structure as a target.

Ex
For the element name 'Data' of the structure name 'Str1'
• Label name length: 9H
• Label name character string: Str1.Data

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>S t r [ 1 , 3 ]</td>
</tr>
<tr>
<td>UTF-16</td>
<td>0053 0074 0072 0031 002E 0044 0061 0074 0061 0061</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303533 30303734 30303732 30303331 30303245 30303434 30303631 30303734 30303631</td>
</tr>
<tr>
<td>Binary code</td>
<td>5300 7400 7200 3100 2E00 4400 6100 7400 6100</td>
</tr>
</tbody>
</table>

Array member
When the structure member is an array type, specify the array element number with square bracket '[]' as is the case in array type label.

Ex
When the element name 'Data' of structure name 'Str1', and 'Data' is a two-dimensional array element.
• Label name length: EH
• Label name character string: Str1.Data[1,3]

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>S t r [ 1 , 3 ]</td>
</tr>
<tr>
<td>UTF-16</td>
<td>0055 0074 0072 0031 002E 0044 0061 0074 0061 0061</td>
</tr>
<tr>
<td>ASCII code</td>
<td>3030 3030 3030 3030 3030 3030 3030 3030 3030 3030 3030 3030</td>
</tr>
<tr>
<td>Binary code</td>
<td>5300 7400 7200 3100 2E00 4400 6100 7400 6100 5B00 3100 2C00 3300 5D00</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>S t r [ 1 , 3 ]</td>
</tr>
<tr>
<td>UTF-16</td>
<td>0055 0074 0072 0031 002E 0044 0061 0074 0061 0061</td>
</tr>
<tr>
<td>ASCII code</td>
<td>3030 3030 3030 3030 3030 3030 3030 3030 3030 3030 3030 3030</td>
</tr>
<tr>
<td>Binary code</td>
<td>5300 7400 7200 3100 2E00 4400 6100 7400 6100 5B00 3100 2C00 3300 5D00</td>
</tr>
</tbody>
</table>
Structure member
When the structure member is a structure type, specify the element name by delimiting with period '.' up to the end member.

Ex.
When specifying the member, 'memberB1', of the structure member name 'memberA3' for the structure type label name 'LabelA'
• Label name character string: LabelA.memberA3.memberB1

Restriction
When arbitrary device is assigned, the structure type label with structure type members cannot be specified.
Timer type label, counter type label

The labels of the following data types are handled as a structure with a contact, coil, and current value for its element.
- Timer
- Retentive timer
- Counter
- Long timer
- Long retentive timer
- Long counter

Specify the following element name with adding a period ‘.’. (UTF-16: ‘.’ = 002E)

<table>
<thead>
<tr>
<th>Item</th>
<th>Element name</th>
<th>Example when a label name is ‘Lbl1’</th>
</tr>
</thead>
<tbody>
<tr>
<td>Contact</td>
<td>S</td>
<td>Lbl1.S</td>
</tr>
<tr>
<td>Coil</td>
<td>C</td>
<td>Lbl1.C</td>
</tr>
<tr>
<td>Current value</td>
<td>N</td>
<td>Lbl1.N</td>
</tr>
</tbody>
</table>

Ex
For the contact of timer type label name 'Lbl1'
- Label name length: 6H
- Label name character string: Lbl1.S

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>UTF-16 004C 0062 006C 0031 002E 0053</td>
</tr>
<tr>
<td></td>
<td>ASCII code 30303443 30303632 30303643 30303331 30303245 30303533</td>
</tr>
<tr>
<td></td>
<td>Binary code 4C00 6200 6C00 3100 2E00 5300</td>
</tr>
</tbody>
</table>

Restriction

The labels of which data type is timer, counter, retentive timer, long timer, long counter, or long retentive timer cannot be specified with the ‘batch read/write array type labels’ (command: 041A, 141A).
Abbreviation specification of label

Abbreviation specification can be used when specifying a structure type label as an access target.

When a label name or a structure member name is specified by the abbreviation specification, the character string specified as a "label name" can be simplified using "%n" (n: offset value).

**Ex**

When a structure type label name 'LabelA' and its structure member name 'memberA3' is specified as abbreviation specification, they can be abbreviated as follows.

\[(\text{LabelA} = %1, \text{memberA3} = %2)\]

<table>
<thead>
<tr>
<th>Actual label name</th>
<th>Abbreviated label name</th>
</tr>
</thead>
<tbody>
<tr>
<td>LabelA.memberA1</td>
<td>%1.memberA1</td>
</tr>
<tr>
<td>LabelA.memberA2</td>
<td>%1.memberA2</td>
</tr>
<tr>
<td>LabelA.memberA3.memberB1</td>
<td>%1.%2.memberB1</td>
</tr>
<tr>
<td>LabelA.memberA3.memberB2</td>
<td>%1.%2.memberB2</td>
</tr>
</tbody>
</table>

**When do not abbreviate labels**

Specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1000...1000</td>
<td>00...00</td>
</tr>
</tbody>
</table>

**When abbreviate labels**

Specify the points to be specified and label name.

Label names can be abbreviated ("%1" to "%n") as an offset value (1 to n) in the specified order.

```
Label specification (1st point)  Label specification (nth point)
Label points (n points)  Label name length  Label name  Label name length  Label name
```

The character strings that include a dot (.) cannot be abbreviated. Abbreviate character string in a label name or member name unit.

The label name and member name of the array type cannot be abbreviated.

**Ex**

The example that cannot be abbreviated is as follows:

<table>
<thead>
<tr>
<th>Actual label name</th>
<th>String that cannot be abbreviated</th>
<th>String that can be abbreviated</th>
</tr>
</thead>
<tbody>
<tr>
<td>LabelA.memberA3.memberB1</td>
<td>&quot;LabelA.memberA3.memberB1&quot;, &quot;LabelA.memberA3&quot;</td>
<td>'LabelA', 'memberA3', 'memberB1'</td>
</tr>
<tr>
<td>LabelA.memberA4[1].memberB1</td>
<td>&quot;memberA4&quot;, &quot;memberA4[1]&quot;</td>
<td>'LabelA', 'memberB1'</td>
</tr>
</tbody>
</table>

**Label points**

Specify the label points which abbreviate a label names by abbreviation specification. (Page 126 Points)

**Label specification**

Specify the following items for each label for the points specified by label points. (Page 119 Labels)

- Label name length: Specify the number of characters of a label name or structure member name.
- Label name: Specify a global label name or a structure member name.

**Ex**

When a structure type label name 'LabelA' and its structure member name 'memberA3' is specified as abbreviation specification
9.1 Data to be Specified in Commands

### Data communication using ASCII code

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>L</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00</td>
</tr>
</tbody>
</table>

### Data communication using binary code

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>m</td>
</tr>
<tr>
<td>UTF-16</td>
<td>006D</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303644</td>
</tr>
<tr>
<td>Binary code</td>
<td>6D00</td>
</tr>
</tbody>
</table>

#### Data communication using ASCII code

In the figure (1) and (2), set the value of "ASCII code" indicated in the table of "Value of code corresponds to character" of each label name.

#### Data communication using binary code

In the figure (1) and (2), set the value of "Binary code" indicated in the table of "Value of code corresponds to character" of each label name.
Points

Specify the number of the data to be read or written.

Setting method

The setting method of each item to specify the number of points is common.
Since data to be transmitted is 1920 bytes at maximum, the maximum number of points which can be specified varies depending on the label name length contained in the data.

■ Data communication using ASCII code

Convert the numerical value to 4-digit ASCII code (hexadecimal), and send it from upper digits.

■ Data communication using binary code

Send 2-byte*1 numerical values from lower byte (L: bits 0 to 7).

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Ex.

For 3 points

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 3</td>
<td>03 00</td>
</tr>
</tbody>
</table>

Array points

Specify the number of arrays.

Label points

Specify the number of labels.
Data type ID

The data type of the read label is stored.
When writing data, the data type ID is not specified. The specified Follow the data type of the specified label.
The value of data type ID of each data type is shown below.

<table>
<thead>
<tr>
<th>Data type</th>
<th>Data type ID (decimal)</th>
<th>Setting value (hexadecimal)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bit</td>
<td>1</td>
<td>01H</td>
</tr>
<tr>
<td>Word [Unsigned]/Bit String [16-bit]</td>
<td>2</td>
<td>02H</td>
</tr>
<tr>
<td>Double Word [Unsigned]/Bit String [32-bit]</td>
<td>3</td>
<td>03H</td>
</tr>
<tr>
<td>Word [Signed]</td>
<td>4</td>
<td>04H</td>
</tr>
<tr>
<td>Double Word [Signed]</td>
<td>5</td>
<td>05H</td>
</tr>
<tr>
<td>FLOAT [Single Precision]</td>
<td>6</td>
<td>06H</td>
</tr>
<tr>
<td>FLOAT [Double Precision]</td>
<td>7</td>
<td>07H</td>
</tr>
<tr>
<td>Time</td>
<td>8</td>
<td>08H</td>
</tr>
<tr>
<td>String</td>
<td>9</td>
<td>09H</td>
</tr>
<tr>
<td>String [Unicode]</td>
<td>10</td>
<td>0AH</td>
</tr>
<tr>
<td>Pointer</td>
<td>Cannot be specified.</td>
<td></td>
</tr>
<tr>
<td>Timer</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Counter</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Retentive timer</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Contact</td>
<td>1</td>
<td>01H</td>
</tr>
<tr>
<td>Coil</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Current value</td>
<td>2</td>
<td>02H</td>
</tr>
<tr>
<td>Long timer</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Long counter</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Long retentive timer</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Contact</td>
<td>1</td>
<td>01H</td>
</tr>
<tr>
<td>Coil</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Current value</td>
<td>3</td>
<td>03H</td>
</tr>
</tbody>
</table>

For an array type label and a structure type label, the data type of the element from which value is read is stored.

Setting method

■ Data communication using ASCII code
Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■ Data communication using binary code
Send a 1-byte numerical value.

Ex
Double Word [Signed]

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 5</td>
<td>05</td>
</tr>
<tr>
<td>300 250</td>
<td></td>
</tr>
</tbody>
</table>
Data length, unit specification

Specify the length of data to be read/written.

Unit specification

Specify the units of data length when reading/writing data from/to array in batch.

- **Bit specification**

  The value of data length is handled as the number of bits.

  Specify this when the data type of the label is bit.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image" alt="Bit specification ASCII code" /></td>
<td><img src="image" alt="Bit specification Binary code" /></td>
</tr>
</tbody>
</table>

  Read data or write data are stored in 16 point unit of bit devices (2 bytes).

  When data length is not a multiple of 16 at the time of bit specification, ‘0’ is stored in an invalid area.

- **Byte specification**

  The value of data length is handled as a number of bytes of read data or write data.

  Specify when the data type of a label is other than bit.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image" alt="Byte specification ASCII code" /></td>
<td><img src="image" alt="Byte specification Binary code" /></td>
</tr>
</tbody>
</table>

Data length

Specify the length of read data or write data.

Specify the following values according to the data type of a label.

Specifying and writing data length which is not suited for the data type of label results in abnormal completion.

<table>
<thead>
<tr>
<th>Data type</th>
<th>Batch read and write array type labels</th>
<th>Random read and write</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Unit specification</td>
<td>Array data length</td>
</tr>
<tr>
<td><strong>Bit</strong></td>
<td>Bit units</td>
<td>1 × Number of array element</td>
</tr>
<tr>
<td><strong>Word [Unsigned]/Bit String [16-bit]</strong></td>
<td>Byte units</td>
<td>2 × Number of array element</td>
</tr>
<tr>
<td><strong>Double Word [Unsigned]/Bit String [32-bit]</strong></td>
<td></td>
<td>4 × Number of array element</td>
</tr>
<tr>
<td><strong>Word [Signed]</strong></td>
<td></td>
<td>2 × Number of array element</td>
</tr>
<tr>
<td><strong>Double Word [Signed]</strong></td>
<td></td>
<td>4 × Number of array element</td>
</tr>
<tr>
<td><strong>FLOAT [Single Precision]</strong></td>
<td></td>
<td>4 × Number of array element</td>
</tr>
<tr>
<td><strong>FLOAT [Double Precision]</strong></td>
<td></td>
<td>8 × Number of array element</td>
</tr>
<tr>
<td><strong>Time</strong></td>
<td></td>
<td>4 × Number of array element</td>
</tr>
<tr>
<td><strong>String</strong></td>
<td></td>
<td>Depend on the number of character strings (1 per 1 character, including end NULL)</td>
</tr>
<tr>
<td><strong>String [Unicode]</strong></td>
<td></td>
<td>Depend on the number of character strings (2 per 1 character, including end NULL)</td>
</tr>
<tr>
<td><strong>Pointer</strong></td>
<td>Cannot be specified.</td>
<td>2</td>
</tr>
<tr>
<td><strong>Counter</strong></td>
<td>Cannot be specified.</td>
<td>2</td>
</tr>
<tr>
<td><strong>Retentive timer</strong></td>
<td>Cannot be specified.</td>
<td>4</td>
</tr>
<tr>
<td><strong>Long timer</strong></td>
<td>Contact</td>
<td>2</td>
</tr>
<tr>
<td><strong>Long counter</strong></td>
<td>Coil</td>
<td>2</td>
</tr>
<tr>
<td><strong>Long retentive timer</strong></td>
<td>Current value</td>
<td>4</td>
</tr>
</tbody>
</table>

*1 Specify the following values per one array element/label.

  Character string length specified to "Data Length of Character String Data Type" with an Engineering tool + 1

  (When the value is an odd number, add 1 and specify with an even number.)

*2 Specify the following values per one array element/label.

  (Character string length specified to "Data Length of Character String Data Type" with an Engineering tool + 1) × 2
Data communication using ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal), and send it from upper digits.

Data communication using binary code
Send 2-byte \(^*1\) numerical values from lower byte (L: bits 0 to 7).

\(^*1\) For C24, the additional code may be added. (Page 33 Additional code (10H))

Setting example

Batch read and write of array
For the bit specification, specify the number of bits to be accessed.
- Unit specification: Bit
- Label: Bit type 3 points
- Array data length: 1 bit \(\times\) Number of array element (3) = 3 bits

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 3</td>
<td>03h 00h</td>
</tr>
</tbody>
</table>

For byte specification, specify the data length of the label to be accessed in byte unit.
- Unit specification: Byte
- Label: Word type 5 points
- Array data length: 2 bytes \(\times\) (5) = 10 bytes

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 A</td>
<td>0Ah 00h</td>
</tr>
</tbody>
</table>

Random read and write
For bit type, data length will be 2 (fixed value).
- Label: Bit type 1 point
- Data length: 2 (fixed)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 2</td>
<td>02h 00h</td>
</tr>
</tbody>
</table>

The character string type [Unicode] will be 2 bytes per one character of UTF-16 code.
- Label: Character string type [Unicode] one point
- "Data Length of Character String Data Type" of an Engineering tool: 32
- Data length: Number of characters \((32 + 1) \times\) Data length per one character string (2) = 66 (42H)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 4 2</td>
<td>42h 00h</td>
</tr>
</tbody>
</table>
Read data, write data

The read data is stored for reading, and the data to be written is stored for writing. Data is stored with variable length. The length of data is specified by "Data length." (Page 128 Data length)
The storing method of data is same as that of reading or writing data in word units (bit device in 16-points). (Page 70 Read data, write data)

For bit type labels

Read data and write data are handled in 16-point units, but '0' is stored in data other than label points to be accessed.

Ex
For bit type label 6 points

```
  b15 b14 b13 b12 b11 b10 b0
  0 0 0 0 0 0 1 0 0 1
```

Fixed to 0

Access target

bit data

For character string type labels

Store NULL at the end of the valid character string. The data after NULL of the read data will be undefined value.

<table>
<thead>
<tr>
<th>Item</th>
<th>Character string type of ASCII code</th>
<th>Character string type of Unicode</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of character strings of label</td>
<td>Odd</td>
<td>Even number</td>
</tr>
<tr>
<td>NULL code to be stored to the end</td>
<td>NULL (00H)</td>
<td>NULL (00H)+2</td>
</tr>
<tr>
<td>Data length of array element/label per one point</td>
<td>Character string specified to &quot;Data Length of Character String Data Type&quot; + 1</td>
<td>Character string specified to &quot;Data Length of Character String Data Type&quot; + 2</td>
</tr>
</tbody>
</table>

Ex
For read data of 1-point character string type (ASCII code) label

- Label character string: 'ABCD' (4 characters)
- "Data Length of Character String Data Type" of an Engineering tool: 32
- Data length: Number of characters (32 + 1) × Data length per one character string (1) = 34 (22H)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>B A D C NULL NULL</td>
<td>4 2 4 1 4 4 3 0 0 0 0 ...</td>
</tr>
<tr>
<td>(&quot;Data Length of String Data Type&quot;(32)+2)x2 bytes</td>
<td>A B C D NULL NULL ...</td>
</tr>
<tr>
<td>34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H 34H 32H</td>
<td></td>
</tr>
</tbody>
</table>

When communicating ASCII code character string data in ASCII code, data is rearranged every two characters and stored.
9.2 Batch Read and Write

Read/write data by specifying the continuous element of array in batch.

**Batch read array type labels (command: 041A)**

Read data by specifying the continuous element of array in batch. Specify the array type label or array type element of structure label. The labels other than array type can be specified in one point unit. (Specify the number of array element as '1'.)

**Message format**

The following shows the message format of the request data and response data of the command.

<table>
<thead>
<tr>
<th>Request data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Command</td>
</tr>
<tr>
<td>Subcommand</td>
</tr>
<tr>
<td>Array points (n points)</td>
</tr>
<tr>
<td>Abbreviation specification</td>
</tr>
<tr>
<td>Array specification (first point)</td>
</tr>
<tr>
<td>...</td>
</tr>
<tr>
<td>Array specification (nth point)</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Response data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Array points (n points)</td>
</tr>
<tr>
<td>Array data (first point)</td>
</tr>
<tr>
<td>...</td>
</tr>
<tr>
<td>Array data (nth point)</td>
</tr>
</tbody>
</table>

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 4 1 A</td>
<td></td>
</tr>
<tr>
<td>30h 34h 31h 41h</td>
<td>3Ah 04h</td>
</tr>
</tbody>
</table>

**Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td></td>
</tr>
<tr>
<td>30h 30h 30h 30h</td>
<td>00h 00h</td>
</tr>
</tbody>
</table>

**Array points**

Specify the point of array to be read. (Page 126 Points)

**Abbreviation specification**

Specify the label name length and label name to be abbreviated. (Page 124 Abbreviation specification of label)

When do not abbreviate, specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td></td>
</tr>
<tr>
<td>30h 30h 30h 30h</td>
<td>00h 00h</td>
</tr>
</tbody>
</table>
# Array specification

Specify the details of arrays for number of arrays specified to array points.

<table>
<thead>
<tr>
<th>Label name length</th>
<th>Label name</th>
<th>Unit specification</th>
<th>Fixed values</th>
<th>Array data length</th>
</tr>
</thead>
</table>

Array specification (Array one point)

Specify the following items for each array.

- Label name length, label name: Specify the label name and label length of a global label. (Page 119 Labels)
- Unit specification: For the bit type labels, specify the unit specification in bit units (0). As for other than bit type label, specify the unit specification in byte units (1).
- Array data length: Specify the data size of array in the unit specified with "Unit specification." (Page 128 Data length, unit specification)
- Fixed value: Fixed to '0'

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>000</td>
</tr>
</tbody>
</table>

Data stored in response data

## Array points

The same data as request data are stored.

## Array data

The read array data is stored for number of arrays which are specified with array point.

<table>
<thead>
<tr>
<th>Data type ID</th>
<th>Unit specification</th>
<th>Array data length</th>
<th>Read data</th>
</tr>
</thead>
</table>

Array data (Array one point)

The following items are stored for each array.

- Data type ID: The data type of the label name is stored with the defined ID. (Page 127 Data type ID)
- Unit specification: For the bit type labels, specify the unit specification in bit units (0). As for other than bit type label, specify the unit specification in byte units (1).
- Array data length: Specify the data size of array in the unit specified with "Unit specification." (Page 128 Data length, unit specification)
- Read data: The value of the read label is stored. (Page 130 Read data, write data)

**Point**

When unit specification is bit specification, read data are stored in 16-bit (2-byte) units.
Communication example (Bit specification)

For one-dimensional array type label "Lbl", read 2-bit data from Lbl [2].

The value of the read label is as follows:

\[
\begin{array}{c}
0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0
\end{array}
\]

\[\text{Fixed to 0} \quad \text{Access target data}\]

Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Array points</th>
<th>Abbreviation specification</th>
<th>Label name length</th>
<th>Label name</th>
<th>Unit specification (Fixed value)</th>
<th>Array data length</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 4 1 A</td>
<td>0 0 0 0 0</td>
<td>G L b I L</td>
<td>0 0 0 0 0 6 (1)</td>
<td>0 0 0 0</td>
<td>0 0 0 0 2</td>
<td></td>
</tr>
</tbody>
</table>

In the figure (1), set the value of "ASCII code" indicated in the following table.

(1) Lbl[2]

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>L b I [ 2 ]</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0062 006C 005B 0032 005D</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303632 30303643 30303542 30303332 30303544</td>
</tr>
</tbody>
</table>

(Response data)

Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Array points</th>
<th>Abbreviation specification</th>
<th>Label name length</th>
<th>Label name</th>
<th>Unit specification</th>
<th>Array data length</th>
</tr>
</thead>
<tbody>
<tr>
<td>1A 04</td>
<td>00 00 00</td>
<td>G L b I [ 2 ]</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

_response_data_

(Array specification (Array one point))

Data communication using binary code
(Response data)

<table>
<thead>
<tr>
<th>Data type ID</th>
<th>Array points</th>
<th>Unit specification</th>
<th>Array data length</th>
<th>Read data</th>
</tr>
</thead>
<tbody>
<tr>
<td>01 M 00</td>
<td>01 M 00</td>
<td>02 M 00</td>
<td>02 M 00</td>
<td></td>
</tr>
</tbody>
</table>

(Array data (Array one point))
Communication example (Byte specification)

For one-dimensional array type label 'Lbl', read 5-word data from Lbl [2].

Data communication using ASCII code

(Request data)

For one-dimensional array type label 'Lbl', read 5-word data from Lbl [2].

Data communication using ASCII code

(Request data)

(1) Lbl[2]

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>UTF-16</td>
<td>004C 0062 006C 005B 0032 005D</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303632 30303643 30303542 30303332 30303544</td>
</tr>
</tbody>
</table>

(Response data)

Data communication using binary code

(Request data)
Communication example (Abbreviate with structure type array)

Read the following data from the structure label 'Typ1', which has the array type element.
- 8 bytes from Typ1.led[2]
- 4 bytes from Typ1.No[1]

The notation of each label when using abbreviation specification (Typ1= %1) is as follows.

(1) Typ1

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>T y p 1</td>
</tr>
<tr>
<td>UTF-16</td>
<td>0054</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303534</td>
</tr>
<tr>
<td>Binary code</td>
<td>5400</td>
</tr>
</tbody>
</table>

(2) Typ1.led[2]

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Abbreviated notation</td>
<td>% 1 . led [ 2 ]</td>
</tr>
<tr>
<td>UTF-16</td>
<td>0025</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303235</td>
</tr>
<tr>
<td>Binary code</td>
<td>2500</td>
</tr>
</tbody>
</table>

(3) Typ1.No[1]

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Abbreviated notation</td>
<td>% 1 . No [ 1 ]</td>
</tr>
<tr>
<td>UTF-16</td>
<td>0025</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303235</td>
</tr>
<tr>
<td>Binary code</td>
<td>2500</td>
</tr>
</tbody>
</table>

Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Array points</th>
<th>Number of abbreviated points</th>
<th>Label name length</th>
<th>Label name</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 4 1 A</td>
<td>30 34 35 36</td>
<td>0 0 0 0</td>
<td>0 0 0 2</td>
<td>0 0 0 4</td>
</tr>
</tbody>
</table>

Abbreviation specification

<table>
<thead>
<tr>
<th>Label name length</th>
<th>Label name</th>
<th>Unit specification (Fixed value)</th>
<th>Array data length</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 9</td>
<td>(2)</td>
<td>0 1 0 0 0 0 0 8</td>
<td>30 31 30 30 30 30 30 30</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Label name length</th>
<th>Label name</th>
<th>Unit specification (Fixed value)</th>
<th>Array data length</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 8</td>
<td>(3)</td>
<td>0 1 0 0 0 0 0 4</td>
<td>30 31 30 30 30 30 30 30</td>
</tr>
</tbody>
</table>

In the figure (1) to (3), set the value of "ASCII code" indicated in the table of "Value of code corresponds to character" of each label.
Data communication using binary code

In the figure (1) to (3), set the value of "Binary code" indicated in the table of "Value of code corresponds to character" of each label.

(Recipe data)
Batch write array type labels (command: 141A)

Write the values in batch with specifying the consecutive array elements.
Specify the array type labels or array type elements of structure type labels.
The labels other than array type can be specified in one point unit. (Specify the number of array element as '1'.)

Message format
The following shows the message format of the request data and response data of the command.

Request data
There is no response data for this command.

Data specified by request data

Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 4 1 A</td>
<td></td>
</tr>
<tr>
<td>3b 3b 3b</td>
<td>1b</td>
</tr>
</tbody>
</table>

Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td></td>
</tr>
<tr>
<td>3b 3b 3b 3b</td>
<td>0b 0b</td>
</tr>
</tbody>
</table>

Array points
Specify the point of array to be written. (Page 126 Points)

Abbreviation specification
Specify the label name length and label name to be abbreviated. (Page 124 Abbreviation specification of label)
When do not abbreviate, specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td></td>
</tr>
<tr>
<td>3b 3b 3b 3b</td>
<td>0b 0b</td>
</tr>
</tbody>
</table>

Array specification
Specify the details of arrays for number of arrays specified to array points.

Label name length | Label name | Unit specification | Fixed values | Array data length | Write data |
|------------------|------------|--------------------|--------------|------------------|------------|

Specify the following items for each array.

- Label name length, label name: Specify the label name and label length of a global label. (Page 119 Labels)
- Unit specification: For the bit type labels, specify the unit specification in bit units (0). As for other than bit type label, specify the unit specification in byte units (1).
- Array data length: Specify the data size of array in the unit specified by "Unit specification." (Page 128 Data length, unit specification)
- Write data: Specify the value to be written. (Page 130 Read data, write data)
• Fixed value: '0'.

### ASCII code | Binary code
--- | ---
0x0 | 0b0

#### Communication example (Bit specification)
For one-dimensional array type label 'Lbl', write 2-bit data from Lbl [2].
The value of the label to be written is as follows:

<table>
<thead>
<tr>
<th>b15</th>
<th>b0</th>
</tr>
</thead>
<tbody>
<tr>
<td>00000000000000000100</td>
<td></td>
</tr>
</tbody>
</table>

- **Fixed to 0**
- **Access target data**

### Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Array points</th>
<th>Abbreviation specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 4 1 A 0 0 0 0 0 0 0 1 0 0 0 0</td>
<td>31 34 41 30 30 30 30 30 30 30 30 30 30 30 30</td>
<td></td>
</tr>
</tbody>
</table>

In the figure (1), set the value of "ASCII code" indicated in the following table.

| Item | Value of code corresponds to character
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>L b l [ 2 ]</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0062 006C 005F 0032 005D</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303632 30303643 30303542 30303332 30303544</td>
</tr>
</tbody>
</table>

### Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Array points</th>
<th>Abbreviation specification</th>
<th>Label name</th>
<th>Unit specification</th>
<th>Array data length</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>1Ah 14h 00h 00h 01h 00h 06h 00h</td>
<td>04 00 00 00 00 00 00 00</td>
<td>L b l [ 2 ]</td>
<td>00 02</td>
<td>02h 00h</td>
<td>02h 00h</td>
<td>00h</td>
</tr>
</tbody>
</table>

Array specification (Array one point)
Communication example (Byte specification)

For one-dimensional array type label 'Lbl', write 5-word data from Lbl [2].

Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Array points</th>
<th>Abbreviation specification</th>
<th>Label name length</th>
<th>Label name</th>
<th>Unit specification (Fixed value)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>4</td>
<td>1</td>
<td>A</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>

Data communication using binary code
(Request data)

Communication example (Abbreviate with structure type array)

Write the following data to three-dimensional structure label 'Typ1', which has the array type element.

• 8 bytes from Typ1.led[5]
• 4 bytes from Typ1.No[7]

The notation of each label when using abbreviation specification (Typ1= %1) is as follows.

(1) Typ1

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>T</td>
</tr>
<tr>
<td>UTF-16</td>
<td>0054</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303534</td>
</tr>
<tr>
<td>Binary code</td>
<td>5400</td>
</tr>
</tbody>
</table>

(2) Typ1.led[5]

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Abbreviated notation</td>
<td>%</td>
</tr>
<tr>
<td>UTF-16</td>
<td>0025</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303235</td>
</tr>
<tr>
<td>Binary code</td>
<td>2500</td>
</tr>
</tbody>
</table>
### Data communication using ASCII code

#### (Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Array points</th>
<th>Number of abbreviated points</th>
<th>Label name length</th>
<th>Label name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 4 1 A</td>
<td>31, 34, 31, 34</td>
<td>0 0 0 0 2</td>
<td>0 0 0 1</td>
<td>0 0 0 4</td>
</tr>
</tbody>
</table>

#### Abbreviation specification (%1)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>UTF-16</td>
<td>% 0025 0031 002E 004E 006F 005B 0037 005D</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303235 30303331 30303245 30303445 30303646 30303542 30303337 30303544</td>
</tr>
<tr>
<td>Binary code</td>
<td>2500 3100 2E00 4E00 6F00 5B00 3700 5D00</td>
</tr>
</tbody>
</table>

In the figure (1) to (3), set the value of "ASCII code" indicated in the table of "Value of code corresponding to character" of each label name.

### Data communication using binary code

#### (Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Array points</th>
<th>Number of abbreviated points</th>
<th>Label name length</th>
<th>Label name</th>
</tr>
</thead>
<tbody>
<tr>
<td>140 14c</td>
<td>00c 00c 02c 00c 01c 00c 04c 00c</td>
<td>0 0 0 0 2</td>
<td>0 0 0 1</td>
<td>0 0 0 4</td>
</tr>
</tbody>
</table>

#### Abbreviation specification (%1)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>UTF-16</td>
<td>% 0025 0031 002E 004E 006F 005B 0037 005D</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303235 30303331 30303245 30303445 30303646 30303542 30303337 30303544</td>
</tr>
<tr>
<td>Binary code</td>
<td>2500 3100 2E00 4E00 6F00 5B00 3700 5D00</td>
</tr>
</tbody>
</table>

In the figure (1) to (3), set the value of "Binary code" indicated in the table of "Value of code corresponding to character" of each label name.
9.3 Random Read and Write

Specify a label and read/write value in one point unit. When reading and writing data in batch by specifying continuous elements of array, use batch read and write command. (Page 131 Batch Read and Write)

Random read labels (command: 041C)

Read value in one point units by specifying multiple labels.

**Message format**

The following shows the message format of the request data and response data of the command.

<table>
<thead>
<tr>
<th>Request data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Command</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Response data</th>
</tr>
</thead>
<tbody>
<tr>
<td>The data of read label is stored for the number of label points specified with request data.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Data specified by request data</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Command</strong></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 4 1 C</td>
<td>1C04</td>
</tr>
<tr>
<td>30h 31h 32h 43h</td>
<td>30h 31h 43h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Subcommand</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00</td>
</tr>
<tr>
<td>30h 30h 30h 30h</td>
<td>30h 30h 30h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Label points</th>
</tr>
</thead>
</table>

Specify the point of label to read. (Page 126 Points)

<table>
<thead>
<tr>
<th>Abbreviation specification</th>
</tr>
</thead>
</table>

Specify the label name length and label name to be abbreviated. (Page 124 Abbreviation specification of label)

When do not abbreviate, specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00</td>
</tr>
<tr>
<td>30h 30h 30h 30h</td>
<td>30h 30h 30h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Label specification</th>
</tr>
</thead>
</table>

Specify the label name and label length of global label for the specified number of label points. (Page 119 Labels)

For a structure type label or array type label, specify the data of each element.
Data stored in response data

■ Label points
The same data as request data are stored.

■ Label data
The data of read label for the specified number of label points is stored.

<table>
<thead>
<tr>
<th>Data type ID</th>
<th>Spare data</th>
<th>Read data length</th>
<th>Read data</th>
</tr>
</thead>
</table>

Label data (1 point)

The following items are stored for each label.
- Data type ID: The data type of label name is stored with the defined ID. (Page 127 Data type ID)
- Read data length: Specify the read data size in byte units. (Page 128 Data length, unit specification)
- Read data: The value of read label is stored in the format of "Data type ID". (Page 130 Read data, write data)
- Spare data: The 2-byte of system data for data communication with ASCII code, and the 1-byte*1 of system data for data communication with binary code is stored.

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Communication example

Read data from three labels.
- Lbl1 (bit type) = 1 (ON)
- Lbl2.Lbl[2] (word type array element of structure label) = 0031H
- Lbl3 (word type) =0001H

The notation of each label when using abbreviation specification (Lbl2 = %1) is as follows.

1. Lbl2 (abbreviation specification)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>L b l 1</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0062 006C 0032</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303632 30303643 30303332</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 6200 6C00 3200</td>
</tr>
</tbody>
</table>

2. Lbl1

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>L b l 1</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0062 006C 0031</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303632 30303643 30303331</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 6200 6C00 3100</td>
</tr>
</tbody>
</table>

3. Lbl2.Lbl[2]

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Abbreviated notation</td>
<td>% 1 . L b l [ 2 ]</td>
</tr>
<tr>
<td>UTF-16</td>
<td>0025 0031 002E 004C 0062 006C 005B 0032 005D</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303235 30303331 30303245 30303443 30303632 30303643 30303542 30303332 30303544</td>
</tr>
<tr>
<td>Binary code</td>
<td>2500 3100 2E00 4C00 6200 6C00 5B00 3200 5D00</td>
</tr>
</tbody>
</table>

4. Lbl3

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>L b l 3</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0062 006C 0033</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303632 30303643 30303333</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 6200 6C00 3300</td>
</tr>
</tbody>
</table>
Data communication using ASCII code

(Request data)

In the figure (1) to (4), set the value of "ASCII code" indicated in the table of "Value of code corresponding to character" of each label name.

(Response data)

Data communication using binary code

(Request data)

In the figure (1) to (4), set the value of "Binary code" indicated in the table of "Value of code corresponding to character" of each label name.

(Response data)
Random write labels (command: 141B)

Write value in one point units by specifying multiple labels.

Message format
The following shows the message format of the request data and response data of the command.

■ Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Label points (n points)</th>
<th>Abbreviation specification</th>
<th>Label specification (1st point)</th>
<th>...</th>
<th>Label specification (nth point)</th>
</tr>
</thead>
</table>

■ Response data
There is no response data for this command.

Data specified by request data

■ Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 4 1 8</td>
<td>18</td>
</tr>
</tbody>
</table>

■ Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00</td>
</tr>
</tbody>
</table>

■ Label points
Specify the number of label points to be written. (Page 126 Points)

■ Abbreviation specification
Specify the label name length and label name to be abbreviated. (Page 119 Labels)
When do not abbreviate, specify ‘0’.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00</td>
</tr>
</tbody>
</table>

■ Label specification
Specify the label name and write data for the specified number of label points.

Specify the following items for each label.
- Label name length, label name: Specify the label name and label length of a global label. (Page 119 Labels)
- Write data length: Specify he read data size in byte unit. (Page 128 Data length, unit specification)
- Write data: Store the values of labels to be written. (Page 130 Read data, write data)
Communication example

Write data to three labels.
- Lbl1 (bit type) = 1 (ON)
- Lbl2.Lbl2 (word type array element of structure label) = 0031H
- Lbl3 (word type) = 0001H

The notation of each label when using abbreviation specification (Lbl2 = %1) is as follows.

(1) Lbl2 (abbreviation specification)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>L b l 1</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0062 006C 0032</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303632 30303643 30303332</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 6200 6C00 3200</td>
</tr>
</tbody>
</table>

(2) Lbl1

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>L b l 1</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0062 006C 0031</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303632 30303643 30303331</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 6200 6C00 3100</td>
</tr>
</tbody>
</table>

(3) Lbl2.Lbl2

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Abbreviated notation</td>
<td>% L b l 2[2]</td>
</tr>
<tr>
<td>UTF-16</td>
<td>0025 0031 002E 004C 0062 006C 005B 0032 005D</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303235 30303331 30303245 30303443 30303632 30303643 30303542 30303332 30303544</td>
</tr>
<tr>
<td>Binary code</td>
<td>2500 3100 2E00 4C00 6200 6C00 5B00 3200 5D00</td>
</tr>
</tbody>
</table>

(4) Lbl3

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Label name</td>
<td>L b l 3</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0062 006C 0033</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303632 30303643 30303333</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 6200 6C00 3300</td>
</tr>
</tbody>
</table>
Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Label points</th>
<th>Number of abbreviated points</th>
<th>Label name length</th>
<th>Label name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>4</td>
<td>18</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>2</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>3</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>4</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>

In the figure (1) to (4), set the value of "ASCII code" indicated in the table of "Value of code corresponding to character" of each label name.

Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Label points</th>
<th>Number of abbreviated points</th>
<th>Label name length</th>
<th>Label name</th>
</tr>
</thead>
<tbody>
<tr>
<td>18</td>
<td>00</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>00</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>00</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>00</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>

In the figure (1) to (4), set the value of "Binary code" indicated in the table of "Value of code corresponding to character" of each label name.
This chapter explains the commands which read and write the buffer memory.

The buffer memory can be accessed with device access function using module access device (Un\G).

10.1 Buffer Memory

This section explains the command which reads and writes data to the buffer memory of the supported device connected to the external device.

The command can only be used for C24 (including multidrop connection station) and E71 connected to an external device. It cannot be used via network.

This command is processed by C24/E71 connected to the CPU module without waiting for the END process.

Data to be specified in commands

This section explains the contents and specification methods for data items which are set in each command related to the access to the host station (supported device) buffer memory.

Start address

Specify the start address of the buffer memory to be read/written.

Data communication using ASCII code

Convert the numerical value to 8-digit (hexadecimal) ASCII code and send it from the upper digits.

Data communication in binary code

Send 4-byte numerical values from the lower byte (L: bits 0 to 7).

Ex.

When the head area address is 1E1H

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 0 0 1 E 1</td>
<td>01</td>
</tr>
</tbody>
</table>
Word length
Specify the word length of the buffer memory to be read/written.

- **Data communication using ASCII code**
  Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

- **Data communication in binary code**
  Send 2-byte numerical values from lower byte (L: bits 0 to 7).

**Ex.**
For 5 words and 20 words

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 words</td>
<td>0 0 0 5</td>
<td>05h 00h</td>
</tr>
<tr>
<td></td>
<td>30h, 30h, 30h, 35h</td>
<td></td>
</tr>
<tr>
<td>20 words</td>
<td>0 0 1 4</td>
<td>14h 00h</td>
</tr>
<tr>
<td></td>
<td>30h, 30h, 31h, 34h</td>
<td></td>
</tr>
</tbody>
</table>

**Read data, write data**
The read buffer memory value is stored for reading, and the data to be written is stored for writing.
This function reads/writes data in word unit.

- **Data communication using ASCII code**
  Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

- **Data communication in binary code**
  Send 2-byte numerical values from lower byte (L: bits 0 to 7).

**Ex.**
When the data for one buffer memory address is 09C1H

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 9 C 1</td>
<td>C1h 09h</td>
</tr>
<tr>
<td>30h, 30h, 43h, 31h</td>
<td></td>
</tr>
</tbody>
</table>
Batch read (command: 0613)

Read data from the buffer memory of the host station (supported device).

**Message format**
The following shows the message format of the request data and response data of the command.

- **Request data**

- **Response data**
The value read from the buffer memory is stored. The data order differs depending on the type of code, ASCII code or binary code.

Refer to [Page 148 Read data, write data]

**Data specified by request data**

- **Command**

- **Subcommand**

- **Start address**
Specify the buffer memory start address to be read. (Refer to [Page 147 Start address])

- **Word length**
Specify the word length of the buffer memory to be read. (Refer to [Page 148 Word length])

Specification range: 1H to 1E0H (480)

- **Point**
Specify the access range within the range of buffer memory.

(Start address + Word length -1) ≤ Buffer memory range
Communication example

Read the data of the buffer memory addresses from 78H to 81H (120 to 129).

Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Start address</th>
<th>Word length</th>
</tr>
</thead>
<tbody>
<tr>
<td>10 0 0 0 0 0 0 0 0 0 7 8 0 0 0 A</td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>Read data 1</th>
<th>Read data 2</th>
<th>Read data 10</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 0 9 C 1</td>
<td>...</td>
<td>0 0 C 8</td>
</tr>
</tbody>
</table>

Values of address 78H = 0500H
Values of address 79H = 09C1H
Values of address 81H = 00C8H

Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Start address</th>
<th>Word length</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0</td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>Read data 1</th>
<th>Read data 2</th>
<th>Read data 10</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Values of address 78H = 0500H
Values of address 79H = 09C1H
Values of address 81H = 00C8H
Batch write (command: 1613)

Write data to the buffer memory of the host station (supported device).

**Restriction**

Do not write any data in "System area" or "Write-protect area" in the buffer memory. Writing data to the "System area" or "Write-protect area" may cause malfunction of the programmable controller system.

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Start address</th>
<th>Word length</th>
<th>Write data 1</th>
<th>...</th>
<th>Write data n</th>
</tr>
</thead>
</table>

**Response data**

There is no response data for this command.

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 1 3</td>
<td>13 16</td>
</tr>
</tbody>
</table>

**Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
</tbody>
</table>

**Start address**

Specify the buffer memory start address to be written. (Page 147 Start address)

**Word length**

Specify the word length of the buffer memory to be written. (Page 148 Word length)

Specification range: 1H to 1E0H(480)

**Write data**

Specify the data to be written in the buffer memory. (Page 148 Read data, write data)

Specify the access range within the range of buffer memory.

(Start address + Word length -1) ≤ Buffer memory range
## Communication example

Write the value to buffer memory addresses from 2680H to 2683H (9856 to 9859).

### Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Start address</th>
<th>Word length</th>
<th>Write data 1</th>
<th>Write data 4</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 1 3</td>
<td>0 0 0 0</td>
<td>0 0 0 4</td>
<td>... 0 0 0 0</td>
</tr>
<tr>
<td>31H 36H 33H</td>
<td>30H 30H 30H</td>
<td>30H 30H 30H</td>
<td>30H 30H 30H</td>
</tr>
<tr>
<td>Values of address 2680H = 2000H</td>
<td>Values of address 2683H = 0H</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Start address</th>
<th>Word length</th>
<th>Write data 1</th>
<th>Write data 4</th>
</tr>
</thead>
<tbody>
<tr>
<td>13H 16H</td>
<td>00H 000H</td>
<td>04H 000H</td>
<td>... 00H 00H</td>
</tr>
<tr>
<td>30H 26H 00H</td>
<td>00H 20H</td>
<td>Values of address 2680H = 2000H</td>
<td>Values of address 2683H = 0H</td>
</tr>
</tbody>
</table>

Values of address 2680H = 2000H
Values of address 2683H = 0H
10.2 Intelligent Function Module

The section explains the commands to read from/write to the buffer memory of an intelligent function module.

Accessible modules

The following shows the accessible intelligent functional modules to buffer memory.

Accessing buffer memory using module access device (Un\G)

The intelligent function modules, which can be accessed the module access device (Un\G), can be accessed by the device access function.

Page 436 Accessing module access devices
Page 63 DEVICE ACCESS

Accessing buffer memory with calculating a start address

Use the command (0601, 1601) shown in this section to access the following devices.

<table>
<thead>
<tr>
<th>Module</th>
<th>Model</th>
<th>Additional values when calculating start address</th>
</tr>
</thead>
<tbody>
<tr>
<td>Load cell input module</td>
<td>Q61LD</td>
<td>2000H</td>
</tr>
<tr>
<td>Loop control module</td>
<td>Q62HLC</td>
<td></td>
</tr>
<tr>
<td>Analog—digital converter module</td>
<td>Q62AD-DGH, Q64AD, Q66AD-DG, Q66AD-G, Q68AD-G, Q68ADV, Q68ADI</td>
<td>1000H</td>
</tr>
<tr>
<td>Digital—analog converter module</td>
<td>Q62DA, Q62DA-FG, Q62DAN, Q64DA, Q64DAN, Q66DA-G, Q68DAV, Q68DAI, Q68DAVN, Q68DAIN</td>
<td>1000H</td>
</tr>
<tr>
<td>Analog input/output module</td>
<td>Q64AD2DA</td>
<td>2000H</td>
</tr>
<tr>
<td>Temperature control module</td>
<td>Q64TCCT, Q64TCRT, Q64TCCTTBW, Q64TCRTBW</td>
<td></td>
</tr>
<tr>
<td>Temperature input module (function version B)</td>
<td>Q64TD, Q64RD</td>
<td>2000H</td>
</tr>
<tr>
<td>Temperature input module (function version C)</td>
<td>Q64TD, Q64TDV-GH, Q64RD, Q64RD-G</td>
<td>8000H</td>
</tr>
<tr>
<td>Channel isolated thermocouple input module</td>
<td>Q68TD-G-H01, Q68TD-G-H02</td>
<td>1000H</td>
</tr>
<tr>
<td>Channel isolated RTD input module</td>
<td>Q68RD3-G</td>
<td>1000H</td>
</tr>
<tr>
<td>ID Interface module</td>
<td>QD35ID1, QD35ID2</td>
<td>4000H</td>
</tr>
<tr>
<td>Intelligent communication module</td>
<td>QD51, QD51-R24</td>
<td>10000H</td>
</tr>
<tr>
<td>Channel isolated pulse input module</td>
<td>QD60P8-G</td>
<td>2000H</td>
</tr>
<tr>
<td>High-speed counter module</td>
<td>QD62, QD62E, QD62D</td>
<td>3CH</td>
</tr>
<tr>
<td>Multichannel high-speed counter module</td>
<td>QD63P6</td>
<td>2000H</td>
</tr>
<tr>
<td>4Mpps capable high-speed counter module</td>
<td>QD64D2</td>
<td>2000H</td>
</tr>
<tr>
<td>Positioning module</td>
<td>QD70P4, QD70P8, QD70D4, QD70D8, QD72P3C3</td>
<td>5000H</td>
</tr>
<tr>
<td>High speed data logger module</td>
<td>QD81DL96</td>
<td>1000H</td>
</tr>
<tr>
<td>CC-Link system master/local module</td>
<td>QJ61BT11, QJ61BT11N</td>
<td>10000H</td>
</tr>
<tr>
<td>CC-LinkLT master module</td>
<td>QJ61CL12</td>
<td>01B4H</td>
</tr>
<tr>
<td>Serial communication module</td>
<td>QJ71C24N, QJ71C24N-R2, QJ71C24N-R4, QJ71C24, QJ71C24-R2</td>
<td>10000H</td>
</tr>
<tr>
<td>AS-i master module</td>
<td>QJ71AS92</td>
<td>10000H</td>
</tr>
<tr>
<td>Ethernet interface module</td>
<td>QJ71E71-100, QJ71E71-B5, QJ71E71-B2</td>
<td>10000H</td>
</tr>
<tr>
<td>FL-net (OPCN-2) interface module</td>
<td>QJ71FL71-T, QJ71FL71-B2, QJ71FL71-B5, QJ71FL71-T-F01, QJ71FL71-B2-F01, QJ71FL71-B5-F01</td>
<td>10000H</td>
</tr>
<tr>
<td>MODBUS interface module</td>
<td>QJ71MB91, QJ71MT91</td>
<td>10000H</td>
</tr>
<tr>
<td>MES interface module</td>
<td>QJ71MES96</td>
<td>10000H</td>
</tr>
<tr>
<td>Web server module</td>
<td>QJ71WS96</td>
<td>10000H</td>
</tr>
<tr>
<td>PROFIBUS-DP Interface module</td>
<td>QJ71PB92D</td>
<td>10000H</td>
</tr>
<tr>
<td>PROFIBUS-DP Master module</td>
<td>QJ71PB92V</td>
<td>10000H</td>
</tr>
<tr>
<td>PROFIBUS-DP Slave module</td>
<td>QJ71PB93D</td>
<td>10004H</td>
</tr>
</tbody>
</table>
By using the command (0601, 1601), MELSEC-QnA series special function modules can be accessed.

When accessing buffer memory of MELSEC-A series special function modules, use the command of 1C/1E frame.

- 1C frame:  Page 377 Read and write Buffer Memory of Special Function Module
- 1E frame:  Page 426 Read and Write Buffer Memory of Special Function Module

Data to be specified in commands

This section explains the contents and specification methods for data items which are set in each command related to the access to the intelligent function module buffer memory.

Start address

Specify the start address of the buffer memory to be read/written.

- Calculation method

To access the buffer memory of the intelligent function module which consisted of word units by byte unit, specify a start address calculated by byte unit.

Calculate the start address as follows:

\[
\text{Start address} = (\text{Buffer memory address} \times 2) + \text{Additional value of a module}
\]

For the arbitrary additional value of the module, refer to the following section.

Page 153 Accessing buffer memory with calculating a start address

Ex.

When specifying Q62DA buffer memory address 18H

\[
(18H \times 2) + 1008H = 30H + 1008H = 1038H
\]

- Data communication using ASCII code

Convert the numerical value to 8-digit (hexadecimal) ASCII code and send it from the upper digits.

- Data communication in binary code

Send 4-byte numerical values from the lower byte (L: bits 0 to 7).

Ex.

When the start address is 1038H

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 1 0 3 8</td>
<td>38h</td>
</tr>
</tbody>
</table>
**Number of bytes**
Specify the number of bytes of the data to be read/written.

**Calculation method**
The buffer memory for intelligent function module consists of two bytes (one word) for one area. Calculate the number of bytes by 2-byte per data for one buffer memory address.
Number of bytes = (Number of buffer memory address × 2)

**Ex.**
When accessing buffer memory address 160 to 161 (A0H to A1H)
(161 - 160 + 1) × 2 = 2 × 2 = 4 bytes

**Data communication using ASCII code**
Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.
Use capitalized code for alphabetical letter.

**Data communication in binary code**
Send 2-byte numerical values from lower byte (L: bits 0 to 7).

**Ex.**
For 20 bytes

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>20 words</td>
<td>0 0 1 4</td>
<td>14 00</td>
</tr>
</tbody>
</table>

**Module number**
Specify the start input/output number of an intelligent function module to be accessed.
For the module number, specify the value obtained by dividing the start input/output number by 16 in 4 digits (hexadecimal).

**When the number of occupied slots are 2**
Specify the value obtained by adding 1 to the module number for the following modules.

<table>
<thead>
<tr>
<th>Module type</th>
<th>Model</th>
</tr>
</thead>
<tbody>
<tr>
<td>Temperature control</td>
<td>Q64TCTTBW, Q64TCRTBW</td>
</tr>
<tr>
<td>module</td>
<td></td>
</tr>
<tr>
<td>Positioning module</td>
<td>QD70D4, QD70D8</td>
</tr>
</tbody>
</table>

**Data communication using ASCII code**
Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.
Use capitalized code for alphabetical letter.

**Data communication in binary code**
Send 2-byte numerical values from lower byte (L: bits 0 to 7).

**Ex.**
When accessing the positioning module whose start input/output number is 0080H

<table>
<thead>
<tr>
<th>Module number</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For QD70P4: 0008H</td>
<td>0 0 0 8</td>
<td>08 00</td>
</tr>
<tr>
<td>For QD70D4 (occupied slots are 2): 0009H + 1 = 0009H</td>
<td>0 0 0 9</td>
<td>09 00</td>
</tr>
</tbody>
</table>
Intelligent function module number of MELSECNET/H remote I/O station

Intelligent function module number of MELSECNET/H remote I/O station is the upper 2 digits of the last number represented with 3-digit number of the following "Input/output signal based on the remote I/O station". Specify this with "Input/output signal based on the remote I/O station" regardless of the contents of common parameters set in the master station of MELSECNET/H remote I/O network.

Read data, write data

The read buffer memory value is stored for reading, and the data to be written is stored for writing. This function reads/writes data in byte unit.

Data communication using ASCII code

Handle a word data for one buffer memory address as 2-byte data. Convert the value to 2-digit (hexadecimal) ASCII code per one byte and send it from the upper digit.

Data communication in binary code

Handle a word data for one buffer memory address as 2-byte data. Send 2-byte numerical values from lower byte (L: bits 0 to 7).

Example

When the data for one buffer memory address is 09C1H

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>C 1 0 9</td>
<td>Cln 0H</td>
</tr>
</tbody>
</table>

When reading data from the following buffer memory addresses, 0H to 2H (additional value of the start address: 10000H)

<table>
<thead>
<tr>
<th>Address</th>
<th>Stored data</th>
<th>Start address</th>
<th>Read data (byte unit)</th>
<th>Read data (byte unit)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Word unit</td>
<td>Byte unit</td>
<td>ASCII code</td>
<td>Binary code</td>
</tr>
<tr>
<td>0H</td>
<td>0003H</td>
<td>03H</td>
<td>10000H</td>
<td>30H, 33H</td>
</tr>
<tr>
<td></td>
<td></td>
<td>00H</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1H</td>
<td>0001H</td>
<td>01H</td>
<td>30H, 31H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td></td>
<td>00H</td>
<td>30H, 30H</td>
<td>00H</td>
</tr>
<tr>
<td>2H</td>
<td>0012H</td>
<td>12H</td>
<td>31H, 32H</td>
<td>12H</td>
</tr>
<tr>
<td></td>
<td></td>
<td>00H</td>
<td>30H, 30H</td>
<td>00H</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Start address</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>10002H</td>
<td>30H, 31H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>30H, 30H</td>
<td>00H</td>
</tr>
<tr>
<td></td>
<td>31H, 32H</td>
<td>12H</td>
</tr>
<tr>
<td></td>
<td>30H, 30H</td>
<td>00H</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Start address</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>30H, 30H</td>
<td>00H</td>
</tr>
<tr>
<td></td>
<td>31H, 32H</td>
<td>12H</td>
</tr>
<tr>
<td></td>
<td>30H, 30H</td>
<td>00H</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Start address</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>30H, 30H</td>
<td>00H</td>
</tr>
<tr>
<td></td>
<td>31H, 32H</td>
<td>12H</td>
</tr>
<tr>
<td></td>
<td>30H, 30H</td>
<td>00H</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Start address</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>30H, 30H</td>
<td>00H</td>
</tr>
<tr>
<td></td>
<td>31H, 32H</td>
<td>12H</td>
</tr>
<tr>
<td></td>
<td>30H, 30H</td>
<td>00H</td>
</tr>
</tbody>
</table>
Batch read (command: 0601)

Read the data from the buffer memory of an intelligent function module.

**Message format**

The following shows the message format of the request data and response data of the command.

- **Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Start address</th>
<th>Number of bytes</th>
<th>Module No.</th>
</tr>
</thead>
</table>

- **Response data**

  The value read from the buffer memory is stored.

  Page 156 Read data, write data

**Data specified by request data**

- **Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0601</td>
<td>01</td>
</tr>
</tbody>
</table>

- **Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000</td>
<td>00</td>
</tr>
</tbody>
</table>

- **Start address**

  Specify the buffer memory start address to be read. (Page 154 Start address)

- **Number of bytes**

  Specify the number of bytes of the buffer memory to be read. (Page 155 Number of bytes)

  Specification range: 2H to 780H (1920)

- **Module number**

  Specify the intelligent function module to be read. (Page 155 Module number)

  Specify the access range within the range of buffer memory.
Communication example

Read the data of the buffer memory addresses 1H to 2H of Q62DA whose input/output signal is from 30H to 4FH (module No.: 03H).

<table>
<thead>
<tr>
<th>Buffer memory of Q62DA</th>
<th>Data for command</th>
</tr>
</thead>
<tbody>
<tr>
<td>Address</td>
<td>Name</td>
</tr>
<tr>
<td>1H</td>
<td>CH1 digital value</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>2H</td>
<td>CH2 digital value</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Start address</th>
<th>Number of bytes</th>
<th>Module No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 6 0 1 0 0 0 1</td>
<td>0 0 0 0 1 0</td>
<td>0 A</td>
</tr>
<tr>
<td>0 0 0 4</td>
<td>0 0 0 3</td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

Values of address 1H =0001H
Values of address 2H =0012H

Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Start address</th>
<th>Number of bytes</th>
<th>Module No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>01H, 06H, 00H, 00H, 0AH, 10H, 00H, 04H, 00H, 03H, 00H</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

Values of address 1H =0001H
Values of address 2H =0012H
Batch write (command: 1601)
Write data to the buffer memory of an intelligent function module.

Restriction
Do not write any data in "System area" or "Write-protect area" in the buffer memory.
Writing data to the "System area" or "Write-protect area" may cause malfunction of the programmable controller system.

Message format
The following shows the message format of the request data and response data of the command.

Request data

Response data
There is no response data for this command.

Data specified by request data

Command

Subcommand

Start address

Number of bytes

Module No.

Write data

ASCII code | Binary code
---|---
1 6 0 1 | 01H, 16H

Subcommand

ASCII code | Binary code
---|---
0 0 0 0 | 00H, 00H

Start address
Specify the buffer memory start address to be written. (Page 154 Start address)

Number of bytes
Specify the number of bytes of the buffer memory to be written. (Page 155 Number of bytes)
Specification range: 2H to 780H (1920)

Module number
Specify the intelligent function module to be written. (Page 155 Module number)

Write data
Specify the data to be written in the buffer memory. (Page 156 Read data, write data)

Specify the access range within the range of buffer memory.
Communication example

Write data to the buffer memory addresses from 1H to 2H of Q62DA whose input/output signals are from 30H to 4FH (module No.: 03H).

<table>
<thead>
<tr>
<th>Address</th>
<th>Name</th>
<th>Stored data (word unit)</th>
<th>Write data (byte unit)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1H</td>
<td>CH1 digital value</td>
<td>01F4H</td>
<td>F4H</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>01H</td>
</tr>
<tr>
<td>2H</td>
<td>CH2 digital value</td>
<td>03E8H</td>
<td>E8H</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>03H</td>
</tr>
</tbody>
</table>

■ Data communication using ASCII code

(Request data)

Start address | Number of bytes | Module No. |
-------------|----------------|------------|
\[16010000100A040030\] Write data |
\[4604010803\]

\(\text{Values of address 1H} = \text{01F4H} \)
\(\text{Values of address 2H} = \text{03E8H} \)

■ Data communication in binary code

(Request data)

Start address | Number of bytes | Module No. | Write data |
-------------|----------------|------------|------------|
\[01000000040503\] Write data |
\[010803\]

\(\text{Values of address 1H} = \text{01F4H} \)
\(\text{Values of address 2H} = \text{03E8H} \)
11 CONTROL MODULE OPERATION

This chapter explains the commands for changing operation status and performing test using the functions of the module.

11.1 Data to be specified in commands

This section explains the contents and specification methods for data items which are set in each command related to module control.

**Mode**

Select the operation when the request target module is already in remote operation by other device.

**Setting method**

- **Data communication using ASCII code**
  Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

- **Data communication using binary code**
  Send 2-byte numerical values from lower byte (L: bits 0 to 7).

<table>
<thead>
<tr>
<th>Process</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Do not execute forcibly</td>
<td>0 0 0 1</td>
<td>01h 00h</td>
</tr>
<tr>
<td>Execute forcibly</td>
<td>0 0 0 3</td>
<td>03h 00h</td>
</tr>
</tbody>
</table>

**Clear mode**

Select the range of the device memory to be cleared by the initialization processing at remote RUN.

When the device initial values are set, they will be reflected after the process with the selected clear mode.

**Setting method**

- **Data communication using ASCII code**
  Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

- **Data communication using binary code**
  Send a 1-byte numerical value.

<table>
<thead>
<tr>
<th>Process</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Do not clear</td>
<td>0 0</td>
<td>00h</td>
</tr>
<tr>
<td>Clear outside the range of latch</td>
<td>0 1</td>
<td>01h</td>
</tr>
<tr>
<td>All clear</td>
<td>0 2</td>
<td>02h</td>
</tr>
</tbody>
</table>
Model name and model code

The model name and model code of the access target module.

Model name

The character string of a model name is stored in 16-digit ASCII code.
If the read model name is less than 16 characters, a space (20H) is stored for the shortage of the characters.
The model name is stored in ASCII code while communicating in binary code.

Ex.
For Q02HCPU

<table>
<thead>
<tr>
<th>ASCII code, binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2 H C P U</td>
</tr>
</tbody>
</table>

Model code

The model code of the module is stored.

■ Data communication using ASCII code

Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

■ Data communication using binary code

Send 2-byte numerical values from lower byte (L: bits 0 to 7).

Ex.
For Q02HCPU (41H)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 4 1</td>
<td>41 00</td>
</tr>
</tbody>
</table>

Model name and model code list

The following shows the list of model names and model codes.

■ MELSEC iQ-R series

<table>
<thead>
<tr>
<th>Model name</th>
<th>Model code</th>
</tr>
</thead>
<tbody>
<tr>
<td>RCPU (^1)</td>
<td>0360H (^1)</td>
</tr>
<tr>
<td>R04CPU</td>
<td>4800H</td>
</tr>
<tr>
<td>R08CPU</td>
<td>4801H</td>
</tr>
<tr>
<td>R16CPU</td>
<td>4802H</td>
</tr>
<tr>
<td>R32CPU</td>
<td>4803H</td>
</tr>
<tr>
<td>R120CPU</td>
<td>4804H</td>
</tr>
</tbody>
</table>

\(^1\) When accessing RCPU from the connected station other than MELSEC iQ-R series, the common model name 'RCPU' and model code '0360H' is stored.

■ MELSEC-L series

<table>
<thead>
<tr>
<th>Model name</th>
<th>Model code</th>
</tr>
</thead>
<tbody>
<tr>
<td>L02SCPU, L02SCPU-P</td>
<td>0543H</td>
</tr>
<tr>
<td>L02CPU, L02CPU-P</td>
<td>0541H</td>
</tr>
<tr>
<td>L06CPU, L06CPU-P</td>
<td>0544H</td>
</tr>
<tr>
<td>L26CPU, L26CPU-P</td>
<td>0545H</td>
</tr>
<tr>
<td>L26CPU-BT, L26CPU-PBT</td>
<td>0542H</td>
</tr>
<tr>
<td>LJ72GF15-T2</td>
<td>0641H</td>
</tr>
</tbody>
</table>
### MELSEC-Q series

<table>
<thead>
<tr>
<th>Model name</th>
<th>Model code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Q00JCPU</td>
<td>0250H</td>
</tr>
<tr>
<td>Q00CPU</td>
<td>0251H</td>
</tr>
<tr>
<td>Q01CPU</td>
<td>0252H</td>
</tr>
<tr>
<td>Q02CPU, Q02HCPU, Q02PHCPU</td>
<td>0041H</td>
</tr>
<tr>
<td>Q06HCPU, Q06PHCPU</td>
<td>0042H</td>
</tr>
<tr>
<td>Q12HCPU, Q12PHCPU</td>
<td>0043H</td>
</tr>
<tr>
<td>Q25HCPU, Q25PHCPU</td>
<td>0044H</td>
</tr>
<tr>
<td>Q12PRHCPU</td>
<td>004BH</td>
</tr>
<tr>
<td>Q25PRHCPU</td>
<td>004CH</td>
</tr>
<tr>
<td>Q00UJCPU</td>
<td>0260H</td>
</tr>
<tr>
<td>Q00UCPU</td>
<td>0261H</td>
</tr>
<tr>
<td>Q01UCPU</td>
<td>0262H</td>
</tr>
<tr>
<td>Q02UCPU</td>
<td>0263H</td>
</tr>
<tr>
<td>Q03UDCPU, Q03UDECPU</td>
<td>0268H</td>
</tr>
<tr>
<td>Q03UDVCPU</td>
<td>0366H</td>
</tr>
<tr>
<td>Q04UDHCPU, Q04UDEHCPU</td>
<td>0269H</td>
</tr>
<tr>
<td>Q04UDVCPU</td>
<td>0367H</td>
</tr>
<tr>
<td>Q06UDHCPU, Q06UDEHCPU</td>
<td>026AH</td>
</tr>
<tr>
<td>Q06UDVCPU</td>
<td>0368H</td>
</tr>
<tr>
<td>Q10UDHCPU, Q10UDEHCPU</td>
<td>0268H</td>
</tr>
<tr>
<td>Q13UDHCPU, Q13UDEHCPU</td>
<td>026BH</td>
</tr>
<tr>
<td>Q13UDVCPU</td>
<td>036AH</td>
</tr>
<tr>
<td>Q20UDHCPU, Q20UDEHCPU</td>
<td>0267H</td>
</tr>
<tr>
<td>Q26UDHCPU, Q26UDEHCPU</td>
<td>026CH</td>
</tr>
<tr>
<td>Q26UDVCPU</td>
<td>036CH</td>
</tr>
<tr>
<td>Q50UDEHCPU</td>
<td>026DH</td>
</tr>
<tr>
<td>Q100UDEHCPU</td>
<td>026EH</td>
</tr>
<tr>
<td>QS001CPU</td>
<td>0230H</td>
</tr>
</tbody>
</table>
Remote password

Remote password length
Specify the number of characters of remote password.
• For MELSEC-Q/L series modules, the character string is fixed to 4 characters.
• For MELSEC iQ-R series modules, specify the number of character string of the remote password (6 to 32 characters).

Data communication using ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

Data communication using binary code
Send 2-byte \*1 numerical values from lower byte (L: bits 0 to 7).
*1 For C24, the additional code may be added. (*“ Page 33 Additional code (10H))

Ex.
For 4 characters, 32 characters

<table>
<thead>
<tr>
<th>Access target</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC-Q/L series module</td>
<td>0 0 0 4</td>
<td>04 00</td>
</tr>
<tr>
<td>(4 characters fixed)</td>
<td>30h 30h 30h 34h</td>
<td></td>
</tr>
<tr>
<td>MELSEC iQ-R series module</td>
<td>0 0 2 0</td>
<td>20 00</td>
</tr>
<tr>
<td>(32 characters)</td>
<td>30h 30h 32h 30h</td>
<td></td>
</tr>
</tbody>
</table>

Remote password
The remote password is set by Engineering tool.
Specify the remote password in ASCII code while communicating in binary code.

Ex.
When password is 'ABCDEF'

<table>
<thead>
<tr>
<th>ASCII code, binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>A B C D E F</td>
</tr>
<tr>
<td>41h 42h 43h 44h 45h 46h</td>
</tr>
</tbody>
</table>
Loopback data

Loopback data length
Number of bytes of loopback data.

Data communication using ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

Data communication using binary code
Send 2-byte *1 numerical values from lower byte (L: bits 0 to 7).
*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Ex.
For 5 bytes

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 5</td>
<td>05 000</td>
</tr>
</tbody>
</table>

Loopback data
The following characters can be used.
• 0 to 9 (30H to 39H)
• A to F (41H to 46H)
Specify the loopback data in ASCII code while communicating in binary code.

Ex.
For 'ABCDEF'

<table>
<thead>
<tr>
<th>ASCII code, binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>41 42 43 44 45 46</td>
</tr>
</tbody>
</table>
Communication error information

A data to specify the communication error information to be initialized.
The data is equivalent to the buffer memory '0H', '1H' of MELSEC-Q/L series C24.
Specify the value (16-bit integer) in bit unit. The communication error information and its corresponding bit are as follows.

<table>
<thead>
<tr>
<th>Item</th>
<th>b15</th>
<th>b14</th>
<th>b13 to b8</th>
<th>b7</th>
<th>b6</th>
<th>b5</th>
<th>b4</th>
<th>b3</th>
<th>b2</th>
<th>b1</th>
<th>b0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Communication error information (CH1)</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>NEU</td>
<td>ACK</td>
<td></td>
<td></td>
<td>NAK</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Communication error information (CH2)</td>
<td>CH1.ERR</td>
<td>CH2.ERR</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The communication error information to be initialized can be specified by turning the corresponding bit ON (1).
When the command is executed, the following corresponding bit of the buffer memory turns OFF (0).
"LED lighting status, communication error status" (Buffer memory 513 (201H), 514 (202H))
For MELSEC iQ-R series C24, specify '0'.

Setting method

Data communication using ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

Data communication using binary code
Send 2-byte *1 numerical values from lower byte (L: bits 0 to 7).
*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Ex
When initializing C/N, P/S, PRO, and SIO (bit 1 to 4) with MELSEC-Q/L series C24.

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Communication error information (CH1)</td>
<td>0 0 1 E</td>
<td></td>
</tr>
<tr>
<td>Communication error information (CH2)</td>
<td>0 0 0 0</td>
<td></td>
</tr>
</tbody>
</table>

Ex
For MELSEC iQ-R series

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Communication error information (CH1)</td>
<td>0 0 0 0</td>
<td></td>
</tr>
<tr>
<td>Communication error information (CH2)</td>
<td>0 0 0 0</td>
<td></td>
</tr>
</tbody>
</table>
11.2 Remote Operation

Change the operation status of CPU module.

For the remote operation function, refer to the manual of each CPU module.

- When powering OFF to ON or resetting the access target CPU after applying remote RUN/STOP/PAUSE, the information of the remote operation will be cancelled. After powering OFF to ON or resetting CPU, the CPU operates with the status of the switch on the CPU module.
- When the system protection of the access target module is enabled, the remote operation cannot be performed and an error response will be returned. Disable the system protection of the CPU module.
- For E71, the communication using UDP/IP is recommended. For the communication using TCP/IP, re-establishment of the connection is required because the connection is disconnected at resetting CPU module.
- One communication of command provides remote operation for 1 station.

Remote RUN (command: 1001)

Perform remote RUN for the access target module.

The command can be executed when the switch of the access target module is RUN. In the STOP status, the command is completed normally, however, the access target CPU will not be in RUN status.

Message format

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Mode</th>
<th>Clear mode</th>
<th>Fixed values</th>
</tr>
</thead>
</table>

**Response data**

There is no response data for this command.
11 CONTROL MODULE OPERATION
11.2 Remote Operation

Data specified by request data

■ Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code (for C24)*1</th>
<th>Binary code (for E71)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 0 0 1</td>
<td>01 10</td>
<td>01 10</td>
</tr>
<tr>
<td>31H 30H 30H 31H</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

*1 For C24, the additional code is added. (Page 33 Additional code (10H))

■ Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
<tr>
<td>30H 30H 30H 30H</td>
<td></td>
</tr>
</tbody>
</table>

■ Mode

Select the operation when the request target module is already in remote operation by other device. (Page 161 Mode)
• 0001H: Do not execute forcibly
• 0003H: Execute forcibly

■ Clear mode

Select the range of the device memory to be cleared by the initialization processing at remote RUN. (Page 161 Clear mode)
• 00H: Do not clear
• 01H: Clear only outside the latch range
• 02H: All clear

■ Fixed value

Fixed to '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>00</td>
</tr>
<tr>
<td>30H 30H</td>
<td></td>
</tr>
</tbody>
</table>

Communication example

Remote RUN is performed when the mode is set to "Do not execute forcibly", and the clear mode is set to "All clear".

■ Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Mode</th>
<th>Clear mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 0 0 1</td>
<td>0 0 0 0 0 0 0 0</td>
</tr>
<tr>
<td>31H 30H 30H 31H</td>
<td>30H 30H 30H 30H</td>
</tr>
<tr>
<td>0 0 0 1</td>
<td>0 2 0 0 0</td>
</tr>
<tr>
<td>31H 30H 30H 31H</td>
<td>30H 32H 30H 30H</td>
</tr>
</tbody>
</table>

■ Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>Mode</th>
<th>Clear mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>01 10</td>
<td>00 00 01 02 00 00</td>
</tr>
</tbody>
</table>
Remote STOP (command: 1002)

Perform remote STOP for the access target module.

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Fixed values</th>
</tr>
</thead>
</table>

**Response data**

There is no response data for this command.

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code (for C24)*1</th>
<th>Binary code (for E71)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 0 0 2</td>
<td>DLE 02H 10H</td>
<td>02H 10H</td>
</tr>
</tbody>
</table>

*1 For C24, the additional code is added. ([Page 33 Additional code (10H)])

**Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00H 00H</td>
</tr>
</tbody>
</table>

**Fixed value**

The value is '0001H'.

**Communication example**

Perform remote STOP.

**Data communication using ASCII code**

(Request data)

<table>
<thead>
<tr>
<th>1 0 0 2</th>
<th>0 0 0 0</th>
<th>0 0 0 1</th>
</tr>
</thead>
<tbody>
<tr>
<td>31H 30H 32H</td>
<td>30H 30H 30H</td>
<td>30H 30H 30H</td>
</tr>
</tbody>
</table>

**Data communication using binary code**

(Request data)

<table>
<thead>
<tr>
<th>02H 10H</th>
<th>00H 00H</th>
<th>01H 00H</th>
</tr>
</thead>
<tbody>
<tr>
<td>02H 10H</td>
<td>00H 00H</td>
<td>01H 00H</td>
</tr>
</tbody>
</table>
Remote PAUSE (command: 1003)

Perform remote PAUSE for the access target module.

The command can be executed when the switch of the access target module is RUN. In the STOP status, the command is completed normally, however, the access target CPU will not be in PAUSE status.

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Mode</th>
</tr>
</thead>
</table>

**Response data**

There is no response data for this command.

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code (for C24)</th>
<th>Binary code (for E71)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 0 0 3</td>
<td>03h DLE 10h 10h</td>
<td>03h 10h</td>
</tr>
</tbody>
</table>

*1 For C24, the additional code is added. (Page 33 Additional code (10H))

**Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00h 00h</td>
</tr>
</tbody>
</table>

**Mode**

Select the operation when the request target module is already in remote operation by other device. (Page 161 Mode)

- 0001H: Do not execute forcibly
- 0003H: Execute forcibly

**Communication example**

Remote PAUSE is performed when the mode is set to "Do not execute forcibly".

**Data communication using ASCII code**

(Request data)

<table>
<thead>
<tr>
<th>1 0 0 3</th>
<th>0 0 0 0</th>
<th>0 0 0 1</th>
</tr>
</thead>
<tbody>
<tr>
<td>31h 30h 30h 33h</td>
<td>30h 30h 30h 30h</td>
<td>30h 30h 30h 31h</td>
</tr>
</tbody>
</table>

**Data communication using binary code**

(Request data)

<table>
<thead>
<tr>
<th>03h</th>
<th>10h</th>
<th>00h</th>
<th>00h</th>
<th>01h</th>
<th>00h</th>
</tr>
</thead>
</table>
Remote latch clear (command: 1005)

Perform remote latch clear for the access target module.

Restriction
- Execute the command after changing the status of the access target module to STOP.
- The remote latch clear cannot be performed when the access target CPU is in remote STOP or remote PAUSE by other devices. The command will be terminated abnormally. Clear the remote STOP or remote PAUSE before executing the command.

Message format
The following shows the message format of the request data and response data of the command.

- **Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Fixed values</th>
</tr>
</thead>
</table>

- **Response data**

  There is no response data for this command.

Data specified by request data

- **Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code (for C24)*1</th>
<th>Binary code (for E71)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 0 0 5</td>
<td>05</td>
<td>05</td>
</tr>
</tbody>
</table>

  *1 For C24, the additional code is added. (Page 33 Additional code (10H))

- **Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00</td>
</tr>
</tbody>
</table>

- **Fixed value**

  The value is '0001H'.

Communication example

Perform remote latch clear.

- **Data communication using ASCII code**

  (Request data)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 0 0 5</td>
<td>05</td>
</tr>
<tr>
<td>0 0 0 0</td>
<td>00</td>
</tr>
<tr>
<td>0 0 0 1</td>
<td>0f</td>
</tr>
</tbody>
</table>

- **Data communication using binary code**

  (Request data)

<table>
<thead>
<tr>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>05 0f 00 01</td>
</tr>
<tr>
<td>00 01 00</td>
</tr>
</tbody>
</table>
Remote RESET (command: 1006)

Perform remote RESET for the access target module.

Restriction

- Execute the command after changing the status of the access target module to STOP. If the CPU module is stopped due to the error, the command can be executed even when the switch of the CPU module is in the position of RUN.
- If a remote RESET operation enable/disable setting exists in the access target parameter, set it to enable.
- Remote RESET may not be performed due to the hardware error of the access target device.
- When performing remote RESET, the response message may not be returned because the access target CPU is reset.

Message format

The following shows the message format of the request data and response data of the command.

■Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Fixed values</th>
</tr>
</thead>
</table>

■Response data

There is no response data for this command.

Data specified by request data

■Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code (for C24)*1</th>
<th>Binary code (for E71)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 0 0 6</td>
<td>DLE 06</td>
<td>10</td>
</tr>
</tbody>
</table>

*1 For C24, the additional code is added. ([Page 33 Additional code (10H)]

■Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00</td>
</tr>
</tbody>
</table>

■Fixed value

The value is ‘0001H’.

Communication example

Perform remote RESET.

■Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>1 0 0 6</th>
<th>0 0 0 0</th>
<th>0 0 0 1</th>
</tr>
</thead>
</table>

■Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>06 10 00 00 01</th>
</tr>
</thead>
</table>
Read CPU model name (command: 0101)

Read model name and model code from the access target module.

Message format

The following shows the message format of the request data and response data of the command.

■ Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
</tr>
</thead>
</table>

■ Response data

Model name and model code are stored. (Page 162 Model name and model code)

• Discriminate the model name of the CPU with the model code.

Data specified by request data

■ Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0101</td>
<td>01</td>
</tr>
</tbody>
</table>

■ Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000</td>
<td>00</td>
</tr>
</tbody>
</table>

Communication example

Execute the command for Q02UCPU to read the model name and model code.

■ Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>0101</th>
</tr>
</thead>
<tbody>
<tr>
<td>30h, 31h, 31h</td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>Q 02 UCPU</th>
</tr>
</thead>
<tbody>
<tr>
<td>55h, 63h, 55h, 63h</td>
</tr>
</tbody>
</table>

■ Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>01 01</th>
</tr>
</thead>
<tbody>
<tr>
<td>01h, 10h</td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>Q 02 UCPU</th>
</tr>
</thead>
<tbody>
<tr>
<td>63h, 02h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>02 63</th>
</tr>
</thead>
<tbody>
<tr>
<td>00h, 00h</td>
</tr>
</tbody>
</table>
11.3 Remote Password

This section explains the commands that unlock or lock the remote password. For details on the remote password, refer to the manuals of access target CPU or CPU module.

**Restriction**

The command can only be used for C24 (including multidrop connection station) and E71 connected to the external device. It cannot be used via network.

For the modem connection, access route must be set as the same route as that of the connected station (host station).

(" Page 43 ACCESS ROUTE SETTINGS")

**Execution procedure**

The communication with the module in which the remote password is set, follow the procedure shown below.

1. **Line connection by modem (C24)/open processing for connection (E71)**

2. **Access permission (unlock processing) (" Page 175 Unlock (command: 1630))**

3. **Access processing**

   Perform data communication by various commands of MC protocol.

4. **Access prohibition (lock processing) (" Page 177 Lock (command: 1631))**

   For C24 or TCP/IP communication of E71, the lock processing is performed automatically at modem disconnection/close processing.

5. **Line disconnection/close processing of connection**

**Point**

All the commands received when the remote password is locked will be an error response. Perform data communication after the unlock processing.
Unlock (command: 1630)

Specify the remote password to unlock the module. (The module can communicate.)

**Restriction**

If the incorrect password is entered several times, the password is locked out and cannot be cleared for a while.

**Point**

When the command is sent to the unlocked module, the unlock status is not changed. (The password verification is not performed.)

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Remote password length</th>
<th>Remote password</th>
</tr>
</thead>
</table>

**Response data**

There is no response data for this command.

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 3 0</td>
<td>30h</td>
</tr>
</tbody>
</table>

**Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00h</td>
</tr>
</tbody>
</table>

**Remote password length**

Specify the number of characters of remote password. (Page 164 Remote password length)

**Remote password**

Specify the set remote password. (Page 164 Remote password)
Communication example (for MELSEC-Q series)

Unlock the MELSEC-Q/L series module in which the following remote password has been set.
- Remote password: ‘1234’ (4 characters)

**Data communication using ASCII code**
(Request data)

```
<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Remote password length</th>
<th>Remote password</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 3 0</td>
<td>31h, 36h, 33h, 30h</td>
<td>1 2 3 4</td>
</tr>
</tbody>
</table>
```

**Data communication using binary code**
(Request data)

```
<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Remote password length</th>
<th>Remote password</th>
</tr>
</thead>
<tbody>
<tr>
<td>30h, 15h</td>
<td>30h, 00h, 05h</td>
<td>1 2 3 4</td>
</tr>
</tbody>
</table>
```

Communication example (for the files of MELSEC iQ-R series)

Unlock the MELSEC iQ-R series module in which the following remote password has been set.
- Remote password: ‘abcdefghijklmnopqrstuvwxyz’ (26 characters)

**Data communication using ASCII code**
(Request data)

```
<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Remote password length</th>
<th>Remote password</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 3 0</td>
<td>31h, 36h, 33h, 30h</td>
<td>a b c d e f g h i j k l m n o p q r s t u v w x y z</td>
</tr>
</tbody>
</table>
```

**Data communication using binary code**
(Request data)

```
<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Remote password length</th>
<th>Remote password</th>
</tr>
</thead>
<tbody>
<tr>
<td>30h, 15h</td>
<td>30h, 00h, 1Ah</td>
<td>a b c d e f g h i j k l m n o p q r s t u v w x y z</td>
</tr>
</tbody>
</table>
```
**Lock (command: 1631)**

Specify the remote password to lock the module. (The module cannot communicate.)

*Point*

When the command is sent to the locked module, the lock status is not changed. (The password verification is not performed.)

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Remote password length</th>
<th>Remote password</th>
</tr>
</thead>
</table>

**Response data**

There is no response data for this command.

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 3 1</td>
<td>31h, 36h, 33h, 31h</td>
</tr>
</tbody>
</table>

**Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>30h, 30h, 30h, 30h</td>
</tr>
</tbody>
</table>

**Remote password length**

Specify the number of characters of remote password. (Page 164 Remote password length)

**Remote password**

Specify the set remote password. (Page 164 Remote password)
Lock the MELSEC-Q/L series module in which the following remote password has been set.

- Remote password: '1234' (4 characters)

**Data communication using ASCII code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Remote password length</th>
<th>Remote password</th>
</tr>
</thead>
<tbody>
<tr>
<td>31h, 36h, 33h, 31h</td>
<td>00h, 00h</td>
<td>1234</td>
</tr>
</tbody>
</table>

**Data communication using binary code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Remote password length</th>
<th>Remote password</th>
</tr>
</thead>
<tbody>
<tr>
<td>31h, 16h</td>
<td>00h, 00h</td>
<td>1234</td>
</tr>
</tbody>
</table>

Lock the MELSEC iQ-R series module in which the following password has been set.

- Remote password: 'abcdefghijklmnopqrstuvwxyz' (26 characters)

**Data communication using ASCII code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Remote password length</th>
<th>Remote password</th>
</tr>
</thead>
<tbody>
<tr>
<td>31h, 36h, 33h, 31h</td>
<td>00h, 00h</td>
<td>01A</td>
</tr>
</tbody>
</table>

**Data communication using binary code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Remote password length</th>
<th>Remote password</th>
</tr>
</thead>
<tbody>
<tr>
<td>31h, 16h</td>
<td>00h, 00h</td>
<td>01A</td>
</tr>
</tbody>
</table>
11.4 Loopback Test

This chapter explains the commands for testing the connection and data communication between an external device and connected station.

Restriction

The command can only be used for C24 (including multidrop connection station) and E71 connected to the external device. It cannot be used via network.

Loopback test (command: 0619)

Perform the test to check whether the communication between the external device and connected station is normal. By performing the loopback test, the connection with external devices and operation of data communication can be checked.

Message format

The following shows the message format of the request data and response data of the command.

■ Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Number of loopback data</th>
<th>Loopback data</th>
</tr>
</thead>
</table>

■ Response data

The same data as "Number of loopback data" and "Loopback data" specified for request message is stored. (Page 165 Loopback data)

<table>
<thead>
<tr>
<th>Number of loopback data</th>
<th>Loopback data</th>
</tr>
</thead>
</table>

Data specified by request data

■ Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 6 1 9</td>
<td>06 01 09</td>
</tr>
</tbody>
</table>

■ Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 00 00</td>
</tr>
</tbody>
</table>

■ Number of loopback data, loopback data

Specify the data to be transmitted by loopback test. (Page 165 Loopback data)

The data can be specified within the range (numerals 0 to 9 and characters A to F) of 1 to 960 bytes.
Communication example

Perform the loopback test with the following loopback data.

- Loopback data: 'ABCDE' (5 characters)

**Data communication using ASCII code**

(Open data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Number of loopback data</th>
<th>Loopback data</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>6 1 9</td>
<td>0 0 0 0 5</td>
</tr>
</tbody>
</table>

(Reply data)

<table>
<thead>
<tr>
<th>Number of loopback data</th>
<th>Loopback data</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 5</td>
<td>ABCDE</td>
</tr>
</tbody>
</table>

**Data communication using binary code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Number of loopback data</th>
<th>Loopback data</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 5</td>
<td>ABCDE</td>
<td>0 0 0 5</td>
</tr>
</tbody>
</table>

(Reply data)

<table>
<thead>
<tr>
<th>Number of loopback data</th>
<th>Loopback data</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 5</td>
<td>ABCDE</td>
</tr>
</tbody>
</table>
11.5 Clear Error Information

This section explains the command to initialize LED display and error information of buffer memory, and recover the supported device.

For details of the related LEDs, input/output signals, and buffer memory, refer to the manual of the access target module.

Turn indicator LED OFF, initialize error code (command: 1617)

Turn OFF the indicator LED of the serial communication module, and initialize the communication error information and error codes.

Restriction

The command can only be used for C24 (including multidrop connection station) connected to the external device. It cannot be used via network.

Message format

The following shows the message format of the request data and response data of the command.

- Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Communication error information (CH1)</th>
<th>Communication error information (CH2)</th>
</tr>
</thead>
</table>

- Response data

  There is no response data for this command.

Data specified by request data

- Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 1 7 31 35 31 37</td>
<td>17 16</td>
</tr>
</tbody>
</table>
### Subcommand

<table>
<thead>
<tr>
<th>Target</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC-Q/L series</td>
<td>CH1 side</td>
<td>0 0 0 5 30H, 30H, 30H, 35H</td>
</tr>
<tr>
<td></td>
<td>CH2 side</td>
<td>0 0 0 A 30H, 30H, 30H, 41H</td>
</tr>
<tr>
<td></td>
<td>CH1 side, CH2 side</td>
<td>0 0 0 F 30H, 30H, 30H, 46H</td>
</tr>
<tr>
<td>MELSEC iQ-R series</td>
<td>CH1 side, CH2 side</td>
<td>0 0 0 1 30H, 30H, 30H, 31H</td>
</tr>
</tbody>
</table>

For C24 of MELSEC-Q/L series, 0 to 3 bits of subcommands are equivalent to the following functions of C24.
The settings in the table above is recommended, even though the initialization can be performed with the values (0001H to 000FH) which combined ON/OFF arbitrarily.

- Bit 0: CH1 Error initialization request (YE) ON
- Bit 1: CH2 Error initialization request (YF) ON
- Bit 2: LED for CH1 OFF, communication error information initialization request (buffer memory address: 0H) ON
- Bit 3: LED for CH2 OFF, communication error information initialization request (buffer memory address: 1H) ON

### Communication error information

Specify the items in "LED lighting status, communication error status" to be initialized. (Page 166 Communication error information)

For MELSEC iQ-R series C24, specify '0'.

### Communication example

Perform the following operations for CH1 interface of QJ71C24N-R2.

- ERR LED: OFF
- Input signal XE "Error occurrence": OFF
- Buffer memory 513 (201H) "LED lighting status, communication error status": Initialized (all items are OFF)
- Error code of buffer memory: Initialized (clear)

### Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Communication error information (CH1)</th>
<th>Communication error information (CH2)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 1 7</td>
<td>0 0 0 5 30H, 30H, 30H, 35H</td>
<td>0 0 F F 30H, 30H, 30H, 46H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 20H</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Communication error information (CH1)</th>
<th>Communication error information (CH2)</th>
</tr>
</thead>
<tbody>
<tr>
<td>17H, 16H</td>
<td>05H, 00H</td>
<td>FFH, 00H</td>
</tr>
<tr>
<td>00H, 00H</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Turn COM.ERR. LED OFF (command: 1617)

Turn the COM.ERR.LED of Ethernet interface module OFF.

Restriction

The commands can be used for E71 connected to an external device and cannot be used via network.

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
</tr>
</thead>
</table>

Response data

There is no response data for this command.

Data specified by request data

Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1617</td>
<td>17n, 16n</td>
</tr>
</tbody>
</table>

Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000</td>
<td>00b, 00b</td>
</tr>
</tbody>
</table>

Communication example

Turn COM.ERR.LED OFF.

Data communication using ASCII code

(Request data)

Subcommand

1617 0000

Data communication using binary code

(Request data)

Subcommand

17n, 16n 00b, 00b
12 FILE CONTROL

This chapter explains the commands that operates files in the supported devices the CPU module. Use this function in the following situations:

- To check the parameters and programs stored in the CPU module
- To change the parameters and programs in the CPU module according to the control content

For file name, extension, and storage location of files that can be handled by MC protocol, refer to the manual of the module to be accessed.

12.1 Execution Procedure

The following shows the file control procedures.

Procedure to read information from all files in directory (folder)

1. Read the file information from the head of the file.
Specify '1' for "Head file No." and '36' (upper limit) for "Number of requested file", and execute the 'read directory/file information' command. The file information of "Number of file information" is stored in the response data.

2. Check if there is a file from which the file information is not read.
When "Number of file information" of the response data is in the status as shown below, it indicates that file information of all the files have been read. Complete the processing.
   - MELSEC-Q/L series (when using subcommand '0000'): "Number of file information" < "Number of requested file"
   - MELSEC iQ-R series (when using subcommand '0040'): "Number of file information" = -1 (FFFH)

3. Read the file information from a file from which the file information is not read.
Specify "Number of requested file" = 36 (upper limit) to the request data, and execute the command.
For "Head file No.", specify one of the following value.
   - MELSEC-Q/L series (when using subcommand '0000'): "Head file No." = previous "Head file No." + "Number of file information"
   - MELSEC iQ-R series (when using subcommand '0040'): "Head file No." = previous "Last file No." + 1

4. Repeat the procedure of Step 2 and later.

Points

The correct information cannot be obtained if the file operation is performed from other devices while reading information of all the files in the directory. Do not perform file operation from other devices while reading file information.
Procedure to read files

1. Check for file existence.
   Any of the following commands can be used.
   • Page 205 Read directory/file information (command: 1810)
   • Page 211 Search directory/file information (command: 1811)

2. Read the files.
   For read command, use open and close command to prohibit access from other devices.
   Execute the commands in the following order.
   • Page 230 Open file (command: 1827)
   • Page 234 Read file (command: 1828)
   • Page 238 Close file (command: 182A)

Procedure to overwrite files

1. Check for file existence.
   Any of the following commands can be used.
   • Page 205 Read directory/file information (command: 1810)
   • Page 211 Search directory/file information (command: 1811)

2. Write data to the file.
   For writing data, use open and close command to prohibit access from other devices.
   Execute the commands in the following order.
   • Page 230 Open file (command: 1827)
   • Page 236 Write to file (command: 1829)
   • Page 238 Close file (command: 182A)

In the following cases, create a new file and write data to it after deleting the target file.
   • When the target file is sequence program file (*.PRG) or FB file (*.PFB) of MELSEC iQ-R series.
   • When changing the file size of MELSEC-Q/L series is required.
   • Page 187 Procedure to delete files
   • Page 186 Procedure to create new file and write data
Procedure to create new file and write data

The procedure varies depending on types of file. Refer to procedure according to file types.

<table>
<thead>
<tr>
<th>File type</th>
<th>File extension</th>
<th>MELSEC-Q/L series</th>
<th>MELSEC iQ-R series</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Header statement file</td>
<td>DAT</td>
<td>—</td>
<td>—</td>
<td>Page 186 When creation of temporary file is required</td>
</tr>
<tr>
<td>Sequence program file</td>
<td>QPG</td>
<td>PRG</td>
<td>—</td>
<td></td>
</tr>
<tr>
<td>Device comment file</td>
<td>QCD</td>
<td>DCM</td>
<td>—</td>
<td></td>
</tr>
<tr>
<td>Device initial value file</td>
<td>QDI</td>
<td>DID</td>
<td>—</td>
<td></td>
</tr>
<tr>
<td>FB file</td>
<td>—</td>
<td>PFB</td>
<td>—</td>
<td>Page 186 When creation of temporary file is required</td>
</tr>
</tbody>
</table>

**Point**

Before creating a file, secure the free space of the target memory. It can be checked and secured by an Engineering tool.

**When creation of temporary file is required**

   Register the file name and reserve the required capacity for the file.
   The extension of the temporary file must be other than DAT, PRG, QPG, PFB, QCD, DCM, QDI, DID.
   - Page 214 Create new file (command: 1820)

2. Write data to the file.
   For writing data, use open and close command to prohibit access from other devices.
   Execute the commands in the following order.
   - Page 230 Open file (command: 1827)
   - Page 236 Write to file (command: 1829)
   - Page 238 Close file (command: 182A)

3. Create a file with the target file extension using the copy function.
   After copying a file, delete the temporary file of the copy source as necessary.
   - Page 220 Copy file (command: 1824)
   - Page 217 Delete file (command: 1822)

**When creation of temporary file is not required**

1. Check for file existence.
   Any of the following commands can be used.
   - Page 205 Read directory/file information (command: 1810)
   - Page 211 Search directory/file information (command: 1811)

2. Create a new file.
   Register the file name to reserve the required capacity for the file.
   - Page 214 Create new file (command: 1820)

3. Write data to the file.
   For writing data, use open and close command to prohibit access from other devices.
   Execute the commands in the following order.
   - Page 230 Open file (command: 1827)
   - Page 236 Write to file (command: 1829)
   - Page 238 Close file (command: 182A)
Procedure to delete files

1. Check for file existence.
   Any of the following commands can be used.
   • Page 205 Read directory/file information (command: 1810)
   • Page 211 Search directory/file information (command: 1811)

2. Delete the file.
   • Page 217 Delete file (command: 1822)

Procedure to copy files

Before copying file, secure the free area of the target memory. It can be checked and secured with Engineering tool.

1. Check for file existence.
   Any of the following commands can be used.
   • Page 205 Read directory/file information (command: 1810)
   • Page 211 Search directory/file information (command: 1811)

2. Copy the file.
   After copying a file, delete the file of the copy source as necessary.
   • Page 220 Copy file (command: 1824)
   • Page 217 Delete file (command: 1822)

Procedure to modify file creation date and time

Modify the date of file creation by the 'modify file creation date and time' (command: 1826).
Page 227 Modify file creation date and time (command: 1826)
12.2 Considerations

The following shows the considerations for file control.

**Files such as read programs and parameters**

If the files such as program files and parameters which affect the system are read from the CPU module, keep the files for backup. Do not edit the data in the file on an external device. If the programs or parameters are required to be changed, use an Engineering tool.

**Access for '$MELPRJ$' folder of RCPU**

The $MELPRJ$ folder of RCPU is the folder that controls the data written from an Engineering. Do not access the $MELPRJ$ folder other than the purpose of data backup or restoration.

When performing data backup or restoration in the '$MELPRJ$' folder, read/write all the files in the '$MELPRJ$' folder. If only a part of '$MELPRJ$' folder is changed, it may not operate properly.

**If the file is protected**

When executing the following command, disable the protection (system protect of CPU module, the protection switch of SD memory card) of the access target CPU. If the command is executed with the access target protected, the command will be terminated abnormally.

<table>
<thead>
<tr>
<th>Function</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Create new file (Register file name)</td>
<td>Page 214 Create new file (command: 1820)</td>
</tr>
<tr>
<td>Delete file</td>
<td>Page 217 Delete file (command: 1822)</td>
</tr>
<tr>
<td>Copy file</td>
<td>Page 220 Copy file (command: 1824)</td>
</tr>
<tr>
<td>Modify file attribute</td>
<td>Page 224 Modify file attribute (command: 1825)</td>
</tr>
<tr>
<td>Modify file creation date and time</td>
<td>Page 227 Modify file creation date and time (command: 1826)</td>
</tr>
<tr>
<td>Write to file</td>
<td>Page 236 Write to file (command: 1829)</td>
</tr>
</tbody>
</table>

**Files that cannot be modified while CPU module is in RUN**

The executing file cannot be modified while the CPU module is in RUN.

When data write or delete command is executed to a file being executed, place CPU module in the STOP status. If the command is executed during RUN, the command completes abnormally.

Page 457 Applicable Commands for Online Program Change
12.3 Data to be specified in commands

This section explains the contents and specification methods for data items which are set in each command related to file control.

**Password**

Specify the password of the file to be accessed. The specification of a password differs depending on the module. Specify a password which corresponds to the module of access target.

For details on the password, refer to the manual of access target module.

<table>
<thead>
<tr>
<th>Access target</th>
<th>Password to be set</th>
<th>Sub command</th>
<th>Data specified by Message</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC-Q series module</td>
<td>Password (4 characters)</td>
<td>0000</td>
<td>Password character string (fixed to 4 characters)</td>
</tr>
<tr>
<td></td>
<td>File password 32 (4 characters)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>MELSEC-L series module</td>
<td>File password 32 (4 to 32 characters)</td>
<td>0004</td>
<td>Password character string (fixed to 32 characters)*1</td>
</tr>
<tr>
<td>MELSEC iQ-R series module</td>
<td>File password (6 to 32 characters)</td>
<td>0040</td>
<td>Number of password characters, password character string (variable length)</td>
</tr>
</tbody>
</table>

*1 If the password is less than 32 characters, append a space (code: 20H).

**Password for MELSEC-Q series module (4 characters)**

Use the subcommand '0000'.

- **When a password is set**
  Send password character string in 4-digit ASCII code.
  Specify the password in ASCII code during data communication in binary code as well.

  **Ex**

  When the password is 'ABCD'

<table>
<thead>
<tr>
<th>ASCII code, binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>A B C D</td>
</tr>
<tr>
<td>41h 42h 43h 44h</td>
</tr>
</tbody>
</table>

  **Restriction**

  When setting the password with the file password 32 function of High-speed universal model QCPU, set it with four characters.

- **When a password is not set**
  Specify 20H for 4 bytes.

<table>
<thead>
<tr>
<th>ASCII code, binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>20h 20h 20h 20h</td>
</tr>
</tbody>
</table>
**File password 32 of MELSEC-L series (4 to 32 characters)**

Use the subcommand ‘0004’.

---

**Restriction**

Subcommand ‘0000’ can be used only when the password is not set to the file.
When subcommand 0000 is used to MELSEC-L series module, specify 20H for 4 bytes.

---

### When a password is set

Send password character string in 32-digit ASCII code.
Specify the password in ASCII code during data communication in binary code as well.
If the password is less than 32 characters, a space (20H) is added for the shortage of the characters.

**Ex.**

When the password is ‘ABCDEF’

<table>
<thead>
<tr>
<th>ASCII code, binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>A B C D E F</td>
</tr>
<tr>
<td>41h 42h 43h 44h 45h 46h</td>
</tr>
<tr>
<td>20h 20h 20h 20h 20h 20h</td>
</tr>
</tbody>
</table>

(32 digits)

### When a password is not set

Specify 20H for 32 bytes.

**ASCII code, binary code**

<table>
<thead>
<tr>
<th>20h 20h 20h 20h 20h 20h 20h 20h</th>
<th></th>
</tr>
</thead>
</table>

(32 digits)
File password for MELSEC iQ-R series (6 to 32 characters)

Use the subcommand '0040'.

- **Point**
  
  If multiple wrong passwords are attempted continuously, the password will be locked out and cannot unlock the password for a while.

---

**When a password is set**

Specify the number of characters and the character string of password.

Specify 'Password character string' with variable length. The length of data is specified in 'Number of characters'. (Page 194 Number of characters)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Number of characters</strong></td>
<td><strong>Password character string</strong></td>
</tr>
<tr>
<td>(4 digits)</td>
<td>(Variable length)</td>
</tr>
</tbody>
</table>

Specify the password character string in ASCII code during data communication in binary code as well.

**Ex.**

Password is "ABCDEFGHIJKLMNOPQRSTUVWXYZ" (26 characters)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Number of characters</strong></td>
<td><strong>Password character string</strong></td>
</tr>
<tr>
<td>0 0 1 A 30h 30h 31h</td>
<td>A B C D ... Z 41h 42h 43h 44h</td>
</tr>
</tbody>
</table>

**When a password is not set**

Specify with the number of character '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>0 0 0 0</strong></td>
<td></td>
</tr>
<tr>
<td>30h 30h 30h</td>
<td>00h</td>
</tr>
</tbody>
</table>
Drive No.

This is a data to specify the drive of CPU module of which files are to be controlled.

<table>
<thead>
<tr>
<th>Specified value</th>
<th>Target drive</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>RCPU</td>
</tr>
<tr>
<td>0000H</td>
<td>—</td>
</tr>
<tr>
<td>0001H</td>
<td>Device/label memory (file storage area)</td>
</tr>
<tr>
<td></td>
<td>The same operation when 0003H is specified.</td>
</tr>
<tr>
<td>0002H</td>
<td>SD memory card</td>
</tr>
<tr>
<td>0003H</td>
<td>Device/label memory (file storage area)</td>
</tr>
<tr>
<td>0004H</td>
<td>Data memory</td>
</tr>
</tbody>
</table>

The program memory of RCPU cannot be accessed. When reading/writing program files, use the data memory. (Page 188 Access for "$MELPRJ$" folder of RCPU)

Setting method

- **Data communication using ASCII code**
  Convert the numerical value that indicates access target drive to 4-digit ASCII code (hexadecimal) and send it from upper digits.

- **Data communication using binary code**
  Send 2-byte numerical values that indicate access target drive from the lower byte (L: bits 0 to 7).

**Ex.**

Drive No. is ‘0003H’

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 3</td>
<td>0b 00 00</td>
</tr>
</tbody>
</table>

| 30h 30h 30h 33h | 0b 00 00 |


File No.

This is a number for module to control files.
File No. can be obtained by following command.

Page 211 Search directory/file information (command: 1811)

### File No. of MELSEC-Q/L series module

Use the subcommand '0000'.
A file No. can be specified within the range of 1 to 256 (1H to 100H).

#### Data communication using ASCII code

Convert the file No. to 4-digit ASCII code (hexadecimal) and send it from upper digits.

#### Data communication using binary code

Send 2-byte*1 numerical values that indicate file No. from lower byte (L: bits 0 to 7).
*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

<table>
<thead>
<tr>
<th>Ex</th>
<th>1FH</th>
</tr>
</thead>
<tbody>
<tr>
<td>ASCII code</td>
<td>Binary code</td>
</tr>
<tr>
<td>0 0 1 F</td>
<td>1F 00</td>
</tr>
</tbody>
</table>

### File No. of MELSEC iQ-R series module

Use the subcommand '0040'.

#### Data communication using ASCII code

Convert the file No. to ASCII code 8 digits (hexadecimal), and transmit it from the upper digits.

#### Data communication using binary code

Send 4-byte*1 numerical values that indicate file No. from the lower byte (L: bits 0 to 7).
*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

<table>
<thead>
<tr>
<th>Ex</th>
<th>For 1FH</th>
</tr>
</thead>
<tbody>
<tr>
<td>ASCII code</td>
<td>Binary code</td>
</tr>
<tr>
<td>0 0 0 0 0 0 0 1 F</td>
<td>1F 00 00 00</td>
</tr>
</tbody>
</table>

---

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))
Number of files

Specify the number of files to be accessed. The number of registered files or the number of accessed files are returned.

**Setting method**

- **Data communication using ASCII code**
  Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

- **Data communication using binary code**
  Send 2-byte numerical values*1 from the lower byte (L: bits 0 to 7).
  *1 For C24, the additional code may be added. ([Page 33 Additional code (10H)])

**Ex.**
Number of file is 3

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 3</td>
<td>03h 00h</td>
</tr>
</tbody>
</table>

Number of characters

This indicates the number of characters of variable length character string to be specified.

**Setting method**

- **Data communication using ASCII code**
  Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

- **Data communication using binary code**
  Send 2-byte numerical values*1 from the lower byte (L: bits 0 to 7).
  *1 For C24, the additional code may be added. ([Page 33 Additional code (10H)])

**Ex.**
Number of characters is 86 characters (56H)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 5 6</td>
<td>56h 00h</td>
</tr>
</tbody>
</table>

Directory specification

Specify the absolute path to a file to be accessed.
Specify 'Path name' with variable length. The length of data is specified in 'Number of characters'. ([Page 194 Number of characters])

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of characters Path name</td>
<td>Number of characters Path name</td>
</tr>
<tr>
<td>(4 digits)  (Variable length)</td>
<td>(2 bytes)  (Variable length)</td>
</tr>
</tbody>
</table>

Specify '0' for the root directory (root folder)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00h 00h</td>
</tr>
</tbody>
</table>
Path name
Specify the absolute path by UTF-16 from the root folder. "Drive name:\" is not required in front of the path. Use \' (005CH) for the delimiter between the folder names.

■ Data communication using ASCII code
Convert the numerical value of UTF-16, which indicates a path character string, to ASCII code (hexadecimal) and send it from upper digits.

■ Data communication using binary code
Send the numerical value of UTF-16 indicating the path character string from lower bytes (L: bits 0 to 7).

Ex.
Folder root folder ‘A’
(UTF-16: ‘A’= 0041)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 4 1</td>
<td>41 00</td>
</tr>
</tbody>
</table>

30h, 30h, 34h, 31h
**File name specification**

Specify the file name to be accessed. A file name differs in specification by the module. Specify a corresponding file name for the module of access target. For details of usable file name, refer to the manual of module for access target.

<table>
<thead>
<tr>
<th>Access target</th>
<th>Usable file name</th>
<th>Sub command</th>
<th>Data specified by Message</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC-Q/L series module</td>
<td>File name (up to 8 characters) and extension (3 characters) Specify with ASCII code character string.</td>
<td>0000, 0004</td>
<td>• File name (8 characters fixed) and extension (3 characters fixed)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Number of characters (up to 12 characters) and file name character string (including the extension)</td>
</tr>
<tr>
<td>MELSEC iQ-R series module</td>
<td>Path name, file name (up to 60 characters) and extension Specify with Unicode character string.</td>
<td>0040</td>
<td>• Number of characters (up to 252 characters) and file name character string (including the path and extension)</td>
</tr>
</tbody>
</table>

**Point**

Files other than the one described as usable files in the manuals of modules are for system. Do not change the file name.

**File name of MELSEC-Q/L series module (File name and extension)**

When using the subcommand 0000 for the read directory/file information (command: 1810), the file name (8 characters fixed) and the extension (3 characters fixed) are stored in the response data. A period is not inserted between the file name and the extension.

**ASCII code, binary code**

Specify the file name and the extension in ASCII code during data communication in binary code as well.

**Ex**

The file name and the extension are "ABCDEFGH.QPG".

**ASCII code, binary code**
**File name of MELSEC-Q/L series module (Number of characters and file name)**

For the data other than response data of read directory/file information (command: 1810), specify with number of characters and file name character string.

Use the subcommand '0000' or '0004'.

The file name and the extension are specified as a variable length character string with a period inserted between them. Specify the length of character string with "number of characters". (Page 194 Number of characters)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of characters</td>
<td>File name + &quot;.&quot; + Extension</td>
</tr>
<tr>
<td>(4 digits)</td>
<td>(Variable length)</td>
</tr>
<tr>
<td>Number of characters</td>
<td>File name + &quot;.&quot; + Extension</td>
</tr>
<tr>
<td>(2 bytes)</td>
<td>(Variable length)</td>
</tr>
</tbody>
</table>

Specify "File name" + "Period (2EH)" + "Extension" in ASCII code during data communication in binary code as well.

**Ex.**

File name and the extension are "ABC.QPG". (7 characters including a period)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 7</td>
<td>A B C . Q P G</td>
</tr>
<tr>
<td>30h, 30h, 30h, 37h</td>
<td>41h, 42h, 43h, 26h, 53h, 50h, 47h</td>
</tr>
<tr>
<td>A B C . Q P G</td>
<td></td>
</tr>
<tr>
<td>02h, 00h, 41h, 42h, 43h, 26h, 53h, 50h, 47h</td>
<td></td>
</tr>
</tbody>
</table>
File name of MELSEC iQ-R series module (Number of characters and file name)

Use the subcommand '0040'.

Specify the file name including absolute path from the root folder with variable length.

The file name and the extension are specified by inserting a period between them. Specify the length of character string with "number of characters". (Page 194 Number of characters)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of characters</td>
<td>File name + &quot;.&quot; + Extension</td>
</tr>
<tr>
<td>(4 digits)</td>
<td>(Variable length)</td>
</tr>
<tr>
<td>Number of characters</td>
<td>File name + &quot;.&quot; + Extension</td>
</tr>
<tr>
<td>(2 bytes)</td>
<td>(Variable length)</td>
</tr>
</tbody>
</table>

Specify "Path name" + "Period (002EH)" + "Extension" by Unicode(UTF-16).
"Drive name:;" is not required in front of the path. Use '\' (005CH) for the delimiter between the folder names.

For the characters that cannot be used for a file name and naming rules, refer to the manual of the access target module.

Data communication using ASCII code

Convert the numerical value of UTF-16, which indicates a file name, to ASCII code (hexadecimal) and send it from the upper digits.

Data communication using binary code

Send the numerical value of UTF-16 that indicates file name from the lower byte (L: bits 0 to 7).

Ex.

When the file name and the extension are 'LINE\LINE.CSV' (13 characters)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000 0000 0000 0000 0000 0000 0000 0000 0000 0000 0000 0000 0000</td>
<td>LINE\LINE.CSV</td>
</tr>
<tr>
<td>0000 0000 0000 0000 0000 0000 0000 0000 0000 0000 0000 0000 0000</td>
<td>LINE\LINE.CSV</td>
</tr>
</tbody>
</table>

The value of the file name 'LINE\LINE.CSV' is as follows.

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>L</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0049 004E 0045 005C 004C 0049 004E 0045 005C 004C 0049 004E 0045</td>
</tr>
<tr>
<td>ASCII code</td>
<td>3030 3030 3030 3030 3030 3030 3030 3030 3030 3030 3030 3030 3030</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 4900 4E00 4500 5C00 4C00 4900 4E00 4500 5C00 4C00 4900 4E00 4500</td>
</tr>
</tbody>
</table>
Attribute

This indicates whether the data can be written to a file or directory.

### File attribute

<table>
<thead>
<tr>
<th>Read-only attribute</th>
<th>Archive attribute</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Read-only</td>
<td>OFF</td>
<td>0 0 0 1</td>
<td>01 00</td>
</tr>
<tr>
<td>ON</td>
<td>00 2 1</td>
<td></td>
<td>21 00</td>
</tr>
<tr>
<td>Writable, readable</td>
<td>OFF</td>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
<tr>
<td>ON</td>
<td>00 2 0</td>
<td></td>
<td>20 00</td>
</tr>
</tbody>
</table>

Do not access the file in which the value other than above is stored in the attribute since the files are reserved for system use.

### Attribute of directory (folder)

<table>
<thead>
<tr>
<th>Read-only attribute</th>
<th>Archive attribute</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Read-only</td>
<td>OFF</td>
<td>0 0 1 1</td>
<td>11 00</td>
</tr>
<tr>
<td>ON</td>
<td>00 3 1</td>
<td></td>
<td>31 00</td>
</tr>
<tr>
<td>Writable, readable</td>
<td>OFF</td>
<td>0 0 1 0</td>
<td>30 00</td>
</tr>
<tr>
<td>ON</td>
<td>00 3 0</td>
<td></td>
<td>30 00</td>
</tr>
</tbody>
</table>

Do not access the directory (folder) in which the value other than above is stored in the attribute since it is reserved for system use.
Creation date and time (last edit date and time)

This is a date and time when the current file contents are registered.

Setting method

Represent the date (year, month, day) and time (hour, minute, second) with 16-bit value, respectively.

- **Data communication using ASCII code**
  Convert the respective numerical value to 4-digit ASCII code (hexadecimal) and send from the upper digits (time, year).

- **Data communication using binary code**
  Send the respective 2-byte numerical value from the lower byte (L: bits 0 to 7).

**Date (year, month, day)**

Represent the year, month, and day with 16-bit value.

- **Year:** The binary value is represented with bits 9 to 15 by setting the year 1980 to '0'. *1
- **Month:** The binary value is represented with bits 5 to 8.
- **Day:** The binary value is represented with bits 0 to 4.

*1 This indicates incremental number of year by regarding 1980 as '0'.

**Ex**

For April 1, 2010

- **(Year)**
  - Numerical values in relevant range: 30+1980 = 2010
  - Represented as: 0010 1110 0001 0000 0000

- **(Month)**
  - Represented as: 1110 0000

- **(Day)**
  - Represented as: 0001 0000

<table>
<thead>
<tr>
<th><strong>ASCII code</strong></th>
<th><strong>Binary code</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td>3 C 8 1</td>
<td>81C3</td>
</tr>
<tr>
<td>33h, 43h, 38h, 31h</td>
<td>81h, 3Ch</td>
</tr>
</tbody>
</table>
**Time (hour, minute, second)**

Represent the hour, minute, second with 16-bit value.
- **Hour**: The binary value is represented with bits 11 to 15.
- **Minute**: The binary value is represented with bits 5 to 10.
- **Second**: The binary value divided by 2 is represented with bits 0 to 4.

**Ex.**

When 20:50:58

<table>
<thead>
<tr>
<th>(Hours)</th>
<th>(Minutes)</th>
<th>(Second)</th>
</tr>
</thead>
<tbody>
<tr>
<td>b15 b14 b13 b12 b11 b10</td>
<td>b9 b8 b7 b6</td>
<td>b5 b4 b3 b2 b1 b0</td>
</tr>
<tr>
<td>1 0 1 0 0 0</td>
<td>1 1 0 1 0 0</td>
<td>1 1 1 1 0 1</td>
</tr>
</tbody>
</table>

Numerical values in relevant range

- 14h(20)
- 32h(50)
- 1Dh(29)
- \(58 \div 2 = 29\)

**Ex.**

The file size is 7168 bytes

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 1 C 0 0</td>
<td>0 0 0 1 C 0 0 0</td>
</tr>
</tbody>
</table>

**File size**

This indicates the file capacity in byte units.

**Setting method**

- **Data communication using ASCII code**
  Convert the numerical value to 8-digit ASCII code (hexadecimal), and send it from the upper digits.

- **Data communication using binary code**
  Send 4-byte numerical values \(^*1\) from the lower byte (L: bits 0 to 7).

  \(^*1\) For C24, the additional code may be added. (Page 33 Additional code (10H))

**Ex.**

The file size is 7168 bytes

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 1 C 0 0</td>
<td>0 0 0 1 C 0 0 0</td>
</tr>
</tbody>
</table>
File pointer No.

This is a number for CPU module to manage files.
The file pointer No. can be acquired with the following command.

Page 230 Open file (command: 1827)

Setting method

■ Data communication using ASCII code
Send 4-byte**1 ASCII code data.

■ Data communication using binary code
Send 2-byte**1 numerical value.

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Ex
For AH

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 A</td>
<td>0000 0000</td>
</tr>
</tbody>
</table>

Offset address

Specify the address (one address/one byte) from the head (offset address: 0H) of each file with an even number.

Setting method

■ Data communication using ASCII code
Convert the numerical value to 8-digit ASCII code (hexadecimal), and send it from the upper digits.

■ Data communication using binary code
Send 4-byte numerical values**1 from the lower byte (L: bits 0 to 7).

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Ex
Offset address is 780H(1920)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 0 7 8 0</td>
<td>0000 0700 0000</td>
</tr>
</tbody>
</table>
Number of bytes

Specify the number of bytes of data to be read or written as one address/one byte.

Setting method

■Data communication using ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

■Data communication using binary code
Send 2-byte numerical values*1 from the lower byte (L: bits 0 to 7).

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Ex
Number of bytes is 780H(1920)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 7 8 0</td>
<td>80 07</td>
</tr>
</tbody>
</table>

Read data, write data

This is a content of file to be read/written. The data for 1 address is handled as 1-byte.

Read data
The data which have been read is stored.
The "Read data" is variable length. The length of data is specified with "Number of bytes read".

Write data
The data to be written is stored.
The "Write data" is variable length. The length of data is specified with "Number of bytes written".
The order of data must be the same as the read data.

■Data communication using ASCII code
Convert the 1-byte data (1 address) to 2-digit ASCII code (hexadecimal) and send it from upper digits.

■Data communication using binary code
Send 1 address as 1 byte.
Open mode

Specify whether the specified file is open for reading or for writing with the 'open file' (command: 1827).

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For reading</td>
<td>30h 30h 30h 30h</td>
<td>00h 00h</td>
</tr>
<tr>
<td>For writing</td>
<td>30h 31h 30h 30h</td>
<td>00h 01h</td>
</tr>
</tbody>
</table>

Close type

Specify a target to be closed with the 'close file' (command: 182A).

<table>
<thead>
<tr>
<th>File to unlock</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>A file specified by the file pointer</td>
<td>30h 30h 30h 30h</td>
<td>00h 00h</td>
</tr>
<tr>
<td>All files</td>
<td>30h 31h 30h 31h</td>
<td>01h 00h</td>
</tr>
<tr>
<td></td>
<td>30h 31h 32h</td>
<td>02h 00h</td>
</tr>
</tbody>
</table>

When all files are specified for unlock, the external device that executes the close (command: 182A) closes all files being open regardless of the hierarchy of drive No. or directory (folder). (There is no difference between 0001H and 0002H.) The files which were opened by the other devices cannot be closed.

Executing the command to files locked by the other external device results in abnormal completion of the command.

Files are closed by restarting a module (such as resetting CPU module).
12.4 File Check

Read directory (folder), file name, file creation date and time, and file No. in the specified drive.
The presence of files to be accessed and the file No. to access can be checked.

**Read directory/file information (command: 1810)**

For the specified storage destination file, read the file name, file creation date and time (last edit date and time) etc.
Read the file information from the head file specified with the file No. to the specified number of files.

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Fixed values</th>
<th>Drive No.</th>
<th>Head file No.</th>
<th>Number of requested files</th>
<th>Directory specification</th>
</tr>
</thead>
</table>

**Response data**

<table>
<thead>
<tr>
<th>Number of file information (n points)</th>
<th>Last file No.</th>
<th>File</th>
<th>Last edit date and time</th>
<th>File size</th>
<th>...</th>
<th>File</th>
<th>Last edit date and time</th>
<th>File size</th>
</tr>
</thead>
</table>

Directory/file information (1st point) Directory/file information (nth point)

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code (for C24)*1</th>
<th>Binary code (for E71)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1810</td>
<td>DLE 10h 10h 18h</td>
<td>18h 10h</td>
</tr>
</tbody>
</table>

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

**Sub command**

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0000</td>
<td>0000</td>
</tr>
<tr>
<td></td>
<td>30h 30h 30h 30h</td>
<td>00h 00h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0040</td>
<td>4000</td>
</tr>
<tr>
<td></td>
<td>30h 30h 34h 30h</td>
<td>40h 00h</td>
</tr>
</tbody>
</table>
### Fixed value
Specify 30H in 4 bytes.

**ASCII code, binary code**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>30 30 30 30</td>
<td>00 00 00 00</td>
</tr>
</tbody>
</table>

### Drive No.
Specify the access target drive. (Page 192 Drive No.)

### Head file No.
Specify the file No. of the file from which the file information is to be read. (Page 193 File No.)
File No. can be obtained by following command.
Page 211 Search directory/file information (command: 1811)

### Number of requested file
Specify the number of files from which file information is read in the range of 1 to 36. (Page 194 Number of files)

### Directory specification
Depending on the access target, specify any of the following:
- MELSEC iQ-R series (when using subcommand '0040'): Specify the target folder with an absolute path. (Page 194 Directory specification)
- MELSEC-Q/L series (when using subcommand '0000'): Specify '0'.

**ASCII code**

<table>
<thead>
<tr>
<th>ASCII code</th>
</tr>
</thead>
<tbody>
<tr>
<td>00 00 00</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>00 00</td>
</tr>
</tbody>
</table>

*Point*
When checking all files in the specified directory (folder), refer to the following section.
Page 184 Procedure to read information from all files in directory (folder)
Data stored in response data

■ Number of file information
The number of file information which has been read is stored. (Page 194 Number of files)
In the following situation, the number of file information will be fewer than the number of requested file.
• When using subcommand '0040', the data of "Number of requested file" cannot be stored at one communication because the file name length is too long.
• When the number of files exist following the "Head file No." is less than the "Number of requested file".
  When no files exist after the specified head file No., the following value is stored.
  • MELSEC-Q/L series (when using subcommand '0000'): "Number of file information" = '0'
  • MELSEC iQ-R series (when using subcommand '0040'): "Number of file information" = -1 (FFFFH)

■ Last file No.
The file No. of the last file from which file information was read is stored. (Page 193 File No.)
For MELSEC-Q/L series (subcommand '0000'), last file No. is not stored.

Point
File No. is also assigned for the system-reserved data that cannot acquire the directory/file information, therefore, the "Last file No." may differ from the file No. of the last file for the read file information.
Acquire the file No. using the following command.
• Page 211 Search directory/file information (command: 1811)
Use "Last file No." in the following process.
• Page 184 Procedure to read information from all files in directory (folder)

■ Directory/file information
Information for number of file information is stored.
When folders exist in the specified storage destination, the information for the folder is also read.

<table>
<thead>
<tr>
<th>File name specification</th>
<th>Attribute</th>
<th>Spare data</th>
<th>Last edit time</th>
<th>Last edit date</th>
<th>Spare data</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>ASCII: 18 bytes</td>
<td></td>
<td></td>
<td>Binary: 9 bytes</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The following items are stored for each file.
• File name specification: The file name is stored. The format differs depending on the subcommand. (Path name is not included in the file name even when using the subcommand 0040.)

<table>
<thead>
<tr>
<th>Sub command</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series (Subcommand: 0000)</td>
<td>Page 196 File name of MELSEC-Q/L series module (File name and extension)</td>
</tr>
<tr>
<td>For MELSEC iQ-R series (Subcommand:0040)</td>
<td>Page 196 File name of MELSEC iQ-R series module (Number of characters and file name)</td>
</tr>
</tbody>
</table>

• Attribute: The file attributes are stored. (Page 199 Attribute)
• Last edit time, Last edit date: The last edit date and time are stored. (Page 200 Creation date and time (last edit date and time))
• Spare data: The system data which are 18 or 4 bytes during data communication in ASCII code and 9 or 2 bytes*1 during data communication in binary code are stored.
• File size: Capacity of file is stored in byte unit. (Page 201 File size)

*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Point
For a folder, the following values will be stored.
• Attribute: Attribute of the directory (folder) is stored. (Page 199 Attribute of directory (folder))
• Last edit time, Last edit date: The folder creation date and time are stored.
• File size: '0' is stored.
Communication example (files for MELSEC-Q/L series)

Read directory/file information under the following conditions.
- Drive No.: 0
- Head file No.: 1
- Number of requested files: 3

**Data communication using ASCII code**

*(Request data)*

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Drive No.</th>
<th>Head file No.</th>
<th>Number of file requests</th>
<th>Directory specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 1 0</td>
<td>0 0 0 0</td>
<td>0 0 0 0</td>
<td>0 0 0 1</td>
<td>0 0 0 3</td>
</tr>
</tbody>
</table>

*(Response data)*

<table>
<thead>
<tr>
<th>Number of file information</th>
<th>Directory/ file information 1</th>
<th>Directory/ file information 2</th>
<th>Directory/ file information 3</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
<th>Spare data</th>
</tr>
</thead>
<tbody>
<tr>
<td>A B C</td>
<td>D E F</td>
<td>G H Q P G</td>
<td>. . .</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Last edit time</th>
<th>Last edit date</th>
<th>Spare data</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;20 h 58 m 58 s&quot;</td>
<td>&quot;April 1, 2010&quot;</td>
<td>. . .</td>
<td>1k byte</td>
</tr>
</tbody>
</table>

**Data communication using binary code**

*(Request data)*

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Drive No.</th>
<th>Head file No.</th>
<th>Number of file requests</th>
<th>Directory specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>10 18 0</td>
<td>00 00 00</td>
<td>00 00 00</td>
<td>00 00 00</td>
<td>00 00 00</td>
</tr>
</tbody>
</table>

*(Response data)*

<table>
<thead>
<tr>
<th>Number of file information</th>
<th>Directory/ file information 1</th>
<th>Directory/ file information 2</th>
<th>Directory/ file information 3</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
<th>Spare data</th>
<th>Last edit time</th>
<th>Last edit date</th>
<th>Spare data</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td>A B C</td>
<td>D E F</td>
<td>G H Q P G</td>
<td>. . .</td>
<td>&quot;20 h 58 m 58 s&quot;</td>
<td>&quot;April 1, 2010&quot;</td>
<td>. . .</td>
<td>1k byte</td>
</tr>
</tbody>
</table>
Communication example (files for MELSEC iQ-R series)

Read directory/file information under the following conditions.

- Drive No.: 4
- Head file No.: 1
- Number of requested files: 3

The path names of directory are shown in the following table.

(1) SUBDIR (6 characters)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>Path name</td>
<td>S U B D I R</td>
</tr>
<tr>
<td>UTF-16</td>
<td>0053 0055 0042 0044 0049 0052</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303533 30303535 30303432 30303434 30303439 30303532</td>
</tr>
<tr>
<td>Binary code</td>
<td>5300 5500 4200 4400 4900 5200</td>
</tr>
</tbody>
</table>

The following shows the file name of a directory/file information 1 to be read.

(2) LINE.CSV (8 characters)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>L I N E . C S V</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0049 004E 0045 002E 0043 0053 0056</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303439 30303445 30303435 30303434 30303433 30303533 30303536</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 4900 4E00 4500 2E00 4300 5300 5600</td>
</tr>
</tbody>
</table>

Data communication using ASCII code

(Request data)

Subcommand (Fixed value) | Drive No. | Head file No. | Number of requested files |
--------------------------|-----------|---------------|---------------------------|
1 8 1 0                   | 0 0 4 0   | 0 0 0 0       | 0 0 0 4                   |
30, 30, 30, 30, 30, 30   | 30, 30, 30, 30, 30, 30 | 30, 30, 30, 30, 30, 30 | 30, 30, 30, 30, 30, 30 |

Number of characters     | Path name |
--------------------------|-----------|
3 0, 30, 30, 30           | (1)       |

In the figure (1), set the value of "ASCII code" in the table of "Value of code corresponds to character" in "Path name".

(Response data)

Number of file information | Last file No. | Directory/file information 1 | Directory/file information 2 | Directory/file information 3 |
---------------------------|---------------|-----------------------------|-----------------------------|-----------------------------|
0 0 0 3                    | 0 0 0 0       | 0 0 0 9                     | Directory/file information 1 | Directory/file information 2 | Directory/file information 3 |
30, 30, 30, 30, 30, 30    | 30, 30, 30, 30, 30, 30 | 30, 30, 30, 30, 30, 30 | 30, 30, 30, 30, 30, 30 |

Number of characters     | File name     | Attribute   | Spare data |
--------------------------|---------------|-------------|------------|
3 0, 30, 30, 30           | (2)           | 0 0 0 1     | (18 bytes) |

In the figure (2), set the value of "ASCII code" in the table of "Value of code corresponds to character" in "File name".
Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>(Fixed value)</th>
<th>Drive No.</th>
<th>Head file No.</th>
<th>Number of file requests</th>
<th>Number of characters</th>
<th>Path name</th>
</tr>
</thead>
<tbody>
<tr>
<td>10h, 18h, 40h, 00h</td>
<td>30h, 30h, 30h, 30h</td>
<td>01h, 00h, 00h, 00h</td>
<td>03h, 00h</td>
<td>06h, 00h</td>
<td>(1)</td>
<td></td>
</tr>
</tbody>
</table>

In the figure (1), set the value of "Binary code" in the table of "Value of code corresponds to character" in "Path name".

(Response data)

<table>
<thead>
<tr>
<th>Drive No.</th>
<th>Number of file information</th>
<th>Last file No.</th>
<th>Directory/ file information 1</th>
<th>Directory/ file information 2</th>
<th>Directory/ file information 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>03h, 00h, 09h, 00h</td>
<td>03h, 00h, 00h, 00h</td>
<td>(2)</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

In the figure (2), set the value of "Binary code" in the table of "Value of code corresponds to character" in "File name".
Search directory/file information (command: 1811)

Read the file No. of the specified file. The file No. indicates the registration number of a file when the file is written to the module.

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Fixed values 1</th>
<th>Drive No.</th>
<th>Fixed values 2</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
</table>

**Response data**

File No. is stored. (Page 193 File No.)

If the file with the specified name does not exist, the command completes abnormally.

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 1 1</td>
<td>11 18</td>
</tr>
</tbody>
</table>

**Sub command**

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
<tr>
<td></td>
<td>30 30 30 30</td>
<td></td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 4 0</td>
<td>40 00</td>
</tr>
<tr>
<td></td>
<td>30 30 34 30</td>
<td></td>
</tr>
</tbody>
</table>

**Fixed value 1**

Specify the following fixed value.

- MELSEC iQ-R series (when using subcommand '0040'): Specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
<tr>
<td>30 30 30 30</td>
<td></td>
</tr>
</tbody>
</table>

- MELSEC-Q/L series (when using subcommand '0000'): Specify 20H in 4 bytes.

**Drive No.**

Specify the access target drive. (Page 192 Drive No.)
**Fixed value 2**
Specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
</tbody>
</table>

**Number of file name characters, file name**
Specify the file name of which file No. is to be read. (Page 196 File name specification)

**Communication example (files for MELSEC-Q series)**
Read the file No. in the following conditions.
- Password: 4 spaces (code: 20H)
- Drive No.: 0
- File name: ABC.QPG (file No.6)

**Data communication using ASCII code**
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>(Fixed value 1)</th>
<th>Drive No.</th>
<th>(Fixed value 2)</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 1 1</td>
<td>31h 38h 31h 31h</td>
<td>0 0 0 0</td>
<td>31h 20h 20h 20h</td>
<td>0 0 0 0</td>
<td>ABC.QPG</td>
</tr>
</tbody>
</table>

(Response data)

```
0 0 0 6
```

**Data communication using binary code**
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>(Fixed value 1)</th>
<th>Drive No.</th>
<th>(Fixed value 2)</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>11h 18h</td>
<td>00h 00h</td>
<td>20h 20h 20h 20h</td>
<td>00h 00h 00h 00h 07h 00h</td>
<td>A B C . Q P G</td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

```
06h 00h
```
Communication example (files for MELSEC iQ-R series)

Read the file No. in the following conditions.
- Drive No.: 4
- File No.: 6

The file name is as follows:
(1) LINE\LINE.CSV (13 characters)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td></td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0049 004E 0045 005C 004C 0049 004E</td>
</tr>
<tr>
<td>ASCII code</td>
<td>3030 3443 3030 3439 3030 3445 3030 3435</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 4900 4E00 4500 5C00 4C00 4900 4E00</td>
</tr>
</tbody>
</table>

■Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>(Fixed value 1)</th>
<th>Drive No.</th>
<th>(Fixed value 2)</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 1 1</td>
<td>0 0 4 0</td>
<td>0 0 0 0</td>
<td>0 0 0 4</td>
<td>0 0 0 0</td>
<td>(1)</td>
</tr>
</tbody>
</table>

In the figure (1), set the value of "ASCII code" in the table of "Value of code corresponds to character" in "File name".
(Response data)

<table>
<thead>
<tr>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 0 0 0 6</td>
</tr>
</tbody>
</table>

■Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>(Fixed value 1)</th>
<th>Drive No.</th>
<th>(Fixed value 2)</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>11 18 18</td>
<td>40 00</td>
<td>00 00</td>
<td>00 00</td>
<td>00 00</td>
<td>(1)</td>
</tr>
</tbody>
</table>

In the figure (1), set the value of "Binary code" in the table of "Value of code corresponds to character" in "File name".
(Response data)

<table>
<thead>
<tr>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>06 00 00 00 00</td>
</tr>
</tbody>
</table>
12.5 File Creation and Deletion

Create a new file or delete a file.

Create new file (command: 1820)

Specify the size to create a new file.
A folder cannot be created with this command. Create a folder with an Engineering tool.

The time on a module is registered as the last edit date and time in a file created using this function.

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Password</th>
<th>Drive No.</th>
<th>File size</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
</table>

Response data

There is no response data for this command.

Data specified by request data

Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>31H 32H 33H 34H</td>
<td>20H 18H</td>
</tr>
</tbody>
</table>

Sub command

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 0 0</td>
<td>00H 00H</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 4 0</td>
<td>40H 00H</td>
</tr>
</tbody>
</table>

Password

Specify the following fixed value.
- MELSEC iQ-R series (when using subcommand '0040'): Specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>30H 30H 30H 30H</td>
<td>00H 00H</td>
</tr>
</tbody>
</table>

- MELSEC-Q/L series (when using subcommand '0000'): Specify 20H in 4 bytes.

<table>
<thead>
<tr>
<th>ASCII code, binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>20H 20H 20H 20H</td>
</tr>
</tbody>
</table>
### Drive No.
Specify the access target drive. (Page 192 Drive No.)

### File size
Specify the file capacity in byte unit. (Page 201 File size)

### Number of file name characters, file name
Specify the file name to be created. (Page 196 File name specification)

---

#### Communication example (files for MELSEC-Q series)

Create a new file in the following conditions:
- Password: 4 spaces (code: 20H)
- Drive No.: 0
- File name: ABC.CSV
- File size: 1K byte

#### Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password</th>
<th>Drive No.</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 0</td>
<td>0 0 0 0</td>
<td>0 0 0 0</td>
<td>0 0 0 0</td>
</tr>
</tbody>
</table>

Number of file name characters: 7

File name: ABC.CSV

#### Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password</th>
<th>Drive No.</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td>201 180 001 000</td>
<td>000000</td>
<td>000000</td>
<td>000000</td>
</tr>
</tbody>
</table>

Number of file name characters: 7

File name: ABC.CSV
Communication example (files for MELSEC iQ-R series)

Create a new file in the following conditions:

- Drive No.: 4
- File size: 7168 byte
- File name: LINE.CSV (8 characters)

The value of the file name is as follows:

1. LINE.CSV (8 characters)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>L I N E . C S V</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0049 004E 0045 002E 0043 0053 0056</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303439 30303445 30303435 30303245 30303433 30303533 30303536</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 4900 4E00 4500 2E00 4300 5300 5600</td>
</tr>
</tbody>
</table>

■ Data communication using ASCII code

(Example)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Drive No.</th>
<th>File size</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 0 0 0 4 0</td>
<td>0 0 0 0 0</td>
<td>0 0 0 4</td>
<td>0 0 0 0 1 C 0 0 0 0 8</td>
<td>(1)</td>
</tr>
</tbody>
</table>

In the figure (1), set the value of "ASCII code" in the table of "Value of code corresponds to character" in "File name".

■ Data communication using binary code

(Example)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Drive No.</th>
<th>File size</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>20h, 18h</td>
<td>40h, 00h</td>
<td>00h, 00h, 00h, 00h</td>
<td>04h, 00h</td>
<td>00h, 1C0h, 00h, 00h</td>
</tr>
</tbody>
</table>

In the figure (1), set the value of "Binary code" in the table of "Value of code corresponds to character" in "File name".
Delete file (command: 1822)

Delete a file.

**Point**

If files are deleted while a programmable controller system is in operation, the system may be stopped. Determine the timing of file deletion for the entire programmable controller system.

**Restriction**

- The files on which the 'open file' command is being executed cannot be deleted. Close the file before deleting it. ([Page 230 Open file (command: 1827)], Page 238 Close file (command: 182A))
- The file being executed cannot be deleted when CPU module is state of RUN. Delete the file after placing CPU module to the STOP state. ([Page 457 Applicable Commands for Online Program Change])

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Password</th>
<th>Drive No.</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
</table>

**Response data**

There is no response data for this command.

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q series</td>
<td>1 8 2 2</td>
<td>18 2 2</td>
</tr>
</tbody>
</table>

**Sub command**

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-L series</td>
<td>0 0 0 0 4</td>
<td>00 0 0 0 4</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 4 0</td>
<td>40 0 0 0 0</td>
</tr>
</tbody>
</table>

**Password**

Specify the password of the file. ([Page 189 Password])

**Drive No.**

Specify the access target drive. ([Page 192 Drive No.])
Specify the file name to be deleted. (Page 196 File name specification)

Delete the file under the following conditions:
- Password: 1234
- Drive No.: 0
- File name: ABC.QPG

Communication example (files for MELSEC-Q series)

Delete the file under the following conditions:
- Password: 1234
- Drive No.: 0
- File name: ABC.QPG

Data communication using ASCII code (Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password</th>
<th>Drive No.</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 2 0 0 0 0 1 2 3 4 0 0 0 0 0 0 7</td>
<td>A B C . Q P G</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Data communication using binary code (Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>22h 18h 00h 00h 1 2 3 4 00h 00h 07h 00h</td>
<td>A B C . Q P G</td>
<td></td>
</tr>
</tbody>
</table>

Communication example (files for MELSEC-L series)

Delete the file under the following conditions:
- Password: AbCd1234... (24 spaces, code: 20H)
- Drive No.: 0
- File name: MAIN.QPG

Data communication using ASCII code (Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password (fixed to 32 characters)</th>
<th>Drive No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 2 0 0 0 4 A b C d 1 2 3 4 0 0 0 0</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Data communication using binary code (Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password</th>
<th>Drive No.</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>22h 18h 04h 00h A b C d 1 2 3 4</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

218 12 FILE CONTROL
12.5 File Creation and Deletion
Communication example (files for MELSEC iQ-R series)

Delete the file under the following conditions:

- Password: A to Z (26 characters)
- Drive No.: 4

The file name is as follows:

(1) LINE.CSV (8 characters)

---

**Data communication using ASCII code**

(Request data)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>L</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00</td>
</tr>
</tbody>
</table>

---

In the figure (1), set the value of "ASCII code" in the table of "Value of code corresponds to character" in "File name".

---

**Data communication using binary code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Number of password characters</th>
<th>Password</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 2 0 0 0 1</td>
<td>A B C D ... Z</td>
<td></td>
</tr>
<tr>
<td>30 30 30 30</td>
<td>31 31 31 31</td>
<td></td>
</tr>
</tbody>
</table>

In the figure (1), set the value of "Binary code" in the table of "Value of code corresponds to character" in "File name".
Copy file (command: 1824)

Copy a file.

When this command is executed to files of parameter and a program being executed, place CPU module in the STOP status. (Page 457 Commands that cannot be executed during RUN)

Message format

The following shows the message format of the request data and response data of the command.

■Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Fixed values</th>
<th>Password</th>
<th>Drive No.</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
</table>

Copy destination

<table>
<thead>
<tr>
<th>Password</th>
<th>Drive No.</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
</table>

Copy source

■Response data

There is no response data for this command.

Data specified by request data

■Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1824</td>
<td>2418</td>
</tr>
</tbody>
</table>

■Sub command

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q series</td>
<td>0000</td>
<td>0000</td>
</tr>
<tr>
<td>For MELSEC-L series</td>
<td>0004</td>
<td>0400</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0040</td>
<td>0400</td>
</tr>
</tbody>
</table>

■Fixed value

Specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(16 characters) (8 bytes)
**Password**
Specify the password of the access target file. (Page 189 Password)

**Drive No.**
Specify the access target drive. (Page 192 Drive No.)

Program memory (drive No.0) of RCPU cannot be specified.

**Number of file name characters, file name**
Specify the file name to be copied. (Page 196 File name specification)

### Communication example (files for MELSEC-Q series)
Copy the file under the following conditions:
- Copy source/destination password: 1234
- Drive No. of copy source, drive No. of copy destination: 0
- Copy source file name: ABC.QPG
- Copy source file name: CBA.QPG

**Data communication using ASCII code**
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Fixed values (16 characters)</th>
<th>Password</th>
<th>Drive No.</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 4</td>
<td>31h 38h 23h 34h 30h 30h 30h 30h 30h 30h 30h 30h 30h 30h 30h 30h</td>
<td>0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 7</td>
<td>C B A . Q P G</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Data communication using binary code**
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Fixed values (8 bytes)</th>
<th>Password</th>
<th>Drive No.</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>24h 18h</td>
<td>00h 00h 00h 00h 00h 00h 00h 00h</td>
<td>1 2 3 4</td>
<td>C B A . Q P G</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Copy source**

**Copy destination**

---

Page 221
### Communication example (files for MELSEC-L series)

Copy the file under the following conditions:
- **Password copy source/destination AbCd1234... (24 spaces, code: 20H)**
- **Drive No. of copy source, drive No. of copy destination: 0**
- **Copy source file name: MAIN.QPG**
- **Copy source file name: DEST.QPG**

#### Data communication using ASCII code

**Request data**

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Fixed values (16 characters)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 4 0 0 0 4 0 0 ... 0 0</td>
<td></td>
</tr>
</tbody>
</table>

- **Password (fixed to 32 characters)**
- **Drive No.**
- **Number of file name characters**
- **File name**

<table>
<thead>
<tr>
<th>A b C d 1 2 3 4</th>
<th>0 0 0 0 0 0 0 8</th>
<th>D E S T . Q P G</th>
</tr>
</thead>
<tbody>
<tr>
<td>41h 62h 43h 43h 43h 32h 33h 34h 20h ... 20h</td>
<td>30h 30h 30h 30h</td>
<td>44h 45h 53h 54h 55h 56h 51h 50h 47h</td>
</tr>
</tbody>
</table>

#### Data communication using binary code

**Request data**

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Fixed values (8 bytes)</th>
</tr>
</thead>
<tbody>
<tr>
<td>24h 18h 04h 00h 00h 00h 00h 00h</td>
<td></td>
</tr>
</tbody>
</table>

- **Copy destination**
  - **Password (fixed to 32 characters)**
  - **Drive No.**
  - **Number of file name characters**
  - **File name**

<table>
<thead>
<tr>
<th>A b C d 1 2 3 4</th>
<th>20h 00h 08h 00h</th>
<th>D E S T . Q P G</th>
</tr>
</thead>
<tbody>
<tr>
<td>41h 62h 43h 43h 43h 32h 33h 34h 20h ... 20h</td>
<td>30h 30h 30h 30h</td>
<td>44h 45h 53h 54h 55h 56h 51h 50h 47h</td>
</tr>
</tbody>
</table>

- **Copy source**
  - **Password (fixed to 32 characters)**
  - **Drive No.**
  - **Number of file name characters**
  - **File name**

<table>
<thead>
<tr>
<th>A b C d 1 2 3 4</th>
<th>00h 00h 00h 00h</th>
<th>M A I N . Q P G</th>
</tr>
</thead>
<tbody>
<tr>
<td>41h 62h 43h 43h 43h 32h 33h 34h 20h ... 20h</td>
<td>30h 30h 30h 30h</td>
<td>40h 41h 49h 45h 26h 51h 50h 47h</td>
</tr>
</tbody>
</table>
Copy the file under the following conditions:
- Drive No. of copy source: 2
- Drive No. of copy destination: 4

The file name of the copy source and copy destination is as follows.

(1) LINE.CSV (8 characters)

### Communication example (files for MELSEC iQ-R series)

- **File Creation and Deletion**

The file name of the copy source and copy destination is as follows.

(1) LINE.CSV (8 characters)

#### Data communication using ASCII code

**Request data**

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>L I N E . C S V</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0049 004E 0045 002E 0043 0053 0056</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303439 30303445 30303435 30303425 30303433 30303533 30303536</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 4900 4E00 4500 2E00 4300 5300 5600</td>
</tr>
</tbody>
</table>

- **Data communication using binary code**

**Request data**

In the figure (1), set the value of "ASCII code" in the table of "Value of code corresponds to character" in "File name".

In the figure (1), set the value of "Binary code" in the table of "Value of code corresponds to character" in "File name".
12.6 File Modification

Read or write data from/to the specified file. Lock the file with the open/close file command during reading or writing so that the file contents will not be changed from other devices. The file is not required to be locked with the open file command when commands other than read/write file command are executed.

When modifying the file attributes and the last edit date and time, executing the open command is not required.

Modify file attribute (command: 1825)

Change the file attributes (read only/writable).

Restriction

When this command is executed to files of parameter and a program being executed, place CPU module in the STOP status. (Page 457 Commands that cannot be executed during RUN)

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Password</th>
<th>Drive No.</th>
<th>Attribute</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
</table>

Response data

There is no response data for this command.

Data specified by request data

Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 5</td>
<td>25 18</td>
</tr>
</tbody>
</table>

Sub command

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q series</td>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
<tr>
<td></td>
<td>30 30 30 30</td>
<td></td>
</tr>
<tr>
<td>For MELSEC-L series</td>
<td>0 0 0 4</td>
<td>04 00</td>
</tr>
<tr>
<td></td>
<td>30 30 30 34</td>
<td></td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 4 0</td>
<td>40 00</td>
</tr>
<tr>
<td></td>
<td>30 30 34 30</td>
<td></td>
</tr>
</tbody>
</table>

Password

Specify the password of the access target file. (Page 189 Password)
### Drive No.
Specify the access target drive. (Page 192 Drive No.)

### Attribute
Specify the file attribute. (Page 199 Attribute)
- Read only: 01H
- Readable, writable: 20H
Do not specify the value other than above since the values are reserved for system use.

### Number of file name characters, file name
Specify the file name to modify attribute. (Page 196 File name specification)

---

#### Communication example (files for MELSEC-Q series)
Change the file attribute in the following conditions.
- Password: 1234
- Drive No.: 0
- File name: ABC.QPG
- Attribute: Read only: 01H

#### Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password</th>
<th>Drive No.</th>
<th>Attribute</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 5</td>
<td>0 0 0 0</td>
<td>1 2 3 4</td>
<td>0 0 0 1</td>
<td>7 A B C D Q P G</td>
<td></td>
</tr>
</tbody>
</table>

#### Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password</th>
<th>Drive No.</th>
<th>Attribute</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 3 4</td>
<td>0 0 1</td>
<td>4 1 3 2</td>
<td>0 0 0 1</td>
<td>7 A B C D Q P G</td>
<td></td>
</tr>
</tbody>
</table>

---

#### Communication example (files for MELSEC-L series)
Change the file attribute in the following conditions.
- Password: AbCd1234... (24 spaces, code: 20H)
- Drive No.: 0
- File name: MAIN.QPG
- Attribute: Read only: 01H

#### Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password (fixed to 32 characters)</th>
<th>Drive No.</th>
<th>Attribute</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 5</td>
<td>A b c d 1 2 3 4</td>
<td>0 0 0 1</td>
<td></td>
</tr>
</tbody>
</table>

#### Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password (fixed to 32 characters)</th>
<th>Drive No.</th>
<th>Attribute</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 3 4</td>
<td>A b c d 1 2 3 4</td>
<td>0 0 0 1</td>
<td></td>
</tr>
</tbody>
</table>
Communication example (files for MELSEC iQ-R series)

Change the file attribute in the following conditions.
- Password: A to Z (26 characters)
- Drive No.: 4
- Attribute: Read only: 01H

The file name is as follows:

(1) LINE.CSV (8 characters)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>L</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00</td>
</tr>
</tbody>
</table>

**Data communication using ASCII code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Number of password characters</th>
<th>Password</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>8</td>
<td>2</td>
</tr>
<tr>
<td>31</td>
<td>38</td>
<td>32</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Drive No.</th>
<th>Attribute</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>4</td>
</tr>
<tr>
<td>30</td>
<td>30</td>
<td>30</td>
<td>30</td>
</tr>
</tbody>
</table>

**Data communication using binary code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Number of password characters</th>
<th>Password</th>
<th>Drive No.</th>
<th>Attribute</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>25</td>
<td>18</td>
<td>40</td>
<td>00</td>
<td>A</td>
<td>B</td>
<td>C</td>
</tr>
<tr>
<td>04</td>
<td>00</td>
<td>01</td>
<td>00</td>
<td>08</td>
<td>00</td>
<td></td>
</tr>
<tr>
<td>(1)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Modify file creation date and time (command: 1826)

Modify the file creation date and time.

Restriction

When this command is executed to files of parameter and a program being executed, place CPU module in the STOP status. (Page 457 Commands that cannot be executed during RUN)

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Date to change</th>
<th>Time to change</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Response data

There is no response data for this command.

Data specified by request data

Command

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0 0 0 0</td>
<td>00h, 00h</td>
</tr>
<tr>
<td></td>
<td>30h, 30h, 30h, 30h</td>
<td></td>
</tr>
</tbody>
</table>

Sub command

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 4 0</td>
<td>40h, 00h</td>
</tr>
<tr>
<td></td>
<td>30h, 30h, 30h, 30h</td>
<td></td>
</tr>
</tbody>
</table>

Fixed value

Specify '0'.

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>0 0 0 0</td>
<td>00h, 00h</td>
</tr>
<tr>
<td></td>
<td>30h, 30h, 30h, 30h</td>
<td></td>
</tr>
</tbody>
</table>

Drive No.

Specify the access target drive. (Page 192 Drive No.)

Date to change, time to change

The file of the last edit date and time is modified with the specified date and time. (Page 200 Creation date and time (last edit date and time))

Number of file name characters, file name

Specify the file name to modify attribute. (Page 196 File name specification)
Communication example (files for MELSEC-Q series)

Modify the date and time of file creation under the following conditions.

- Drive No.: 0
- Date to change: 2010/04/01
- Time to change: 20:50:58
- File name: ABC.QPG

### Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand (Fixed value)</th>
<th>Drive No.</th>
<th>Date to change</th>
<th>Time to change</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 6 0 0 0 0 0 0 0 0</td>
<td>0 0 0 0 0</td>
<td>3 C 8 1 A 6 5 D</td>
<td>...</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 7</td>
<td>A B C . Q P G</td>
</tr>
</tbody>
</table>

### Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand (Fixed value)</th>
<th>Drive No.</th>
<th>Date to change</th>
<th>Time to change</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>26 1</td>
<td>00 0 0 0</td>
<td>00 0 0 0</td>
<td>00 0 0 0</td>
<td>0 0 0 0 3</td>
<td>A B C . Q P G</td>
</tr>
</tbody>
</table>

...
Communication example (files for MELSEC iQ-R series)

Modify the date and time of file creation under the following conditions.

- Drive No.: 4
- Date to change: 2010/04/01
- Time to change: 20:50:58

The file name is as shown below.
(1) LINE.CSV (8 characters)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>L  I  N  E  .  C  S  V</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C 0049 004E 0045 002E 0043 0053 0056</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443 30303439 30303445 30303435 30303245 30303433 30303533 30303536</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00 4900 4E00 4500 2E00 4300 5300 5600</td>
</tr>
</tbody>
</table>

■ Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>(Fixed value)</th>
<th>Drive No.</th>
<th>Date to change</th>
<th>Time to change</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 6</td>
<td>0 0 4 0</td>
<td>0 0 0 4</td>
<td>3 C 8 1</td>
<td>A 6 5 D</td>
</tr>
<tr>
<td>0 0 8</td>
<td>(1)</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

■ Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>(Fixed value)</th>
<th>Drive No.</th>
<th>Date to change</th>
<th>Time to change</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>26h 18h</td>
<td>40h 50h</td>
<td>00h 00h</td>
<td>00h 00h</td>
<td>04h 00h</td>
<td>3Ch 50h 4Ch 08h 00h</td>
<td>(1)</td>
</tr>
</tbody>
</table>
Open file (command: 1827)

Open a file and lock the file so that the file contents are not modified from other devices.

The file is unlocked by any of the following.
• Close file (command: 182A)
• Restarting a module. (Resetting the CPU module, etc.)

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Password</th>
<th>Open mode</th>
<th>Drive No.</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
</table>

Response data

The file pointer No. is stored. (Page 202 File pointer No.)

Data specified by request data

Command

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q series</td>
<td>1 8 2 7</td>
<td>27 18</td>
</tr>
<tr>
<td>For MELSEC-L series</td>
<td>0 0 0 4</td>
<td>04 00</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0 0 4 0</td>
<td>40 00</td>
</tr>
</tbody>
</table>

Password

Specify the password of the access target file. (Page 189 Password)

Open mode

Specify whether the specified file is open for reading or for writing. (Page 204 Open mode)
• Open for read: 0000H
• Open for write: 0100H
- **Drive No.**
  Specify the access target drive. (Page 192 Drive No.)

- **Number of file name characters, file name**
  Specify the file name to be open. (Page 196 File name specification)

### Communication example (files for MELSEC-Q series)
Open the file of QCPU in the following conditions.
- **Password**: 1234
- **Drive No.**: 0
- **File name**: ABC.QPG
- **Open mode**: Open for write

#### Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password</th>
<th>Open mode</th>
<th>Drive No.</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>18</td>
<td>2</td>
<td>7</td>
<td>0 0 0 0</td>
<td></td>
</tr>
<tr>
<td>31h</td>
<td>38h</td>
<td>32h</td>
<td>37h</td>
<td>30h 30h 30h 30h</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>12</td>
<td>3</td>
<td>4</td>
<td>0 1 0 0</td>
<td></td>
</tr>
<tr>
<td>30h 31h</td>
<td>33h 34h</td>
<td>30h 30h</td>
<td>30h 30h</td>
<td>30h 30h 30h 30h</td>
<td></td>
</tr>
<tr>
<td>0</td>
<td>0 0 0</td>
<td>7</td>
<td>A</td>
<td>B</td>
<td></td>
</tr>
<tr>
<td>41h 42h</td>
<td>43h 44h</td>
<td>2En 51h</td>
<td>50h 47h</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

File pointer No.

- **Drive No.**

#### Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password</th>
<th>Open mode</th>
<th>Drive No.</th>
<th>Number of file name characters</th>
<th>File name</th>
</tr>
</thead>
<tbody>
<tr>
<td>27h</td>
<td>18h</td>
<td>00h</td>
<td>1</td>
<td>2 3 4</td>
<td></td>
</tr>
<tr>
<td>31h</td>
<td>32h</td>
<td>33h</td>
<td>34h</td>
<td>00h 01h</td>
<td></td>
</tr>
<tr>
<td>00h 00h</td>
<td>07h 00h</td>
<td>A</td>
<td>B</td>
<td>C</td>
<td></td>
</tr>
<tr>
<td>41h 42h</td>
<td>43h 44h</td>
<td>2En 51h</td>
<td>50h 47h</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

File pointer No.
Communication example (files for MELSEC-L series)

Open the file of LCPU in the following condition.
- Password: AbCd1234□□□□ (24 spaces, code: 20H)
- Drive No.: 0
- File name: MAIN.QPG
- Open mode: Open for write

■ Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password (fixed to 32 characters)</th>
<th>Open mode</th>
<th>Drive No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 7</td>
<td>0 0 0 4 A b C d 1 2 3 4</td>
<td>0 1 0 0</td>
<td>0 0 0 0</td>
</tr>
</tbody>
</table>

Number of file name characters File name
0 0 0 8 MAIN.QPG

(Response data)

File pointer No.

0 0 0 0

■ Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Password (fixed to 32 characters)</th>
<th>Open mode</th>
<th>Drive No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>27 18</td>
<td>06 00 A b C d 1 2 3 4</td>
<td>00 00</td>
<td>MAIN.QPG</td>
</tr>
</tbody>
</table>

Number of file name characters File name
20 08 00 20 08 00 50 06 47
Communication example (files for MELSEC iQ-R series)

Open a file of MELSEC iQ-R series CPU module.
- Password: A to Z (26 characters)
- Drive No.: 4
- Open mode: Open for write

The file name is as follows:
(1) LINE.CSV (8 characters)

<table>
<thead>
<tr>
<th>Item</th>
<th>Value of code corresponds to character</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>L</td>
</tr>
<tr>
<td>UTF-16</td>
<td>004C</td>
</tr>
<tr>
<td>ASCII code</td>
<td>30303443</td>
</tr>
<tr>
<td>Binary code</td>
<td>4C00</td>
</tr>
</tbody>
</table>

Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Number of password characters</th>
<th>Password</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 7</td>
<td>0 0 4 0</td>
<td>A B C D</td>
</tr>
<tr>
<td>31 38 32 37</td>
<td>30 30 34 30</td>
<td>... Z</td>
</tr>
</tbody>
</table>

Open mode | Drive No. | Number of file name characters | File name |
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 0 0</td>
<td>0 0 0 4</td>
<td>0 0 0 8</td>
<td>(1)</td>
</tr>
</tbody>
</table>

(Response data)

File pointer No.

0 0 0 0
30 30 30 30

Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Number of password characters</th>
<th>Password</th>
</tr>
</thead>
<tbody>
<tr>
<td>27 18</td>
<td>A B C D</td>
<td>... Z</td>
</tr>
<tr>
<td>40 20 1</td>
<td>41 42 43 44</td>
<td>34</td>
</tr>
</tbody>
</table>

Open mode | Drive No. | Number of file name characters | File name |
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 1</td>
<td>0 0 0 0</td>
<td>0 0 0 0</td>
<td>(1)</td>
</tr>
</tbody>
</table>

(Response data)

File pointer No.

0 0 0
Read file (command: 1828)

Read the content of a file.
Use the open/close command in order to prohibit access from other devices when this command is used.

Message format

The following shows the message format of the request data and response data of the command.

- **Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>File pointer No.</th>
<th>Offset address</th>
<th>Number of bytes read</th>
</tr>
</thead>
</table>

- **Response data**

The data which have been read is stored.

<table>
<thead>
<tr>
<th>Number of bytes read</th>
<th>Read data</th>
</tr>
</thead>
</table>

Data specified by request data

- **Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 8</td>
<td>28 18</td>
</tr>
</tbody>
</table>

- **Sub command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
</tbody>
</table>

- **File pointer No.**

Specify the file pointer No. obtained with the 'open file' (command: 1827). (Page 202 File pointer No.)

- **Offset address**

Specify the start address to start reading. (Page 202 Offset address)

- **Number of bytes read**

Specify the number of bytes to be read from file in the range of 0 to 1920. (Page 203 Number of bytes)
Specify it as one address/one byte.

When the file size is 1921 bytes or more, use an offset address and read data divide into multiple steps. The file size can be checked by reading directory/file information (command: 1810). (Page 205 Read directory/file information (command: 1810)

Data stored in response data

- **Number of bytes read**

The number of data bytes read from file is stored. (Page 203 Number of bytes)

- **Read data**

The contents of the read file are stored.
Communication example

Read the file under the following conditions:
• File pointer No.: 0
• Number of bytes read: 1K bytes

■ Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>File pointer No.</th>
<th>Offset address</th>
<th>Number of bytes read</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 8</td>
<td>0 0 0 0</td>
<td>0 0 0 0</td>
<td>0 0 0 0</td>
</tr>
</tbody>
</table>

(Response data)
Number of bytes read  Read data
30 34 33 30 (Contents of a file)

■ Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>File pointer No.</th>
<th>Subcommand</th>
<th>Offset address</th>
<th>Number of bytes read</th>
</tr>
</thead>
<tbody>
<tr>
<td>28 18</td>
<td>00 00 00</td>
<td>00 00 00</td>
<td>00 00 04</td>
</tr>
</tbody>
</table>

(Response data)
Number of bytes read  Read data
00 04 (Contents of a file)
Write to file (command: 1829)

Write contents to a file. Use the open/close command in order to prohibit access from other devices when this command is used.

**Restriction**

When this command is executed to files of parameter and a program being executed, place CPU module in the STOP status. (Page 457 Commands that cannot be executed during RUN)

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>File pointer No.</th>
<th>Offset address</th>
<th>Number of bytes written</th>
<th>Write data</th>
</tr>
</thead>
</table>

**Response data**

The number of data bytes written in the file is stored. (Page 203 Number of bytes)

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 9</td>
<td>29h, 18h</td>
</tr>
</tbody>
</table>

**Sub command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00h, 00h</td>
</tr>
</tbody>
</table>

**File pointer No.**

Specify the file pointer No. obtained with the 'open file' (command: 1827). (Page 202 File pointer No.)

**Offset address**

Specify the start address to start writing. (Page 202 Offset address)

- Writing data to a file of which drive name is ‘00H’ (program memory): Specify the address in multiples of 4 (0, 4, 8,... in decimal notation).
- Writing data to a file of which drive name is other than ‘00H’: Specify the addresses in even numbered addresses (0, 2, 4, 6, 8,... in decimal notation).

**Number of bytes written**

Specify the number of bytes to be written to a file in the range of 0 to 1920. (Page 203 Number of bytes)

Specify it as one address/one byte.

**Point**

Write data to the file within the file size reserved by creating new file.

When the file size is 1921 bytes or more, use an offset address and write data divide into multiple steps. The file size can be checked by reading directory/file information (command: 1810).

Page 205 Read directory/file information (command: 1810)
■ Write data
Specify the data to be written to a file.

Communication example
Write the file under the following conditions:
• File pointer No.: 0
• Offset address: 0
• Number of bytes written: 1K byte

■ Data communication using ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>File pointer No.</th>
<th>Offset address</th>
<th>Number of bytes written</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>8</td>
<td>2</td>
<td>0</td>
<td>9</td>
</tr>
<tr>
<td>31a</td>
<td>38a</td>
<td>32m</td>
<td>39m</td>
<td>0</td>
</tr>
<tr>
<td>30a</td>
<td>31a</td>
<td>30a</td>
<td>30a</td>
<td>30a</td>
</tr>
<tr>
<td>30a</td>
<td>30a</td>
<td>30a</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>4</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>

(Contents of a file)

(Response data)
Number of bytes written

0 4 0 0

30a 34a 30a 30a

■ Data communication using binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>File pointer No.</th>
<th>Offset address</th>
<th>Number of bytes written</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>29a</td>
<td>18a</td>
<td>00a</td>
<td>00a</td>
<td>00a</td>
</tr>
<tr>
<td>00a</td>
<td>00a</td>
<td>00a</td>
<td>00a</td>
<td>00a</td>
</tr>
<tr>
<td>00a</td>
<td>00a</td>
<td>04a</td>
<td>(Contents of a file)</td>
<td></td>
</tr>
</tbody>
</table>

(Response data)
Number of bytes written

00a 04a
Close file (command: 182A)

Close a file and unlock the file which has been locked by the 'open file' (command: 1827).

Message format

The following shows the message format of the request data and response data of the command.

■Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>File pointer No.</th>
<th>Close type</th>
</tr>
</thead>
</table>

■Response data

There is no response data for this command.

Data specified by request data

■Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1824A</td>
<td>2A018</td>
</tr>
</tbody>
</table>

■Sub command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000</td>
<td>00000000</td>
</tr>
</tbody>
</table>

■File pointer No.

Specify the file pointer No. obtained with the 'open file' (command: 1827). (Page 202 File pointer No.)

■Close type

Specify the file to be closed. (Page 204 Close type)

When closing a file specified by file pointer, specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000</td>
<td>00000000</td>
</tr>
</tbody>
</table>

The locked files which have been opened by other devices cannot be unlocked.

Executing the command to files which have been opened by the other external device results in abnormal completion of the command.

Files are closed by restarting a module (such as resetting CPU module).
Communication example

Close the file under the following conditions:

- File pointer No.: 0
- Close type: 2

■ Data communication using ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>File pointer No.</th>
<th>Close type</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 8 2 A</td>
<td>00 00 0</td>
<td>00 00 2</td>
</tr>
</tbody>
</table>

■ Data communication using binary code

(Request data)

<table>
<thead>
<tr>
<th>File pointer No.</th>
<th>Close type</th>
</tr>
</thead>
<tbody>
<tr>
<td>2A 18</td>
<td>02 00</td>
</tr>
</tbody>
</table>
13 SERIAL COMMUNICATION MODULE
DEDICATED COMMANDS

This chapter explains the dedicated commands for serial communication module.

13.1 User Frame

A user frame is a data name which is used to send/receive data by registering the fixed format portion in a message to be communicated between an external device and serial communication module.

Control code or sum check code in the message are registered as a default registration frame. The data such as an access route can be registered to the user frame. By using the user frame, the following data communication can be performed.

• Transmission of on-demand data by MC protocol
• Data communication by nonprocedural protocol

This section explains the commands for an external device to register, delete, and read user frames to C24. For transmission and reception of data using a user frame, refer to the following manual.

MELSEC-Q/L Serial Communication Module User's Manual (Application)
MELSEC iQ-R Serial Communication Module User's Manual (Application)

Restriction

The command can only be used for C24 (including multidrop connection station) connected to the external device. It cannot be used via network.

Point

This command is processed by the connected C24/E71 without waiting for the END processing by CPU module.
Data to be specified in command

This section explains the contents and specification methods for data items which are set in each command related to the user frame.

**Frame No.**

Specify the number of target user frame.

<table>
<thead>
<tr>
<th>Type</th>
<th>Setting value</th>
<th>Registration destination</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Default registration frame</td>
<td>1H to 3E7H</td>
<td>ROM for C24 operating system</td>
<td>Read only</td>
</tr>
<tr>
<td>User frame</td>
<td>3E8H to 4AFH</td>
<td>Flash ROM of C24</td>
<td>Read, write, delete</td>
</tr>
<tr>
<td></td>
<td>8001H to 801FH</td>
<td>Buffer memory of C24 (addresses 1B00H to 1FF6H)</td>
<td>Read, write, delete</td>
</tr>
</tbody>
</table>

**Data communication in ASCII code**

Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

**Data communication in binary code**

Send 2-byte numerical values from lower byte (L: bits 0 to 7).

**Ex**

For 3E8H

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 3 E 8</td>
<td>E8 03</td>
</tr>
</tbody>
</table>

**Number of registration data byte, number of frame byte**

Specify the number of bytes of registration data.

<table>
<thead>
<tr>
<th>Function</th>
<th>Setting value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Data registration, read data</td>
<td>1H to 50H (1 to 80)</td>
</tr>
<tr>
<td>Deletion</td>
<td>0H</td>
</tr>
</tbody>
</table>

For the number of registration data byte, calculate the variable data as 2 bytes.

For the number of frame byte, calculate the variable data as 1 byte.

For the variable data, refer to the following manuals.

- MELSEC-Q/L Serial Communication Module User’s Manual (Application)
- MELSEC iQ-R Serial Communication Module User’s Manual (Application)

**Data communication in ASCII code**

Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

**Data communication in binary code**

Send 2-byte numerical values from lower byte (L: bits 0 to 7).

**Ex**

When the registration data is ETX + variable data (sum check code) + CR + LF

Number of registration data byte = 1-byte (ETX) + 2-byte (variable data) + 1-byte (CR) + 1-byte (LF) = 5

Number of frame byte = 1-byte (ETX) + 1-byte (variable data) + 1-byte (CR) + 1-byte (LF) = 4

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of registration data byte</td>
<td>0 0 0 5</td>
<td>05 00</td>
</tr>
<tr>
<td></td>
<td>30H, 30H, 30H, 35H</td>
<td></td>
</tr>
<tr>
<td>Number of frame byte</td>
<td>0 0 0 4</td>
<td>04 00</td>
</tr>
<tr>
<td></td>
<td>30H, 30H, 30H, 34H</td>
<td></td>
</tr>
</tbody>
</table>
Registration data

The following shows the content of data in a user frame.

**Data communication in ASCII code**
Convert the data to 2-digit (hexadecimal) ASCII code and send it from upper digit.

**Data communication in binary code**
Send data from the first frame.

**Ex.**
When the registration data is ETX + Variable data (sum check code) + CR + LF

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>ETX 3 FF F F 1 0 D 0 A</td>
<td>ETX 3 FF FF 00 00</td>
</tr>
<tr>
<td>30h, 33h, 46h, 46h, 31h, 30h, 44h, 30h, 41h</td>
<td></td>
</tr>
</tbody>
</table>
Read registered data (command: 0610)

Read the registered content of user frames.

**Message format**
The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Frame No.</th>
</tr>
</thead>
</table>

**Response data**
The read registration data is stored.

<table>
<thead>
<tr>
<th>Registration data byte count</th>
<th>Frame byte count</th>
<th>Registration data</th>
</tr>
</thead>
</table>

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code*1</th>
</tr>
</thead>
<tbody>
<tr>
<td>06 10</td>
<td>D0 0E 10 06</td>
</tr>
</tbody>
</table>

*1 For C24, an additional code is added. (Page 33 Additional code (10H))

**Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>00 00 00</td>
<td>00 00</td>
</tr>
</tbody>
</table>

**Frame No.**
Specify the number of user frame to be read. (Page 241 Frame No.)

<table>
<thead>
<tr>
<th>Type</th>
<th>Setting value</th>
<th>Registration destination</th>
</tr>
</thead>
<tbody>
<tr>
<td>Default registration frame</td>
<td>1H to 3E7H</td>
<td>ROM for C24 operating system</td>
</tr>
<tr>
<td>User frame</td>
<td>3E8H to 4AFH</td>
<td>Flash ROM of C24</td>
</tr>
<tr>
<td></td>
<td>8001H to 801FH</td>
<td>Buffer memory of C24 (addresses 1B00H to 1FF6H)</td>
</tr>
</tbody>
</table>

**Point**
When the frame No. whose user frame is not registered is specified, an error occurs and an abnormal response is returned.

**Data to be stored by response data**

**Number of registration data byte, number of frame byte**
The data byte count of the registration data is stored. (Page 241 Number of registration data byte, number of frame byte)

**Registration data**
The data content of user frames to be registered is stored. (Page 242 Registration data)
## Example for data communication

Read the following registration data from frame No. 3E8H.
Registration data: ETX + Variable data (sum check code) + CR + LF

### Data communication in ASCII code

#### Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Frame No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>6</td>
<td>1</td>
</tr>
<tr>
<td>30h</td>
<td>36h</td>
<td>31h</td>
</tr>
<tr>
<td>30h</td>
<td>30h</td>
<td>30h</td>
</tr>
<tr>
<td>30h</td>
<td>38h</td>
<td>45h</td>
</tr>
<tr>
<td>38h</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

#### Response data

<table>
<thead>
<tr>
<th>Number of registration data byte</th>
<th>Number of frame byte</th>
<th>ETX</th>
<th>Variable data</th>
<th>CR</th>
<th>LF</th>
</tr>
</thead>
<tbody>
<tr>
<td>30h</td>
<td>30h</td>
<td>0</td>
<td>0</td>
<td>3</td>
<td>F</td>
</tr>
<tr>
<td>30h</td>
<td>30h</td>
<td>0</td>
<td>0</td>
<td>3</td>
<td>F</td>
</tr>
<tr>
<td>30h</td>
<td>30h</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>D</td>
</tr>
<tr>
<td>30h</td>
<td>30h</td>
<td>0</td>
<td>0</td>
<td>A</td>
<td></td>
</tr>
</tbody>
</table>

### Data communication in binary code

#### Request data

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Frame No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>10b</td>
<td>10b</td>
</tr>
<tr>
<td>00b</td>
<td>00b</td>
</tr>
<tr>
<td>38b</td>
<td>03b</td>
</tr>
</tbody>
</table>

#### Response data

<table>
<thead>
<tr>
<th>Number of registration data byte</th>
<th>Number of frame byte</th>
<th>ETX</th>
<th>Variable data</th>
<th>CR</th>
<th>LF</th>
</tr>
</thead>
<tbody>
<tr>
<td>30h</td>
<td>30h</td>
<td>0</td>
<td>0</td>
<td>3</td>
<td>F</td>
</tr>
<tr>
<td>04h</td>
<td>00h</td>
<td>03h</td>
<td>FFh</td>
<td>00h</td>
<td></td>
</tr>
<tr>
<td>00h</td>
<td>00h</td>
<td>04h</td>
<td>00h</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Registration data
Register user frames to C24.

Restriction

For MELSEC iQ-R series, the user frame is replaced with the contents registered using module extended parameters by powering OFF → ON or switching the CPU module STOP → RUN. For more information on user frame registration using module extended parameters, refer to the following manual. MELSEC iQ-R Serial Communication Module User’s Manual (Application)

Point

When registering a user frame with the same frame No. again, deleted the user frame first and registered again. If it is attempted to register a user frame by specifying an already registered frame No., an error occurs and an abnormal response is returned.

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Frame No.</th>
<th>Number of registration data byte</th>
<th>Number of frame byte</th>
<th>Registration data</th>
</tr>
</thead>
</table>

Response data

There is no response data for this command.

Data specified by request data

Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code*1</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 1 0</td>
<td>01 00 10</td>
</tr>
</tbody>
</table>

*1 For C24, an additional code is added. (Page 33 Additional code (10H))

Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
</tbody>
</table>

Frame No.

Specify the number of user frame to be registered. (Page 241 Frame No.)

<table>
<thead>
<tr>
<th>Type</th>
<th>Setting value</th>
<th>Registration destination</th>
</tr>
</thead>
<tbody>
<tr>
<td>User frame</td>
<td>3E8H to 4AFH</td>
<td>Flash ROM of C24</td>
</tr>
<tr>
<td></td>
<td>8001H to 801FH</td>
<td>Buffer memory of C24 (addresses 1B00H to 1FF6H)</td>
</tr>
</tbody>
</table>

Number of registration data byte, number of frame byte

Specify the byte count of registration data within the range of 1 to 80. (Page 241 Number of registration data byte, number of frame byte)

Registration data

Store the content of user frame data to be registered. (Page 242 Registration data)
### Example for data communication

Register the following data in frame No. 3E8H.
Registration data: ETX + Variable data (sum check code) + CR + LF

#### Data communication in ASCII code
(Receive data)

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Frame No.</th>
<th>Number of registration data byte</th>
<th>Number of frame byte</th>
<th>ETX</th>
<th>Variable data</th>
<th>CR</th>
<th>LF</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>6</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>3E</td>
<td>0</td>
<td>0</td>
<td>OA</td>
</tr>
<tr>
<td>31h</td>
<td>36h</td>
<td>31h</td>
<td>0</td>
<td>0</td>
<td>3E</td>
<td>FF</td>
<td>1</td>
<td>0D</td>
</tr>
</tbody>
</table>

#### Data communication in binary code
(Receive data)

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Frame No.</th>
<th>Number of registration data byte</th>
<th>Number of frame byte</th>
<th>ETX</th>
<th>Variable data</th>
<th>CR</th>
<th>LF</th>
</tr>
</thead>
<tbody>
<tr>
<td>10h</td>
<td>10h</td>
<td>16h</td>
<td>0</td>
<td>0</td>
<td>FF</td>
<td>FF</td>
<td>1</td>
<td>0D</td>
</tr>
</tbody>
</table>

Registration data
Delete registered data (command: 1610)

Delete the registered user frame.

**Message format**
The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Frame No.</th>
<th>Number of registration data byte</th>
<th>Number of frame byte</th>
</tr>
</thead>
</table>

**Response data**
There is no response data for this command.

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 1 0</td>
<td>&quot;DLE&quot;</td>
</tr>
</tbody>
</table>

*1 For C24, an additional code is added. ([Page 33](#) Additional code (10H))

**Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 1</td>
<td>01h, 00h</td>
</tr>
</tbody>
</table>

**Frame No.**
Specify the number of user frame to be deleted. ([Page 241](#) Frame No.)

<table>
<thead>
<tr>
<th>Type</th>
<th>Setting value</th>
<th>Registration destination</th>
</tr>
</thead>
<tbody>
<tr>
<td>User frame</td>
<td>3E8H to 4AFH</td>
<td>Flash ROM of C24</td>
</tr>
<tr>
<td></td>
<td>8001H to 801FH</td>
<td>Buffer memory of C24 (addresses 1B00H to 1FF6H)</td>
</tr>
</tbody>
</table>

**Point**
When the frame No. whose user frame is not registered is specified, an error occurs and an abnormal response is returned.

**Number of registration data byte, number of frame byte**
Specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00h, 00h</td>
</tr>
</tbody>
</table>
Delete the registration data of frame No. 3E8H.

**Data communication in ASCII code**

(Example for data communication)

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Frame No.</th>
<th>Number of registration data byte</th>
<th>Number of frame byte</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>6</td>
<td>10</td>
<td>0 0 0 1</td>
<td>0 0 0 0</td>
</tr>
</tbody>
</table>

**Data communication in binary code**

(Example for data communication)

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Frame No.</th>
<th>Number of registration data byte</th>
<th>Number of frame byte</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>10</td>
<td>16</td>
<td>0 1 0 0</td>
<td>0 0 0 0</td>
</tr>
</tbody>
</table>
13.2 Global Function

The global function is a function to turn ON/OFF the global signals (input signals: X1A/X1B) of serial communication module connected to external devices with the multidrop communications. This is used as interlock signals for emergency command, simultaneous startup, and applicability of data transmission/reception to CPU modules.

**Restriction**

The command can only be used for C24 (including multidrop connection station) connected to the external device. It cannot be used via network.

**Point**

The global signal is turned OFF by powering OFF, resetting, or switching the mode of CPU module.

### Compatibility with global function of Computer link module

This function (command: 1618) is compatible with GW command for dedicated protocol of Computer link module.

- **Operation of serial communication module when GW command is received**
  When GW command is executed from Computer link module connected with the multidrop connection, the global signal (input signal: X1A/X1B) at the side where the command was received turns ON/OFF.
  - Received from CH1: X1A
  - Received from CH2: X1B

- **Command: Operation of computer link module when 1618 is received**
  When this function (command: 1618) is used to Computer link module, the global signal (input signal: X2) of Computer link module turns ON/OFF.
**Global signal ON/OFF (command: 1618)**

Turn ON/OFF the global signal from an external device.

### Message format

The following shows the message format of the request data and response data of the command.

#### Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Global signal specification</th>
</tr>
</thead>
</table>

#### Response data

There is no response data for this command.

### Data specified by request data

#### Command

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>OFF</td>
<td>1618</td>
<td>1618</td>
</tr>
</tbody>
</table>

#### Subcommand

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>OFF</td>
<td>0000</td>
<td>0000</td>
</tr>
<tr>
<td>ON</td>
<td>0001</td>
<td>0100</td>
</tr>
</tbody>
</table>

#### Global signal specification

Specify which global signal (X1A or X1B) is turned ON/OFF.

<table>
<thead>
<tr>
<th>Global signal to be turned ON/OFF</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
</table>
| Global signal at the side where command was received  
  * Received from CH1: X1A  
  * Received from CH2: X1B | 0000       | 0000        |
| X1A regardless of the interface  
  | 0001       | 0100        |
| X1B regardless of the interface  
  | 0002       | 0010        |

---

**Point**

The target station (all stations/only 1 specified station) of which global signal is turned ON/OFF is specified by a station No.

Page 48 Station No.
Communication example (turn ON)
Turn the global signal X1A ON.

■ Data communications in ASCII code (Format 1)
(Request data)

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Global signal specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 1 8</td>
<td>0 0 0 1</td>
<td>0 0 0 1</td>
</tr>
</tbody>
</table>

■ Data communications in binary code (Format 5)
(Request data)

Communication example (turn OFF)
Turn OFF the global signal X1A.

■ Data communications in ASCII code (Format 1)
(Request data)

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Global signal specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 1 8</td>
<td>0 0 0 0</td>
<td>0 0 0 1</td>
</tr>
</tbody>
</table>

■ Data communications in binary code (Format 5)
(Request data)
13.3 Transmission sequence initialization function

The transmission sequence initialization function is a function to initialize the transmission sequence of data communication using format 5 of 4C frame, and to place C24 into the state where it waits to receive commands from external devices.

**Restriction**

The command can only be used for C24 (including multidrop connection station) connected to the external device. It cannot be used via network.

**Initialize transmission sequence (command: 1615)**

Initialize the transmission sequence of data communication using format 5 of 4C frame, and make C24 wait to receive commands from external devices.

This function is equivalent to EOT, CL during data communication in ASCII code. Use the control codes, EOT, CL during data communication in ASCII code. ([Page 32 EOT(04H), CL(0CH)]

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
</tr>
</thead>
</table>

**Response data**

There is no response data for this command.

**Data specified by request data**

**Command**

**Binary code**

| 15 | 16 |

**Subcommand**

**Binary code**

| 00 | 00 |

**Example for data communication**

Initialize transmission sequence.

(Request data)

```
  15 16 00 00
```
13.4 Mode Switching Function

The mode switching function is a function to switch the current communication protocol (operation mode) or transmission specification for the specified interface from external devices after C24 starts up. For more details on the mode switching function, refer to the following manuals.

- MELSEC-Q/L Serial Communication Module User's Manual (Application)
- MELSEC iQ-R Serial Communication Module User's Manual (Application)

Restriction

The command can only be used for C24 (including multidrop connection station) connected to the external device. It cannot be used via network.

Data to be specified in command

This section explains the contents and specification method for data item which is set in the command to switch mode.

Channel No.

Specify the target interface.

<table>
<thead>
<tr>
<th>Target interface</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>CH1</td>
<td>0 1</td>
<td>01x</td>
</tr>
<tr>
<td>CH2</td>
<td>0 2</td>
<td>02x</td>
</tr>
</tbody>
</table>

Switching instruction

Select which specify the contents to be switched, by data in the command or by Engineering tool.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Item</th>
<th>Setting of Engineering tool</th>
<th>OFF (0)</th>
<th>ON (1)</th>
</tr>
</thead>
<tbody>
<tr>
<td>b0</td>
<td>Mode No.</td>
<td>Communication protocol setting</td>
<td>Specified by Engineering tool</td>
<td>Specified by command</td>
</tr>
<tr>
<td>b1</td>
<td>Transmission setting</td>
<td>Transmission setting</td>
<td>Off (0)</td>
<td>On (1)</td>
</tr>
<tr>
<td>b2</td>
<td>Communication speed setting</td>
<td>Communication speed setting</td>
<td>Off (0)</td>
<td>On (1)</td>
</tr>
<tr>
<td>b3 to b7</td>
<td>(Fixed to '0')</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Data communication in ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Data communication in binary code

Send 1-byte numerical values from lower byte (L: bits 0 to 7).

Ex.
When the switching instruction is '1' (Only mode No. is specified by command)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1</td>
<td>01x</td>
</tr>
</tbody>
</table>
Specify the communication protocol setting after switching the C24 mode.

### Mode No.

<table>
<thead>
<tr>
<th>Mode No.</th>
<th>Operation mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>01H</td>
<td>MC Protocol (Format 1)</td>
</tr>
<tr>
<td>02H</td>
<td>MC Protocol (Format 2)</td>
</tr>
<tr>
<td>03H</td>
<td>MC Protocol (Format 3)</td>
</tr>
<tr>
<td>04H</td>
<td>MC Protocol (Format 4)</td>
</tr>
<tr>
<td>05H</td>
<td>MC Protocol (Format 5)</td>
</tr>
<tr>
<td>06H</td>
<td>Nonprocedural protocol</td>
</tr>
<tr>
<td>07H</td>
<td>Bidirectional protocol</td>
</tr>
<tr>
<td>09H</td>
<td>Predefined protocol</td>
</tr>
<tr>
<td>FFH</td>
<td>MELSOFT connection, GX Developer connection</td>
</tr>
</tbody>
</table>

**Data communication in ASCII code**

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

**Data communication in binary code**

Send 1-byte numerical values from lower byte (L: bits 0 to 7).

**Ex.**

When mode No. is '1' (MC protocol (Format 1))

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>[0, 1]</td>
<td>01</td>
</tr>
</tbody>
</table>
Transmission setting

Specify the transmission setting after switching the C24 mode.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Item</th>
<th>OFF (0)</th>
<th>ON (1)</th>
</tr>
</thead>
<tbody>
<tr>
<td>b0</td>
<td>Operation setting</td>
<td>Independent</td>
<td>Interlink</td>
</tr>
<tr>
<td>b1</td>
<td>Data bit</td>
<td>7</td>
<td>8</td>
</tr>
<tr>
<td>b2</td>
<td>Parity bit</td>
<td>None</td>
<td>Yes</td>
</tr>
<tr>
<td>b3</td>
<td>Odd/even parity</td>
<td>Odd</td>
<td>Even</td>
</tr>
<tr>
<td>b4</td>
<td>Stop bit</td>
<td>1</td>
<td>2</td>
</tr>
<tr>
<td>b5</td>
<td>Sum check code</td>
<td>None</td>
<td>Yes</td>
</tr>
<tr>
<td>b6</td>
<td>Online change</td>
<td>Disable</td>
<td>Enable</td>
</tr>
<tr>
<td>b7</td>
<td>Setting change</td>
<td>Disable</td>
<td>Enable</td>
</tr>
</tbody>
</table>

For the transmission setting, refer to the following manuals.

MELSEC iQ-R Serial Communication Module User’s Manual (Application)
MELSEC-Q/L Serial Communication Module User’s Manual (Application)

Data communication in ASCII code

Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

Data communication in binary code

Send 1-byte numerical values from lower byte (L: bits 0 to 7).

When the transmission settings are as follows:

<table>
<thead>
<tr>
<th>Bit</th>
<th>Item</th>
<th>Setting</th>
<th>ON/OFF</th>
</tr>
</thead>
<tbody>
<tr>
<td>b0</td>
<td>Operation setting</td>
<td>Independent</td>
<td>OFF</td>
</tr>
<tr>
<td>b1</td>
<td>Data bit</td>
<td>8</td>
<td>ON</td>
</tr>
<tr>
<td>b2</td>
<td>Parity bit</td>
<td>Yes</td>
<td>ON</td>
</tr>
<tr>
<td>b3</td>
<td>Odd/even parity</td>
<td>Odd</td>
<td>OFF</td>
</tr>
<tr>
<td>b4</td>
<td>Stop bit</td>
<td>1</td>
<td>OFF</td>
</tr>
<tr>
<td>b5</td>
<td>Sum check code</td>
<td>Yes</td>
<td>ON</td>
</tr>
<tr>
<td>b6</td>
<td>Online change</td>
<td>Enable</td>
<td>ON</td>
</tr>
<tr>
<td>b7</td>
<td>Setting change</td>
<td>Enable</td>
<td>ON</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>E 6</td>
<td>E5h</td>
</tr>
</tbody>
</table>
**Communication speed**

Specify the communication speed after switching the C24 mode.

<table>
<thead>
<tr>
<th>Specified value</th>
<th>Communication speed</th>
</tr>
</thead>
<tbody>
<tr>
<td>0FH</td>
<td>50bps</td>
</tr>
<tr>
<td>00H</td>
<td>300bps</td>
</tr>
<tr>
<td>01H</td>
<td>600bps</td>
</tr>
<tr>
<td>02H</td>
<td>1200bps</td>
</tr>
<tr>
<td>03H</td>
<td>2400bps</td>
</tr>
<tr>
<td>04H</td>
<td>4800bps</td>
</tr>
<tr>
<td>05H</td>
<td>9600bps</td>
</tr>
<tr>
<td>06H</td>
<td>14400bps</td>
</tr>
<tr>
<td>07H</td>
<td>19200bps</td>
</tr>
<tr>
<td>08H</td>
<td>28800bps</td>
</tr>
<tr>
<td>09H</td>
<td>38400bps</td>
</tr>
<tr>
<td>0AH</td>
<td>57600bps</td>
</tr>
<tr>
<td>0BH</td>
<td>115200bps</td>
</tr>
<tr>
<td>0CH</td>
<td>230400bps</td>
</tr>
</tbody>
</table>

**Point**

The communication speed that can be set differs depending on the module or channel. For the communication speed setting, refer to the following manuals.

- MELSEC iQ-R Serial Communication Module User's Manual (Application)
- MELSEC-Q/L Serial Communication Module User's Manual (Application)

**Data communication in ASCII code**

Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

**Data communication in binary code**

Send 1-byte numerical values from lower byte (L: bits 0 to 7).

**Ex**

For communication speed 05H (9600 bps)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>05</td>
<td>05</td>
</tr>
</tbody>
</table>
Switch mode (command: 1612)

Switch the C24 mode from external devices.

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Channel No.</th>
<th>Switching instruction</th>
<th>Mode No.</th>
<th>Transmission setting</th>
<th>Communication speed</th>
</tr>
</thead>
</table>

Response data

There is no response data for this command.

Data specified by request data

Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 1 2</td>
<td>12 16</td>
</tr>
</tbody>
</table>

Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 0</td>
</tr>
</tbody>
</table>

Channel No.

Specify the target interface (CH1/CH2). (Page 253 Channel No.)

Switching instruction

Select which specify the contents to be switched, by data in the command or by Engineering tool. (Page 253 Switching instruction)

〇: Specified by command, ー: Specified by Engineering tool

<table>
<thead>
<tr>
<th>Switching instruction</th>
<th>Mode No.</th>
<th>Transmission setting</th>
<th>Communication speed</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>ー</td>
<td>ー</td>
<td>ー</td>
</tr>
<tr>
<td>1</td>
<td>〇</td>
<td>ー</td>
<td>ー</td>
</tr>
<tr>
<td>2</td>
<td>ー</td>
<td>〇</td>
<td>ー</td>
</tr>
<tr>
<td>3</td>
<td>〇</td>
<td>〇</td>
<td>ー</td>
</tr>
<tr>
<td>4</td>
<td>ー</td>
<td>ー</td>
<td>〇</td>
</tr>
<tr>
<td>5</td>
<td>〇</td>
<td>ー</td>
<td>〇</td>
</tr>
<tr>
<td>6</td>
<td>ー</td>
<td>〇</td>
<td>〇</td>
</tr>
<tr>
<td>7</td>
<td>〇</td>
<td>〇</td>
<td>〇</td>
</tr>
</tbody>
</table>

Mode No.

Specify the operation mode within the range of 1H to 9H or FFH. (Page 254 Mode No.)

When the setting by command enabled (Switching instruction: 1, 3, 5, or 7), the operation mode is changed according to the specified value.

As for the setting by command is disabled (Switching instruction: 0, 2, 4, or 6), the operation mode is changed according to the Communication protocol setting set with Engineering tool.

Even when the setting by command is disabled, specify the value (1 to 9H or FFH). (Do not specify ‘0’.)
■ Transmission setting
Specify the transmission setting. (Page 255 Transmission setting)
When the setting by command is enabled (Switching instruction: 2, 3, 6, or 7), the transmission setting is changed according to the specified value.
As for the setting by command is disabled (Switching instruction: 0, 1, 4, or 5), the transmission setting is changed according to the transmission setting set with Engineering tool.
When the setting is invalid, specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 30h 30h</td>
<td>00h</td>
</tr>
</tbody>
</table>

■ Communication speed
Specify the communication speed. (Page 256 Communication speed)
When the setting by command is enabled (Switching instruction: 4, 5, 6, or 7), the communication speed is changed according to the specified value.
When the setting by command is disabled (Switching instruction: 0, 1, 2, or 3), the communication speed is changed according to the communication speed setting set with Engineering tool.
When the setting is invalid, specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 30h 30h</td>
<td>00h</td>
</tr>
</tbody>
</table>

Example for data communication
Perform mode switching for CH1 interface.
• Operation mode: MC protocol (Format 1) (Specified value: 01H)
• Operation setting: Following settings (Specified value: B0H)

<table>
<thead>
<tr>
<th>Item</th>
<th>Setting</th>
<th>Bit</th>
<th>ON/OFF</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operation setting</td>
<td>Independent</td>
<td>b0</td>
<td>OFF</td>
</tr>
<tr>
<td>Data bit</td>
<td>7</td>
<td>b1</td>
<td>OFF</td>
</tr>
<tr>
<td>Parity bit</td>
<td>None</td>
<td>b2</td>
<td>OFF</td>
</tr>
<tr>
<td>Odd/even parity</td>
<td>Odd</td>
<td>b3</td>
<td>OFF</td>
</tr>
<tr>
<td>Stop bit</td>
<td>2</td>
<td>b4</td>
<td>ON</td>
</tr>
<tr>
<td>Sum check code</td>
<td>Yes</td>
<td>b5</td>
<td>ON</td>
</tr>
<tr>
<td>Online change</td>
<td>Disable</td>
<td>b6</td>
<td>OFF</td>
</tr>
<tr>
<td>Setting change</td>
<td>Enable</td>
<td>b7</td>
<td>ON</td>
</tr>
</tbody>
</table>

• Communication speed: 9600bps (Specified value: 05H)

■ Data communication in ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Channel No.</th>
<th>Switching instruction</th>
<th>Mode No.</th>
<th>Transmission setting</th>
<th>Communication speed</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 6 1 2</td>
<td>0 0 0 0 0 0 0 1 0</td>
<td>0 1 0 7 0 1 8 0 0 5</td>
<td>31h 36h 31h 32h 30h 30h 30h 30h 30h</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Channel No.</th>
<th>Switching instruction</th>
<th>Mode No.</th>
<th>Transmission setting</th>
<th>Communication speed</th>
</tr>
</thead>
<tbody>
<tr>
<td>12x, 16x</td>
<td>00x, 00x</td>
<td>01x</td>
<td>07x</td>
<td>01x, 80x, 05x</td>
</tr>
</tbody>
</table>

- Command Subcommand:

12x, 16x
00x, 00x
01x
07x
01x
80x
05x
13.5 Programmable controller CPU monitoring function

Programmable controller CPU monitoring function is a function that C24 monitors CPU module with the monitoring information which was registered in advance.

For the Programmable controller CPU monitoring function, refer to the following manuals.

- MELSEC iQ-R Serial Communication Module User's Manual (Application)
- MELSEC-Q/L Serial Communication Module User's Manual (Application)

**Restriction**

The command can only be used for C24 (including multidrop connection station) connected to the external device. It cannot be used via network.

### Data to be specified in command

#### Cycle time units

Specify the unit of cycle time.

<table>
<thead>
<tr>
<th>Time unit</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>100 ms</td>
<td>0 0</td>
<td>00h</td>
</tr>
<tr>
<td>1 second</td>
<td>0 1</td>
<td>01h</td>
</tr>
<tr>
<td>1 minute</td>
<td>0 2</td>
<td>02h</td>
</tr>
</tbody>
</table>

#### Cycle time

Specify the time interval (period for 1 cycle) that C24 reads the monitoring information from CPU module.

- **Data communication in ASCII code**
  Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

- **Data communication in binary code**
  Send 2-byte numerical values from lower byte (L: bits 0 to 7).

#### Programmable controller CPU monitoring function

Specify the send timing (fixed cycle send/condition match send) of the monitoring result.

<table>
<thead>
<tr>
<th>Programmable controller CPU monitoring function</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Fixed cycle send</td>
<td>0 1</td>
<td>01h</td>
</tr>
<tr>
<td>(Sending information in the cycle time interval.)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Condition match send</td>
<td>0 2</td>
<td>02h</td>
</tr>
<tr>
<td>(Sending information when the specified condition matches.)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
CPU error monitoring, CPU status information

Specify whether to perform error monitoring for the host station CPU module.

<table>
<thead>
<tr>
<th>CPU error monitoring</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Do not perform error monitoring for the host station CPU module.</td>
<td>0 0 30h, 30h</td>
<td></td>
</tr>
<tr>
<td>Perform error monitoring for the host station CPU module.</td>
<td>0 1 30h, 31h</td>
<td>31h</td>
</tr>
</tbody>
</table>

When the error monitoring is performed, the CPU monitoring result is stored in the response data as a CPU status information.

The following values are stored in the CPU status information.

<table>
<thead>
<tr>
<th>Specified value</th>
<th>CPU status</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000H</td>
<td>During normal operation</td>
</tr>
<tr>
<td>0001H</td>
<td>Module warning occurring</td>
</tr>
<tr>
<td>0002H</td>
<td>Module error/module system error occurring</td>
</tr>
</tbody>
</table>

■Data communication in ASCII code

Convert the numerical value to 4-digit ASCII code (hexadecimal) and store it in the 'Device Data' in the following format from upper digits.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Device data</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 30h, 31h</td>
<td></td>
</tr>
</tbody>
</table>

■Data communication in binary code

Store the 2-byte numerical values in the 'Device Data' in the following format from lower byte (L: bits 0 to 7).

<table>
<thead>
<tr>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0101H</td>
</tr>
</tbody>
</table>

Monitoring condition

When 'fixed cycle send' is specified with the programmable controller CPU monitoring function, specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td></td>
</tr>
</tbody>
</table>

When 'condition match send' is specified with the Programmable controller CPU monitoring function, specify the value below. The timing to send the result can be selected.

- Edge trigger transmission: Send the result when the condition matches.
- Level trigger transmission: Send the result in the cycle time interval during the condition matches

<table>
<thead>
<tr>
<th>Edge trigger transmission</th>
<th>Level trigger transmission</th>
<th>Monitoring condition</th>
<th>Device type that can be specified</th>
</tr>
</thead>
<tbody>
<tr>
<td>0001H</td>
<td>0101H</td>
<td>ON/OFF status of device = ON/OFF status of monitoring condition</td>
<td>Bit device</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Device value = Monitoring condition value</td>
<td>Word device</td>
</tr>
<tr>
<td>0002H</td>
<td>0102H</td>
<td>ON/OFF status of device ≠ ON/OFF status of monitoring condition</td>
<td>Bit device</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Device value ≠ Monitoring condition value</td>
<td>Word device</td>
</tr>
</tbody>
</table>
### Data communication in ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

### Data communication in binary code
Send 2-byte numerical values from lower byte (L: bits 0 to 7).

#### Monitoring condition value
When 'fixed cycle send' is specified with the Programmable controller CPU monitoring function, specify '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00h 00h</td>
</tr>
</tbody>
</table>

When 'condition match send' is specified with the Programmable controller CPU monitoring function, specify the value below.

<table>
<thead>
<tr>
<th>Monitoring condition value</th>
<th>Monitoring condition value</th>
<th>Device type</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000H</td>
<td>OFF</td>
<td>Bit device</td>
</tr>
<tr>
<td>0001H</td>
<td>ON</td>
<td></td>
</tr>
<tr>
<td>0000H to FFFFH</td>
<td>Numerical value</td>
<td>Word device</td>
</tr>
</tbody>
</table>

### Data communication in ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

### Data communication in binary code
Send 2-byte numerical values from lower byte (L: bits 0 to 7).
Register (command: 0630)

Register the target devices to be monitored with the Programmable controller CPU monitoring function and its monitoring conditions in CPU module.

Specify the monitoring target device for multiple blocks with the consecutive word devices and bit devices treated as one block. The host station CPU module can also be specified as error monitoring target.

The monitoring is started when executing the registration command.

Message format

The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Cycle time unit</th>
<th>Cycle time</th>
<th>Programmable controller CPU monitoring function</th>
<th>Transmission method</th>
<th>Number of registered word blocks (m points)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Number of registered bit blocks (n points)</td>
</tr>
<tr>
<td>Number of registered bit blocks (n points)</td>
<td>CPU error monitoring</td>
<td>Block (first point)</td>
<td>···</td>
<td>Block (mth point)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Word device registration

| Block (first point) | ··· | Block (mth point) | CPU error monitoring registration |

Bit device registration

Response data

The device information of the monitoring result and Programmable controller CPU status information are stored.

<table>
<thead>
<tr>
<th>Fixed value</th>
<th>Programmable controller CPU monitoring function</th>
<th>Number of registered word blocks (n points)</th>
<th>Number of registered bit blocks (n points)</th>
<th>CPU error monitoring</th>
</tr>
</thead>
<tbody>
<tr>
<td>Block (first point)</td>
<td>···</td>
<td>Block (mth point)</td>
<td>Block (first point)</td>
<td>···</td>
</tr>
</tbody>
</table>

Word device information

Bit device information

CPU status information

The response data of this command will be sent as same as that of the on-demand function.

For the transmission methods and its timing of monitoring result, refer to the following manuals.
- MELSEC iQ-R Serial Communication Module User's Manual (Application)
- MELSEC-Q/L Serial Communication Module User's Manual (Application)
Data specified by request data

■ Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 6 3 0</td>
<td>30h, 35h, 33h, 30h</td>
</tr>
</tbody>
</table>

■ Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>30h, 30h, 30h, 30h</td>
</tr>
</tbody>
</table>

■ Cycle time units, cycle time

Specify the following time interval (period for 1 cycle). (Page 260 Cycle time)
- Time interval that C24 reads monitoring information from CPU module
- Transmission interval of monitoring result when 'fixed cycle send' is specified with the Programmable controller CPU monitoring function

The time unit (100 ms/1 second/1 minute) can be selected. (Page 260 Cycle time units)

■ Programmable controller CPU monitoring function

Specify the send timing (fixed cycle send/condition match send) of the monitoring result. (Page 260 Programmable controller CPU monitoring function)

■ Transmission method

Fixed '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>30h, 30h</td>
</tr>
</tbody>
</table>

■ Number of registered word blocks, number of registered bit blocks

Specify the number of blocks of word device registration and bit device registration. (Page 69 Number of blocks)

■ CPU error monitoring, CPU error monitoring registration

Specify whether to perform error monitoring (status monitoring) of host station CPU module together. (Page 261 CPU error monitoring, CPU status information)

- When do not perform CPU error monitoring (0): CPU error monitoring registration is not required.
- When perform CPU error monitoring (1): Register the following fixed values to CPU error monitoring registration.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 0 0 0 0 0 0 0 0 0 0 1 0 0 0 5 0 0 0 1</td>
<td>30h, 31h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 31h</td>
</tr>
</tbody>
</table>
**Word device registration, bit device registration**

Specify the monitoring target device for multiple blocks with the consecutive word devices and bit devices treated as one block.

Specify the following items for every block.

- Monitoring start device: Specify the device code and device number. ([Page 63 Devices])
- Number of registered points: Specify the device points from the start device in word units. ([Page 67 Number of device points])
- Monitoring condition: Specify the monitoring condition and transmission method for the device to be registered. ([Page 261 Monitoring condition])
- Monitoring condition value: Specify a value to judge the conditions have been matched or ON/OFF state of the bit. ([Page 262 Monitoring condition value])
Data to be stored by response data

■Fixed value

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>2 1 0 2</td>
<td>32n, 31n, 30n, 32n</td>
</tr>
<tr>
<td>02n, 21n</td>
<td></td>
</tr>
</tbody>
</table>

■Programmable controller CPU monitoring function

The send timing (fixed cycle send/condition match send) of the monitoring result is stored. ([Page 260 Programmable controller CPU monitoring function]

■Number of registered word blocks, number of registered bit blocks

The number of blocks of word device information and bit device information are stored. ([Page 69 Number of blocks]

■Word device information, bit device information

The information of device, whose monitoring condition is satisfied, is stored for multiple blocks with the consecutive word devices and bit devices treated as one block.

The following items are stored for each block.

<table>
<thead>
<tr>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Device data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Block (1 point)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- Monitoring start device: Device code and device number are stored. ([Page 63 Devices]
- Number of registered points: Number of device data points is stored in word unit. ([Page 67 Number of device points]
- Device data: The device value is stored.

The order of device data differ depending on the setting of "Word/byte units designation" in Engineering tool.

For byte units, handle the word data as 2-byte data and send the numerical values from the lower byte (L: bits 0 to 7).

Ex.
2 points data of word device (1234H, 5678H)
- Word unit (0)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 3 4</td>
<td>31n, 32n, 33n, 34n</td>
</tr>
<tr>
<td>5 6 7 8</td>
<td>35n, 36n, 37n, 38n</td>
</tr>
<tr>
<td>12n, 34n, 56n, 78n</td>
<td></td>
</tr>
</tbody>
</table>

- Byte unit (1)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>3 4 1 2</td>
<td>33n, 34n, 31n, 32n</td>
</tr>
<tr>
<td>7 8 5 6</td>
<td>37n, 38n, 35n, 36n</td>
</tr>
<tr>
<td>34n, 12n, 78n, 56n</td>
<td></td>
</tr>
</tbody>
</table>

■CPU error monitoring, CPU status information

Specify whether to include the result of error monitoring (state monitoring) of the host station CPU module. ([Page 261 CPU error monitoring, CPU status information]

- When do not perform CPU error monitoring (0): CPU status information is not stored.
- When perform CPU error monitoring (1): CPU status information is stored.
Communication example (for fixed cycle send)

Perform the Programmable controller CPU monitoring registration with the following conditions.
• Cycle time units, cycle time: 30 seconds
• Programmable controller CPU monitoring function: Fixed cycle send
• Number of registered word blocks: 2 blocks
• Number of registered bit blocks: 1 block
• CPU error monitoring: Included

The response data indicates the following data.
(1) Word device information (1-point)

<table>
<thead>
<tr>
<th>Device data</th>
<th>D0</th>
<th>D1</th>
<th>D2</th>
<th>D3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device value</td>
<td>Decimal</td>
<td>99</td>
<td>4144</td>
<td>5445</td>
</tr>
<tr>
<td></td>
<td>Hexadecimal</td>
<td>0063H</td>
<td>1030H</td>
<td>1545H</td>
</tr>
</tbody>
</table>

(2) Bit device information (1-point)

<table>
<thead>
<tr>
<th>Device data</th>
<th>M15 to M8</th>
<th>M7 to M0</th>
<th>M31 to M24</th>
<th>M23 to M16</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device value</td>
<td>Bit</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td>Byte</td>
<td>11H</td>
<td>31H</td>
<td>48H</td>
</tr>
<tr>
<td></td>
<td>Word</td>
<td>1131H</td>
<td>31H</td>
<td>48H</td>
</tr>
</tbody>
</table>

(3) CPU status information
• CPU status information: Module warning occurring (0001)
Data communication in ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Cycle time unit</th>
<th>Cycle time</th>
<th>Programmable controller CPU monitoring function</th>
<th>Transmission method</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>30h, 3Ch</td>
<td>30h, 3Ch</td>
<td>00 00 00</td>
<td>01</td>
<td>00 01 E</td>
<td>01</td>
<td>02</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>01</td>
</tr>
</tbody>
</table>

Word device registration (first point)

<table>
<thead>
<tr>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Monitoring condition</th>
<th>Monitoring condition value</th>
</tr>
</thead>
<tbody>
<tr>
<td>D</td>
<td>00 00 00 00 00</td>
<td>00 00 00</td>
<td>00 00 00</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Word device registration (second point)

<table>
<thead>
<tr>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Monitoring condition</th>
<th>Monitoring condition value</th>
</tr>
</thead>
<tbody>
<tr>
<td>W</td>
<td>00 00 01 00 00</td>
<td>00 00 00</td>
<td>00 00 00</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Bit device registration (first point)

<table>
<thead>
<tr>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Monitoring condition</th>
<th>Monitoring condition value</th>
</tr>
</thead>
<tbody>
<tr>
<td>M</td>
<td>00 00 00 00 00</td>
<td>00 00 00</td>
<td>00 00 00</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

CPU error monitoring registration (Fixed value)

<table>
<thead>
<tr>
<th></th>
<th>01 00 01 00 00</th>
<th>00 00 05</th>
<th>00 00 1</th>
</tr>
</thead>
</table>

(Response data)

<table>
<thead>
<tr>
<th>Fixed value</th>
<th>Programmable controller CPU monitoring function</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>01 02</td>
<td>01 02</td>
<td>01</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Word device information

<table>
<thead>
<tr>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Device data</th>
</tr>
</thead>
<tbody>
<tr>
<td>D</td>
<td>00 00 00 00 00</td>
<td>(1)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Bit device information

<table>
<thead>
<tr>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Device data</th>
</tr>
</thead>
<tbody>
<tr>
<td>M</td>
<td>00 00 00 00 00</td>
<td>(2)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

CPU status information

<table>
<thead>
<tr>
<th>Device data</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
</tr>
</tbody>
</table>

In the figure (1) and (2), set the value of "ASCII Code" in the table of "Device data" of each response data. The order of device data differ depending on the setting of "Word/byte units designation" in Engineering tool.
Data communication in binary code

(Request data)

In the figure (1) and (2), set the value to "Binary code" in the tables of "Device data" of each response data. The order of device data differ depending on the setting of "Word/byte units designation" in Engineering tool.
Communication example (for condition match send)

Perform the Programmable controller CPU monitoring registration function with the following conditions.

- Cycle time units, cycle time: 30 seconds
- Programmable controller CPU monitoring function: Condition match send
- Number of registered word blocks: 2 blocks
- Number of registered bit blocks: 1 block
- CPU error monitoring designation: Included

The response data indicates the following data.

For the condition match send, the registration data information will be sent individually. (Device information will be sent per block.)

1. When the condition of D0 = 99 (word device registration (first point) of request data) is satisfied.
   *1 The additional code is added. (Page 33 Additional code (10H))
2. When the condition of M0 \( \neq \) OFF (bit device registration (1 point) of request data) is satisfied.
3. When CPU error monitoring condition is satisfied
   - CPU status information: Module warning occurring (0001)

When the error is detected at the first time, the monitoring result is sent with the equivalent method to the edge trigger transmission.

<table>
<thead>
<tr>
<th>Block</th>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Monitoring condition</th>
<th>Monitoring condition value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Word device registration (1-point)</td>
<td>D0</td>
<td>4 points</td>
<td>Edge triggered transmission: Device value = Monitoring condition value</td>
<td>99</td>
</tr>
<tr>
<td>Word device registration (2-point)</td>
<td>W100</td>
<td>8 points</td>
<td>Edge triggered transmission: Device value ( \neq ) Monitoring condition value</td>
<td>0</td>
</tr>
<tr>
<td>Bit device registration (1-point)</td>
<td>M0</td>
<td>2 points</td>
<td>Edge trigger transmission: ON/OFF status of device ( \neq ) ON/OFF status of monitoring condition</td>
<td>OFF</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Device data</th>
<th>D0</th>
<th>D1</th>
<th>D2</th>
<th>D3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device value</td>
<td>Decimal</td>
<td>99</td>
<td>4144</td>
<td>5445</td>
</tr>
<tr>
<td></td>
<td>Hexadecimal</td>
<td>0063H</td>
<td>1030H</td>
<td>1545H</td>
</tr>
<tr>
<td>ASCII code</td>
<td>Word unit</td>
<td>30303633</td>
<td>31303333</td>
<td>31353435</td>
</tr>
<tr>
<td></td>
<td>Byte unit</td>
<td>36333030</td>
<td>33303130</td>
<td>34353135</td>
</tr>
<tr>
<td></td>
<td>Word unit</td>
<td>0063</td>
<td>101030</td>
<td>1545</td>
</tr>
<tr>
<td></td>
<td>Byte unit</td>
<td>6300</td>
<td>301010</td>
<td>4515</td>
</tr>
</tbody>
</table>

*1 The additional code is added. (Page 33 Additional code (10H))

<table>
<thead>
<tr>
<th>Device data</th>
<th>M15 to M8</th>
<th>M7 to M0</th>
<th>M31 to M24</th>
<th>M23 to M16</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device value</td>
<td>Bit</td>
<td>0 0 0 1 0 0 1 0 0 0</td>
<td>0 1 0 0 1 0 0 0</td>
<td>0 0 1 0 0 0 1 0 0</td>
</tr>
<tr>
<td></td>
<td>Byte</td>
<td>11H</td>
<td>31H</td>
<td>48H</td>
</tr>
<tr>
<td></td>
<td>Word</td>
<td>111H</td>
<td>48H</td>
<td>49H</td>
</tr>
<tr>
<td>ASCII code</td>
<td>Word unit</td>
<td>31313331</td>
<td>34383439</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Byte unit</td>
<td>33313131</td>
<td>34393438</td>
<td></td>
</tr>
<tr>
<td>Binary code</td>
<td>Word unit</td>
<td>1131</td>
<td>4849</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Byte unit</td>
<td>3111</td>
<td>4948</td>
<td></td>
</tr>
</tbody>
</table>
### Data communication in ASCII code

#### (Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Cycle time (unit)</th>
<th>Cycle time</th>
<th>Programmable controller CPU monitoring function</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>0 6 3 0</td>
<td>0 0 0 0 0 0</td>
<td>0 1</td>
<td>0 0 1 E</td>
<td>0 2 0 0</td>
<td>0 1 0 1</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Word device registration (first point)</th>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Monitoring condition</th>
<th>Monitoring condition value</th>
</tr>
</thead>
<tbody>
<tr>
<td>D *</td>
<td>0 0 0 0 0 0 0</td>
<td>0 0 0 4</td>
<td>0 0 0 1</td>
<td>0 0 6 3</td>
</tr>
<tr>
<td>D0 to D3</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Word device registration (second point)</th>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Monitoring condition</th>
<th>Monitoring condition value</th>
</tr>
</thead>
<tbody>
<tr>
<td>W *</td>
<td>0 0 0 1 0 0</td>
<td>0 0 0 8</td>
<td>0 0 0 2</td>
<td>0 0 0 0</td>
</tr>
<tr>
<td>W100 to D107</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Bit device registration (first point)</th>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Monitoring condition</th>
<th>Monitoring condition value</th>
</tr>
</thead>
<tbody>
<tr>
<td>M *</td>
<td>0 0 0 0 0 0</td>
<td>0 0 0 2</td>
<td>0 0 0 2</td>
<td>0 0 0 0</td>
</tr>
<tr>
<td>M0 to M31</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>CPU error monitoring registration (Fixed value)</th>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Device data</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

When the condition (D0 = 99) of word device registration (first point) is established

<table>
<thead>
<tr>
<th>Fixed value</th>
<th>Programmable controller CPU monitoring function</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Device data</th>
</tr>
</thead>
<tbody>
<tr>
<td>2 1 0 2 0</td>
<td>0 2 0 1 0 0</td>
<td>0 0 0 D *</td>
<td>0 0 0 0</td>
<td>0 0 0 4</td>
<td>(1)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>32h, 31h, 30h</td>
<td></td>
<td>32h, 31h, 30h</td>
<td>32h, 31h, 30h</td>
<td>32h, 31h, 30h</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

When the condition (M0 ≠ OFF) of bit device registration (first point) is established

<table>
<thead>
<tr>
<th>Fixed value</th>
<th>Programmable controller CPU monitoring function</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
<th>Monitoring start device</th>
<th>Number of registered points</th>
<th>Device data</th>
</tr>
</thead>
<tbody>
<tr>
<td>2 1 0 2 0</td>
<td>0 2 0 0 0</td>
<td>0 0 0 M *</td>
<td>0 0 0 0</td>
<td>0 0 0 2</td>
<td>(2)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>32h, 31h, 30h</td>
<td></td>
<td>32h, 31h, 30h</td>
<td>32h, 31h, 30h</td>
<td>32h, 31h, 30h</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

When the condition of CPU error monitoring is established (Module warning being generated)

<table>
<thead>
<tr>
<th>Fixed value</th>
<th>Programmable controller CPU monitoring function</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
<th>Fixed value</th>
<th>Device data</th>
</tr>
</thead>
<tbody>
<tr>
<td>2 1 0 2 0</td>
<td>0 2 0 0 0</td>
<td>0 0 0</td>
<td>0 0 0</td>
<td>0 0 0 1</td>
<td>0 0 0 1</td>
<td></td>
</tr>
<tr>
<td>32h, 31h, 30h</td>
<td></td>
<td>32h, 31h, 30h</td>
<td>32h, 31h, 30h</td>
<td>32h, 31h, 30h</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

In the figure (1) and (2), set the value of “ASCII Code” in the table of “Device data” of each response data. The order of device data differ depending on the setting of “Word/byte units designation” in Engineering tool.
### Data communication in binary code

#### (Request data)

#### Word device registration (first point)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Cycle time</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
</tr>
</thead>
<tbody>
<tr>
<td>02h, 21h</td>
<td>02h</td>
<td>00h, 00h</td>
<td>01h</td>
<td>1Eh, 00h</td>
</tr>
</tbody>
</table>

#### Word device registration (second point)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Cycle time</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
</tr>
</thead>
<tbody>
<tr>
<td>02h, 21h</td>
<td>02h</td>
<td>00h, 00h</td>
<td>01h</td>
<td>1Eh, 00h</td>
</tr>
</tbody>
</table>

#### Bit device registration (first point)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Cycle time</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
</tr>
</thead>
<tbody>
<tr>
<td>02h, 21h</td>
<td>02h</td>
<td>00h, 00h</td>
<td>01h</td>
<td>1Eh, 00h</td>
</tr>
</tbody>
</table>

#### Bit device registration (first point)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Cycle time</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
</tr>
</thead>
<tbody>
<tr>
<td>02h, 21h</td>
<td>02h</td>
<td>00h, 00h</td>
<td>01h</td>
<td>1Eh, 00h</td>
</tr>
</tbody>
</table>

#### CPU error monitoring

When the condition (D0 = 99) of word device registration (first point) is established

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Cycle time</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
</tr>
</thead>
<tbody>
<tr>
<td>02h, 21h</td>
<td>02h</td>
<td>00h, 00h</td>
<td>01h</td>
<td>1Eh, 00h</td>
</tr>
</tbody>
</table>

When the condition (M0 ≠ OFF) of bit device registration (first point) is established

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Cycle time</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
</tr>
</thead>
<tbody>
<tr>
<td>02h, 21h</td>
<td>02h</td>
<td>00h, 00h</td>
<td>01h</td>
<td>1Eh, 00h</td>
</tr>
</tbody>
</table>

When the condition of CPU error monitoring is established (Module warning being generated)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Cycle time</th>
<th>Number of registered word blocks</th>
<th>Number of registered bit blocks</th>
<th>CPU error monitoring</th>
</tr>
</thead>
<tbody>
<tr>
<td>02h, 21h</td>
<td>02h</td>
<td>00h, 00h</td>
<td>01h</td>
<td>1Eh, 00h</td>
</tr>
</tbody>
</table>

### Response data

In the figure (1) and (2), set the value of "Binary code" in the tables of "Device data" of each response data. The order of device data differ depending on the setting of "Word/byte units designation" in Engineering tool.
Deregister (command: 0631)

Deregister the Programmable controller CPU monitoring function.
Execute the cancel command to end monitoring.

Message format
The following shows the message format of the request data and response data of the command.

■Request data

Command | Subcommand
---------|---------

■Response data
There is no response data for this command.

Data specified by request data

■Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 6 3 1</td>
<td>00 00 00</td>
</tr>
</tbody>
</table>

■Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
</tbody>
</table>

Example for data communication
Deregister the Programmable controller CPU monitoring function.

■Data communication in ASCII code
(Request data)

Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 6 3 1</td>
<td>00 00 00</td>
</tr>
</tbody>
</table>

■Data communication in binary code
(Request data)

Subcommand

| 31 06 00    |
13.6 On-demand function

On-demand function is a function that transmits data to external device using MC protocol after starting up the function from CPU module. This function can be used to sent the emergency data that is required to notify to external devices from the CPU module.

**Restriction**

The command can only be used for C24 connected to the external device on 1:1 basis. It cannot be used via network.

If the on-demand function is used with multidrop connection of 1:n station or m:n station, the on-demand data will be collapsed and proper data is not sent.

### Settings for using the on-demand function

The following shows the setting items for the on-demand function.

#### Settings of serial communication module

Set the following values in the parameter of serial communication module or the buffer memory.

<table>
<thead>
<tr>
<th>Setting item</th>
<th>Description</th>
<th>Corresponding buffer memory</th>
</tr>
</thead>
<tbody>
<tr>
<td>Communication protocol setting</td>
<td>Set the format of the message format to be used.</td>
<td></td>
</tr>
<tr>
<td></td>
<td>• MC protocol (Format 1) to MC protocol (Format 4): Data is sent by 1C frame</td>
<td>CH1 CH2</td>
</tr>
<tr>
<td></td>
<td>• MC protocol (Format 5): Data is send by 4C frame.</td>
<td></td>
</tr>
<tr>
<td>Word/byte units designation</td>
<td>Set the unit of data length (number of data).</td>
<td>150 (96H) 310 (136H)</td>
</tr>
<tr>
<td>Buffer memory start address</td>
<td>Set the start address of the buffer memory to be used for the on-demand</td>
<td>160 (A0H) 320 (140H)</td>
</tr>
<tr>
<td>designation</td>
<td>function.</td>
<td></td>
</tr>
<tr>
<td>Data length designation</td>
<td>Set the data length of the area to which the transmitted data is stored by</td>
<td>161 (A1H) 321 (141H)</td>
</tr>
<tr>
<td></td>
<td>the on-demand function.</td>
<td></td>
</tr>
</tbody>
</table>

The execution result is stored in the following:

<table>
<thead>
<tr>
<th>Execution result</th>
<th>Description</th>
<th>Corresponding buffer memory</th>
</tr>
</thead>
<tbody>
<tr>
<td>On-demand execution results</td>
<td>• Normal completion: 0</td>
<td>598 (256H) 614 (266H)</td>
</tr>
<tr>
<td></td>
<td>• Abnormal completion (error code): Other than 0</td>
<td></td>
</tr>
</tbody>
</table>

The setting content can be checked and changed by using any of the following Engineering tools.

- GX Works3 (Module parameter)
- GX Works2, GX Configurator-SC

For details on the setting items and buffer memory, refer to the following manuals.

- MELSEC iQ-R Serial Communication Module User's Manual (Application)
- MELSEC-Q/L Serial Communication Module User's Manual (Application)

#### Specification of interface to be sent and send data

Specify the transmission channel (CH1/CH2) and data equivalent to the response data with the arguments of the following dedicated instruction. Set the arguments in the program.

- G(P).ONDEMAND

For the dedicated instruction "G(P).ONDEMAND", refer to the following manuals.

- MELSEC iQ-R Programming Manual (Instructions, Standard Functions/Function Blocks)
- MELSEC-Q/L Serial Communication Module User's Manual (Application)
Execution procedure

The procedures for the on-demand function are as shown below.

Procedure for CPU module and C24

The following shows the procedure to send data using the on-demand function from CPU module.

1. Set the items for the on-demand function.
   - Page 274 Settings for using the on-demand function
2. Execute the serial communication module dedicated instruction 'G (P). ONDEMAND'.
   - MELSEC iQ-R Programming Manual (Instructions, Standard Functions/Function Blocks)
   - MELSEC-Q/L Serial Communication Module User's Manual (Application)

Procedure for external device

The following shows the procedure to receive the data (on-demand data) transmitted using the on-demand function from CPU module.

1. Receive the message.
2. Judge whether the received message is issued from the on-demand function by "PC No.".
   For the message of on-demand function, 'PC No.' will be 'FE'. (Page 50 Network No., PC No.)
3. Process the received on-demand data.
Execution timing

The following shows the execution timing of send/receive processing while C24 is being sending/receiving other message of MC protocol, when data transmission instruction by the on-demand function is executed in the CPU module.

When sending on-demand data or response data, the timeout check is performed by send monitoring timer (timer 2). If a timeout error occurs, change the send monitoring time (timer 2).

When C24 is receiving request message of other command from external device

C24 sends on-demand data before the response message to the external device is sent.
• Full-duplex communication: C24 sends on-demand data during the request message from the external device is being received.

When C24 is sending response message of other command to external device

C24 sends the on-demand data to the external device after the response message to the external device.
On-demand (command: 2101)

Send data using the on-demand function from CPU module. Any message other than send data is added automatically in the message format selected in the communication protocol setting. ('FE' is specified to the 'PC No.' for the access route.)
- Communication protocol setting is MC protocol (Format 1) to MC protocol (Format 4): Message format of 1C frame
- Communication protocol setting is MC protocol (Format 5): Message format of 4C frame

When using 2C/3C/4C frame (Format 1 to 4), register the message format of each format in the user frame.
- Page 27 Message Formats of Each Protocol
- For the user frames, refer to the following manuals.
  - MELSEC iQ-R Serial Communication Module User's Manual (Application)
  - MELSEC-Q/L Serial Communication Module User's Manual (Application)

Message format

The following shows the message format of the request data and response data of the command.

- Request data
  There is no request data for this command.

- Response data

Data stored in response data

- Command
  It is added only when the message is sent with MC protocol format 5 specified in the communication protocol setting.

<table>
<thead>
<tr>
<th>Command</th>
<th>Transmission data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Binary code</td>
<td></td>
</tr>
<tr>
<td>01h 21h</td>
<td></td>
</tr>
</tbody>
</table>

- Transmission data
  The transmission data specified in the dedicated instruction 'G(P).ONDEMAND' is stored.
  The order of data differ depending on the setting of "Word/byte units designation" in Engineering tool.
  For byte units, regard the word data as 2-byte data and send numerical values from lower byte (L: bits 0 to 7).

**Ex**

When transmitting 2-word data (1234H, 5678H)
- Word unit (0)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 3 4 5 6 7 8</td>
<td>12h 34h 56h 78h</td>
</tr>
</tbody>
</table>

- Byte unit (1)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>3 4 1 2 7 8 5 6</td>
<td>34h 12h 78h 56h</td>
</tr>
</tbody>
</table>
**Communication example (communication protocol setting is format 1 to 4)**

Send 2-word data (1234H, 5678H) to the external device from the CPU module under the following settings.

- Communication protocol setting: MC protocol (Format 1 to 4)
- Word/byte units designation: Word unit

(Response data)

<table>
<thead>
<tr>
<th>Transmission data</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
</tr>
<tr>
<td>31H</td>
</tr>
</tbody>
</table>

**Communication example (communication protocol is format 5)**

Send 2-word data (1234H, 5678H) to the external device from the CPU module under the following settings.

- Communication protocol setting: MC Protocol (Format 5)
- Word/byte units designation: Word unit

(Response data)

<table>
<thead>
<tr>
<th>Command</th>
<th>Transmission data</th>
</tr>
</thead>
<tbody>
<tr>
<td>01H</td>
<td>21H</td>
</tr>
</tbody>
</table>
This part explains the specifications when using MELSEC-QnA series devices.

14 MELSEC-QnA SERIES SUPPORTED SPECIFICATIONS

15 QnACPU DEDICATED COMMANDS
14 MELSEC-QnA SERIES SUPPORTED SPECIFICATIONS

This chapter explains the specifications of the messages of MC protocol and access ranges when using the MELSEC-QnA series devices as follows:

• When accessing system including MELSEC-QnA series modules
• When utilizing software for data communication created for MELSEC-QnA series programmable controller.

14.1 Frames and Commands that can be used

When accessing MELSEC-QnA series modules, all frames of MC protocol can be used. However, the commands that can be used have some restrictions. (Page 465 Accessible Modules for Each Command)

QnA-compatible frame

The following frames have compatibility with the message protocol and the message format for MELSEC-QnA series.

<table>
<thead>
<tr>
<th>Frame</th>
<th>Compatible message format</th>
<th>Access range</th>
</tr>
</thead>
<tbody>
<tr>
<td>4C frame</td>
<td>Dedicated protocols for MELSEC-QnA series serial communication modules (QnA extension frame)</td>
<td>Page 43 Accessible range of 4C frame</td>
</tr>
<tr>
<td>3C frame</td>
<td>Dedicated protocols for MELSEC-QnA series serial communication modules (QnA frame)</td>
<td>Page 44 Accessible range of 3C frame</td>
</tr>
<tr>
<td>2C frame</td>
<td>Dedicated protocols for MELSEC-QnA series serial communication modules (QnA simplified frame)</td>
<td>Page 44 Accessible range of 2C frame</td>
</tr>
<tr>
<td>3E frame</td>
<td>Message formats for MELSEC-QnA series Ethernet interface modules</td>
<td>Page 46 Accessible range of 4E frame, 3E frame</td>
</tr>
</tbody>
</table>

14.2 Accessible Modules

Accessible to the following MELSEC-QnA series modules within the access range.

Accessible modules to other stations

The following modules of other station can be accessed.

<table>
<thead>
<tr>
<th>Type</th>
<th>Model name</th>
</tr>
</thead>
<tbody>
<tr>
<td>CPU module</td>
<td>Q2ACPU, Q2ACPU-S1, Q2ASCPU, Q2ASCPU-S1, Q2ASHCPU, Q2ASHCPU-S1, Q3ACPU, Q4ACPU</td>
</tr>
<tr>
<td>Redundant system</td>
<td>Q4ARCPU</td>
</tr>
<tr>
<td>MELSECNET/10 remote I/O</td>
<td>AJ72QLP25(G), AJ72QBR15, A1SJ72QLP25, A1SJ72QBR15</td>
</tr>
<tr>
<td>Special function module</td>
<td>Refer to the following section.</td>
</tr>
</tbody>
</table>

Modules that can be relayed between networks

The following shows the modules that can be relayed between networks when accessing a MELSEC-QnA series module.

**MELSEC-QnA series modules**

<table>
<thead>
<tr>
<th>Network</th>
<th>Model name</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSECNET/10</td>
<td>QJ71LP21, QJ71LP21-25, QJ71LP21S-25, QJ71LP21G, QJ71BR11 (MELSECNET/10 mode)</td>
</tr>
<tr>
<td>Ethernet<strong>1</strong></td>
<td>AJ71QLP21 (S/G), AJ71QBR11, A1SJ71QLP21 (S), A1SJ71QBR11</td>
</tr>
</tbody>
</table>

**1** QnA series Ethernet interface modules can be relayed between networks when using the module with the function version B or later. Check the function version with the production date printed on the rating plate on the side of the module.

(Manufactured date: Year (lower two digits), Month (two digits), function version (one digit))
■ Modules other than MELSEC-QnA series

<table>
<thead>
<tr>
<th>Network</th>
<th>Module type</th>
<th>Model</th>
</tr>
</thead>
<tbody>
<tr>
<td>CC-Link IE Field Network</td>
<td>CC-Link IE Field Network master/local module</td>
<td>LJ71GF11-T2, QJ71GF11-T2, QS0J71GF11-T2</td>
</tr>
<tr>
<td>CC-Link IE Controller Network</td>
<td>CC-Link IE Controller Network module</td>
<td>QJ71GP21-SX, QJ71GP21S-SX</td>
</tr>
<tr>
<td>MELSECNET/H</td>
<td>MELSECNET/H module</td>
<td>QJ71LP21, QJ71LP21-25, QJ71LP21S-25, QJ71LP21G, QJ71BR11, QJ71NT11B</td>
</tr>
<tr>
<td>Ethernet</td>
<td>Ethernet interface module</td>
<td>LJ71E71-100, QJ71E71-100, QJ71E71-B5, QJ71E71-B2, QJ71E71</td>
</tr>
</tbody>
</table>

The following shows the considerations when using MELSEC-QnA series devices.

14.3 Considerations

Considerations when connecting E71

■ Setting range of monitoring timer

When accessing QnACPU for the first time, the wait time for CPU monitoring timer is required before receiving a response message because QnACPU identifies the CPU type. Be sure to set a value within the setting range shown below.

<table>
<thead>
<tr>
<th>Access target</th>
<th>Monitoring timer</th>
</tr>
</thead>
<tbody>
<tr>
<td>Connected station (host station)</td>
<td>1H to 28H (0.25s to 10s)</td>
</tr>
<tr>
<td>Other station</td>
<td>2H to F0H (0.5s to 60s)</td>
</tr>
</tbody>
</table>
This chapter shows the QnACPU dedicated commands.

### 15.1 QnACPU Dedicated Commands List

The following shows the list of QnACPU dedicated commands.

There are some commands that cannot be executed while the CPU module is in RUN. Refer to the following section.

> Page 457 Applicable Commands for Online Program Change

For the number of points processed per communication, refer to the following section.

> Page 459 Number of Processing per One Communication

#### Drive memory defragmentation

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Description</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Read memory usage status</td>
<td>0205</td>
<td>Reads the cluster usage status of the driver.</td>
<td>0000</td>
</tr>
<tr>
<td>Defragment memory</td>
<td>1207</td>
<td>Increases the consecutive free area by defragmenting the drive memory. (Defragmentation of file storage position)</td>
<td>0000</td>
</tr>
</tbody>
</table>

#### File control

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Description</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Read file information table</td>
<td>0201</td>
<td>Reads a file list (file name, last edit date and time, file size).</td>
<td>0000</td>
</tr>
<tr>
<td>Read file presence (Search file)</td>
<td>0202</td>
<td>Reads a file list (header statement attached to a file, file name, last edit date and time, file size).</td>
<td>0000</td>
</tr>
<tr>
<td>Read file No. usage status</td>
<td>0203</td>
<td>Reads file No. usage status.</td>
<td>0000</td>
</tr>
<tr>
<td>Read file</td>
<td>0204</td>
<td>Reads content of file.</td>
<td>0000</td>
</tr>
<tr>
<td>Lock file</td>
<td>0808</td>
<td>Locks the file in order to prevent the file contents from being edited from other devices while accessing the specified file.</td>
<td>0001 Register</td>
</tr>
<tr>
<td>Create new file (Register file name)</td>
<td>1202</td>
<td>Secures the file area for the specified file name.</td>
<td>0000 Deregister</td>
</tr>
<tr>
<td>Write to file</td>
<td>1203</td>
<td>Writes the specified data (n byte) to a file.</td>
<td>0000 Arbitrary data</td>
</tr>
<tr>
<td>Modify file information</td>
<td>1204</td>
<td>Modifies the date and time of the last edit of the file.</td>
<td>0000 Modify last edit date and time</td>
</tr>
<tr>
<td>Delete file</td>
<td>1205</td>
<td>Deletes a file.</td>
<td>0000</td>
</tr>
<tr>
<td>Copy file</td>
<td>1206</td>
<td>Copies a file.</td>
<td>0000</td>
</tr>
</tbody>
</table>
15.2 Defragmentation of Drive Memory

An external device performs the following functions for other station QnACPU drive which stores parameters and program files that the sequence programs are written.

Read drive memory usage status

Check the usage status of the drive memory (cluster usage status) of the specified drive.

Defragment drive memory

When the valid data written in the drive memory is not consecutive, increase the consecutive free area in cluster unit by defragmentation.

A cluster is the minimum unit when files are stored to drive memory (such as memory card) and the memory containing data is managed by FAT*1.

The size of one cluster of each QnACPU drive is as follows:
- Internal memory : 4096 bytes
- Other memory : 512 bytes

For example, if a data less than 512 bytes is written to a memory card, one cluster of drive memory is used to write the data.

If 513 to 1024 bytes of data are written, two clusters of drive memory is used to write the data.

*1 An abbreviation for 'File Allocation Table'. A table used by the operating system to manage the location of files on the drive memory.

Images of drive memory defragmentation

☐: Cluster in not used (empty), ■: Cluster is being used (valid data is written in it)

• Before drive memory defragmentation

| Cluster | b15 | b14 | b13 | b12 | b11 | b10 | b9 | b8 | b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 |
|---------|-----|-----|-----|-----|-----|-----|----|----|----|----|----|----|----|----|----|
| First 16 clusters |  ■  |  ■  |  ■  |  ■  |  □  |  □  |  □  |  □  |  □  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |
|       |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |  ■  |
|       |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |
|       |  .  |  .  |  .  |  .  |  .  |  .  |  .  |  .  |  .  |  .  |  .  |  .  |  .  |  .  |  .  |  .  |  .  |
|       |  □  |  ■  |  ■  |  ■  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |
| Last 16 clusters |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |  □  |

• After drive memory defragmentation

<table>
<thead>
<tr>
<th>Cluster</th>
<th>b15</th>
<th>b14</th>
<th>b13</th>
<th>b12</th>
<th>b11</th>
<th>b10</th>
<th>b9</th>
<th>b8</th>
<th>b7</th>
<th>b6</th>
<th>b5</th>
<th>b4</th>
<th>b3</th>
<th>b2</th>
<th>b1</th>
<th>b0</th>
</tr>
</thead>
<tbody>
<tr>
<td>First 16 clusters</td>
<td>■</td>
<td>■</td>
<td>■</td>
<td>■</td>
<td>■</td>
<td>■</td>
<td>■</td>
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<td>□</td>
<td>□</td>
</tr>
<tr>
<td>Last 16 clusters</td>
<td>□</td>
<td>□</td>
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</tr>
</tbody>
</table>
Data to be specified in commands

The following explains the data to be specified in commands when an external device performs defragmentation to the drive memory of QnACPU.

Keyword
A data to allow/prohibit the access to the drive, which is the character string (up to 6 characters) that are registered to the specified drive.
When a keyword has already registered, specify the same keyword.

■ Data communication in ASCII code
Use the keyword registered in the specified drive and send as is.

■ Data communication in binary code
Convert the keyword registered in the specified drive to 3-byte binary code, and send it from lower byte (L: bits 0 to 7).

Ex.
When the registered keyword is '012345'

<table>
<thead>
<tr>
<th>Values converted to binary code</th>
<th>Transmission order</th>
</tr>
</thead>
<tbody>
<tr>
<td>01H, 23H, 45H</td>
<td>45H, 23H, 01H</td>
</tr>
</tbody>
</table>

Ex.
When the keyword registered is '012300'

<table>
<thead>
<tr>
<th>Values converted to binary code</th>
<th>Transmission order</th>
</tr>
</thead>
<tbody>
<tr>
<td>01H, 23H, 00H</td>
<td>00H, 23H, 01H</td>
</tr>
</tbody>
</table>

■ The content of data when a keyword is not registered in a specified drive
- Data communication in ASCII code: '000000'
- Data communication in binary code: '00H', '00H', '00H'

Setting flag
A data that indicates whether the keyword registered to the specified drive is specified to the keyword above.

■ Data communication in ASCII code
Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

■ Data communication in binary code
Send 1-byte numerical value.

■ Setting flag to be specified

<table>
<thead>
<tr>
<th>Setting value</th>
<th>Content to be specified</th>
</tr>
</thead>
<tbody>
<tr>
<td>00H</td>
<td>Keyword is invalid (specify a dummy)</td>
</tr>
<tr>
<td>01H</td>
<td>Keyword is enabled (specify the keyword registered in the specified drive).</td>
</tr>
</tbody>
</table>
### Drive name
A data to perform reading usage status of drive memory, or specify the QnACPU drive to perform defragmentation.

- **Data communication in ASCII code**
  Convert the numerical value that indicates access target drive to 4-digit ASCII code (hexadecimal) and send it from upper digits.

- **Data communication in binary code**
  Send 2-byte numerical values that indicate access target drive from the lower byte (L: bits 0 to 7).

- **Specified content of drive name (Other content cannot be specified.)**

<table>
<thead>
<tr>
<th>Setting value</th>
<th>Target drive</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000H</td>
<td>Internal memory (built-in RAM)</td>
</tr>
<tr>
<td>0001H</td>
<td>RAM area of memory card A</td>
</tr>
<tr>
<td>0002H</td>
<td>ROM area of memory card A</td>
</tr>
<tr>
<td>0003H</td>
<td>RAM area of memory card B</td>
</tr>
<tr>
<td>0004H</td>
<td>ROM area of memory card B</td>
</tr>
<tr>
<td>000FH</td>
<td>Drive that the parameter files currently used (specified with the QnACPU dip switch) is stored.</td>
</tr>
</tbody>
</table>

### Cluster No.
A data to specify the first cluster No. within the range of drive memory whose usage status is to be read. Specify the data in multiples of 16 (00H, 10H, 20H... in hexadecimal notation).

- **Data communication in ASCII code**
  Convert the cluster No. which is higher than '00H' to 4-digit (hexadecimal) ASCII code and send it from upper digits.

- **Data communication in binary code**
  Send 2-byte numerical values that indicate cluster No. which is higher that '00H' from lower byte (L: bits 0 to 7).

- **Drive memory defragmentation**
  When performing defragmentation of drive memory, specification of the cluster No. is not required.

### Number of clusters to be read
A data to specify the number of clusters within the range of drive memory whose usage status is to be read. Specify the data in multiples of 16 (10H, 20H... in hexadecimal notation).

- **Data communication in ASCII code**
  Convert the number of clusters '10H' to '100H' (16 to 256) to 4-digit ASCII code (hexadecimal) and send them from upper digits.

- **Data communication in binary code**
  Send 2-byte numerical value that indicates the number of clusters from '10H' to '100H' (16 to 256) from lower byte (L: bits 0 to 7).

- **Drive memory defragmentation**
  When performing defragmentation of drive memory, specification of the number of clusters to be read is not required.

---

**Point**
Specify the number of clusters to be read within the range of the usable memory size after formatting the drive to be read from.

- Number of clusters = Usable memory size/Number of bytes in one cluster (4096 or 512)

For the number of bytes in one cluster, refer to the following section.

Page 283 Defragment drive memory
Free cluster table
A data indicating the status of cluster usage. It is a response data to 'read drive memory usage status' (command: 0205).

■ Data communication in ASCII code
The numerical value that indicates usage status is converted to n-digit (hexadecimal) ASCII code and sent to the external device. (16 clusters/4 digits)

■ Data communication in binary code
An m-byte numerical value that indicates usage status is sent to the external device. (16 clusters/2 bytes)

■ Content of free cluster table
The usage status of each cluster is indicated by one cluster per bit.

Ex
0: Empty, 1: Used

| Cluster | b15 | b14 | b13 | b12 | b11 | b10 | b9  | b8  | b7  | b6  | b5  | b4  | b3  | b2  | b1  | b0  | Values for 16 bits |
|---------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------------------|
| First 16 clusters | 0\(^1\) | 0 | 1 | 1 | 1 | 1 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1\(^2\) | 3CFFH |
| - | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 003FH |
| - | | | | | | | | | | | | | | | | | |
| Last 16 clusters | 0\(^3\) | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0000H |

*1 16th cluster from the head cluster
*2 First cluster
*3 Last cluster

When the usage status is as shown above, the content of free cluster table that is returned to the external device is as follows:

- When 32 clusters are returned while communicating in ASCII code
  - ‘3CFF003F’ is returned and it is sent from ‘3’.
- When 32 clusters are returned while communicating in binary code
  - ‘FFH’, ‘3CH’, ‘3FH’, and ‘00H’ are returned and these are sent from ‘FFH’.

■ Drive memory defragmentation
When performing defragmentation of drive memory, the free cluster table is not returned.
Read drive memory usage status (command: 0205)

Read the usage status of the drive memory.

When creating a new file (registering new file), a consecutive free area for the file size to be created is required.

To calculate the capacity (size) of the consecutive free area of the specified drive, check the number of consecutive free clusters (number of consecutive OFF bits) by reading the usage status of that drive memory.

Capacity of consecutive free area (size) = number of consecutive free cluster × 4096 or 512 (byte)

When the consecutive area is insufficient, perform the following memory defragmentation.

Message format

The following shows the message format of the request data and response data of the command.

■ Request data

The free cluster table is stored. The order of data differs depending on the ASCII code or binary code.

Data specified by request data

■ Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2 0 5</td>
<td>05h, 02h</td>
</tr>
</tbody>
</table>

■ Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0</td>
<td>00h, 00h</td>
</tr>
</tbody>
</table>

■ Keyword

Set whether to allow/prohibit access to a drive. (Page 292 Keyword)

■ Setting flag

This indicates whether the keyword registered in the specified drive matches the keyword of request data. (Page 284 Setting flag)

■ Drive name

Read the usage status of the drive memory, and specify the QnACPU drive to be defragmented. (Page 285 Drive name)

■ Cluster No.

Specify the first cluster No. within the range of drive memory whose usage status is to be read. (Page 285 Cluster No.)
15.2 Defragmentation of Drive Memory

■ Number of clusters to be read
Specify the number of clusters within the range of drive memory whose usage status is to be read. (Page 285 Number of clusters to be read)

Communication example
Read the usage status of the drive memory of the RAM area in a memory card A (drive name: 01H) for 32 clusters.

■ Data communication in ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>Cluster No.</th>
<th>Number of clusters to be read</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>0 1 2 3 4 5 0 1 0 0 0 1 0 0 0 0 0 0 2 0</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>30h, 32h, 30h, 35h</td>
<td>30h, 30h, 30h, 30h</td>
<td>30h, 31h, 30h, 30h</td>
<td>30h, 30h, 30h, 30h</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

Free cluster table

<table>
<thead>
<tr>
<th>Cluster No.0 to 15</th>
<th>Cluster No.16 to 31</th>
</tr>
</thead>
<tbody>
<tr>
<td>3 C F F</td>
<td>30h, 30h, 33h, 46h</td>
</tr>
</tbody>
</table>

■ Data communication in binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Cluster No.</th>
<th>Number of clusters to be read</th>
</tr>
</thead>
<tbody>
<tr>
<td>05h, 02h, 00h, 01h</td>
<td>01h, 23h, 01h, 00h</td>
<td>00h, 00h, 20h, 00h</td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

Free cluster table

<table>
<thead>
<tr>
<th>Cluster No.0 to 15</th>
<th>Cluster No.16 to 31</th>
</tr>
</thead>
<tbody>
<tr>
<td>FFh, 3Ch</td>
<td>3Fe, 00h</td>
</tr>
</tbody>
</table>
Defragment drive memory (command: 1207)

Perform the defragmentation of drive memory.
Perform the defragmentation of drive memory in the following situation.
• When the specified QnACPU is STOP.
• The usage status of drive memory (check with command 0205) is not consecutive and the files cannot be stored.

Message format

The following shows the message format of the request data and response data of the command.

Request data

ASCII

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 0 7</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Binary

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Setting flag</th>
<th>Keyword</th>
<th>Drive name</th>
</tr>
</thead>
<tbody>
<tr>
<td>07h 12m</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Response data

There is no response data for this command.

In the following cases, an error occurs and an abnormal response will be returned.
• When QnACPU is protected by system protection.
• When the keyword registered in the specified drive is not specified.
• When the drive memory is faulty (defective cluster, etc.).
• When the subdirectory is created by using an IC memory card read/writer.
• When the file is not stored in one consecutive area by using an IC memory card read/writer.

Data specified by request data

Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 0 7</td>
<td>07h 12m</td>
</tr>
</tbody>
</table>

Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00h 00h</td>
</tr>
</tbody>
</table>

Keyword
Set whether to allow/prohibit access to a drive. (Page 292 Keyword)

Setting flag
This indicates whether the keyword registered in the specified drive matches the keyword of request data. (Page 284 Setting flag)

Drive name
Read the usage status of the drive memory, and specify the QnACPU drive to be defragmented. (Page 285 Drive name)
Communication example

Perform defragmentation for the drive memory of the RAM area in a memory card A (drive name: 01H).

**Data communication in ASCII code**
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 0 7</td>
<td>0 0 0 0</td>
<td>0 1 2 3 4 0</td>
<td>0 0 0 1</td>
</tr>
</tbody>
</table>

**Data communication in binary code**
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Setting flag</th>
<th>Keyword</th>
<th>Drive name</th>
</tr>
</thead>
<tbody>
<tr>
<td>07 12</td>
<td>00 00</td>
<td>01 23</td>
<td>01 00</td>
</tr>
</tbody>
</table>
15.3 File Control

Read, register, and delete files in QnACPU modules.

Use this function in the following situations:

- Read parameters and sequence programs from an external device
- Write the files read from CPU module to an external device according to the commands.

For the file name, extension, and location of a file stored in CPU module, refer to the user’s manual (function explanation, program fundamentals) of the CPU module used.

Considerations for file control

The following are the considerations when controlling files of QnACPU.

Editing files

The files read from CPU module are used for storage on an external device. The external device cannot edit the content of a file read from CPU module.

Data read/write

When the data of the entire file size cannot be read/written in a single communication, use several communications to read/write the data.

The file size can be verified using the following functions.

<table>
<thead>
<tr>
<th>Function</th>
<th>Reference</th>
</tr>
</thead>
</table>
| Read file information table function | Page 302 Read file information table without header statement (command: 0201)  
|                                    | Page 305 Read file information table with header statement (command: 0202)  |
| Read file presence function        | Page 308 Read file presence (Search file) (command: 0203)  |

System protection

If the CPU module is protected by system protection when using the following functions, an error occurs and an abnormal completion message is returned.

<table>
<thead>
<tr>
<th>Function</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Create new file (Register file name)</td>
<td>Page 317 Create new file (Register file name) (command: 1202)</td>
</tr>
<tr>
<td>Write to file</td>
<td>Page 319 Write to file (command: 1203)</td>
</tr>
<tr>
<td>Delete file</td>
<td>Page 329 Delete file (command: 1205)</td>
</tr>
<tr>
<td>Copy file</td>
<td>Page 331 Copy file (command: 1206)</td>
</tr>
<tr>
<td>Modify file information (date created, attribute)</td>
<td>Page 323 Modify file information (command: 1204)</td>
</tr>
</tbody>
</table>

Registration of keyword

When registering a keyword in the file, keep the registered keyword.

When accessing the following files, specifying the registered keyword when opening or reading/writing to that file is required.

- Parameter file
- Program files

File attribute

The file attribute is valid only when the following functions are used. For other commands, the attribute is handled as a dummy.

<table>
<thead>
<tr>
<th>Function</th>
<th>Reference</th>
</tr>
</thead>
</table>
| Read file information table function          | Page 302 Read file information table without header statement (command: 0201)  
|                                    | Page 305 Read file information table with header statement (command: 0202)  |
| Create new file (Register file name)          | Page 317 Create new file (Register file name) (command: 1202)  |
| Modify file information (date created, attribute) | Page 323 Modify file information (command: 1204)  |
Data to be specified in commands

This section explains the data to be specified in command when an external device controls files in the CPU module.

Keyword

Allow/prohibit the access to the specified drive.
When a keyword has already been registered, specify the same keyword.
For the content of the data, refer to the following section.
Page 284 Keyword

Setting flag

A data that indicates whether the keyword registered to the specified drive is specified to the keyword above.
For the content of the data, refer to the following section.
Page 284 Setting flag

Drive name, Drive No.

A data that specifies the drive of the CPU module whose files are to be controlled.
For the method on how to specify the drive name and its corresponding drive, refer to the following section.
Page 285 Drive name

File No.

A value to specify the registered number when a file specified by file name and extension is registered (written) to CPU module, or the registration number when registering to CPU module.

Data communication in ASCII code
Convert the file No. to 4-digit ASCII code (hexadecimal) and send it from upper digits.

Data communication in binary code
Send the 2-byte*1 value that indicates file No. from the lower byte (L: bits 0 to 7).
*1 For C24, the additional code may be added. (Page 33 Additional code (10H))

Ex.
1FH

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 1 F</td>
<td>1Fh 00h</td>
</tr>
</tbody>
</table>

Specified content of file No.

<table>
<thead>
<tr>
<th>Value to be specified</th>
<th>Description</th>
<th>Content to be specified</th>
</tr>
</thead>
<tbody>
<tr>
<td>01H to 100H</td>
<td>File No.</td>
<td>Specify when the file No. is known.</td>
</tr>
<tr>
<td>FFFFFH</td>
<td>File No. unknown</td>
<td>Specify when C24/E71 searches for file No.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>(The request to read/write data from/to C24/E71 will be delayed for more than one sequence scan time.)</td>
</tr>
</tbody>
</table>

The file No. of the registered file can be checked using the following functions.
Page 302 Read file information table without header statement (command: 0201)
Page 305 Read file information table with header statement (command: 0202)
Page 308 Read file presence (Search file) (command: 0203)
The unused file No. at registering new file can be checked using the following function.
Page 310 Read file No. usage status (command: 0204)
Number of requested file, total number of registered files, number of file information

A data that indicates the number of request files, number of files registered in the specified drive, and number of files that return file information when reading file information.

Data communication in ASCII code
Convert the numerical value described in the reference section relevant to the corresponding function to 4-digit ASCII code (hexadecimal) and send it from upper digits.

Data communication in binary code
Send the 2-byte numerical value described in the reference section relevant to the corresponding function from each low byte (L: bits 0 to 7).

File name, extension, and attribute

For file name, extension, and storage location that can be specified
For file name, extension, and storage location of files that can be specified in CPU modules, refer to the user’s manual (function explanation, program fundamentals) of the CPU module used.

Files not described in the user’s manual (function explanation, program fundamentals) of the CPU module used may also be shown for file control. Do not access them since they are for the system use.

When creating files or changing the file names

When creating a new file or changing the file name, specify the file name (up to 8 characters) and extension (3 characters) in accordance with the file naming rule of Engineering tool.

File name, extension
For QnACPU, specify the file name by a file name + extension.

<table>
<thead>
<tr>
<th>Item</th>
<th>Specification method</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>Specify the file name within 8 characters. If the file name is less than 8 characters, add space (code: 20H) after the file name and fill the characters to 8 characters.</td>
</tr>
<tr>
<td>Extension</td>
<td>Specify the extension within 3 characters.</td>
</tr>
</tbody>
</table>

Ex.
When the file name is 'ABC.QPG'
File name: ABC □□□□□QPG (□ indicates a space)

Attribute
Add an attribute a file.
Specify the attribute with 1 byte.
Specify '20H' as an attribute value (disk files that can be read/written) at a new file creation and when a dummy is specified.
When the attribute of the created file is not changed, the attribute of readable/writable disk file will be attached.

The attributes for the existing files can be checked using the following functions.
- Page 302 Read file information table without header statement (command: 0201)
- Page 305 Read file information table with header statement (command: 0202)
The attribute of the created files can be changed between '01H' (Read Only file) ⇒ '20H' (readable/writable disk file).
- Page 323 Modify file information (command: 1204)
Last edit time and last edit date
A data that indicates the date and time when the current file content was registered.

■ Data communication in ASCII code
Convert the numerical value to a 4-digit (hexadecimal) ASCII code and send it from upper digits (time, year). When dummy is specified, send '0000H'.

■ Data communication in binary code
Send 2-byte numerical value from lower bytes (L: bits 0 to 7). When dummy is specified, send '0000H'.

■ Date (year, month, day)
Specify year, month, and day with 16-bit value.
- Year: The binary value is represented with bits 9 to 15 by setting the year 1980 to '0'. *1
- Month: Specify the binary value in bit 5 to 8.
- Day: Specify the binary value in bit 0 to 4.
*1 This indicates incremental number of year by regarding 1980 as '0'.

Ex
April 1st, 2010

<table>
<thead>
<tr>
<th>(Year)</th>
<th>(Month)</th>
<th>(Day)</th>
</tr>
</thead>
<tbody>
<tr>
<td>b15</td>
<td>b10</td>
<td>b5</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>1</td>
</tr>
</tbody>
</table>

30+1980 = 2010

Ex
When 20:50:58

<table>
<thead>
<tr>
<th>(Hours)</th>
<th>(Minutes)</th>
<th>(Second)</th>
</tr>
</thead>
<tbody>
<tr>
<td>b15</td>
<td>b10</td>
<td>b5</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>1</td>
</tr>
</tbody>
</table>

58=2 = 29

Ex
When 03:14:25

<table>
<thead>
<tr>
<th>(Hours)</th>
<th>(Minutes)</th>
<th>(Second)</th>
</tr>
</thead>
<tbody>
<tr>
<td>b15</td>
<td>b10</td>
<td>b5</td>
</tr>
<tr>
<td>0</td>
<td>3</td>
<td>0</td>
</tr>
</tbody>
</table>

43+1980=2023

---

ASCII code / Binary code

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>3 C 8 1</td>
<td>81C3</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>A 6 5 D</td>
<td>5D6A</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>41 36 35 44</td>
<td>35D4A6</td>
</tr>
</tbody>
</table>
File size
A data that indicates the current file size in number of bytes.

- **Data communication in ASCII code**
  Convert the numerical value to 8-digit (hexadecimal) ASCII code and send it from the upper digits.

- **Data communication in binary code**
  Send 4-byte\(^1\) numerical from the lower byte (L: bits 0 to 7).

  \(^1\) For C24, the additional code may be added. (Page 33 Additional code (10H))

**Ex.**
When the file size is 7168 bytes

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000001C00</td>
<td>0000100100</td>
</tr>
</tbody>
</table>

Header statement
A header statement given to the file specified by Engineering tool supporting QnACPU (up to 32 characters).

- **Data communication in ASCII code**
  Send data from the first character.
  If the header statement is less than 32 characters, append a space (code: 20H).

**Ex.**
The header statement at the registration is ‘1 line-PC5’
The header statement becomes ‘1 line-PC5□□...’, and is sequentially sent from ‘1’. (□: indicating a space.)

- **Data communication in binary code**
  Use the character code of header statement as binary value, and send if from the first character.
  When the header statement is less than 32 characters, 20H is added for the shortage.

**Ex.**
The header statement at registration is ‘1 line-PC5’

Offset address
A data to specify the start address of the file range for which data is read and written.
Specify the address (one address/one byte) from the head (offset address: 0H) of each file with an even number.

- **Data communication in ASCII code**
  Convert the address described in the reference section relevant to the corresponding function to 8-digit (hexadecimal) ASCII code and send it from the upper digits.

- **Data communication in binary code**
  Send 4-byte numerical values described in the reference section relevant to the corresponding function from lower byte (L: bits 0 to 7).

- **Offset addresses that can be specified**
  Check the file size (number of bytes) with the following read file information table functions, and calculate the offset address (0H to nH) by the size.
  - Page 302 Read file information table without header statement (command: 0201)
  - Page 305 Read file information table with header statement (command: 0202)
Number of bytes read, number of bytes written
A data to specify the number of bytes in the file range from/to which data is read/written. Specify it as one address per one byte.

- **Data communication in ASCII code**
  Convert the numerical value described in the reference section of the relevant function to 4-digit ASCII code (hexadecimal) and send it from upper digits.

- **Data communication in binary code**
  Send 2-byte numerical value described in the reference section of the relevant function from the lower byte (L: bits 0 to 7).

Read data, write data (for batch read and batch write functions)
A data read from or to be written to the file in the CPU module.

- **Data communication in ASCII code**
  Convert one byte (one address) to 2-digit ASCII code (hexadecimal) and send it for the specified number of bytes from the upper digits.

- **Data communication in binary code**
  Send the specified number of bytes as one byte for one address.

- **Data order**
  - When reading data: Store the data to the external device without changing the order of data read from the CPU module.
  - When writing data: Specify the data without changing the order of data read from CPU module.

Write data (identical data write function)
A data for the identical data write function used to wrote the identical data to the existing QnACPU files.

- **Data communication in ASCII code**
  Convert the numerical value for one word to 4-digit ASCII code (hexadecimal) and send it from the upper digits.

- **Data communication in binary code**
  Send the numerical value for one word from the lower byte (L: bits 0 to 7).

Capacity
A data to reserve the file area on the specified disk when registering a new file. Specify the data in the number of bytes.

- **Data communication in ASCII code**
  Convert the numerical value which represents the area for specified file to be reserved in 2 words to 8-digit ASCII code (hexadecimal) and send it from the upper digits.

- **Data communication in binary code**
  Send the numerical value which represents the area for the specified file to be reserved in 2 words from the lower byte (L: bits 0 to 7).

- **Point**
  A new file with the same contents as the existing file can be registered from an external device.
  The size of the relevant existing file must be checked using the read file information table function.
  - Page 302 Read file information table without header statement (command: 0201)
  - Page 305 Read file information table with header statement (command: 0202)
  - Page 308 Read file presence (Search file) (command: 0203)
Fixed value
Specify ‘0’.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>30h, 30h, 30h, 30h</td>
<td>00h, 00h</td>
</tr>
</tbody>
</table>

Modification pattern (for changing file name and file size)
A data to specify which information to be modified when information (file name, size, date and time created) of the existing file is modified.

Data communication in ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal) and sent it from the upper digits.

Data communication in binary code
Send 2-byte numerical value from the low byte (L: bits 0 to 7).

Specified value and contents of modification pattern

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
<th>Value to be specified</th>
</tr>
</thead>
<tbody>
<tr>
<td>b0</td>
<td>File name and extension specification existence</td>
<td>0: Do not modify the file name and extension, 1: Modify the file name and extension</td>
</tr>
<tr>
<td>b1</td>
<td>File attribute modification specification existence</td>
<td>0: Do not modify the attribute, 1: Modify the attribute</td>
</tr>
<tr>
<td>b2</td>
<td>Last edit time modification specification existence</td>
<td>0: Do not modify the last edit time, 1: Modify the last edit time</td>
</tr>
<tr>
<td>b3</td>
<td>Last edit date modification specification existence</td>
<td>0: Do not modify the last edit date, 1: Modify the last edit date</td>
</tr>
<tr>
<td>b4</td>
<td>Modification mode for date and time specification</td>
<td>When modifying date or time, specify which data to use. 0: Use date and time in a message, 1: Use date and time of QnACPU (specify dummy date and time in the message)</td>
</tr>
<tr>
<td>b5</td>
<td>File size modification specification existence</td>
<td>0: Do not modify the file size, 1: Modify the file size</td>
</tr>
</tbody>
</table>

Modifying the file creation date and time (command: 1204, subcommand: 0000)
04H, 08H, 0CH, 14H, 18H, or 1CH can be specified with 16 bits.

<table>
<thead>
<tr>
<th>Bit string</th>
<th>b15</th>
<th>b14</th>
<th>b13</th>
<th>b12</th>
<th>b11</th>
<th>b10</th>
<th>b9</th>
<th>b8</th>
<th>b7</th>
<th>b6</th>
<th>b5</th>
<th>b4</th>
<th>b3</th>
<th>b2</th>
<th>b1</th>
<th>b0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Specification range</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1/0</td>
<td>1/0</td>
<td>1/0</td>
<td>0</td>
<td>0</td>
<td></td>
</tr>
</tbody>
</table>

Modifying the file name and file size (command: 1204, subcommand: 0001)
01H, 02H, 03H, 20H, 21H, 22H, or 23H can be specified with 16 bits.

<table>
<thead>
<tr>
<th>Bit string</th>
<th>b15</th>
<th>b14</th>
<th>b13</th>
<th>b12</th>
<th>b11</th>
<th>b10</th>
<th>b9</th>
<th>b8</th>
<th>b7</th>
<th>b6</th>
<th>b5</th>
<th>b4</th>
<th>b3</th>
<th>b2</th>
<th>b1</th>
<th>b0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Specification range</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1/0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1/0</td>
<td></td>
</tr>
</tbody>
</table>

Modifying the file information in batch (command: 1204; subcommand: 0002)
The range from 01H to 3FH can be specified with 16 bits.

<table>
<thead>
<tr>
<th>Bit string</th>
<th>b15</th>
<th>b14</th>
<th>b13</th>
<th>b12</th>
<th>b11</th>
<th>b10</th>
<th>b9</th>
<th>b8</th>
<th>b7</th>
<th>b6</th>
<th>b5</th>
<th>b4</th>
<th>b3</th>
<th>b2</th>
<th>b1</th>
<th>b0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Specification range</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1/0</td>
<td>1/0</td>
<td>1/0</td>
<td>1/0</td>
<td>1/0</td>
<td>1/0</td>
<td></td>
</tr>
</tbody>
</table>
File No. usage
A data that shows the usage status of the file No. for 256 files to be returned to external devices when the usage status of file No. is read.

■Data communication in ASCII code
Convert the numerical value to 64-digit ASCII code (hexadecimal) and send it to the external device side. (File No. for 8 files: 2 digits)

■Data communication in binary code
Send the following 32-byte value which indicate the usage status to the external device side from the lower bytes (L: bits 0 to 7). (File No. for 8 files: 1 byte)

■Content of file No. usage
The usage status of each file No. is indicated as one file number per bit.

Ex
File No. usage
0: Not used, 1: Used

<table>
<thead>
<tr>
<th>Bit string</th>
<th>b7</th>
<th>b6</th>
<th>b5</th>
<th>b4</th>
<th>b3</th>
<th>b2</th>
<th>b1</th>
<th>b0</th>
<th>Values for 8 bits</th>
</tr>
</thead>
<tbody>
<tr>
<td>1st byte</td>
<td>1</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>2</td>
</tr>
<tr>
<td>2nd byte</td>
<td>1</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>2</td>
</tr>
<tr>
<td>3rd byte</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>2</td>
</tr>
<tr>
<td>4th byte</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>0</td>
<td>2</td>
</tr>
<tr>
<td>5th byte</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>2</td>
</tr>
<tr>
<td>31st byte</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>2</td>
</tr>
<tr>
<td>32nd byte</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>2</td>
</tr>
</tbody>
</table>

*1 Usage of file No. 8
*2 Usage of file No. 1
*3 Usage of file No. 256

The contents of file No. usage to be returned to external devices under the conditions above are shown below.

- Data communication in ASCII code: 'D3B97A' ... 'FFFF' are returned, and are sequentially send beginning from the 'D'.
- Data communication in binary code: 'D3H', 'B9H', '7AH', 'FFH', 'FFH' are returned, and sequentially send beginning from 'D3H'.

File lock mode
A data to specify whether or not a locked file is forcefully unlocked in order to allow access to the specified file from other devices.

■Data communication in ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal) and sent it from the upper digits.

■Data communication in binary code
Send 2-byte numerical value from the low byte (L: bits 0 to 7).

■Specified value and contents of the file lock mode (Other values cannot be specified.)

<table>
<thead>
<tr>
<th>Specified value</th>
<th>Content to be specified</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000H</td>
<td>Unlock the locked file normally.</td>
</tr>
<tr>
<td>0002H</td>
<td>Unlock the locked file forcefully.</td>
</tr>
</tbody>
</table>

■Unlock method for locked file
There are two methods for locking files:

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Normal execution</td>
<td>The locked file cannot be unlocked when other device has registered the file lock. When the file lock deregistration is requested, an error occurs and an abnormal response is returned.</td>
</tr>
<tr>
<td>Forced execution</td>
<td>The locked file is forcefully unlocked even if other device has registered the file lock. Use the forced execution function when a locked file cannot be unlocked because of problems in the device that registered the file lock.</td>
</tr>
</tbody>
</table>
Copy mode

A data to specify whether or not the last edit data and time of the source file to the target file at the completion of copying. The QnACPU management time at a new file creation will remain when the date and time are not copied.

- **Data communication in ASCII code**
  Convert the numerical value to 4-digit ASCII code (hexadecimal) and sent it from the upper digits.

- **Data communication in binary code**
  Send 2-byte numerical value from the low byte (L: bits 0 to 7).

- **Specified value and contents of the copy mode**

<table>
<thead>
<tr>
<th>Setting value</th>
<th>Content to be specified</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000H</td>
<td>Do not copy the last edit date and time of the source file at completion of copying.</td>
</tr>
<tr>
<td>0001H</td>
<td>Copy the last edit date and time of the source file at completion of copying.</td>
</tr>
</tbody>
</table>
File control execution procedure for the QnACPU

The following shows the procedures for executing file control on QnACPU.

Procedure when reading contents of file

1. Check for file existence.
   Check with any of the following commands.
   - Page 302 Read file information table without header statement (command: 0201)
   - Page 305 Read file information table with header statement (command: 0202)
   - Page 308 Read file presence (Search file) (command: 0203)

2. Prohibit access from other devices. (Prohibit file content modification.)
   - Page 315 Register and deregister file locks (command: 0808)

3. Read all content of the file.
   - Page 312 Read file (command: 0206)

4. Allow access from other devices. (Allow file content modification.)
   - Page 315 Register and deregister file locks (command: 0808)

   Store the following file information of the file (for storage) read to an external device.
   - File No.
   - File name and file attribute
   - File size

Procedure when overwriting data to existing file (changing file information)

1. Check for file existence.
   Check with any of the following commands.
   - Page 302 Read file information table without header statement (command: 0201)
   - Page 305 Read file information table with header statement (command: 0202)
   - Page 308 Read file presence (Search file) (command: 0203)

2. Prohibit access from other devices. (Prohibit modification of file.)
   - Page 315 Register and deregister file locks (command: 0808)

3. Before changing the file size, change the QnACPU status to STOP. *1

4. Write data when overwriting or copying data, or changing file size.
   - Page 319 Write to file (command: 1203)

5. Modify the file creation date and time.
   - Page 323 Modify file information (command: 1204)

6. Allow access from other devices. (Allow file content modification).
   - Page 315 Register and deregister file locks (command: 0808)

*1 The file size can be changed using the file information modification function (Page 323 Modify file information (command: 1204)) only when the file size is made smaller. When the file size must be made larger, write data in the same procedure as create a new file. (Page 301 Procedure for creating a new file and write data to it (creating a file by copying))
Procedure for creating a new file and write data to it (creating a file by copying)

1. Check for file existence.
   Check with any of the following commands.
   • Page 302 Read file information table without header statement (command: 0201)
   • Page 305 Read file information table with header statement (command: 0202)
   • Page 308 Read file presence (Search file) (command: 0203)

2. Check unused file No. only when copying a file.
   • Page 310 Read file No. usage status (command: 0204)

3. Check the capacity of consecutive free area.
   • Page 287 Read drive memory usage status (command: 0205)

4. Delete an unnecessary file when free area is insufficient. Or, increase consecutive free area.*1
   • Page 301 Procedure for deleting files
   • Page 289 Defragment drive memory (command: 1207)

5. Register a file name and reserve the capacity.
   • Page 317 Create new file (Register file name) (command: 1202)

6. Prohibit access from other devices. (Prohibit file content modification.)
   • Page 315 Register and deregister file locks (command: 0808)

7. Write data to the file.
   Write data with any of the following commands.
   • Page 319 Write to file (command: 1203)
   • Page 331 Copy file (command: 1206)

8. Modify the file creation date and time. (Can be skipped.)
   • Page 323 Modify file information (command: 1204)

9. Allow access from other devices. (Allow file content modification.)
   • Page 315 Register and deregister file locks (command: 0808)

10. Check the file No. of the created file only when creating a new file.
    • Page 308 Read file presence (Search file) (command: 0203)

*1 Use the remote STOP function (Page 169 Remote STOP (command: 1002)) to place the QnACPU into the STOP status before defragmenting the memory. After the completion of the processing of this section, the remote RUN function (Page 167 Remote RUN (command: 1001)) can be used to set the QnACPU to the RUN status.

Procedure for deleting files

1. Check for file existence.
   Check with any of the following commands.
   • Page 302 Read file information table without header statement (command: 0201)
   • Page 305 Read file information table with header statement (command: 0202)
   • Page 308 Read file presence (Search file) (command: 0203)

2. Delete a file.*1
   • Page 329 Delete file (command: 1205)

*1 Determine the file deletion timing for the entire system, including the QnACPU and related devices.
Read file information table without header statement (command: 0201)

The following examples show the control procedure for reading file information table without header statement within the range of the specified file No.

**Message format**

The following shows the message format of the request data and response data of the command.

- **Request data**

  **ASCII**
  
<table>
<thead>
<tr>
<th>0 2 0 1</th>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
<th>Number of requested files</th>
</tr>
</thead>
<tbody>
<tr>
<td>30n, 32n, 30n, 31n</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

  **Binary**
  
<table>
<thead>
<tr>
<th>01n</th>
<th>Subcommand</th>
<th>Setting flag</th>
<th>Keyword</th>
<th>Drive name</th>
<th>File No.</th>
<th>Number of requested files</th>
</tr>
</thead>
</table>

- **Response data**

<table>
<thead>
<tr>
<th>Total number of registered files</th>
<th>Number of file information</th>
<th>File No.</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
<th>Last edit time</th>
<th>Last edit date</th>
<th>File size</th>
<th></th>
</tr>
</thead>
</table>

  File information (first point)

**Data specified by request data**

- **Command**

  **ASCII code**
  
<table>
<thead>
<tr>
<th>0 2 0 1</th>
<th>30n, 32n, 30n, 31n</th>
</tr>
</thead>
</table>

  **Binary code**
  
<table>
<thead>
<tr>
<th>01n</th>
<th>02n</th>
</tr>
</thead>
</table>

- **Subcommand**

  **ASCII code**
  
<table>
<thead>
<tr>
<th>0 0 0 0</th>
<th>30n, 32n, 30n, 30n</th>
</tr>
</thead>
</table>

  **Binary code**
  
<table>
<thead>
<tr>
<th>00n</th>
<th>00n</th>
</tr>
</thead>
</table>

- **Keyword**

  Allow/prohibit the access to the file of the target memory. (Page 292 Keyword)

- **Setting flag**

  Data that indicates whether the keyword is registered in the specified drive. (Page 292 Setting flag)

- **Drive name**

  A data to specify the drive of CPU module which controls files. (Page 292 Drive name, Drive No.)

- **File No.**

  A data to specify the registration number of files. (Page 292 File No.)

  Specify within the following range.

  \[ 1 \leq \text{File No.} \leq 256 \]
Number of requested file
Number of request files when reading file information. (Page 293 Number of requested file, total number of registered files, number of file information)
Specify within the following range.
\[1 \leq \text{Number of requested file} \leq 36\]

Data stored by response data

Total number of registered files
Number of files registered in the specified drive. (Page 293 Number of requested file, total number of registered files, number of file information)
The value is returned within the following range.
\[1 \leq \text{Total number of registered files} \leq 256\]

Number of file information
Number of files that return file information when reading the file information (Page 293 Number of requested file, total number of registered files, number of file information)
The value is returned within the following range.
\[0 \leq \text{Number of file information} \leq \text{Number of requested file}\]
(0: No registered files after the specified head file No.)

File No.
This indicates the registration number of a file. (Page 292 File No.)

File name
Character string data of a file name. (Page 293 File name, extension, and attribute)

Extension
A character string data of extension of a file. (Page 293 File name, extension, and attribute)

Attribute
A data that indicates the file attribute (applicability of data read/write). (Page 293 File name, extension, and attribute)

Last edit time and last edit date
A data that indicates the date and time when the current data was registered. (Page 294 Last edit time and last edit date)

File size
A data that indicates the capacity of the current file in number of bytes. (Page 295 File size)

Point
- The total number of registered files is the current total number of files registered in the specified drive.
- When all the files are not registered within the specified file number range, the number of file information will be the number of files registered in the specified range (number of file information to be returned).
## Communication example

Read the file information table without header statement in following conditions.
- **Drive name**: 1 (RAM area of memory card A)
- **File No.**: 10
- **Number of requested file**: 2

### Data communication in ASCII code

#### (Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
<th>Number of requested files</th>
</tr>
</thead>
<tbody>
<tr>
<td>0201000001200000100001</td>
<td>A B C D 12</td>
<td>30h, 30h, 30h, 30h</td>
<td>10h</td>
<td>10h</td>
<td>2h</td>
</tr>
</tbody>
</table>

#### (Response data)

<table>
<thead>
<tr>
<th>Total number of registered files</th>
<th>Number of file information</th>
</tr>
</thead>
<tbody>
<tr>
<td>0010</td>
<td>0002</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>File No.</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
<th>Time of last update</th>
<th>Date of last update</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td>000A</td>
<td>A B C D 12</td>
<td>Q P G</td>
<td>20h, 20h, 20h</td>
<td>02h, 02h, 02h, 02h</td>
<td>02h, 02h, 02h, 02h</td>
<td>(20 hours 50 minutes 58 seconds) (January 8, 1996)</td>
</tr>
</tbody>
</table>

### Data communication in binary code

#### (Request data)

<table>
<thead>
<tr>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
<th>Number of requested files</th>
</tr>
</thead>
<tbody>
<tr>
<td>01h, 02h, 00h, 00h, 01h, 00h, 01h, 00h</td>
<td>30h, 30h, 30h, 30h</td>
<td>02h, 02h, 02h, 02h, 02h</td>
<td></td>
</tr>
</tbody>
</table>

#### (Response data)

<table>
<thead>
<tr>
<th>Total number of registered files</th>
<th>Number of file information</th>
</tr>
</thead>
<tbody>
<tr>
<td>01h, 00h</td>
<td>02h, 00h, 02h, 00h, 02h, 00h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>File information 1 (Information of file No. 10)</th>
<th>Last edit time</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td>File No.</td>
<td>File name</td>
<td>Extension</td>
</tr>
<tr>
<td>-----------</td>
<td>-----------</td>
<td>-----------</td>
</tr>
<tr>
<td>01h, 00h</td>
<td>A B C D 12</td>
<td>Q P G</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>File information 2 (Information of file No. 11)</th>
<th>Last edit time</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td>File No.</td>
<td>File name</td>
<td>Extension</td>
</tr>
<tr>
<td>-----------</td>
<td>-----------</td>
<td>-----------</td>
</tr>
<tr>
<td>01h, 00h</td>
<td>E F G H S</td>
<td>Q P G</td>
</tr>
</tbody>
</table>
Read file information table with header statement (command: 0202)

The following examples show the control procedure for reading file information table with header statement within the range of the specified file No.

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>ASCII</th>
<th>Binary</th>
</tr>
</thead>
<tbody>
<tr>
<td>Subcommand</td>
<td>Setting flag</td>
</tr>
<tr>
<td>0 2 0 2</td>
<td>02n</td>
</tr>
</tbody>
</table>

**Response data**

<table>
<thead>
<tr>
<th>Total number of registered files</th>
<th>Number of file information</th>
<th>File No.</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
<th>Last edit time</th>
<th>Last edit date</th>
<th>File size</th>
<th>Header statement</th>
<th>...</th>
<th>File information (nth point)</th>
</tr>
</thead>
</table>

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2 0 2</td>
<td>02n</td>
</tr>
</tbody>
</table>

**Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00n</td>
</tr>
</tbody>
</table>

**Keyword**

Allow/prohibit the access to the file of the target memory. (Page 292 Keyword)

**Setting flag**

Data that indicates whether the keyword is registered in the specified drive. (Page 292 Setting flag)

**Drive name**

A data to specify the drive of CPU module which controls files. (Page 292 Drive name, Drive No.)

**File No.**

A data to specify the registration number of files. (Page 292 File No.)

Specify within the following range.

1 ≤ File No. ≤ 256
**Number of requested file**  
Number of request files when reading file information. (Page 293 Number of requested file, total number of registered files, number of file information)  
Specify within the following range.  
$1 \leq \text{Number of requested file} \leq 16$

**Data stored by response data**

**Total number of registered files**  
Number of files registered in the specified drive. (Page 293 Number of requested file, total number of registered files, number of file information)  
The value is returned within the following range.  
$1 \leq \text{Total number of registered files} \leq 256$

**Number of file information**  
Number of files that return file information when reading the file information. (Page 293 Number of requested file, total number of registered files, number of file information)  
The value is returned within the following range.  
$0 \leq \text{Number of file information} \leq \text{Number of requested file}$  
(0: No registered files after the specified head file No.)

**File No.**  
This indicates the registration number of a file. (Page 292 File No.)

**File name**  
Character string data of a file name. (Page 293 File name, extension, and attribute)

**Extension**  
A character string data of extension of a file. (Page 293 File name, extension, and attribute)

**Attribute**  
A data that indicates the file attribute (applicability of data read/write). (Page 293 File name, extension, and attribute)

**Last edit time and last edit date**  
A data that indicates the date and time when the current data is registered. (Page 294 Last edit time and last edit date)

**File size**  
A data that indicates the capacity of the current file in number of bytes. (Page 295 File size)

**Header statement**  
The header statement attached to the file specified with Engineering tool. (Page 295 Header statement)

**Point**
- The total number of registered files is the current total number of files registered in the designated drive.  
- When all the files are not registered within the specified file number range, the number of file information will be the number of files registered in the specified range (number of file information to be returned).
Communication example

Read the file information table with header statement in following conditions.

- Drive name: 1 (RAM area of memory card A)
- File No.: 10
- Number of requested file: 2

Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
<th>Number of requested files</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2 0 2</td>
<td>0 0 0 0 0</td>
<td>0 1 2 0 0 0 0</td>
<td>0 1 0 0 0 0 1</td>
<td>0 0 0 A</td>
<td>0 0 0 2</td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>File No.</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
<th>Last edit time</th>
<th>Last edit date</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 A</td>
<td>A B C D 1 2</td>
<td>Q P G</td>
<td>A 6 5 D</td>
<td>2 0 2 8</td>
<td>0 0 0 0 1 C 0 0</td>
<td></td>
</tr>
</tbody>
</table>

(Data communication in binary code)

(Request data)

<table>
<thead>
<tr>
<th>Setting flag</th>
<th>Keyword</th>
<th>Drive name</th>
<th>File No.</th>
<th>Number of requested files</th>
</tr>
</thead>
<tbody>
<tr>
<td>02h</td>
<td>00h</td>
<td>00h</td>
<td>01h</td>
<td>02h</td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>File No.</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
<th>Last edit time</th>
<th>Last edit date</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td>15h 00h</td>
<td>A B C D 1 2</td>
<td>Q P G</td>
<td>A 6 5 D</td>
<td>2 0 2 8</td>
<td>0 0 0 0 1 C 0 0</td>
<td></td>
</tr>
</tbody>
</table>

(The order of data items is the same as that of file information 1.)
Read file presence (Search file) (command: 0203)

The following examples show the control procedure for searching for the specified file, and reading its file No. and file size.

**Message format**

- **Request data**

  ASCII

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2 0 3</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>30h, 32h, 30h, 33h</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

  Binary

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
</tr>
</thead>
<tbody>
<tr>
<td>03h, 02h</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- **Response data**

  File No.  File size

**Point**

If the specified file does not exist, an error occurs and the end code at the occurrence of error is returned.

**Data specified by request data**

- **Command**

  **ASCII code**

  | 0 2 0 3 |
  | 30h, 32h, 30h, 33h |

  **Binary code**

  | 03h, 02h |

- **Subcommand**

  **ASCII code**

  | 0 0 0 0 |
  | 30h, 30h, 30h, 30h |

  **Binary code**

  | 00h, 00h |

- **Keyword**

  Allow/prohibit the access to the file of the target memory. (Page 292 Keyword)

- **Setting flag**

  Data that indicates whether the keyword is registered in the specified drive. (Page 292 Setting flag)

- **Drive name**

  A data to specify the drive of CPU module which controls files. (Page 292 Drive name, Drive No.)

- **File name**

  Character string data of a file name. (Page 293 File name, extension, and attribute)

- **Extension**

  A character string data of extension of a file. (Page 293 File name, extension, and attribute)

- **Attribute**

  A data to specify the file attribute (applicability of data read/write). (Page 293 File name, extension, and attribute)
Data stored by response data

■ File No.
This indicates the registration number of a file. (Page 292 File No.)

■ File size
This value indicates the capacity of the current file in number of bytes. (Page 295 File size)

Communication example

Read the existence of a specified file under the following condition.
- Drive name: 1 (RAM area of memory card A)
- File name: ABC12.QPG

■ Data communication in ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2 0 3</td>
<td>0 0 0 0 0</td>
<td>0 1 2 3 0 0</td>
<td>0 1 0 0 0 1</td>
<td>A B C 1 2</td>
<td>□ □ □</td>
<td>□ P G</td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>File No.</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 1 0 0</td>
<td>1 C 0 0 5 0 4 7 2 0 0</td>
</tr>
</tbody>
</table>

■ Data communication in binary code
(Request data)

<table>
<thead>
<tr>
<th>Setting flag</th>
<th>Subcommand</th>
<th>Keyword</th>
<th>Drive name</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 0 0 0</td>
<td>0 0 0 0 0 0</td>
<td>0 1 0 0</td>
<td>0 0 0 0 0 0</td>
<td>0 0 0 0 0 0</td>
<td>0 0 0 0 0 0</td>
<td>0 0 0 0 0 0</td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>File No.</th>
<th>File size</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 1 0 0 0</td>
<td>0 0 0 0 0</td>
</tr>
</tbody>
</table>
Read file No. usage status (command: 0204)

The following examples show the control procedure for reading the usage status of a file No.

### Message format

**Request data**

ASCII

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2 0 4</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Binary</th>
</tr>
</thead>
<tbody>
<tr>
<td>04 02</td>
</tr>
</tbody>
</table>

**Response data**

The file No. of usage status is stored. (Page 298 File No. usage)

When a drive memory that cannot store maximum of 256 files is specified, the file No. of which file cannot be stored (shortage) will be in use (the corresponding bit will be ‘1’).

### Data specified by request data

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2 0 4</td>
<td>04 02</td>
</tr>
</tbody>
</table>

**Subcommand**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
</tbody>
</table>

**Keyword**

Allow/prohibit the access to the file of the target memory. (Page 292 Keyword)

**Setting flag**

Data that indicates whether the keyword is registered in the specified drive. (Page 292 Setting flag)

**Drive name**

A data to specify the drive of CPU module which controls files. (Page 292 Drive name, Drive No.)
Communication example

Read the file No. usage in the following conditions.
• Drive name: 1 (RAM area of memory card A)

■ Data communication in ASCII code

( Request data )

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
</tr>
</thead>
<tbody>
<tr>
<td>0204</td>
<td>000000</td>
<td>01230001</td>
<td>000001</td>
</tr>
</tbody>
</table>

( Response data )

File No. usage status (64 characters)

■ Data communication in binary code

( Request data )

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Drive name</th>
</tr>
</thead>
<tbody>
<tr>
<td>04020000</td>
<td>01010001</td>
<td>0000</td>
</tr>
</tbody>
</table>

( Response data )

File No. usage status (32 bytes)
Read file (command: 0206)

The following examples show the control procedure for reading the data written in the specified file.

**Point**

The maximum number of data bytes to be read per one time is fixed. Read all the data written to the specified file with adjusting the offset address and number of bytes read, and dividing them for several times. Additionally, save the read data to the external device.

Check the file size with the following function.

* Page 302 Read file information table without header statement (command: 0201)
* Page 305 Read file information table with header statement (command: 0202)
* Page 308 Read file presence (Search file) (command: 0203)

---

**Message format**

**Request data**

**ASCII**

<table>
<thead>
<tr>
<th>0 2 0 6</th>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>30n, 32n, 30n, 34n</td>
<td>File name</td>
<td>Extension</td>
<td>Attribute</td>
<td>Offset address</td>
<td>Number of bytes read</td>
</tr>
</tbody>
</table>

**Binary**

<table>
<thead>
<tr>
<th>06, 02</th>
<th>Subcommand</th>
<th>Setting flag</th>
<th>Keyword</th>
<th>Drive name</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>File name</td>
<td>Extension</td>
<td>Attribute</td>
<td>Offset address</td>
<td>Number of bytes read</td>
<td></td>
</tr>
</tbody>
</table>

**Response data**

The read data are stored.

* Page 296 Read data, write data (for batch read and batch write functions)
Data specified by request data

■ Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2 0 6</td>
<td>06 02</td>
</tr>
</tbody>
</table>

■ Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
</tbody>
</table>

■ Keyword
Allow/prohibit the access to the file of the target memory. (Page 292 Keyword)

■ Setting flag
Data that indicates whether the keyword is registered in the specified drive. (Page 292 Setting flag)

■ Drive name
A data to specify the drive of CPU module which controls files. (Page 292 Drive name, Drive No.)

■ File No.
A data to specify the registration number of files. (Page 292 File No.)
Specify within the following range.
1 ≤ File No. ≤ 256

■ File name
Character string data of a file name. (Page 293 File name, extension, and attribute)

■ Extension
A character string data of extension of a file. (Page 293 File name, extension, and attribute)

■ Attribute
A data to specify the file attribute (applicability of data read/write). (Page 293 File name, extension, and attribute)
Handle the file attribute to be read as dummy data.

■ Offset address
A data to specify the start address of the range from which data is read to a file. (Page 295 Offset address)
Specify within the following range.
0 ≤ Address (specify with even address) ≤ (File size - 1)

■ Number of bytes read
A data to specify the number of bytes of the range from which data is read to a file.
Specify within the following range.
0 ≤ Number of bytes ≤ 960
## Communication example

Read the data written in the specified file under the following condition.

- Drive name: 1 (RAM area of memory card A)
- File No.: 1
- File name: ABC12.QPG
- Offset address: 100H
- Number of bytes read: 50 bytes

### Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2 0 6</td>
<td>0 0 0 0 0</td>
<td>0 1 2 3 0 0 0 0 1</td>
<td>0 0 0</td>
<td>1 0 0 0 0 1</td>
</tr>
</tbody>
</table>

### Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Setting flag</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Drive name</td>
<td>File name</td>
</tr>
<tr>
<td>Offset address</td>
<td>Number of bytes read</td>
</tr>
</tbody>
</table>

### (Response data)

Data read (For 50 bytes)

```
1 3 S F O C O 2 ... 0 1 0 B 1 E
```

Address 100H to 130H

### Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Setting flag</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Subcommand</td>
<td>Keyword</td>
</tr>
<tr>
<td>Drive name</td>
<td>File name</td>
</tr>
<tr>
<td>Offset address</td>
<td>Number of bytes read</td>
</tr>
</tbody>
</table>

### (Response data)

Data read (For 50 bytes)

```
13 5F 0C 02 ... 01 0B 1E
```

Address 100H to 130H
Register and deregister file locks (command: 0808)

The following examples show the control procedure for registering and deregistering a file lock.

Restarting QnACPU (such as resetting CPU module) with the file lock registered results in the file lock deregistered state.

Message format

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>File lock mode</th>
<th>Drive name</th>
<th>File No.</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
</tr>
</thead>
</table>

**Response data**

There is no response data for this command.

Data specified by request data

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 8 0 8</td>
<td>08h</td>
</tr>
</tbody>
</table>

**Subcommand**

- Register

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 1</td>
<td>01h</td>
</tr>
</tbody>
</table>

- Deregister

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00h</td>
</tr>
</tbody>
</table>

**File lock mode**

A data to specify whether a locked file is to be forcefully unlocked in order to allow other devices to access the specified file. (Page 298 File lock mode)

**Drive name**

A data to specify the drive of CPU module which controls files. (Page 292 Drive name, Drive No.)

**File No.**

A data to specify the registration number of files. (Page 292 File No.)

**File name**

Character string data of a file name. (Page 293 File name, extension, and attribute)

**Extension**

A character string data of extension of a file. (Page 293 File name, extension, and attribute)

**Attribute**

A data to specify the file attribute (applicability of data read/write). (Page 293 File name, extension, and attribute) The attribute assigned by a new file creation, etc. is valid as the attribute of the file that will be locked and unlocked. When registering and deregistering file lock, handle the file attribute as dummy data.
## Communication example (Register)

Read the existence of a specified file under the following condition.

- **File lock mode:** 0 (usual practice)
- **Drive name:** 1 (RAM area of memory card A)
- **File No.:** 1
- **File name:** ABC12.QPG

### Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>File lock mode</th>
<th>Drive name</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 8 0 8</td>
<td>0 0 0 1</td>
<td>0 0 0 1</td>
<td>0 0 0 1</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Data communication in ASCII code (Request data)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Subcommand</td>
</tr>
<tr>
<td>0 8 0 8</td>
</tr>
<tr>
<td>0 0 0 1</td>
</tr>
</tbody>
</table>

### Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>File lock mode</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>08, 08, 01, 00, 01, 00, 04, 42, 43, 31, 32, 20, 20, 51, 50, 47, 20</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Data communication in binary code (Request data)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Subcommand</td>
</tr>
<tr>
<td>08, 08</td>
</tr>
<tr>
<td>01, 00, 01, 00, 04, 42, 43, 31, 32, 20, 20, 51, 50, 47, 20</td>
</tr>
</tbody>
</table>
Create new file (Register file name) (command: 1202)

The following examples show the control procedure for registering a new file and reserving a file area on the specified disk. Write data to the file created using this function with the following function.

Page 319 Write to file (command: 1203)
The content of file in which data is not written cannot be read.

- A new file can be created on the specified drive memory within the size of consecutive unused clusters. Creating a new file considering the rest of the capacity for future use is recommended.
- The QnACPU management time is registered as the last edit date and time to a new file created using this function.

Message format

Request data

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>Fixed value</th>
<th>Fixed value</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 0 2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

File No. is stored. (Page 292 File No.)

Response data

Data specified by request data

Command

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Setting flag</th>
<th>Keyword</th>
<th>Drive name</th>
<th>Fixed value</th>
<th>Fixed value</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 0 2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Subcommand

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Fixed value</th>
<th>Fixed value</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Keyword

Allow/prohibit the access to the file of the target memory. (Page 292 Keyword)

Setting flag

Data that indicates whether the keyword is registered in the specified drive. (Page 292 Setting flag)
**Drive name**
A data to specify the drive of CPU module which controls files. (Page 292 Drive name, Drive No.)

**Fixed value**
'0000' (at the time of an ASCII code) or 0000H (at the time of a binary code) is transmitted. (Page 297 Fixed value)

**File name**
Character string data of a file name. (Page 293 File name, extension, and attribute)

**Extension**
A character string data of extension of a file. (Page 293 File name, extension, and attribute)

**Attribute**
A data to specify the file attribute (applicability of data read/write). (Page 293 File name, extension, and attribute)
Specify '20H' (readable/writable disk file) for the attribute of a new file.

**Capacity**
A data to reserve the file area on the specified disk when registering a new file. It is specified with the number of bytes. (Page 296 Capacity)

### Communication example
Read the data written in the specified file under the following condition.
- Drive name: 1 (RAM area of memory card A)
- File name: ABC12.QPG
- Capacity: 172 bytes

#### Data communication in ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>Fixed value</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>2</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>1</td>
<td>2</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1</td>
<td>2</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>1</td>
<td>2</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>

(Response data)

#### Data communication in binary code
(Request data)

<table>
<thead>
<tr>
<th>Command</th>
<th>Setting flag</th>
<th>Keyword</th>
<th>Drive name</th>
<th>Fixed value</th>
<th>Fixed value</th>
<th>File name</th>
<th>Extension</th>
</tr>
</thead>
<tbody>
<tr>
<td>02h</td>
<td>0</td>
<td>00h</td>
<td>00h</td>
<td>01h</td>
<td>02h</td>
<td>00h</td>
<td>00h</td>
</tr>
<tr>
<td>00h</td>
<td>0</td>
<td>00h</td>
<td>00h</td>
<td>01h</td>
<td>01h</td>
<td>00h</td>
<td>00h</td>
</tr>
<tr>
<td>00h</td>
<td>0</td>
<td>00h</td>
<td>00h</td>
<td>00h</td>
<td>00h</td>
<td>00h</td>
<td>00h</td>
</tr>
<tr>
<td>00h</td>
<td>0</td>
<td>00h</td>
<td>00h</td>
<td>00h</td>
<td>00h</td>
<td>00h</td>
<td>00h</td>
</tr>
</tbody>
</table>

(Response data)
Write to file (command: 1203)

The following example shows the control procedure for writing the data of the file that has been read from the QnACPU and stored in an external device to the specified file ("batch write"), and the control procedure for writing n-bytes of arbitrary one-word data to the specified file ("identical data write (FILL)").

The maximum number of data bytes to be read per one time is static.
- For batch writing, all the data read from QnACPU and stored to an external device must be written to the specified file with adjusting the offset address and number of bytes written and divide them for several times.
- For writing identical data, adjust the offset address and number of bytes written, and divide them and write arbitrary 1 word data within the range of specified file for several times. Note that, if the data size to be written remains 1 byte, the numerical value of upper bytes of 1 word data (bit 8 to 15) is not written since the data write is performed in byte units.

Message format

<table>
<thead>
<tr>
<th>Request data</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>ASCII</strong></td>
</tr>
<tr>
<td>1  2  0  3</td>
</tr>
<tr>
<td>31h, 32h, 30h, 33h</td>
</tr>
<tr>
<td>Offset address</td>
</tr>
<tr>
<td></td>
</tr>
</tbody>
</table>

| **Binary**   |
| 03h, 12h     | Subcommand | Setting flag | Keyword | Drive name | File No. | File name | Extension | Attribute |
|              |            |             |         |           |          |           |           |           |
| Offset address | Number of bytes written | Write data |
|               |                          |              |

<table>
<thead>
<tr>
<th>Response data</th>
</tr>
</thead>
<tbody>
<tr>
<td>There is no response data for this command.</td>
</tr>
</tbody>
</table>

An error occurs if one of the following files is specified while the QnACPU is in RUN, and error end code will be returned.
- Parameter file
- Currently executing file in the built-in RAM (drive name: 00H)
Data specified by request data

- **Command**

  **ASCII code** | **Binary code**
  --- | ---
  1 2 0 3 | 03h 12h

- **Subcommand**

  **Type** | **ASCII code** | **Binary code**
  --- | --- | ---
  Batch write | 0 0 0 0 | 00h 00h

  Writing the identical data (FILL) | 0 0 0 1 | 01h 00h

- **Keyword**

  Allow/prohibit the access to the file of the target memory. (Page 292 Keyword)

- **Setting flag**

  Data that indicates whether the keyword is registered in the specified drive. (Page 292 Setting flag)

- **Drive name**

  A data to specify the drive of CPU module which controls files. (Page 292 Drive name, Drive No.)

- **File No.**

  A data to specify the registration number of files. (Page 292 File No.)

- **File name**

  Character string data of a file name. (Page 293 File name, extension, and attribute)

- **Extension**

  A character string data of extension of a file. (Page 293 File name, extension, and attribute)

- **Attribute**

  A data to specify the file attribute (applicability of data read/write). (Page 293 File name, extension, and attribute)
  The attribute assigned by a new file creation, etc. is valid as the attribute of the file to which data is written. When writing data, handle the attribute as dummy data.

- **Offset address**

  A data which specifies the start address of the range in which data is written to a file. (Page 295 Offset address)
  Specify within the following range.
  \[0 \leq \text{Address} \leq (\text{File size} - 1)\]
  - Writing data to file of which drive name is '00H' (built-in RAM): Specify with multiples of 4 (0, 4, 8, ... in decimal notation).
  - Writing to the file of which drive name is other than '00H': Specify with even number (for decimal data, 0, 2, 4, 6, 8, ...).

- **Number of bytes written**

  Data to specify the number of bytes of data to be written. (Page 296 Number of bytes read, number of bytes written)
  Specify within the following range.
  \[0 \leq \text{Number of bytes} \leq 960\]

- **Write data**

  Data to be written to a file. (Page 296 Read data, write data (for batch read and batch write functions))
**Communication example (Batch write)**

Batch write is executed under the following condition:

- **Drive name**: 1 (RAM area of memory card A)
- **File No.**: 1
- **File name**: ABC12.QPG
- **Offset address**: 7CH
- **Number of bytes written**: 416 bytes

**Data communication in ASCII code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 0 3</td>
<td>0 0 0 0</td>
<td>0 1 2 3 0 0 0 1 0 0 0 1</td>
<td>0 0 0 1</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
<th>Offset address</th>
<th>Number of bytes written</th>
</tr>
</thead>
<tbody>
<tr>
<td>A B C 1 2</td>
<td>Q P G 0 0 0 0 0 0 7 C 0 1 A 0</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Address 7CH | Address 7DH to 21AH | Address 21BH

---

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Setting flag</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>03 12 00 0 01</td>
<td>00 00 01</td>
<td></td>
</tr>
</tbody>
</table>

Number of bytes written | Address 7DH to 21AH | Address 21BH

---

<table>
<thead>
<tr>
<th>Extension</th>
<th>Attribute</th>
<th>Offset address</th>
</tr>
</thead>
<tbody>
<tr>
<td>51 50 47 20 7C 00 00 00 A0 01 19 99 12</td>
<td>02 05 DC</td>
<td></td>
</tr>
</tbody>
</table>

Write data (For 416 bytes)
Communication example (Write identical data (FILL))

The identical data are written (FILL) by FFFFH under the following condition.

- Drive name: 1 (RAM area of memory card A)
- File No.: 1
- File name: ABC12.QPG
- Offset address: 7CH
- Number of bytes written: 416 bytes

Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 0 3</td>
<td>0 0 0 1</td>
<td>0 1 2 3 0 0</td>
<td>0 0 0 1</td>
<td>0 0 0 1</td>
</tr>
</tbody>
</table>

Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Setting flag</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>03h 12h</td>
<td>01h 00h</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Extension</th>
<th>Attribute</th>
<th>Offset address</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>51h 47h</td>
<td>20h</td>
<td>JCh 00h 00h</td>
<td>0Ah 01h</td>
</tr>
</tbody>
</table>
Modify file information (command: 1204)

The following examples show the procedure to modify the file information of the specified file.

Message format

- **Request data**
  - Modify file creation date and time (subcommand: 0000)

  **ASCII**

  ```
  1 2 0 4 Subcommand Keyword Setting flag Drive name File No. File name Extension Attribute
  31h 32h 30h 34h
  Modification pattern Last edit time Last edit date
  ```

  **Binary**

  ```
  04h 12h Subcommand Setting flag Keyword Drive name File No. File name Extension Attribute
  Modification pattern Last edit time Last edit date
  ```

  - Modify file name, attribute, file size (subcommand: 0001)

  **ASCII**

  ```
  1 2 0 4 Subcommand Keyword Setting flag Drive name File No. File name (Before modification) Extension (Before modification) Attribute (Before modification) Modification pattern File name (After modification) Extension (After modification) Attribute (After modification) File size Fixed value
  31h 32h 30h 34h
  ```

  **Binary**

  ```
  04h 12h Subcommand Setting flag Keyword Drive name File No. File name (Before modification) Extension (Before modification) Attribute (Before modification) File size Fixed value
  Modification pattern File name (After modification) Extension (After modification) Attribute (After modification)
  ```

- The size can be modified only while the QnACPU is in STOP. A consecutive free area of the specified size is necessary on the specified drive. The free area can be checked by reading memory usage status shown in the following section.

  Page 287 Read drive memory usage status (command: 0205)
**Batch modify file information (subcommand: 0002)**

**Response data**

There is no response data for this command.

An error occurs if one of the following files is specified while the QnACPU is in RUN, and error end code will be returned.

- Parameter file
- Currently executing file in the built-in RAM (drive name: 00H)
Data specified by request data

■ Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>31 32 04</td>
<td>04</td>
</tr>
</tbody>
</table>

■ Subcommand

<table>
<thead>
<tr>
<th>Type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Modify file creation date and time</td>
<td>0 0 0 0</td>
<td>00</td>
</tr>
<tr>
<td>Batch modify file information</td>
<td>0 0 0 2</td>
<td>02</td>
</tr>
</tbody>
</table>

■ Keyword
Allow/prohibit the access to the file of the target memory. (Page 292 Keyword)

■ Setting flag
Data that indicates whether the keyword is registered in the specified drive. (Page 292 Setting flag)

■ Drive name
A data to specify the drive of CPU module which controls files. (Page 292 Drive name, Drive No.)

■ File No.
A data to specify the registration number of files. (Page 292 File No.)
Specify within the following range.
1 ≤ File No. ≤ 256

■ File name
Character string data of a file name. (Page 293 File name, extension, and attribute)

■ Extension
A character string data of extension of a file. (Page 293 File name, extension, and attribute)

■ Attribute
A data to specify the file attribute (applicability of data read/write). (Page 293 File name, extension, and attribute)
The attribute can only be modified between 01H (read only file) ↔ 20H (read/write enabled file)

■ Modification pattern
A data to specify which information is to modify when modifying information (file name, size, created date and time) of the existing file. (Page 297 Modification pattern (for changing file name and file size))

■ Last edit time and last edit date
A data that indicates the date and time when the current data was registered. (Page 294 Last edit time and last edit date)

■ File size
A data that indicates the capacity of the current file in number of bytes. (Page 295 File size)

■ Fixed value
Send ‘0000’ (at the time of ASCII code) or 0000H (at the time of binary code). (Page 297 Fixed value)
Communication example (Modify file creation time) (subcommand: 0000)

Modify the creation time of the following file.
- Drive name: 1 (RAM area of memory card A)
- File name: ABC12.QPG
- Modification pattern: 14H (specify the time of QnACPU for the last edit time.)

**Data communication in ASCII code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>01 00 00 00</td>
<td>01 00 00 00</td>
<td>FF FF FF FF</td>
<td>01 00 00 00</td>
<td></td>
</tr>
</tbody>
</table>

**Data communication in binary code**

(Request data)

<table>
<thead>
<tr>
<th>Setting flag</th>
<th>Keyword</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>FF FF FF FF</td>
<td>01 00 00 00</td>
<td></td>
</tr>
</tbody>
</table>

Subcommand: 0000

**Communication example (Modify file creation time) (subcommand: 0000)**

Modify the creation time of the following file.
- Drive name: 1 (RAM area of memory card A)
- File name: ABC12.QPG
- Modification pattern: 14H (specify the time of QnACPU for the last edit time.)

**Data communication in ASCII code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>01 00 00 00</td>
<td>01 00 00 00</td>
<td>FF FF FF FF</td>
<td>01 00 00 00</td>
<td></td>
</tr>
</tbody>
</table>

**Data communication in binary code**

(Request data)

<table>
<thead>
<tr>
<th>Setting flag</th>
<th>Keyword</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>FF FF FF FF</td>
<td>01 00 00 00</td>
<td></td>
</tr>
</tbody>
</table>

Subcommand: 0000
Modify the file name and attribute of the following file.

- **Drive name:** 1 (RAM area of memory card A)
- **File No.:** 1
- **File name (before modification):** ABC12.QPG
- **File name (after modification):** ABC1234.QPG
- **Attribute (before modification):** 20H (disk files that can be read/written)
- **Attribute (after modification):** 01H (read only file)

### Data communication in ASCII code

(Request data)

![ASCII Data Communication Diagram]

### Data communication in binary code

(Request data)

![Binary Data Communication Diagram]
Communication example (Batch modify file information) (subcommand: 0002)

Modify the file name of the following files, attribute, and last edit date and time.

- Drive name: 1 (RAM area of memory card A)
- File No.: 1
- File name (before modification): ABC12.QPG
- File name (after modification): ABC1234.QPG
- Attribute (before modification): 20H (disk files that can be read/written)
- Attribute (after modification): 01H (read only file)
- Modification pattern: 1FH (Specify the date and time of QnACPU to the last edit day and last edit time)

**Data communication in ASCII code**

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 0 4</td>
<td>0 0 0 2</td>
<td>0 1 2 3 0 0</td>
<td>0 1 0 0 1 1</td>
<td>0 0 0 1</td>
</tr>
</tbody>
</table>

 Attribute (Before modification)

<table>
<thead>
<tr>
<th>A B C 1 2</th>
<th>Q P G</th>
<th>0 0 0 1 F</th>
<th>A B C 1 2 3 4</th>
</tr>
</thead>
<tbody>
<tr>
<td>43h, 42h, 43h, 31h, 32h, 20h, 20h, 20h</td>
<td>51h, 50h, 47h</td>
<td>20h</td>
<td>30h, 30h, 31h, 66h</td>
</tr>
</tbody>
</table>

 Attribute (After modification)

<table>
<thead>
<tr>
<th>Extension (Before modification)</th>
<th>Last edit time</th>
<th>Last edit date</th>
<th>File size</th>
<th>Fixed value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Q P G</td>
<td>0 0 0 0 0</td>
<td>0 0 0 0</td>
<td>0 0 0</td>
<td>0 0 0 0 0</td>
</tr>
<tr>
<td>51h, 50h, 47h</td>
<td>01h, 30h, 30h, 30h, 30h</td>
<td>30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h</td>
<td>30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h, 30h</td>
<td></td>
</tr>
</tbody>
</table>

**Data communication in binary code**

(Request data)

<table>
<thead>
<tr>
<th>Setting flag</th>
<th>Keyword</th>
<th>Drive name</th>
</tr>
</thead>
<tbody>
<tr>
<td>04h, 12h</td>
<td>02h, 00h</td>
<td>01h, 23h</td>
</tr>
</tbody>
</table>

 Attribute (Before modification)

<table>
<thead>
<tr>
<th>Extension (Before modification)</th>
<th>Modification pattern</th>
<th>File name (Before modification)</th>
</tr>
</thead>
<tbody>
<tr>
<td>43h, 42h, 43h, 31h, 32h, 20h, 20h, 20h</td>
<td>51h, 50h, 47h</td>
<td>20h</td>
</tr>
<tr>
<td>41h, 00h</td>
<td>41h, 42h, 43h, 31h, 32h, 33h, 34h, 20h</td>
<td></td>
</tr>
</tbody>
</table>

 Attribute (After modification)

<table>
<thead>
<tr>
<th>Extension (After modification)</th>
<th>Last edit time</th>
<th>File size</th>
<th>Fixed value</th>
</tr>
</thead>
<tbody>
<tr>
<td>51h, 50h, 47h</td>
<td>01h, 00h, 00h, 00h</td>
<td>00h, 00h, 00h, 00h</td>
<td>00h, 00h</td>
</tr>
</tbody>
</table>

---

15 QnACPU DEDICATED COMMANDS
15.3 File Control
Delete file (command: 1205)

The following examples show the procedure to delete the existing files.

Determine the file deletion timing for the entire system, including the QnACPU and related devices.
The file in which the file lock has been registered cannot be deleted.
When QnACPU is in RUN, the following files cannot be deleted.
- Program file (Q.PG)
- Parameter file (Q.PA)
- Boot setting file (Q.BT)

Message format

**Request data**

<table>
<thead>
<tr>
<th>ASCII</th>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>1</td>
<td>2</td>
<td>0</td>
<td>5</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>35n</td>
<td>33n</td>
<td>32n</td>
<td>30n</td>
<td>35n</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Response data**

There is no response data for this command.

Data specified by request data

**Command**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 0 5</td>
<td>05n 12n</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Subcommand</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00n 00n</td>
</tr>
</tbody>
</table>

**Keyword**

Allow/prohibit the access to the file of the target memory. ([Page 292 Keyword])

**Setting flag**

Data that indicates whether the keyword is registered in the specified drive. ([Page 292 Setting flag])

**Drive name**

A data to specify the drive of CPU module which controls files. ([Page 292 Drive name, Drive No.)

**File No.**

A data to specify the registration number of files. ([Page 292 File No.)

**File name**

Character string data of a file name. ([Page 293 File name, extension, and attribute])
**Extension**
A character string data of extension of a file. (Page 293 File name, extension, and attribute)

**Attribute**
A data to specify the file attribute (applicability of data read/write). (Page 293 File name, extension, and attribute)
When deleting a file, handle the attribute as dummy data.

## Communication example
Delete files under the following conditions.
- Drive name: 1 (RAM area of memory card A)
- File No.: 1
- File name: ABC12.QPG

### Data communication in ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x12</td>
<td>0x50</td>
<td>0x00</td>
<td>0x03</td>
<td>0x00</td>
</tr>
</tbody>
</table>

**File name**

<table>
<thead>
<tr>
<th>A</th>
<th>8</th>
<th>C</th>
<th>1</th>
<th>2</th>
<th>Q</th>
<th>P</th>
<th>G</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x41</td>
<td>0x42</td>
<td>0x43</td>
<td>0x31</td>
<td>0x32</td>
<td>0x20</td>
<td>0x20</td>
<td>0x20</td>
</tr>
</tbody>
</table>

### Data communication in binary code
(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Drive name</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x05</td>
<td>0x12</td>
<td>0x00</td>
<td>0x00</td>
</tr>
</tbody>
</table>

**File name**

<table>
<thead>
<tr>
<th>A</th>
<th>8</th>
<th>C</th>
<th>1</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x41</td>
<td>0x42</td>
<td>0x43</td>
<td>0x31</td>
<td>0x32</td>
</tr>
</tbody>
</table>
Copy file (command: 1206)

The following examples show the procedure to copy a file. (For QnACPU)

The maximum number of data bytes to be copied per one time is static. For the data which are already written, adjust the offset address and number of copy bytes, and divide them and write to the new registration file for several times.

**Message format**

**Request data**

- **ASCI**

  - 1 2 0 6 Subcommand

  - 31H, 32H, 30H, 36H

  - Keyword Setting flag Drive name File No. File name Extension Attribute Offset address Number of bytes read Copy mode

  - Copy source

  - 36H 12H Subcommand

  - Setting flag Keyword Drive name File No. File name Extension Attribute Offset address

  - Copy destination

**Response data**

There is no response data for this command.

- **Point**

  An error occurs if one of the following files is specified while the QnACPU is in RUN, and error end code will be returned.
  - Parameter file
  - Currently executing file in the built-in RAM (drive name: 00H)
Data specified by request data

■ Command

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 0 6</td>
<td>06 12</td>
</tr>
</tbody>
</table>

■ Subcommand

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>00 00</td>
</tr>
</tbody>
</table>

■ Keyword
Allow/prohibit the access to the file of the target memory. (Page 292 Keyword)

■ Setting flag
This indicates whether the keyword registered in the specified drive matches the keyword of request data. (Page 284 Setting flag)

■ Drive name
A data to specify the drive of CPU module which controls files. (Page 292 Drive name, Drive No.)

■ File No.
A data to specify the registration number of files. (Page 292 File No.)

■ File name
Character string data of a file name. (Page 293 File name, extension, and attribute)

■ Extension
A character string data of extension of a file. (Page 293 File name, extension, and attribute)

■ Attribute
A data to specify the file attribute (applicability of data read/write). (Page 293 File name, extension, and attribute)
The attribute assigned by a new file creation, etc. is valid as the attribute of the source and destination files. When copying a file, handle the attribute as dummy data.

■ Offset address
A data to specify the start address of the range from which data is read to a file. (Page 295 Offset address)
Specify within the following range.
Offset address: $0 \leq \text{Address} \leq (\text{File size} - 1)$
• Copy to the file whose drive name is '00H' (Built-in RAM): Specify with multiples of 4 (0, 4, 8, ... in decimal notation).
• Copy to the file whose drive name is other than '00H': Specify with even number (for decimal data, 0, 2, 4, 6, 8, ...).

■ Number of bytes read (number of copy bytes)
A data to specify the range from which data is read in byte unit to file. Specify the data as one address per one byte. (Page 296 Number of bytes read, number of bytes written)
Specify within the following range.
Number of copied bytes: $0 \leq \text{Number of bytes} \leq 480$

■ Copy mode
A data to specify whether to copy the last edit time and data of the source file to the target file at the completion of copying.
When the time and date are not copied, the QnACPU management time at a new file creation will remain. (Page 299 Copy mode)
Communication example

Copy the file with the following condition.

- Drive name (copy source): 1 (RAM area of memory card A)
- Drive name (copy destination): 3 (RAM area of memory card B)
- File No. (copy source): 1H (1)
- File No. (copy destination): AH (10)
- File name (copy source): ABC12.QPG
- File name (copy destination): ABC12001.QPG
- Offset address (copy source): 1E0H
- Number of bytes read (copy source): 480 bytes
- Copy mode (copy source): 0 (Do not copy the last edit date and time of the copy source.)

Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Keyword</th>
<th>Setting flag</th>
<th>Drive name</th>
<th>File No.</th>
<th>Copy source</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 0 6</td>
<td>0 0 0 0</td>
<td>1 2 3 0</td>
<td>0 0 1</td>
<td>0 0 0 1</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Copy source</th>
</tr>
</thead>
<tbody>
<tr>
<td>31H, 32H, 30H, 36H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 30H</td>
</tr>
<tr>
<td>30H, 31H, 32H, 33H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 31H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 31H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 31H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 31H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 31H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 31H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 31H</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>File name</th>
<th>Extension</th>
<th>Attribute</th>
<th>Offset address</th>
<th>Number of bytes read</th>
<th>Copy mode</th>
</tr>
</thead>
<tbody>
<tr>
<td>A B C 1 2</td>
<td>0 0 0 0</td>
<td>1 E 0</td>
<td>0 1 E 0</td>
<td>0 0 0 0</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Copy source</th>
</tr>
</thead>
<tbody>
<tr>
<td>43H, 42H, 43H, 31H</td>
</tr>
<tr>
<td>32H, 20H, 32H</td>
</tr>
<tr>
<td>30H, 31H, 30H, 33H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 32H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 34H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 35H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 36H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 37H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 38H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 39H</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Copy destination</th>
</tr>
</thead>
<tbody>
<tr>
<td>4 4 8 8 0 0 1 0 0 3</td>
</tr>
<tr>
<td>A B C 1 2 0 0 1</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Copy destination</th>
</tr>
</thead>
<tbody>
<tr>
<td>34H, 32H, 34H, 38H</td>
</tr>
<tr>
<td>30H, 31H, 30H, 33H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 32H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 34H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 35H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 36H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 37H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 38H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 39H</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Extension</th>
<th>Attribute</th>
<th>Offset address</th>
</tr>
</thead>
<tbody>
<tr>
<td>Q P G</td>
<td>0 0 0 0</td>
<td>0 1 E 0</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Copy destination</th>
</tr>
</thead>
<tbody>
<tr>
<td>Q P G 0 0 0 0 0 1 E 0</td>
</tr>
<tr>
<td>51H, 50H, 47H</td>
</tr>
<tr>
<td>20H, 30H, 30H, 30H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 31H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 30H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 30H</td>
</tr>
<tr>
<td>30H, 30H, 30H, 30H</td>
</tr>
</tbody>
</table>
### Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Setting flag</th>
<th>File No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Subcommand</td>
<td></td>
</tr>
<tr>
<td>Keyword</td>
<td>Drive name</td>
</tr>
<tr>
<td></td>
<td>File name</td>
</tr>
</tbody>
</table>

- **Copy source**
  - Offset address
  - Copy mode
  - Setting flag

- **Copy destination**
  - Extension Attribute
  - Number of bytes read
  - Keyword
  - Drive name

- **Copy source**
  - File No.
  - File name
  - Extension Attribute

- **Copy destination**
  - Offset address

**Data Structure**

```
06h 12h 00h 00h 01h 00h 23h 01h 01h 00h 01h 00h 41h 42h 43h 31h 32h 20h 20h 20h
```

**Copy Source**

```
51h 50h 47h 20h 00h 01h 00h 00h 00h 01h 00h 88h 44h 03h 00h
```

**Copy Destination**

```
0Ah 00h 41h 42h 43h 31h 32h 30h 31h 51h 50h 47h 20h 00h 01h 00h 00h
```
This part explains the specifications when using MELSEC-A series devices.

16 MELSEC-A SERIES SUPPORTED SPECIFICATIONS

17 COMMUNICATING USING 1C FRAMES

18 COMMUNICATING USING 1E FRAMES
16 MELSEC-A SERIES SUPPORTED SPECIFICATIONS

This chapter explains the specifications of the messages of MC protocol and access ranges when using the MELSEC-A series devices as follows:

- When accessing system including MELSEC-A series modules
- When utilizing the software for data communication created for MELSEC-A series programmable controller.

16.1 Frames and Commands that can be Used

When accessing MELSEC-A series modules, all frames of MC protocol can be used. However, the commands that can be used have some restrictions. (Page 465 Accessible Modules for Each Command)

A compatible frame

The following frames have compatibility with the message protocol and the message format for MELSEC-A series.

<table>
<thead>
<tr>
<th>Frame</th>
<th>Compatible message format</th>
<th>Access range</th>
</tr>
</thead>
<tbody>
<tr>
<td>1C frame</td>
<td>Dedicated protocol for MELSEC-A series computer link modules</td>
<td>Page 45 Accessible range of 1C frame</td>
</tr>
<tr>
<td>1E frame</td>
<td>Message formats for MELSEC-A series Ethernet interface modules</td>
<td>Page 47 Accessible range of 1E frame</td>
</tr>
</tbody>
</table>

16.2 Accessible modules

The following MELSEC-A series modules can be accessed within the access range.

Accessible modules to other stations

The following modules can be accessed.

<table>
<thead>
<tr>
<th>Type</th>
<th>Model name</th>
</tr>
</thead>
<tbody>
<tr>
<td>CPU module</td>
<td>A1NCPU, A2NCPU, A2NCPU-S1, A3NCPU, A2ACPU, A2ACPU-S1, A3ACP, A2UCPU, A2UCPU-S1, A3UCPU, A4UCPU</td>
</tr>
<tr>
<td></td>
<td>A15CPU, A15CPU(-S3), A1SHCPU, A1SHCPU, A25CPU, A25CPU, A2SHCPU, A2UCPU, A2UCPU-S1, A2USCPU, A2USCPU-S1</td>
</tr>
<tr>
<td></td>
<td>A0J2HCPU</td>
</tr>
<tr>
<td></td>
<td>Q02CPU-A, Q02CPU-A, Q09CPU-A</td>
</tr>
<tr>
<td></td>
<td>A2CCPUC24 and A2CCPUC24-PRF (when connected to an external device by multidrop connection.)</td>
</tr>
<tr>
<td>MELSECNET/10 remote I/O</td>
<td>AJ72LP25 (G), AJ72BR15</td>
</tr>
<tr>
<td>Special function module</td>
<td>Refer to the following section. (Page 379 Accessible modules)</td>
</tr>
</tbody>
</table>

Modules that can be relayed between networks

For the modules that can be relayed between networks when accessing MELSEC-A series module, refer to the following table.

<table>
<thead>
<tr>
<th>MELSEC-A series module</th>
</tr>
</thead>
<tbody>
<tr>
<td>Network</td>
</tr>
<tr>
<td>MELSECNET/10</td>
</tr>
</tbody>
</table>

Module other than MELSEC-A series

Page 280 Modules that can be relayed between networks
16.3 Considerations

The following shows the considerations when using MELSEC-A series devices.

**Considerations when connecting C24**

- **When a computer link module is included in multidrop connection**
  Access in ASCII code (format 1 to format 4). A binary code (format 5) cannot be used. (Including the access to the connected station)

**Considerations when connecting E71**

- **Setting range of monitoring timer**
  When accessing ACPU for the first time, the wait time for CPU monitoring timer is required before receiving a response message because QnACPU identifies the CPU type. Be sure to set a value within the setting range shown below.

<table>
<thead>
<tr>
<th>Access target</th>
<th>Monitoring timer</th>
</tr>
</thead>
<tbody>
<tr>
<td>Connected station (host station)</td>
<td>1H to 28H (0.25 s to 10 s)</td>
</tr>
<tr>
<td>Other station</td>
<td>2H to F0H (0.5 s to 60 s)</td>
</tr>
</tbody>
</table>
This chapter explains the functions when accessing using 1C frame and their message format. 1C frame is compatible with the communication function of the dedicated protocols supported by A series computer link modules. Only the commands for 1C frame explained in this chapter can be used for 1C frame.

### 17.1 Message Format

This section explains the message format when communicating data using 1C frame.

#### Message format

- **Request message**

- **Response message (Normal completion: Response data)**

- **Response message (Normal completion: No response data)**

- **Response message (Abnormal completion)**
## Setting data

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Data by format</strong></td>
<td>The message formats differ depending on the set format (Format 1 to Format 4).</td>
<td>Page 27 Message Formats of Each Protocol</td>
</tr>
<tr>
<td>Access route</td>
<td>Station No. Specify the station to be connected from an external device.</td>
<td>Page 48 Station No.</td>
</tr>
<tr>
<td></td>
<td>PC No. Specify the network module station No. of an access target.</td>
<td>Page 50 Network No., PC No.</td>
</tr>
<tr>
<td>Request data</td>
<td>Command Specify the function to request such as read or write.</td>
<td>Page 340 Command</td>
</tr>
<tr>
<td></td>
<td>Message wait A data to generate a delay time for response transmission.</td>
<td>Page 341 Message wait</td>
</tr>
<tr>
<td></td>
<td>Character area A data that instructs the CPU module to execute a request specified by command. The content of the character areas differs depending on the command.</td>
<td>Page 341 Character area</td>
</tr>
<tr>
<td>Response data</td>
<td>Character area A data that C24 returns to a request specified by a command. The content of the character areas differs depending on the command.</td>
<td></td>
</tr>
<tr>
<td>Error code</td>
<td>Error code indicates the content of occurred error.</td>
<td>Page 342 Error code</td>
</tr>
</tbody>
</table>
17.2 Details of Setting Data

This section explains how to specify the common data items and their content in each message.

Command

Set the command type. (Page 343 Command and Function Lists for 1C Frame)
The setting values for each command are as follows.

<table>
<thead>
<tr>
<th>Function</th>
<th>ACPU common command</th>
<th>AnA/AnUCPU common command</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Symbol</td>
<td>ASCII code</td>
<td>Symbol</td>
<td>ASCII code</td>
</tr>
<tr>
<td>Device memory read and write</td>
<td>BR 42H, 52H</td>
<td>JR 4AH, 52H</td>
<td>Page 348 Batch read (bit units) (command: BR, JR)</td>
</tr>
<tr>
<td></td>
<td>WR 57H, 52H</td>
<td>QR 51H, 52H</td>
<td>Page 350 Batch read (word units) (command: WR, QR)</td>
</tr>
<tr>
<td></td>
<td>BW 42H, 57H</td>
<td>JW 4AH, 57H</td>
<td>Page 352 Batch write (bit units) (command: BW, JW)</td>
</tr>
<tr>
<td></td>
<td>WW 57H, 57H</td>
<td>QW 51H, 57H</td>
<td>Page 354 Batch write (word units) (command: WW, QW)</td>
</tr>
<tr>
<td></td>
<td>BT 42H, 54H</td>
<td>JT 4AH, 54H</td>
<td>Page 356 Test (random write) (bit units) (command: BT, JT)</td>
</tr>
<tr>
<td></td>
<td>WT 57H, 54H</td>
<td>QT 51H, 54H</td>
<td>Page 358 Test (random write) (word units) (command: WT, QT)</td>
</tr>
<tr>
<td></td>
<td>BM 42H, 4DH</td>
<td>JM 4AH, 4DH</td>
<td>Page 361 Register monitor data (bit units) (command: BM, JM)</td>
</tr>
<tr>
<td></td>
<td>WM 57H, 4DH</td>
<td>QM 51H, 4DH</td>
<td>Page 362 Register monitor data (word units) (command: WM, QM)</td>
</tr>
<tr>
<td>Read and write extended file register</td>
<td>MB 4DH, 42H</td>
<td>MJ 4DH, 4AH</td>
<td>Page 363 Monitor (bit units) (command: MB, MJ)</td>
</tr>
<tr>
<td></td>
<td>MN 4DH, 4EH</td>
<td>MQ 4DH, 51H</td>
<td>Page 364 Monitor (word units) (command: MN, MQ)</td>
</tr>
<tr>
<td></td>
<td>ER 45H, 52H</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>EW 45H, 57H</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>—</td>
<td>—</td>
<td>NR 4EH, 52H</td>
</tr>
<tr>
<td></td>
<td>—</td>
<td>—</td>
<td>NW 4EH, 57H</td>
</tr>
<tr>
<td></td>
<td>ET 45H, 54H</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>EM 45H, 4DH</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>ME 4DH, 45H</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>Read/write buffer memory of special function module</td>
<td>TR 54H, 52H</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>TW 54H, 57H</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>Loopback test</td>
<td>TT 54H, 54H</td>
<td>—</td>
<td>—</td>
</tr>
</tbody>
</table>

Setting method

Use the commands by converting to 2-digit (hexadecimal) ASCII codes.

Ex

Device memory batch read (BR) in bit unit

B R

\[
\begin{array}{c}
42H \\
52H
\end{array}
\]
Message wait

Message wait is a data to generate a delay time for response transmission. Some external devices may take time to become receiving status after sending a command. Specify the minimum wait time to send the result after C24 is received a command from an external device. Specify the wait time in accordance with the specifications of the external device.

Setting method

Specify the wait time within the range of 0 to 150 ms in 10 ms units. Convert 0H to FH (0 to 15) to 1-digit (hexadecimal) ASCII codes regarding 10 ms as 1H.

Ex.

When the message wait time is 100 ms

If the following value is set to message wait in request message, after passing 100 ms or more, transmission of a response message will be started.

A 41h

Character area

The content of the character areas differs depending on the command. The character area of request data is equivalent to the character A area and the character C area of the dedicated protocols for A series computer link module. The character area of response data is equivalent to the character B area of a dedicated protocols.

- Character area A: A data that C24 instructs the CPU module to perform the read request specified by command.
- Character area B: A data that C24 returns to a request specified by a command.
- Character area C: A data that C24 instructs the CPU module to perform the write request specified by command.

When reading data (Response data)

The following shows the image when the response data (character B area of the dedicated protocol) is included in the response message.

(The head of the message data in the figure is a control code of format 1. Page 27 Message Formats of Each Protocol)
When writing data (No response data)

The following shows the image when the response data is not included in the response message.
(The head of the message data in the figure is a control code of format 1. Page 27 Message Formats of Each Protocol)

Error code

Error code indicates the content of occurred error.
If more than one error occurs at the same time, the error code detected first is returned.
For the content of error code and its corrective action, refer to the user’s manual of the module used.

- MELSEC iQ-R Serial Communication Module User's Manual (Application)
- Q Corresponding Serial Communication Module User's Manual (Basic)
- MELSEC-L Serial Communication Module User's Manual (Basic)

Setting method

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Ex.
For error code 05H

```
0 5
```

17.3 Command and Function Lists for 1C Frame

Use the following commands for data communication using 1C frame.

<table>
<thead>
<tr>
<th>Function</th>
<th>ACPU common command</th>
<th>AnA/AnUCPU common command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device memory</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>*1 Batch read</td>
<td>Bit units</td>
<td>JR</td>
<td>Reads bit devices (X, Y, M, etc.) in 1-point units.</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>WR, QR</td>
<td>Reads bit devices (X, Y, M, etc.) in 16-point units.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Reads word devices (D, T, C, etc.) in 1-point units.</td>
</tr>
<tr>
<td>Batch write</td>
<td>Bit units</td>
<td>BW, JW</td>
<td>Writes bit devices (X, Y, M, etc.) in 1-point units.</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>WW, QW</td>
<td>Writes bit devices (X, Y, M, etc.) in 16-point units.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Writes word devices (D, T, C, etc.) in 1-point units.</td>
</tr>
<tr>
<td>Test (random write)</td>
<td>Bit units</td>
<td>BT, JT</td>
<td>Set/reset devices and device numbers to bit devices (X, Y, M, etc.) by specifying them randomly in 1 point unit.</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>WT, QT</td>
<td>Set/reset devices and device numbers to bit devices (X, Y, M, etc.) by specifying them randomly in 16 point units.</td>
</tr>
<tr>
<td>Register monitor data*2</td>
<td>Bit units</td>
<td>BM, JM</td>
<td>Registers bit devices (X, Y, M, etc.) to be monitored in 1-point units.</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>WM, QM</td>
<td>Registers bit devices (X, Y, M, etc.) to be monitored in 16-point units.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Registers word devices (D, T, C, etc.) to be monitored in 1-point units.</td>
</tr>
<tr>
<td>Monitor</td>
<td>Bit units</td>
<td>MB, MJ</td>
<td>Monitors the devices registered by monitor data registration.</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>MN, MQ</td>
<td></td>
</tr>
<tr>
<td>Extended file register</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Batch read</td>
<td>ER</td>
<td>—</td>
<td>Reads extended file register (R) in 1-point units.</td>
</tr>
<tr>
<td>Batch write</td>
<td>EW</td>
<td>—</td>
<td>Writes extended file register (R) in 1-point units.</td>
</tr>
<tr>
<td>Direct read</td>
<td>Word units</td>
<td>—, NR</td>
<td>Read data in 1 point units by specifying the consecutive device number regardless of the block number of extended file register.</td>
</tr>
<tr>
<td>Direct write</td>
<td>Word units</td>
<td>NW</td>
<td>Write data in 1 point units by specifying the consecutive device number regardless of the block number of extended file register.</td>
</tr>
<tr>
<td>Test (Random write)</td>
<td>ET</td>
<td>—</td>
<td>Write block numbers and device numbers to extended file register (R) by specifying them randomly in 1 point units.</td>
</tr>
<tr>
<td>Register monitor data*2</td>
<td>EM</td>
<td>—</td>
<td>Register extended file register (R) in 1-point units.</td>
</tr>
<tr>
<td>Monitor</td>
<td>Word units</td>
<td>ME</td>
<td>Monitor the extended file register (R) registered by monitor data registration.</td>
</tr>
<tr>
<td>Special function module</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Batch read</td>
<td>TR</td>
<td>—</td>
<td>Reads data in the buffer memory of a special function module.</td>
</tr>
<tr>
<td>Batch write</td>
<td>TW</td>
<td>—</td>
<td>Writes data to the buffer memory of a special function module.</td>
</tr>
<tr>
<td>Loopback test</td>
<td>TT</td>
<td>—</td>
<td>Send (returns) characters received from an external device back to the external device unchanged.</td>
</tr>
</tbody>
</table>

*1 Use the dedicated commands for extended registers to read/write extended file registers from/to ACPU.

*2 The devices for the five types of commands (BM, JM, WM, QM, EM) for registering monitor monitor data can be registered simultaneously in C24 for each interface.

ACPU common command, AnA/AnUCPU common command

ACPU common command is a communication function issued by MC protocol. The command is accessible for ACPU. AnA/AnUCPU common command is a command for AnACPU and AnUCPU. The command cannot be executed for other than AnA/AnUCPU.

○: Executable, △: Executable (with restrictions), ×: Not executable

<table>
<thead>
<tr>
<th>Type</th>
<th>ACPU other than AnA/AnUCPU</th>
<th>AnA/AnUCPU</th>
<th>Module other than ACPU</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACPU common command</td>
<td>○</td>
<td>○</td>
<td>△</td>
</tr>
<tr>
<td>AnA/AnUCPU common command</td>
<td>×</td>
<td>○</td>
<td>△</td>
</tr>
</tbody>
</table>

When accessing modules other than ACPU, there is a restriction for the accessible device range.

Page 344 Considerations when accessing devices other than ACPU module
17.4 Device Memory Read and Write

This section explains the specification content and examples of the control procedure when reading from/writing to the device memory are as shown below.

For the message formats other than request data and response data, refer to the following sections.

Page 338 Message Format, Page 340 Details of Setting Data

To read and write the extended file register, use the commands dedicated to the extended file register.

Page 365 Read and Write Extended File Register

Considerations

The considerations when reading/writing device memory using the commands described in this section.

Considerations when accessing devices other than ACPU module

■ Accessible devices

Only the devices with the same names that exist in ACPU can be accessed within the device range of AnACPU.

Page 346 Accessible device range

The following devices cannot be accessed from the external devices:

• Added devices
• Latch relay (L) and step relay (S)*1
• File register (R) of QnACPU
*1 Even when the latch relay (L) or step relay (S) is specified, the internal relay (M) can be accessed.

■ Special relays and special registers

Special relays and special registers can be accessed within the following range.

• Access SM1000 to SM1255 by specifying M9000 to M9255.
• Access SD1000 to SD1255 by specifying D9000 to D9255.

■ Universal model QCPU

Use the Universal model QCPU with a serial number whose first five digits are ‘10102’ or later.

As for the serial number whose first five digits are ‘10101’ or earlier, access using 2C/3C/4C frame.
## Data to be specified in command

### Device codes, device numbers

The settings of each device when reading/writing device memory can be performed using device code and device number as shown in the following figure.

Specify the device to be accessed by a device code and a device number.

The setting data size differ between ACPU common commands and AnA/AnUCPU commands.

### ACPU common commands

- **Device code**: Convert the device name to 1-digit ASCII code (2-digits for timer or counter), and send it from the upper digits.
- **Device number**: Convert the numerical value to 4-digit ASCII code (3-digits for timer or counter), and send it from the upper digits.

### AnA/AnUCPU common commands

- **Device code**: Convert the device name to 1-digit ASCII code (2-digits for timer or counter), and send it from the upper digits.
- **Device number**: Convert the numerical value to 6-digit ASCII code (5-digits for timer and counter), and send it from the upper digits.

#### Ex.

Current value of input (X) 40 and timer (T) 10

<table>
<thead>
<tr>
<th>Device</th>
<th>ACPU common command</th>
<th>AnA/AnUCPU common command</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input (X) 40</td>
<td><img src="image1.png" alt="Image" /></td>
<td><img src="image2.png" alt="Image" /></td>
</tr>
<tr>
<td>Current value of timer (T) 10</td>
<td><img src="image3.png" alt="Image" /></td>
<td><img src="image4.png" alt="Image" /></td>
</tr>
</tbody>
</table>
Accessible device range

The following table shows the devices and device number range that can be specified when accessing the device memory. Access the CPU module within the range of device number that can be used by commands and the range of the device number that can be used in the access target CPU. (Page 344 Considerations when accessing devices other than ACPU module)
- Specify 0 (30H) or space (20H)

<table>
<thead>
<tr>
<th>Device name</th>
<th>Symbol</th>
<th>Type</th>
<th>Representation</th>
<th>Device code</th>
<th>Device number</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input</td>
<td>X</td>
<td>Bit</td>
<td>Hexadecimal X</td>
<td>ACPU common command</td>
<td>0000 to 07FF</td>
</tr>
<tr>
<td>Output</td>
<td>Y</td>
<td>Bit</td>
<td>Hexadecimal Y</td>
<td>ACPU common command</td>
<td>0000 to 07FF</td>
</tr>
<tr>
<td>Internal relay</td>
<td>M</td>
<td>Bit</td>
<td>Decimal M</td>
<td>AnA/AnUCPU common command</td>
<td>0000 to 2047</td>
</tr>
<tr>
<td>Latch relay</td>
<td>L</td>
<td>Bit</td>
<td>Decimal L</td>
<td>AnA/AnUCPU common command</td>
<td>0000 to 2047</td>
</tr>
<tr>
<td>Step relay</td>
<td>S</td>
<td>Bit</td>
<td>Decimal S</td>
<td>AnA/AnUCPU common command</td>
<td>0000 to 2047</td>
</tr>
<tr>
<td>Annunciator</td>
<td>F</td>
<td>Bit</td>
<td>Decimal F</td>
<td>AnA/AnUCPU common command</td>
<td>0000 to 255</td>
</tr>
<tr>
<td>Link relay</td>
<td>B</td>
<td>Bit</td>
<td>Hexadecimal B</td>
<td>AnA/AnUCPU common command</td>
<td>0000 to 3FF</td>
</tr>
<tr>
<td>Timer</td>
<td>T</td>
<td>Word</td>
<td>Decimal TN</td>
<td>AnA/AnUCPU common command</td>
<td>0000 to 255</td>
</tr>
<tr>
<td>Contact</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>0000 to 2047</td>
</tr>
<tr>
<td>Coil</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>0000 to 2047</td>
</tr>
<tr>
<td>Counter</td>
<td>C</td>
<td>Word</td>
<td>Decimal CN</td>
<td>AnA/AnUCPU common command</td>
<td>0000 to 255</td>
</tr>
<tr>
<td>Contact</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>0000 to 1023</td>
</tr>
<tr>
<td>Coil</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>0000 to 2047</td>
</tr>
<tr>
<td>Data register</td>
<td>D</td>
<td>Word</td>
<td>Decimal D</td>
<td></td>
<td>0000 to 1023</td>
</tr>
<tr>
<td>Link register</td>
<td>W</td>
<td>Word</td>
<td>Hexadecimal W</td>
<td></td>
<td>0000 to 3FF</td>
</tr>
<tr>
<td>File register</td>
<td>R</td>
<td>Word</td>
<td>Decimal R</td>
<td></td>
<td>0000 to 6191</td>
</tr>
<tr>
<td>Special relay</td>
<td>M</td>
<td>Bit</td>
<td>Decimal M</td>
<td></td>
<td>9000 to 9255</td>
</tr>
<tr>
<td>Special register</td>
<td>D</td>
<td>Word</td>
<td>Decimal D</td>
<td></td>
<td>9000 to 9255</td>
</tr>
</tbody>
</table>

- Do not write data to the devices which cannot be written in the range of the special relays (M9000 to M9255) and special registers (D9000 to D9255). For details on the special relays and special registers, refer to manual of ACPU to be accessed.
- The range of M, L, and S devices can be specified for MELSEC-A series CPU module, however, if the range of M is specified by L or S or vice versa, they are processed equivalently.

- For word unit specification, the head device number of bit device must be specified in multiple of 16.
- For special relay M9000 or later, (9000 + multiple of 16) can be specified.
Number of device points

Specify the number of device points to be read or written. Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Specify the number of device points in one command within the device points that can be processed in one communication.

Ex. Page 459 Number of Processing per One Communication
Specify ‘00’ for 256 points.

5 points, 20 points, 256 points

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>ASCII code</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 points</td>
<td>0 5</td>
</tr>
<tr>
<td></td>
<td>30h 35h</td>
</tr>
<tr>
<td>20 points</td>
<td>1 4</td>
</tr>
<tr>
<td></td>
<td>31h 34h</td>
</tr>
<tr>
<td>256 points</td>
<td>0 0</td>
</tr>
<tr>
<td></td>
<td>30h 30h</td>
</tr>
</tbody>
</table>

Read data, write data

The data storage method is the same as reading/writing data with device access of 4C/3C/2C frame. (Ex. Page 70 Read data, write data)
Batch read (bit units) (command: BR, JR)

Reads bit devices (X, Y, M, etc.) in batch.

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Message wait</th>
<th>Head device</th>
<th>Number of device points</th>
</tr>
</thead>
</table>

**Response data**

The value of read device is stored in bit units. ([Page 70 Read data, write data](#))

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>ACPU common</th>
<th>AnA/AnUCPU common</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>BR</code></td>
<td><code>JR</code></td>
</tr>
</tbody>
</table>

**Message wait**

Specify the delayed time of the response transmission. ([Page 341 Message wait](#))

**Head device**

Specify the head device. ([Page 345 Device codes, device numbers](#))

**Number of device points**

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Specify the number of device points within the following range:

- $1 \leq \text{Number of device points} \leq 256$ (for 256 points, specify '00H')
- Head device No. + Number of device points - 1 $\leq$ Maximum device No.
Communication example

Read data in bit units under the following conditions.
- Message wait: 100 ms
- Head device: X040
- Number of device points: 5 points

(Request data)

**When using BR (ACPU common command)**

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Head device</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>B R A X 0 0 4 0 0 5</td>
<td>42h, 52h, 41h</td>
<td>58h, 30h, 34h, 30h, 35h</td>
</tr>
</tbody>
</table>

**When using JR (AnA/AnUCPU common command)**

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Head device</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>J R A X 0 0 0 0 4 0 0 5</td>
<td>40h, 52h, 41h</td>
<td>58h, 30h, 34h, 30h, 35h</td>
</tr>
</tbody>
</table>

(Response data)

Data read

<table>
<thead>
<tr>
<th>0 1 1 1 0 1</th>
</tr>
</thead>
<tbody>
<tr>
<td>30h 31h 30h 31h</td>
</tr>
</tbody>
</table>

(X40) (X41) (X42) (X43) (X44)
Batch read (word units) (command: WR, QR)

Reads bit devices (X, Y, M, etc.) in 16-point units.
Reads word devices (D, T, C, etc.) in 1-point units

Message format

The following shows the message format of the request data and response data of the command.

- **Request data**

  The value of read device is stored in word units. (Page 70 Read data, write data)

- **Response data**

  Data specified by request data

  - **Command**

    | ACPU common | AnA/AnUCPU common |
    |-------------|-------------------|
    | W R 57h 52h | Q R 51h 50h |

  - **Message wait**

    Specify the delayed time of the response transmission. (Page 341 Message wait)

  - **Head device**

    Specify the head device. (Page 345 Device codes, device numbers)

  - **Number of device points**

    Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.
    Specify the number of device points within the following range:
    - For bit device: \( 1 \leq \text{Number of device points} \leq 32 \)
    - For bit device: Head device No. + Number of device points × 16 - 1 \( \leq \) Maximum device No.
    - For word device: \( 1 \leq \text{Number of device points} \leq 64 \)
    - For word device: Head device No. + Number of device points - 1 \( \leq \) Maximum device No.

    • When specifying bit devices, set the head device No. in multiples of 16 (0, 16, ... in decimal notation).
Communication example (Reading bit device memory)

Read bit devices in 16-point units under the following conditions.
• Message wait: 0 ms
• Head device: X040
• Number of device points: 32 points (2 words)

(Request data)

■ When using WR (ACPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Head device</th>
<th>Number of device points (Number of words)</th>
</tr>
</thead>
<tbody>
<tr>
<td>W R 0 0 0 4 0 0 2</td>
<td>X 57h 52h</td>
<td>30h 30h 30h 30h 30h 30h 30h 30h</td>
</tr>
</tbody>
</table>

■ When using QR (AnA/AnUCPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Head device</th>
<th>Number of device points (Number of words)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Q R 0 0 0 0 4 0 0 2</td>
<td>X 51h 52h</td>
<td>30h 30h 30h 30h 30h 30h 30h 30h</td>
</tr>
</tbody>
</table>

(Response data)

Data read

<table>
<thead>
<tr>
<th>0001 (Hexadecimal : 1)</th>
<th>0010 (Hexadecimal : 2)</th>
<th>0011 (Hexadecimal : 3)</th>
<th>0100 (Hexadecimal : 4)</th>
<th>1010 (Hexadecimal : A)</th>
<th>1011 (Hexadecimal : B)</th>
<th>1100 (Hexadecimal : C)</th>
<th>1101 (Hexadecimal : D)</th>
</tr>
</thead>
<tbody>
<tr>
<td>(X4F) to (X4C)</td>
<td>(X4B) to (X48)</td>
<td>(X47) to (X44)</td>
<td>(X43) to (X40)</td>
<td>(X5F) to (X5C)</td>
<td>(X5B) to (X58)</td>
<td>(X57) to (X54)</td>
<td>(X53) to (X50)</td>
</tr>
</tbody>
</table>

Communication example (Reading word device memory)

Read word devices in 1-point units under the following conditions.
• Message wait: 0 ms
• Head device: Current value of T123
• Number of device points: 2 points (2 words)

(Request data)

■ When using WR (ACPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Head device</th>
<th>Number of device points (Number of words)</th>
</tr>
</thead>
<tbody>
<tr>
<td>W R 0 T N 1 2 3 0 2</td>
<td>X 57h 52h</td>
<td>30h 30h 30h 30h 30h 30h 30h 30h</td>
</tr>
</tbody>
</table>

■ When using QR (AnA/AnUCPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Head device</th>
<th>Number of device points (Number of words)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Q R 0 T N 0 0 1 2 3 0 2</td>
<td>X 51h 52h</td>
<td>30h 30h 30h 30h 30h 30h 30h 30h</td>
</tr>
</tbody>
</table>

(Response data)

Data read

<table>
<thead>
<tr>
<th>7 8 9</th>
<th>0 1 2 3 4</th>
</tr>
</thead>
<tbody>
<tr>
<td>37h 42h 43h 39h</td>
<td>31h 32h 33h 34h</td>
</tr>
<tr>
<td>(T123)</td>
<td>(T124)</td>
</tr>
</tbody>
</table>
Batch write (bit units) (command: BW, JW)

Writes bit devices (X, Y, M, etc.) in batch.

Message format
The following shows the message format of the request data and response data of the command.

■ Request data
ACPU common command

<table>
<thead>
<tr>
<th>Command</th>
<th>Message wait</th>
<th>Head device</th>
<th>Number of device points</th>
<th>Write data for the number of device points</th>
</tr>
</thead>
</table>

■ Response data
There is no response data for this command.

Data specified by request data

■ Command

<table>
<thead>
<tr>
<th>Command</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACPU common</td>
</tr>
<tr>
<td>8W</td>
</tr>
<tr>
<td>42n 57n</td>
</tr>
</tbody>
</table>

■ Message wait
Specify the delayed time of the response transmission. (Page 341 Message wait)

■ Head device
Specify the head device. (Page 345 Device codes, device numbers)

■ Number of device points
Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.
Specify the number of device points within the following range:
• 1 ≤ Number of device points ≤ 160
• Head device No. + Number of device points - 1 ≤ Maximum device No.

■ Write data for the number of device points
Store the data to be written in batch. (Page 347 Read data, write data)
**Communication example**

Write data in bit units in batch under the following conditions.

- **Message wait**: 0 ms
- **Head device**: M903
- **Number of device points**: 5 points

(Request data)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points (Number of words)</th>
<th>Head device</th>
<th>Write data for the number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>B W</td>
<td></td>
<td>M 0 9 0 3</td>
<td>0 5 0 1 1 0 1</td>
</tr>
<tr>
<td>42H 57H</td>
<td></td>
<td>30H</td>
<td>30H 30H 30H 30H 33H 30H 35H</td>
</tr>
<tr>
<td></td>
<td></td>
<td>M903 (M904) (M905) (M906) (M907)</td>
<td></td>
</tr>
</tbody>
</table>

*When using BW (ACPU common command)*

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points (Number of words)</th>
<th>Head device</th>
<th>Write data for the number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>J W</td>
<td></td>
<td>M 0 0 0 9 0 3</td>
<td>0 5 0 1 1 0 1</td>
</tr>
<tr>
<td>44H 57H</td>
<td></td>
<td>30H</td>
<td>30H 30H 30H 30H 30H 33H 30H 35H</td>
</tr>
<tr>
<td></td>
<td></td>
<td>M903 (M904) (M905) (M906) (M907)</td>
<td></td>
</tr>
</tbody>
</table>
Batch write (word units) (command: WW, QW)

Write data to bit devices (X, Y, M, etc.) in 16-point units.
Write data to word devices (D, T, C, etc.) in 1-point units.

Message format
The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Message wait</th>
<th>Head device</th>
<th>Number of device points</th>
<th>Write data for the number of device points</th>
</tr>
</thead>
</table>

Response data
There is no response data for this command.

Data specified by request data

Command

<table>
<thead>
<tr>
<th>ACPU common</th>
<th>AnAI/AnUCPU common</th>
</tr>
</thead>
<tbody>
<tr>
<td>WW</td>
<td>www</td>
</tr>
<tr>
<td>QW</td>
<td>www</td>
</tr>
</tbody>
</table>

Message wait
Specify the delayed time of the response transmission. (Page 341 Message wait)

Head device
Specify the head device. (Page 345 Device codes, device numbers)

Number of device points
Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.
Specify the number of device points within the following range:
• For bit device: 1 ≤ Number of device points ≤ 10
• For bit device: Head device No. + Number of device points × 16 - 1 ≤ Maximum device No.
• For word device: 1 ≤ Number of device points ≤ 64
• For word device: Head device No. + Number of device points - 1 ≤ Maximum device No.

Write data for the number of device points
Store 4-digit data per one device point. (Page 347 Read data, write data)

Point
When specifying bit devices, set the head device No. in multiples of 16 (0, 16, ... in decimal notation).
### Communication example (Writing to word bit memory)

Write data to bit devices in 16-point units under the following conditions.

- • Message wait: 0 ms
- • Head device: M640
- • Number of device points: 32 points (2 words)

(Request data)

**When using WW (ACPU common command)**

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points (Number of words)</th>
</tr>
</thead>
<tbody>
<tr>
<td>W W</td>
<td></td>
</tr>
<tr>
<td>57n, 57n</td>
<td></td>
</tr>
<tr>
<td>30b</td>
<td></td>
</tr>
<tr>
<td>D0</td>
<td></td>
</tr>
<tr>
<td>30h to 36h</td>
<td></td>
</tr>
<tr>
<td>31h to 37h</td>
<td></td>
</tr>
<tr>
<td>41h to 47h</td>
<td></td>
</tr>
<tr>
<td>(M671) to (M656)</td>
<td></td>
</tr>
</tbody>
</table>

**When using QW (AnA/AnUCPU common command)**

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points (Number of words)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Q W</td>
<td></td>
</tr>
<tr>
<td>57n, 57n</td>
<td></td>
</tr>
<tr>
<td>30b</td>
<td></td>
</tr>
<tr>
<td>D0</td>
<td></td>
</tr>
<tr>
<td>30h to 36h</td>
<td></td>
</tr>
<tr>
<td>31h to 37h</td>
<td></td>
</tr>
<tr>
<td>41h to 47h</td>
<td></td>
</tr>
<tr>
<td>(M671) to (M656)</td>
<td></td>
</tr>
</tbody>
</table>

### Communication example (Writing to word device memory)

Write data to word devices in 1-point units under the following conditions.

- • Message wait: 0 ms
- • Head device: D0
- • Number of device points: 2 points (2 words)

(Request data)

**When using WW (ACPU common command)**

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points (Number of words)</th>
</tr>
</thead>
<tbody>
<tr>
<td>W W</td>
<td></td>
</tr>
<tr>
<td>57n, 57n</td>
<td></td>
</tr>
<tr>
<td>30b</td>
<td></td>
</tr>
<tr>
<td>D0</td>
<td></td>
</tr>
<tr>
<td>30h to 36h</td>
<td></td>
</tr>
<tr>
<td>31h to 37h</td>
<td></td>
</tr>
<tr>
<td>41h to 47h</td>
<td></td>
</tr>
<tr>
<td>(D0) (D1)</td>
<td></td>
</tr>
</tbody>
</table>

**When using QW (AnA/AnUCPU common command)**

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points (Number of words)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Q W</td>
<td></td>
</tr>
<tr>
<td>57n, 57n</td>
<td></td>
</tr>
<tr>
<td>30b</td>
<td></td>
</tr>
<tr>
<td>D0</td>
<td></td>
</tr>
<tr>
<td>30h to 36h</td>
<td></td>
</tr>
<tr>
<td>31h to 37h</td>
<td></td>
</tr>
<tr>
<td>41h to 47h</td>
<td></td>
</tr>
<tr>
<td>(D0) (D1)</td>
<td></td>
</tr>
</tbody>
</table>
Test (random write) (bit units) (command: BT, JT)

Set/reset devices and device numbers to bit devices (X, Y, M, etc.) by specifying them randomly in 1 point units.

Message format
The following shows the message format of the request data and response data of the command.

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Message wait</th>
<th>Number of device points (n points)</th>
<th>Device (first point)</th>
<th>Set/reset (first point)</th>
<th>⋯</th>
<th>Device (nth point)</th>
<th>Set/reset (nth point)</th>
</tr>
</thead>
</table>

Response data
There is no response data for this command.

Data specified by request data

Command

<table>
<thead>
<tr>
<th>ACPU common</th>
<th>AnA/AnUCPU common</th>
</tr>
</thead>
<tbody>
<tr>
<td><img src="image" alt="Command" /></td>
<td><img src="image" alt="Command" /></td>
</tr>
</tbody>
</table>

Message wait
Specify the delayed time of the response transmission. (Page 341 Message wait)

Number of device points
Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.
Specify the number of device points within the following range:
• 1 ≤ Number of device points ≤ 20

Device
Specify the device to test. (Page 345 Device codes, device numbers)

Set/Reset
• 0 (30H): Reset (OFF)
• 1 (31H): Set (ON)
Communication example

Perform the test in bit units under the following conditions.

- Message wait: 0 ms
- Number of device points: 3 points
- Device: Turn ON M50, turn OFF B31A, and turn ON Y02F

(Request data)

■ When using BT (ACPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points (Number of words)</th>
<th>Set/ reset</th>
<th>Device</th>
<th>Set/ reset</th>
<th>Device</th>
<th>Set/ reset</th>
</tr>
</thead>
<tbody>
<tr>
<td>B</td>
<td>T</td>
<td>0</td>
<td>0</td>
<td>3</td>
<td>M</td>
<td>0</td>
</tr>
<tr>
<td>42</td>
<td>35</td>
<td>54</td>
<td>30</td>
<td>33</td>
<td>40</td>
<td>30</td>
</tr>
</tbody>
</table>

■ When using JT (AnA/AnUCPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points (Number of words)</th>
<th>Set/ reset</th>
<th>Device</th>
<th>Set/ reset</th>
<th>Device</th>
<th>Set/ reset</th>
</tr>
</thead>
<tbody>
<tr>
<td>J</td>
<td>T</td>
<td>0</td>
<td>0</td>
<td>3</td>
<td>M</td>
<td>0</td>
</tr>
<tr>
<td>40</td>
<td>41</td>
<td>54</td>
<td>30</td>
<td>33</td>
<td>40</td>
<td>30</td>
</tr>
</tbody>
</table>

| Y 0 0 0 0 2 | F 1                                      | 1          | 59      | 30      | 30      | 30      | 32      | 46      | 31        |
Test (random write) (word units) (command: WT, QT)

Set/reset devices and device numbers to bit devices (X, Y, M, etc.) by specifying them randomly in 16 point units. Write devices and device numbers to word devices (D, T, C, etc.) by specifying them randomly in 1 point units. A mixture of word devices and bit devices (16 bit units) can be specified.

**Message format**
The following shows the message format of the request data and response data of the command.

**Request data**
There is no response data for this command.

**Data specified by request data**

**Command**

<table>
<thead>
<tr>
<th>Command</th>
<th>Message wait</th>
<th>Number of device points (n points)</th>
<th>Device (first point)</th>
<th>Write data (first point)</th>
<th>…</th>
<th>Device (nth point)</th>
<th>Write data (nth point)</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACPU common</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>W T</td>
<td>57h</td>
<td>54h</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>AnA/AnUCPU common</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Q T</td>
<td>57n</td>
<td>54n</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Write data**

When specifying bit devices, set the head device No. in multiples of 16 (0, 16, … in decimal notation).
Communication example

Write data with mixture specification of word devices and bit devices (16-point unit) under the following conditions.
- Message wait: 0 ms
- Number of device points: 3 points (3 words)
- Device: Set 1234H to D500, BCA9H from Y100 to Y10F, and 64H to current values of C100
  (Request data)

■ When using WT (ACPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points</th>
<th>Device</th>
<th>Write data</th>
<th>Device</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>W T 0 0 3</td>
<td>D 0 5 0 0</td>
<td>1 2 3 4</td>
<td>Y 0 1 0 0</td>
<td>B C A 9</td>
<td></td>
</tr>
<tr>
<td>57H 55H 04H</td>
<td>31H 30H 33H</td>
<td>23H 13H</td>
<td>31H 30H 32H</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

■ When using QT (AnA/AnUCPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points</th>
<th>Device</th>
<th>Write data</th>
<th>Device</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Q T 0 0 3</td>
<td>D 0 0 0 5 0 0</td>
<td>1 2 3 4</td>
<td>Y 0 0 1 0 0</td>
<td>B C A 9</td>
<td></td>
</tr>
<tr>
<td>51H 54H 30H</td>
<td>31H 30H 33H</td>
<td>23H 13H</td>
<td>31H 30H 32H</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(Y10F) to (Y108) (Y107) to (Y100)
Monitor (Command: BM, JM, WM, QM, MB, MJ, MN, MQ)

The monitor data registration function registers the devices and numbers to be monitored from an external device to C24. The monitor function reads the data of the registered devices from the CPU module and processes it in the external device. When the batch read (BR/WR/JR/QR) is performed, the read device numbers will be consecutive, however, by using this function, devices can be monitored by specifying the device numbers randomly. The following example shows the control procedure for monitoring and registering name and number of the devices to be monitored to the C24.

Monitoring procedure

1. Process the monitor data registration (Edit of commands for registration and transmission of device specification.)
   - ACPU common commands: BM, WM
   - AnA/AnUCPU common commands: JM, QM
2. Perform read process. (Execution of command for monitoring.)
   - ACPU common commands: MB, MN
   - AnA/AnUCPU common commands: MJ, MQ
3. Process the data. (Screen display, etc.)
4. If do not change the devices to be monitored, return to step 2, and repeat the process.

- When monitoring data as the procedure shown above, the monitor data registration is required. If monitoring data without registering the data, a protocol error occurs.
- The content of registered monitor data are deleted when C24 is rebooted.
- The devices can be registered for each command for bit units (BM or JM), word units (WM or QM), or the extended file register (EM) in C24. (Monitoring extended file register Page 372 Monitor (command: EM, ME))
- When registering device memory of the CPU module as a monitor data from more than one C24s on the same station, the recently registered device memory will be available since the registration data is overwritten.
Register monitor data (bit units) (command: BM, JM)

Set the bit devices (X, Y, M, etc.) to be monitored in 1-point units. Monitor the device memory registered in bit units using the following command.

Page 363 Monitor (bit units) (command: MB, MJ)

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Message wait</th>
<th>Number of device points (n points)</th>
<th>Device (first point)</th>
<th>...</th>
<th>Device (nth point)</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACPU common</td>
<td>AnA/AnUCPU common</td>
<td>BM 42h 40h</td>
<td>JS 4Ah 40h</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- Command: Specify the commands to be used.
- Message wait: Specify the delayed time of the response transmission. (Page 341 Message wait)
- Number of device points: Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.
- Device: Specify the devices to be monitored. (Page 345 Device codes, device numbers)

Point

Specify the number of device points within the following range:

\[ 1 \leq \text{Number of device points} \leq 40 \]

When using the BM command and accessing ACPU other than AnA/AnU, device X (input) has two processing points per point.

Response data

There is no response data for this command.

Communication example (Monitor data registration in bit units)

Perform monitor data registration of the bit device under the following conditions.
- Message wait: 0 ms
- Number of device points: 3 points (3 bits)
- Device: Contacts of X40, Y060, and T123.

(Request data)
- When using BM (ACPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points</th>
<th>Device</th>
<th>Device</th>
<th>Device</th>
</tr>
</thead>
<tbody>
<tr>
<td>BM 42h 40h</td>
<td>X 0 0 4 0</td>
<td>Y 0 0 0 6 0</td>
<td>T 5 1 2 3</td>
<td></td>
</tr>
</tbody>
</table>

- When using JM (AnA/AnUCPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points</th>
<th>Device</th>
<th>Device</th>
</tr>
</thead>
<tbody>
<tr>
<td>JM 4Ah 40h</td>
<td>X 0 0 0 0 0 4 0</td>
<td>Y 0 0 0 0 6 0</td>
<td>T 5 0 0 1 2 3</td>
</tr>
</tbody>
</table>

ACPU common

AnA/AnUCPU common
Register monitor data (word units) (command: WM, QM)

Register the bit devices (X, Y, M, etc.) to be monitored in 16-point units.
Register the word devices (D, T, C, etc.) to be monitored in 1-point units.
A mixture of word devices and bit devices (16 bit units) can be specified.
Monitor the device memory registered in word units using the following command.
Page 364 Monitor (word units) (command: MN, MQ)

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Message wait</th>
<th>Number of device points (n points)</th>
<th>Device (first point)</th>
<th>...</th>
<th>Device (nth point)</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACPU common</td>
<td></td>
<td>W</td>
<td>M</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>57h</td>
<td>4Dh</td>
<td></td>
<td></td>
</tr>
<tr>
<td>AnA/AnUCPU common</td>
<td></td>
<td>Q</td>
<td>M</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>51h</td>
<td>4Dh</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- **Message wait:** Specify the delayed time of the response transmission. (Page 341 Message wait)
- **Number of device points:** Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.
- **Device:** Specify the devices to be monitored. (Page 345 Device codes, device numbers)

Specify the number of device points within the following range:
1 ≤ Number of device points ≤ 20
When using the WM command and accessing ACPU other than AnA/AnU, device X (input) has two processing points per point.

**Response data**

There is no response data for this command.

**Communication example (Monitor data registration in word units)**

Register the monitor data in a word unit under the following conditions.
- **Message wait:** 0 ms
- **Number of device points:** 4 points (4 words)
- **Device:** Current value of D15, W11E, and T123, and Y060 to Y06F

(Request data)
- **When using WM (ACPU common command)**

```
<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points</th>
<th>Device</th>
<th>Device</th>
<th>Device</th>
<th>Device</th>
</tr>
</thead>
<tbody>
<tr>
<td>W</td>
<td>M</td>
<td>0</td>
<td>4</td>
<td>D</td>
<td>0</td>
</tr>
<tr>
<td>57h</td>
<td>4Dh</td>
<td>30h</td>
<td>44h</td>
<td>30h</td>
<td>30h</td>
</tr>
</tbody>
</table>
```

- **When using QM (AnA/AnUCPU common command)**

```
<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points</th>
<th>Device</th>
<th>Device</th>
<th>Device</th>
<th>Device</th>
</tr>
</thead>
<tbody>
<tr>
<td>Q</td>
<td>M</td>
<td>0</td>
<td>4</td>
<td>D</td>
<td>0</td>
</tr>
<tr>
<td>51h</td>
<td>4Dh</td>
<td>30h</td>
<td>44h</td>
<td>30h</td>
<td>30h</td>
</tr>
</tbody>
</table>
```

```
<table>
<thead>
<tr>
<th>Device</th>
</tr>
</thead>
<tbody>
<tr>
<td>Y</td>
</tr>
<tr>
<td>59h</td>
</tr>
</tbody>
</table>
```
Monitor (bit units) (command: MB, MJ)
Monitor the registered bit devices (X, Y, M, etc.).

- The bit device memory registered with BM command is monitored using MB command.
- The bit device memory registered with JM command is monitored using MJ command.

### Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Message wait</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACPU common</td>
<td>AnA/AnUCPU common</td>
</tr>
<tr>
<td>M B 4Dh 42h</td>
<td>M J 4Dh 4Ah</td>
</tr>
</tbody>
</table>

- Message wait: Specify the delayed time of the response transmission. (Page 341 Message wait)

### Response data

Monitoring result (For the number of device points)
The value of read device is stored in bit units. (Page 70 Read data, write data)

### Communication example
Monitor bit devices specified with monitor data registration under the following conditions.
- Message wait: 0 ms
- Registered devices for monitoring: 3 points (3 bits) of contacts for X040, Y060 and T123.

(Request data)
- When using MB (ACPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
</tr>
</thead>
<tbody>
<tr>
<td>M B 4Dh 42h</td>
</tr>
<tr>
<td>0 30h</td>
</tr>
</tbody>
</table>

- When using MJ (AnA/AnUCPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
</tr>
</thead>
<tbody>
<tr>
<td>M J 4Dh 4Ah</td>
</tr>
<tr>
<td>0 30h</td>
</tr>
</tbody>
</table>

(Response data)
Monitoring result (For the number of device points)

<table>
<thead>
<tr>
<th>1</th>
<th>0</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td>31h</td>
<td>30h</td>
<td>31h</td>
</tr>
</tbody>
</table>

(X040) (Y060) (Contact of T123)
Monitor (word units) (command: MN, MQ)
Monitor the registered bit devices (X, Y, M, etc.) in 16-point units.
Monitor the registered word device (D, T, C, etc.) in 1-point unit.

- The bit device memory registered with WM command is monitored using MN command.
- The bit device memory registered with QM command is monitored using MQ command.

**Request data**

<table>
<thead>
<tr>
<th>Command</th>
<th>Message wait</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACPU common</td>
<td>AnA/AnUCPU common</td>
</tr>
<tr>
<td>MN 4Dn 4En</td>
<td>MQ 4Dn 5Fn</td>
</tr>
</tbody>
</table>

- Message wait: Specify the delayed time of the response transmission. (Page 341 Message wait)

**Response data**

The value of read device is stored in word units. (Page 70 Read data, write data)

**Communication example**
Monitor bit devices or word devices specified with monitor data registration under the following conditions.
- Message wait: 0 ms
- Registered devices for monitoring: Current values of D15, W11E, T123, and 4 points (4 words) of Y060 to Y06F.

(Request data)
- When using MN (ACPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
</tr>
</thead>
<tbody>
<tr>
<td>MN 4Dn 4En</td>
</tr>
<tr>
<td>Message wait</td>
</tr>
</tbody>
</table>

- When using MQ (AnA/AnUCPU common command)

<table>
<thead>
<tr>
<th>Message wait</th>
</tr>
</thead>
<tbody>
<tr>
<td>MQ 4Dn 5Fn</td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>Monitoring result (For the number of device points)</th>
</tr>
</thead>
<tbody>
<tr>
<td>(Decimal : 4660) (Decimal : 80) (Decimal : 100) (Decimal : 80)</td>
</tr>
<tr>
<td>(D15) (W11E) (Current value of T123) (Y06F) to (Y06C) (Y06B) to (Y068) (Y067) to (Y064) (Y063) to (Y060)</td>
</tr>
</tbody>
</table>
17.5 Read and Write Extended File Register

The extended file register is a memory area that stores required data and operation result for various data processing by using the software package for extended file register ‘SWOGHP-UTLP-FCN1’ or ‘SW0SRX-FNUP’ (hereinafter abbreviated to UTLP-FN1 and FNUP) and AnACPU and AnUSCPU extended file register dedicated instructions. The extended file register uses free area of user memory area in CPU module as a file register.

The following example shows the control procedure to read and write extended file register.

Considerations for reading and writing extended file register

The following shows the considerations when reading writing extended file register using the commands described in this section.

Accessible CPU modules

Only CPU modules that can handle the extended file register can be accessed.
This function cannot be used for CPU modules that cannot handle an extended file register (such as A1N).

Error detection for block numbers that do not exist

Depending on the type of memory cassette inserted in the CPU module, an error (character area error '06H') may not be detected even when a read/write operation is performed by specifying the block numbers that do not exist. In this case, the read data is incorrect. If writing data to the CPU module, the user memory of the CPU module will be collapsed.
Check the type of memory cassette and parameter settings before using these functions.

<table>
<thead>
<tr>
<th>Memory cassette model name</th>
<th>Block numbers that do not cause character area error (06H)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A3NMCA-12</td>
<td>No.10 to No.11</td>
</tr>
<tr>
<td>A3NMCA-18</td>
<td>No.10 to No.28</td>
</tr>
<tr>
<td>A3NMCA-24</td>
<td>No.13 to No.20</td>
</tr>
<tr>
<td>A3NMCA-40</td>
<td>No.21 to No.28</td>
</tr>
<tr>
<td>A3AMCA-96</td>
<td>No.21 to No.48&lt;sup&gt;*&lt;/sup&gt;&lt;sub&gt;1&lt;/sub&gt;</td>
</tr>
</tbody>
</table>

<sup>*</sup> A3AMCA-96 can be used for A3A, A3U, and A4UCPU.
For details, refer to the manual of UTLP-FN1 or FNUP, or user's manual of the access target CPU module.

Block numbers of extended file register that can be handled by A2USCPU(S1)

The block numbers of the extended file register that can be handled by A2USCPU(S1) is as follows.
- A2USCPU: No.1 to 3
- A2USCPU-S1: No.1 to 8, No.10 to 16

Extended file register of R/L/Q/QnACPU

The extended file register of R/L/Q/QnACPU cannot be read/written.
### Specification method for extended file register

The specification method differs depending on the command.

- **ACPU common command**: Specify with device number and block number.
- **AnA/AnUCPU common command**: Specify the address from device number 0 of block number 1 as a device number.
  
  (Access with the consecutive device number of extended file register using usable number of blocks \( \times 8192 \) points.)

#### Range of block number and device number that can be specified

An extended file register has blocks numbered from '0' to 'n' (the n differs depending on the memory cassette). Block number '0' has a number of points registered with a parameter of the CPU module, while block numbers '1' to 'n' have a register of 8192 points in each block.

However, the range that can be read from or written to the CPU module will be the range specified in the parameter of 0 block. The range of block numbers and device numbers that can be specified differ depending on the type of memory cassette and the parameter setting in the CPU module. For details, refer to the operating manual of UTLP-FN1 or FNUP, or user's manuals of AnACPU and AnUCPU.

- **Point**
  - The AnA/AnUCPU common commands can be used for reading/writing data to the extended file register of block number 1 to 256. In addition, the commands can be used regardless of the existence of file register parameter.
  - When accessing the file register (R) set by parameter or when accessing it by specifying block number, use ACPU common commands.
Device number (address) specification using AnA/AnUCPU common commands

By using AnA/AnU common command function, the extended file register of block number 1 to 256 can be accessed regardless of each block number by specifying the address from device number '0' of the block number '1' as a device number. (Access with the consecutive device number of extended file register using usable number of blocks \( \times \) 8192 points.)

**Device number calculation method**

The calculation formula of the head device number to be specified by AnA/AnUCPU common commands is as follows:

(When specifying the device number \( 'm' \) (0 to 8191) of \( n \) block (more than 1) from the head of the block.)

Head device number = \( (n - 1) \times 8192 + m \)

**Range of device number that can be specified**

The range of device number that can be specified are as follows.

0 to (number of available blocks \( \times \) 8192) - 1

A device number is not assigned to a block number which does not exist in the memory cassette. As shown below, the device numbers are automatically assigned by skipping block numbers that do not exist in the memory cassette.

The following table shows the range of device numbers to be specified when using AnA/AnUCPU common commands for 28 blocks per each block.

<table>
<thead>
<tr>
<th>Device number</th>
<th>Position of target block</th>
<th>Device number</th>
<th>Position of target block</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 to 8191</td>
<td>First block R0 to R8191</td>
<td>114688 to 122879</td>
<td>15th block R0 to R8191</td>
</tr>
<tr>
<td>8192 to 16383</td>
<td>2nd block R0 to R8191</td>
<td>122880 to 131071</td>
<td>16th block R0 to R8191</td>
</tr>
<tr>
<td>16384 to 24575</td>
<td>3rd block R0 to R8191</td>
<td>131072 to 139263</td>
<td>17th block R0 to R8191</td>
</tr>
<tr>
<td>24576 to 32767</td>
<td>4th block R0 to R8191</td>
<td>139264 to 147455</td>
<td>18th block R0 to R8191</td>
</tr>
<tr>
<td>32768 to 40959</td>
<td>5th block R0 to R8191</td>
<td>147456 to 155647</td>
<td>19th block R0 to R8191</td>
</tr>
<tr>
<td>40960 to 49151</td>
<td>6th block R0 to R8191</td>
<td>155648 to 163839</td>
<td>20th block R0 to R8191</td>
</tr>
<tr>
<td>49152 to 57343</td>
<td>7th block R0 to R8191</td>
<td>163840 to 172031</td>
<td>21st block R0 to R8191</td>
</tr>
<tr>
<td>57344 to 65535</td>
<td>8th block R0 to R8191</td>
<td>172032 to 180223</td>
<td>22nd block R0 to R8191</td>
</tr>
<tr>
<td>65536 to 73727</td>
<td>9th block R0 to R8191</td>
<td>180224 to 188415</td>
<td>23rd block R0 to R8191</td>
</tr>
<tr>
<td>73728 to 81919</td>
<td>10th block R0 to R8191</td>
<td>188416 to 196607</td>
<td>24th block R0 to R8191</td>
</tr>
<tr>
<td>81920 to 90111</td>
<td>11th block R0 to R8191</td>
<td>196608 to 204799</td>
<td>25th block R0 to R8191</td>
</tr>
<tr>
<td>90112 to 98303</td>
<td>12th block R0 to R8191</td>
<td>204800 to 212991</td>
<td>26th block R0 to R8191</td>
</tr>
<tr>
<td>98304 to 106495</td>
<td>13th block R0 to R8191</td>
<td>212992 to 221183</td>
<td>27th block R0 to R8191</td>
</tr>
<tr>
<td>106496 to 114687</td>
<td>14th block R0 to R8191</td>
<td>221184 to 229375</td>
<td>28th block R0 to R8191</td>
</tr>
</tbody>
</table>
Data to be specified in command

Device number

■ ACPU common command
Specify the block number and device number with 7 digits.
- When the block number is less than 2 digits
  'Block number (2 digits)' + 'R' + 'Device number (4 digits)'
- When the block number is 3 digits
  'Block number (3 digits)' + 'Device number (4 digits)'

![Diagram showing device number specification]

■ AnA/AnUCPU common command
Specify the address from device number 0 of block number 1 in 7 digits.

- Device number (address) specification using AnA/AnUCPU common commands

![Diagram showing device number specification]
Batch read (command: ER)

Read extended file register (R) in 1-point units.

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

```
|   E   |   R   | Message wait | Head device No. | Number of device points (Number of words) |
```

**Response data**

The value of read device is stored in word units. (Page 70 Read data, write data)

**Data specified by request data**

**Command**

```
ACPU common
```

**Message wait**

Specify the delayed time of the response transmission. (Page 341 Message wait)

**Head device No.**

Specify the block number and device number of head device with 7 digits. (Page 368 Device number)

**Number of device points**

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Specify the number of device points within the following range:
- \(1 \leq \text{Number of device points} \leq 64\)
- Head device No. + Number of device points - 1 \(\leq\) Maximum device No.

**Communication example**

Read data of 2 points (R8190 and R8191) of block number 12 under the following conditions.
- Message wait: 0 ms
- Block number: 12
- Head device: R8190
- Number of device points: 2 points (2 words)

(Request data)

```
<table>
<thead>
<tr>
<th>E</th>
<th>R</th>
<th>Message wait</th>
<th>Head device No.</th>
<th>Number of device points (Number of words)</th>
</tr>
</thead>
<tbody>
<tr>
<td>(45_5)</td>
<td>(52_5)</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
```

(Response data)

```
<table>
<thead>
<tr>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
<th>5</th>
<th>6</th>
<th>7</th>
<th>A</th>
<th>B</th>
<th>C</th>
</tr>
</thead>
<tbody>
<tr>
<td>(31_5), (32_5), (33_5), (34_5), (35_5)</td>
<td>(37_5), (41_5), (42_5), (43_5)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
```

\(\text{R8190 in NO.12}\)

\(\text{R8191 in NO.12}\)
Batch write (command: EW)

Write extended file register (R) in 1-point units.

Message format

The following shows the message format of the request data and response data of the command.

- **Request data**

<table>
<thead>
<tr>
<th>E</th>
<th>W</th>
</tr>
</thead>
<tbody>
<tr>
<td>45n</td>
<td>57n</td>
</tr>
</tbody>
</table>

- **Response data**

There is no response data for this command.

Data specified by request data

- **Command**

  ACPI common

- **Message wait**

  Specify the delayed time of the response transmission. (Page 341 Message wait)

- **Head device No.**

  Specify the block number and device number of head device with 7 digits. (Page 368 Device number)

- **Number of device points**

  Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

  Specify the number of device points within the following range:
  
  - $1 \leq \text{Number of device points} \leq 64$
  
  - : Head device No. + Number of device points - 1 $\leq \text{Maximum device No.}$

- **Write data for the number of device points**

  Store the data to be written in batch.

Communication example

Write data of 3 points (R7010 to R7012) of block number 5 under the following conditions.

- Message wait: 0 ms
- Block number: 5
- Head device: R7010
- Number of device points: 3 points (3 words)

(Request data)
Test (random write) (command: ET)

Specify the block number and device number to the extended file register (R) in 1-point units and write them randomly.

Message format

The following shows the message format of the request data and response data of the command.

### Request data

<table>
<thead>
<tr>
<th>E</th>
<th>T</th>
<th>Message wait</th>
<th>Number of device points</th>
<th>Device No.</th>
<th>Write data</th>
</tr>
</thead>
</table>

### Response data

There is no response data for this command.

Data specified by request data

#### Command

ACPU common

#### Message wait

Specify the delayed time of the response transmission. (Page 341 Message wait)

#### Number of device points

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.
Specify the number of device points within the following range:
- \( 1 \leq \text{Number of device points} \leq 10 \)

#### Device number

Specify the block number and device number to be test with 7 digits. (Page 368 Device number)

#### Write data

Store 4 characters per one device point.

Communication example

Write data of three points (3 words) randomly under the following conditions.
- Message wait: 0 ms
- Number of device points: 3 points (3 words)
- Device: Set R1234H to R1050 of block number 5, 1A1BH to R2121 of block number 7, and 506H to R3210 of block number 10.

(Request data)
Monitor (command: EM, ME)

The monitor data registration function registers the devices and numbers to be monitored from an external device to C24. The monitor function reads the data of the registered devices from the CPU module and processes it in the external device. When the batch read (ER) or direct read (NR) is performed, the read device numbers will be consecutive, however, by using this function, devices can be monitored by specifying the device numbers randomly. The following example shows the control procedure for monitoring and registering name and number of the devices to be monitored to the C24.

**Monitoring procedure**

1. Process the monitor data registration (Edit of EM command and transmission of device specification.)
   - Register monitor data (command: EM)
2. Perform read process. (Execution of ME command)
   - Monitor (command: ME)
3. Process the data. (Screen display, etc.)
4. If do not change the devices to be monitored, return to step 2, and repeat the process.

**Point**

- When monitoring data as the procedure shown above, the monitor data registration is required. If monitoring data without registering the data, a protocol error occurs.
- The content of registered monitor data are deleted when C24 is rebooted.
- Five kinds of monitor data can be registered for the extended file register (EM), device memory in bit units (BM or JM), and word units (WM or QM).
- When registering device memory of the CPU module as a monitor data from more than one external devices on the same station, the recently registered device memory will be available since the registration data is overwritten. (Monitoring device memory Page 360 Monitor (Command: BM, JM, WM, QM, MB, MJ, MN, MQ))
### Register monitor data (command: EM)

Register the device number to be monitored in 1-point units.
Monitor the extended file register registered with EM command using the following command.

Page 374 Monitor (command: ME)

**Request data**

<table>
<thead>
<tr>
<th>E</th>
<th>M</th>
<th>Message wait</th>
<th>Number of device points</th>
<th>Device No. (for the number of device points)</th>
</tr>
</thead>
</table>

- **Command**

  ACPU common

- **Message wait**: Specify the delayed time of the response transmission. ([Page 341 Message wait])
- **Number of device points**: Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.
- **Device number**: Specify the block number and device number of the device to be monitored with 7 digits. ([Page 368 Device number])

Specify the number of device points within the following range:

\[1 \leq \text{Number of device points} \leq 20\]

**Response data**

There is no response data for this command.

**Communication example**

Perform monitor data registration of 4 points (4 words) under the following conditions.

- **Message wait**: 0 ms
- **Number of device points**: 4 points (4 words)
- **Device number**: Register R1234 of block number 5, R2345 of block number 6, R3055 of block number 15, and R8000 of block number 17.

(When the extended file register of block number 1 to 8 and 10 to 17 exist.)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points</th>
<th>Device No.</th>
<th>Device No.</th>
<th>Device No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>45h 4Dh</td>
<td>0 0 4 0 5 R 1 2 3 4</td>
<td>0 6 R 2 3 4 5</td>
<td>1 5 R 3 0 5 5</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>3 1 3 5 5 2 3</td>
<td>3 0 3 5 5 1</td>
<td></td>
</tr>
</tbody>
</table>

Device No.

\[1 7 R 8 0 0 0\]

\[31h 37h 52h 38h 30h 30h 30h\]
Monitor (command: ME)

Monitor the registered extended file registers.

■ Message format
  • Request data

  
<table>
<thead>
<tr>
<th>M</th>
<th>E</th>
</tr>
</thead>
<tbody>
<tr>
<td>4Dh</td>
<td>45h</td>
</tr>
</tbody>
</table>

  Message wait

  • Response data

  Monitoring result (For the number of device points)

  The value of read device is stored in word units. (Page 70 Read data, write data)

■ Data specified by request data
  • Command

<table>
<thead>
<tr>
<th>M</th>
<th>E</th>
</tr>
</thead>
<tbody>
<tr>
<td>4Dh</td>
<td>45h</td>
</tr>
</tbody>
</table>

  • Message wait: Specify the delayed time of the response transmission. (Page 341 Message wait)

■ Communication example

Monitor data of 4 points (4 word) specified with monitor data registration under the following conditions.
  • Message wait: 0 ms
  • Registered devices for monitoring: R1234 of block number 5, R2345 of block number 6, R3055 of block number 15, and 4-point of R8000 of block number 17.

(Request data)

<table>
<thead>
<tr>
<th>M</th>
<th>E</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>4Dh</td>
<td>45h</td>
<td>30h</td>
</tr>
</tbody>
</table>

(Decimai: 13569) (Decimai: 20315) (Decimai: 366) (Decimai: 366)
(R1234 in No.5) (R2345 in No.6) (R3055 in No.15) (R8000 in No.17)
Direct read (command: NR)

Read extended file register in 1-point (1 word) units by specifying the consecutive device number of extended file register.

Message format

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>N</th>
<th>R</th>
</tr>
</thead>
<tbody>
<tr>
<td>4E</td>
<td>52h</td>
</tr>
</tbody>
</table>

**Response data**

The value of read device is stored in word units. (Page 70 Read data, write data)

Data specified by request data

**Command**

ACPU common

<table>
<thead>
<tr>
<th>N</th>
<th>R</th>
</tr>
</thead>
<tbody>
<tr>
<td>4E</td>
<td>52h</td>
</tr>
</tbody>
</table>

**Message wait**

Specify the delayed time of the response transmission. (Page 341 Message wait)

**Head device No.**

Specify the device number of head device with 7 digits. (Page 368 Device number)

**Number of device points**

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Specify the number of device points within the following range:

- \(1 \leq \text{Number of device points} \leq 64\)
- Head device No. + Number of device points - 1 \(\leq\) Maximum device No.

Communication example

Read data of 2 points (R8190 and R8191) of block number 2 under the following conditions.

- Message wait: 0 ms
- Block number: 2
- Head device: R8190
- Number of device points: 2 points (2 words)

(Request data)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Head device No.</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>N</td>
<td>R</td>
<td>0</td>
</tr>
<tr>
<td>4E</td>
<td>52h</td>
<td>30h</td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>Data read</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 2 3 4 7 A B C</td>
</tr>
<tr>
<td>(Decimal: 4660) (Decimal: 31420)</td>
</tr>
<tr>
<td>31h, 32h, 33h, 34h</td>
</tr>
<tr>
<td>(R8190 in No.2) (R8191 in No.2)</td>
</tr>
</tbody>
</table>
Direct write (command: NW)

Write extended file register in 1-point (1 word) units by specifying the consecutive device number of extended file register.

Message format

The following shows the message format of the request data and response data of the command.

■Request data

<table>
<thead>
<tr>
<th>N</th>
<th>W</th>
<th>Message wait</th>
<th>Head device No.</th>
<th>Number of device points</th>
<th>Write data for the number of device points</th>
</tr>
</thead>
</table>

■Response data

There is no response data for this command.

Data specified by request data

■Command

ACPU common

![ACPU common]

■Message wait

Specify the delayed time of the response transmission. (Page 341 Message wait)

■Head device No.

Specify the device number of head device with 7 digits. (Page 368 Device number)

■Number of device points

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Specify the number of device points within the following range:

- $1 \leq \text{Number of device points} \leq 64$
- Head device No. + Number of device points - 1 $\leq$ Maximum device No.

■Write data for the number of device points

Store 4-digit data per one device point.

Communication example

Write data of 3 points under the following conditions.

- Message wait: 0 ms
- Write data: Write R8190 and R8191 of block number 12 and RO of block number 13.
  (When the extended file register of block number 1 to 8 and 10 to 13 exist.)
- Number of device points: 3 points (3 words)

(Request data)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Number of device points (Number of words)</th>
</tr>
</thead>
<tbody>
<tr>
<td>N W</td>
<td>Head device No.</td>
</tr>
<tr>
<td>4En, 57a</td>
<td>30h</td>
</tr>
<tr>
<td>0 0 0 0 0 0 0</td>
<td>30h 30h 30h 30h 30h 30h 30h</td>
</tr>
<tr>
<td>0 0 0 0 0 0 0</td>
<td>30h 30h 30h 30h 30h 30h 30h</td>
</tr>
<tr>
<td>0 3</td>
<td>30h 30h 30h 30h 30h 30h 30h</td>
</tr>
<tr>
<td>0 1 2 3</td>
<td>A 8 C 7</td>
</tr>
<tr>
<td>(Decimal : 291)</td>
<td>(Decimal : 21753)</td>
</tr>
<tr>
<td>20h 31h 32h 33h</td>
<td>30h 41h 42h 43h 44h 45h 46h</td>
</tr>
<tr>
<td>(R8190 in No.12)</td>
<td>(R8191 in No.12)</td>
</tr>
</tbody>
</table>
17.6 Read and write Buffer Memory of Special Function Module

The following examples the commands that perform data read/write to the buffer memory of MELSEC-A series special function modules.

Point

This command accesses in byte units regardless of the word/byte specification.

Data to be specified in command

This section explains the contents and specification methods for data items which are set in each command related to the access to the special function module buffer memory.

For details of the specification method of address and module number for commands (TR, TW), refer to the following manual.

Computer Link Module (Com. link func./Print. func.) User's Manual

Start address

Specify the start address of the buffer memory to be read/written.

Convert the numerical value to 5-digit ASCII code (hexadecimal), and send it from the upper digits.

Calculation method

Calculate the start address as follows:

Start address = (Buffer memory address × 2) + the arbitrary additional value of a module

For the additional values (buffer memory start address) for each module, refer to the following section.

Page 379 Accessible modules

Example

When specifying buffer memory address 1H of AD61

(1H × 2) + 80H = 82H

Byte length

Specify the byte length of the special function module buffer memory data to be read/written.

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Read data, write data

The read buffer memory value is stored for reading, and the data to be written is stored for writing.

This function reads/writes data in byte unit.

Page 156 Read data, write data
**Special function module No.**

Specify the last input/output signal (I/O address) of the special function module. (Specify the upper 2-digit in 3-digit representation.)

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

### Special function module No. which occupies 1 slot

Special function module No. is the upper 2 digits of the input/output signal (I/O address) of the last number represented with 3-digits on the slot where the module is mounted.

<table>
<thead>
<tr>
<th>Power supply module</th>
<th>CPU module</th>
<th>Input</th>
<th>16 points</th>
<th>Output</th>
<th>32 points</th>
<th>Input</th>
<th>16 points</th>
<th>Output</th>
<th>32 points</th>
<th>Special function module</th>
<th>Input</th>
<th>16 points</th>
<th>32 points</th>
<th>Output</th>
<th>32 points</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>00 to 0F</td>
<td>10 to 2F</td>
<td>30 to 4F</td>
<td>50 to 5F</td>
<td>60 to 7F</td>
<td>80 to 8F</td>
<td>90 to AF</td>
<td>B0 to CF</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Module No. &quot;0AH&quot;</td>
<td></td>
<td>Module No. &quot;07H&quot;</td>
<td></td>
<td>Module No. &quot;13H&quot;</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Special function module No. which occupies 2 slots

For a special function module which occupies two slots, the number of occupied points for each slot is fixed for each module. Special function module No. specified for the operation procedure is the upper 2 digits of the input/output signal (I/O address) of the last number represented with 3-digits of the slot assigned as a special function module on the slot.

For details of the assigned slot for each module, refer to the manual of the modules.

**Ex**

A module that assign the first part of the slots as empty slots (AD72, A84AD, etc.)

<table>
<thead>
<tr>
<th>(Empty slot)</th>
<th>Special function module</th>
</tr>
</thead>
<tbody>
<tr>
<td>16 points</td>
<td>32 points</td>
</tr>
<tr>
<td>00 to 0F</td>
<td>10 to 2F</td>
</tr>
</tbody>
</table>

**Ex**

A module that assign the last part of the slots as empty slots (A61LS, etc.)

<table>
<thead>
<tr>
<th>Special function module</th>
<th>(Empty slot)</th>
</tr>
</thead>
<tbody>
<tr>
<td>32 points</td>
<td>16 points</td>
</tr>
<tr>
<td>00 to 0F</td>
<td>20 to 2F</td>
</tr>
</tbody>
</table>

**Ex**

A module in which both assignment of special function module and I/O assignment exist (A81CPU)

<table>
<thead>
<tr>
<th>Special function module</th>
<th>Input module</th>
</tr>
</thead>
<tbody>
<tr>
<td>64 points</td>
<td>64 points</td>
</tr>
<tr>
<td>00 to 3F</td>
<td>40 to 7F</td>
</tr>
</tbody>
</table>
### Accessible modules

The accessible special function modules are as follows.

<table>
<thead>
<tr>
<th>Module</th>
<th>Type</th>
<th>Additional values when calculating start address (Buffer memory start address)</th>
<th>Module number when module is mounted on slot 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>High-speed counter module</td>
<td>AD61 (S1)</td>
<td>80H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A1SD61, A1SD62 (E/D)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Analog-digital converter module</td>
<td>A616AD</td>
<td>10H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A68AD(S2), A68ADN</td>
<td>80H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A84AD</td>
<td>10H</td>
<td>02H</td>
</tr>
<tr>
<td></td>
<td>A1S64AD</td>
<td>10H</td>
<td>01H</td>
</tr>
<tr>
<td>Digital-analog converter module</td>
<td>A616DAI, A616DAV/A62DA (S1)</td>
<td>10H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A68DAV/DAI</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>A1S64AD</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Temperature-digital converter module</td>
<td>A616TD</td>
<td>10H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A68RD3/4</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>A1S62RD3/4</td>
<td></td>
<td></td>
</tr>
<tr>
<td>PID control module</td>
<td>A81CPU</td>
<td>200H</td>
<td>03H</td>
</tr>
<tr>
<td>Position detection module</td>
<td>A61LS</td>
<td>80H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A62LS (S5)</td>
<td>80H</td>
<td>02H</td>
</tr>
<tr>
<td>MELSECNET/Mini master module</td>
<td>AJ71PT32 (S3), AJ71T32-S3</td>
<td>20H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A1S71PT32-S3</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CC-Link system master/local module</td>
<td>AJ61BT11</td>
<td>2000H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A1S61BT11</td>
<td>2000H</td>
<td>01H</td>
</tr>
<tr>
<td>Multidrop link module</td>
<td>AJ71CC2 (S1)</td>
<td>1000H</td>
<td>01H</td>
</tr>
<tr>
<td>Computer link module</td>
<td>AJ71C24 (S3/S6/S8)</td>
<td>1000H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>AJ71UC24</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>A1S71J7 (U) C24-R2</td>
<td>400H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A1S71J7 (U) C24-PRF</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>A1S71J7 (U) C24-R4</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Intelligent communication module</td>
<td>AD51H (S3), AD51H (S3)</td>
<td>800H</td>
<td>02H</td>
</tr>
<tr>
<td>Terminal interface module</td>
<td>AJ71C21 (S1)</td>
<td>400H</td>
<td>01H</td>
</tr>
<tr>
<td>B/NET interface module</td>
<td>AJ71B62</td>
<td>20H</td>
<td>01H</td>
</tr>
<tr>
<td>SUMINET interface module</td>
<td>AJ71P41</td>
<td>400H</td>
<td>01H</td>
</tr>
<tr>
<td>Ethernet interface module</td>
<td>AJ71E71 (S3)</td>
<td>400H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A1S71E71 (S3)</td>
<td>4000H</td>
<td>01H</td>
</tr>
<tr>
<td>External fault diagnosis module</td>
<td>AD51FD (S3)</td>
<td>280H</td>
<td>02H</td>
</tr>
<tr>
<td>Graphic controller module</td>
<td>AD57G (S3)</td>
<td>280H</td>
<td>02H</td>
</tr>
<tr>
<td>Vision sensor module</td>
<td>A525VS, A550VS</td>
<td>100H</td>
<td>02H</td>
</tr>
<tr>
<td></td>
<td>A550VS-GN</td>
<td>80H</td>
<td>02H</td>
</tr>
<tr>
<td>Memory card interface module</td>
<td>AD59 (S1)</td>
<td>1800H</td>
<td>01H</td>
</tr>
<tr>
<td>Positioning module</td>
<td>AD70 (D) (S2)</td>
<td>80H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>AD71 (S1/S2/S7)</td>
<td>200H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>AD72 A1SD71-S2/S7</td>
<td>200H</td>
<td>02H</td>
</tr>
<tr>
<td></td>
<td>AD75P1/P2/P3 (S3), AD75M1/M2/M3</td>
<td>800H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A1SD75P1/P2/P3 (S3), A1SD75M1/M2/M3</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Positioning module for 1 axis</td>
<td>A1SD70</td>
<td>80H</td>
<td>01H</td>
</tr>
<tr>
<td>Analog input/output module</td>
<td>A1S63ADA</td>
<td>10H</td>
<td>01H</td>
</tr>
<tr>
<td>Temperature control module</td>
<td>A1S64TCTT (BW)-S1</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>A1S64TCTT (BW)-S1</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>A1S64TCTT (BW)-S1</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>A1S62TCTT (BW)-S2</td>
<td>20H</td>
<td>01H</td>
</tr>
<tr>
<td></td>
<td>A1S62TCTT (BW)-S2</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>A1S62TCTT (BW)-S2</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Batch read (command: TR)

Read the buffer memory of a special function module.

Message format

The following shows the message format of the request data and response data of the command.

■Request data

<table>
<thead>
<tr>
<th>T</th>
<th>R</th>
</tr>
</thead>
<tbody>
<tr>
<td>5a</td>
<td>52</td>
</tr>
</tbody>
</table>

■Response data

The value read from the buffer memory is stored.
2-digit ASCII code data is stored per 1 byte of buffer memory data.

Data specified by request data

■Command

ACPU common

<table>
<thead>
<tr>
<th>T</th>
<th>R</th>
</tr>
</thead>
<tbody>
<tr>
<td>5a</td>
<td>52</td>
</tr>
</tbody>
</table>

■Message wait

Specify the delayed time of the response transmission. (Page 341 Message wait)

■Start address

Specify the start address of the buffer memory to be read in five digits. (Page 380 Start address)

■Byte length

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.
Specify the byte length within the following ranges:

- $1 \leq \text{Byte length} \leq 128$

■Special function module No.

Specify with 2 digits. (Page 380 Special function module No.)

The content of one data may cross 2 or 3 bytes depending on the special function module. For the specifications of byte length, refer to the manual of each module.


**Communication example**

Read data of 4 bytes under the following conditions.

- Message wait: 0 ms
- Start address: 7FOH
- Byte length: 4 bytes
- Special function module No.: 13 (input/output signals are 120H to 13FH)

(Request data)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Start address</th>
<th>Byte length</th>
<th>Special function module No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>T R 0 0 7 F 0 4 1 3</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

Data read

<table>
<thead>
<tr>
<th>1 2 7 8 4 3 6 5</th>
</tr>
</thead>
<tbody>
<tr>
<td>31n, 32n, 37n, 38n, 34n, 33n, 36n, 35n</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Start address</th>
<th>Buffer memory</th>
</tr>
</thead>
<tbody>
<tr>
<td>7FOH</td>
<td>7812H</td>
</tr>
<tr>
<td>7F2H</td>
<td>6543H</td>
</tr>
</tbody>
</table>
Batch write (command: TW)

Write data to the buffer memory of a special function module.

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>T</th>
<th>W</th>
</tr>
</thead>
<tbody>
<tr>
<td>54h</td>
<td>57h</td>
</tr>
<tr>
<td>Message wait</td>
<td>Start address</td>
</tr>
</tbody>
</table>

**Response data**

There is no response data for this command.

**Data specified by request data**

**Command**

ACPU common

**Message wait**

Specify the delayed time of the response transmission. (Page 341 Message wait)

**Start address**

Specify the start address of the buffer memory to be written in five digits. (Page 380 Start address)

**Byte length**

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Specify the byte length within the following ranges:

- $1 \leq \text{Byte length} \leq 128$

**Special function module No.**

Specify in two characters. (Page 380 Special function module No.)

**Write data**

Store the data written to buffer memory.

*Point*

The content of one data may cross 2 or 3 bytes depending on the special function module. For the specifications of byte length, refer to the manual of each module.

**Communication example**

Write data of 4 bytes under the following conditions.

- Message wait: 0 ms
- Start address: 27FAH
- Byte length: 4 bytes
- Special function module No.: 13 (input/output signals are 120H to 13FH)

(Request data)
17.7 Loopback Test

A loopback test checks whether the communication function between an external device and C24 operates normally.

Loopback test (Command: TT)

Return the characters received from an external device to the external device unchanged.

Message format

The following shows the message format of the request data and response data of the command.

- **Request data**

  - Command
  - Message wait
  - Character length
  - Loopback data

- **Response data**

  - Character length
  - Loopback data

Data specified by request data

- **Command**

  - ACPU common

- **Message wait**

  Specify the delayed time of the response transmission. ([Page 341 Message wait]

- **Character length**

  Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

  Specify the character length within the following range:

  \[
  1 \leq \text{Character length} \leq 254
  \]

- **Loopback data**

  Store the loopback data for character length.

Data stored by response data

- **Character length**

  The same data as request data is stored.

- **Loopback data**

  The same data as request data is stored.

**Point**

Specify 'FF' for PC No.
Communication example

Return 5-digit data received from an external device to the external device unchanged under the following conditions.
- Message wait: 0 ms
- Character length: 5 characters
- Loopback data: 'ABCDE'

(request data)

<table>
<thead>
<tr>
<th>Message wait</th>
<th>Character length</th>
<th>Loopback data</th>
</tr>
</thead>
<tbody>
<tr>
<td>T</td>
<td>0</td>
<td>5</td>
</tr>
<tr>
<td>T</td>
<td>0</td>
<td>5</td>
</tr>
<tr>
<td>T</td>
<td>0</td>
<td>5</td>
</tr>
<tr>
<td>T</td>
<td>0</td>
<td>5</td>
</tr>
<tr>
<td>T</td>
<td>0</td>
<td>5</td>
</tr>
</tbody>
</table>

(request data)

<table>
<thead>
<tr>
<th>Character length</th>
<th>Loopback data</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>A</td>
</tr>
<tr>
<td>0</td>
<td>B</td>
</tr>
<tr>
<td>0</td>
<td>C</td>
</tr>
<tr>
<td>0</td>
<td>D</td>
</tr>
<tr>
<td>0</td>
<td>E</td>
</tr>
<tr>
<td>30</td>
<td>45</td>
</tr>
<tr>
<td>30</td>
<td>45</td>
</tr>
<tr>
<td>30</td>
<td>45</td>
</tr>
<tr>
<td>30</td>
<td>45</td>
</tr>
<tr>
<td>30</td>
<td>45</td>
</tr>
</tbody>
</table>
18 COMMUNICATING USING 1E FRAMES

This chapter explains the functions when accessing using 1E frame and their message format. 1E frame is compatible with the communication function supported by MELSEC-A series Ethernet interface modules. Only the commands for 1E frame explained in this chapter can be used for 1E frame.

18.1 Message Format

This section explains the message format when communicating data using 1E frame.

## Message format

<table>
<thead>
<tr>
<th>Request message</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Header</td>
<td>Subheader</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Response message (Normal completion: Response data)</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Header</td>
<td>Subheader</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Response message (Normal completion: No response data)</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Header</td>
<td>Subheader</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Response message (Abnormal completion)</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Header</td>
<td>Subheader</td>
</tr>
</tbody>
</table>

### Setting data

Set the following items.

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Header</td>
<td>A header of Ethernet. Normally, it is added automatically.</td>
<td>Page 386 Header</td>
</tr>
<tr>
<td>Subheader</td>
<td>Set the command type.</td>
<td>Page 386 Subheader</td>
</tr>
<tr>
<td>PC No.</td>
<td>Specify the network module station No. of an access target.</td>
<td>Page 387 PC No.</td>
</tr>
<tr>
<td>ACPU monitoring timer</td>
<td>Set the wait time up to the completion of reading and writing processing.</td>
<td>Page 388 ACPU monitoring timer</td>
</tr>
<tr>
<td>Request data</td>
<td>Set the commands that indicates request content.</td>
<td>Page 391 Read and Write Device Memory</td>
</tr>
<tr>
<td>Response data</td>
<td>For the response data, store the read data for the command at normal completion. Refer to “Response data” rows of each command.</td>
<td>Page 412 Read and Write Extended File Register</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Page 426 Read and Write Buffer Memory of Special Function Module</td>
</tr>
<tr>
<td>End code</td>
<td>The command processing result is stored.</td>
<td>Page 389 End code, Abnormal code</td>
</tr>
<tr>
<td>Abnormal code</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

18.2 Detail of Setting Data

This section explains how to specify the common data items and their content in each message.
**Header**

A header for TCP/IP and UDP/IP. A header of a request message is added on the external device side and sent. Normally, it is added automatically by an external device. A header for a response message is set automatically by E71.

**Subheader**

Set the command type. (See Page 390 Commands and Function List for 1E Frame)

The setting values for each command are as follows.

<table>
<thead>
<tr>
<th>Function</th>
<th>Subheader</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Request message</td>
<td>Response message</td>
</tr>
<tr>
<td>Read and write device memory</td>
<td>00H</td>
<td>80H</td>
</tr>
<tr>
<td></td>
<td>01H</td>
<td>81H</td>
</tr>
<tr>
<td></td>
<td>02H</td>
<td>82H</td>
</tr>
<tr>
<td></td>
<td>03H</td>
<td>83H</td>
</tr>
<tr>
<td></td>
<td>04H</td>
<td>84H</td>
</tr>
<tr>
<td></td>
<td>05H</td>
<td>85H</td>
</tr>
<tr>
<td></td>
<td>06H</td>
<td>86H</td>
</tr>
<tr>
<td></td>
<td>07H</td>
<td>87H</td>
</tr>
<tr>
<td></td>
<td>08H</td>
<td>88H</td>
</tr>
<tr>
<td></td>
<td>09H</td>
<td>89H</td>
</tr>
<tr>
<td>Read and write extended file register</td>
<td>17H</td>
<td>97H</td>
</tr>
<tr>
<td></td>
<td>18H</td>
<td>98H</td>
</tr>
<tr>
<td></td>
<td>19H</td>
<td>99H</td>
</tr>
<tr>
<td></td>
<td>1AH</td>
<td>9AH</td>
</tr>
<tr>
<td></td>
<td>1BH</td>
<td>9BH</td>
</tr>
<tr>
<td></td>
<td>3BH</td>
<td>BBH</td>
</tr>
<tr>
<td></td>
<td>3CH</td>
<td>BCH</td>
</tr>
<tr>
<td>Read and write buffer memory of special function module</td>
<td>0EH</td>
<td>8EH</td>
</tr>
<tr>
<td></td>
<td>0FH</td>
<td>8FH</td>
</tr>
</tbody>
</table>

**Setting method**

- **Data communication in ASCII code**
  Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

- **Data communication in binary code**
  Send 1-byte numerical value.

**Example**

Device memory batch read (word units)

**Request message**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>00</td>
<td>00</td>
</tr>
</tbody>
</table>

**Response message**

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>80</td>
<td>80</td>
</tr>
</tbody>
</table>
PC No.

Specify the station No. of the access target.

**Accessing the connected station (host station)**

Specify 'FF'.

![Diagram of external device, connected station (host station), and access target station]

**Accessing other stations via network**

Specify the network module station No. 01H to 40H (1 to 64) of the access target.

![Diagram of external device, network, other station, and access target station]

**Setting method**

- **Data communication in ASCII code**
  Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

- **Data communication in binary code**
  Send 1-byte numerical value.

**Ex.**

Accessing the connected station (host station)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>FF</td>
<td>FF</td>
</tr>
</tbody>
</table>

When accessing other station of network station No. '3'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>03</td>
<td>03</td>
</tr>
</tbody>
</table>

**Point**

The station No. of the network module can be checked by using the following parameters of Engineering tool.
- GX Developer and GX Works2: "Network Parameter"
- GX Works3: "Module Parameter"

The network module station No. is set in decimal. However, the PC No. is set in hexadecimal.

When specifying the network of the access target is required, set "Valid Module During Other Station Access" with an Engineering tool.
ACPU monitoring timer

Set the wait time up to the completion of reading and writing processing.
- 0000H (0): Wait infinitely (Waits until a processing is completed.)
- 0001H to FFFFH (1 to 65535): Waiting time (unit: 250 ms)

To perform normal data communication, using the timer within the setting range in the table below is recommended depending on the communication destination.

<table>
<thead>
<tr>
<th>Access target</th>
<th>The recommended value for monitoring timer</th>
</tr>
</thead>
<tbody>
<tr>
<td>Connected station (host station)</td>
<td>1H to 28H (0.25 s to 10 s)</td>
</tr>
<tr>
<td>Other station</td>
<td>2H to F0H (0.5 s to 60 s)</td>
</tr>
</tbody>
</table>

When accessing QnACPU or ACPU for the first time, the wait time for CPU monitoring timer is required before receiving a response message because QnACPU identifies the CPU type. Be sure to set a value within the range of recommended range.

Setting method

Data communication in ASCII code
Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

Data communication in binary code
Send 2-byte numerical values from lower byte (L: bits 0 to 7).

**Ex.**
When specifying ‘10H’ for the monitoring timer

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 1 0</td>
<td>10 00</td>
</tr>
<tr>
<td>30h, 30h, 31h, 30h</td>
<td>10h, 00h</td>
</tr>
</tbody>
</table>
End code, Abnormal code

The command processing result is stored.

End code

At normal completion, '0' is stored.
At abnormal completion, an error code of the access target is stored.
Error code indicates the content of occurred error.
If more than one error occurs at the same time, the error code detected first is returned.
For the content of error code and its corrective action, refer to the user's manual of the module used.

▶ QCPU User's Manual (Hardware Design, Maintenance and Inspection)
▶ MELSEC-L CPU Module User's Manual (Hardware Design, Maintenance and Inspection)
▶ Q Corresponding Ethernet Interface Module User's Manual (Basic)
▶ MELSEC-L Ethernet Interface Module User's Manual (Basic)

Abnormal code

When an end code is '5BH', the details of abnormal content are displayed.

Setting method

Data communication in ASCII code
Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

Data communication in binary code
Use a 1-byte value.

Ex.

Normal completion

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>00</td>
</tr>
</tbody>
</table>

When Error code '10H' is returned

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 0</td>
<td>10</td>
</tr>
</tbody>
</table>

When error code '5BH' and an abnormal code '10H' (PC No. error) are returned,

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 8 1 0</td>
<td>5B</td>
</tr>
</tbody>
</table>
## 18.3 Commands and Function List for 1E Frame

Use the following commands for data communication using 1E frame.

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Device memory</strong>¹</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Batch read</td>
<td>Bit units 00H</td>
<td>Reads bit devices (X, Y, M, etc.) in 1-point units.</td>
</tr>
<tr>
<td></td>
<td>Word units 01H</td>
<td>Reads bit devices (X, Y, M, etc.) in 16-point units.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Reads word devices (D, T, C, etc.) in 1-point units.</td>
</tr>
<tr>
<td>Batch write</td>
<td>Bit units 02H</td>
<td>Writes bit devices (X, Y, M, etc.) in 1-point units.</td>
</tr>
<tr>
<td></td>
<td>Word units 03H</td>
<td>Writes bit devices (X, Y, M, etc.) in 16-point units.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Writes word devices (D, T, C, etc.) in 1-point units.</td>
</tr>
<tr>
<td>Test (random write)</td>
<td>Bit units 04H</td>
<td>Specify the devices and device numbers of bit devices (X, Y, M, etc.) in 1-point units randomly, and set/reset them.</td>
</tr>
<tr>
<td></td>
<td>Word units 05H</td>
<td>Specify the devices and device numbers of bit devices (X, Y, M, etc.) in 16-point units randomly, and set/reset them.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Specify the devices and device numbers of word devices (D, T, C, etc.) in 1-point units randomly, and write them.</td>
</tr>
<tr>
<td>Register monitor data ²</td>
<td>Bit units 06H</td>
<td>Registers bit devices (X, Y, M, etc.) to be monitored in 1-point units.</td>
</tr>
<tr>
<td></td>
<td>Word units 07H</td>
<td>Registers bit devices (X, Y, M, etc.) to be monitored in 16-point units.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Registers word devices (D, T, C, etc.) to be monitored in 1-point units.</td>
</tr>
<tr>
<td>Monitoring</td>
<td>Bit units 08H</td>
<td>Monitors the devices registered by monitor data registration.</td>
</tr>
<tr>
<td></td>
<td>Word units 09H</td>
<td></td>
</tr>
<tr>
<td><strong>Extended file register</strong></td>
<td>Batch read 17H</td>
<td>Reads extended file register (R) in 1-point units.</td>
</tr>
<tr>
<td></td>
<td>Batch write 18H</td>
<td>Writes extended file register (R) in 1-point units.</td>
</tr>
<tr>
<td>Test (random write)</td>
<td>19H</td>
<td>Specify the block numbers and device numbers in 1-point units and write them to the extended file register (R) randomly.</td>
</tr>
<tr>
<td>Register monitor data ²</td>
<td>1AH</td>
<td>Registers extended file register (R) in 1-point units.</td>
</tr>
<tr>
<td>Monitoring</td>
<td>1BH</td>
<td>Monitors extended file register (R) with monitor data registered.</td>
</tr>
<tr>
<td>Direct read</td>
<td>3BH</td>
<td>Reads extended file register in 1-point units with direct designation.</td>
</tr>
<tr>
<td>Direct write</td>
<td>3CH</td>
<td>Writes extended file register in 1-point units by direct specification.</td>
</tr>
<tr>
<td><strong>Special function module</strong></td>
<td>Batch read 0EH</td>
<td>Reads the content in the buffer memory of a special function module.</td>
</tr>
<tr>
<td></td>
<td>Batch write 0FH</td>
<td>Writes data to the buffer memory of a special function module.</td>
</tr>
</tbody>
</table>

---

¹ Use the dedicated commands for extended registers when performing extended file registers read/write.

² The devices that can be registered to E71 is for 1 command out of the three types of commands (06H, 07H, 1AH). The specified device recently used by any of the above commands is registered to E71.
18.4 Read and Write Device Memory

This section explains the specification content and examples of the request data and the response data when reading and writing device memory.

For the message formats other than request data and response data, refer to the following sections.

Page 385 Message Format, Page 385 Detail of Setting Data

To read and write the extended file register, use the commands dedicated to the extended file register.

Page 412 Read and Write Extended File Register

Considerations

Considerations when reading/writing data to module other than ACPU module

■ Accessible devices

Only the devices with the same names that exist in ACPU can be accessed within the device range of AnACPU.

The following devices cannot be accessed from the external devices

• Added devices
• Latch relay (L) and step relay (S)
• File register (R)

■ Special relays and special registers

Special relays and special registers can be accessed within the following range.

• Access SM1000 to SM1255 by specifying M9000 to M9255.
• Access SD1000 to SD1255 by specifying D9000 to D9255.

■ Universal model QCPU

Use the Universal model QCPU with a serial number whose first five digits are '10102' or later.

When the module with the serial number whose first five digits are '10101' or earlier, access using 3E frame or 4E frame.

When accessing the built-in Ethernet port of the CPU module, refer to the following manual.

QnUCPU User's Manual (Communication via Built-in Ethernet Port)

Data to be specified in command

Device codes and device numbers

The settings of each device when reading/writing device memory can be performed using device code and device number as shown in the following figure.

Specify the device to be accessed by a device code and a device number.

The order of data differs depending on the ASCII code or binary code.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device code</td>
<td>Device number</td>
</tr>
<tr>
<td>(4 digits)</td>
<td>(8 digits)</td>
</tr>
</tbody>
</table>

■ Data communication in ASCII code

• Device code: Convert the numerical value to 4-digit ASCII code (hexadecimal), and send it from upper digits.
• Device number: Convert the numerical value to 8-digit (hexadecimal) ASCII code and send it from the upper digits.

■ Data communication in binary code

• Device number: Send 4-byte numerical values from the lower byte (L: bits 0 to 7).
• Device code: Send 2-byte numerical values from lower byte (L: bits 0 to 7).
Example

Data register (D) 1234 (device number is decimal)

Convert a device number to hexadecimal. ‘1234’ (decimal)→‘4D2’ (hexadecimal)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 0 4 D 2</td>
<td>02 04 00 00 20 44</td>
</tr>
</tbody>
</table>

For the values of each device code, refer to the following section.

Space

Access the devices within the range that can be used in the access target CPU.

For the accessible device range, refer to the following section.

--- Page 393 Accessible device range

- For word unit specification, the head device number of bit device must be specified in multiple of 16.
- For special relay M9000 or later, (9000 + multiple of 16) can be specified.
# Accessible device range

## List of devices (ACPU other than AnU)

Specify the device number within the range of the access target module.

- **Accessible**
- **—**: No device

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Input</strong></td>
<td>X0 to X0FF</td>
<td>0000H to 00FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>X100 to X1FF</td>
<td>0100H to 01FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>X200 to X2FF</td>
<td>0200H to 03FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>X400 to X7FF</td>
<td>0400H to 07FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Output</strong></td>
<td>Y0 to Y0FF</td>
<td>0000H to 00FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>Y100 to Y1FF</td>
<td>0100H to 01FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>Y200 to Y3FF</td>
<td>0200H to 03FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>Y400 to Y7FF</td>
<td>0400H to 07FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Internal relay</strong></td>
<td>M0 to M2047</td>
<td>0000H to 07FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>M2048 to M8191</td>
<td>0800H to 1FFF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>M9000 to M9255</td>
<td>2328H to 2427H</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Annunciator</strong></td>
<td>F0 to F255</td>
<td>0000H to 00FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>F256 to F2047</td>
<td>0100H to 07FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Link relay</strong></td>
<td>B0 to B3FF</td>
<td>0000H to 03FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>B400 to BFFF</td>
<td>0400H to 0FFF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Timer</strong></td>
<td>T0 to T255</td>
<td>0000H to 00FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>T256 to T2047</td>
<td>0100H to 07FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Contact</strong></td>
<td>T0 to T255</td>
<td>0000H to 00FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>T256 to T2047</td>
<td>0100H to 07FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Coil</strong></td>
<td>T0 to T255</td>
<td>0000H to 00FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>T256 to T2047</td>
<td>0100H to 07FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Counter</strong></td>
<td>C0 to C255</td>
<td>0000H to 00FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>C256 to C1023</td>
<td>0100H to 03FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Contact</strong></td>
<td>C0 to C255</td>
<td>0000H to 00FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>C256 to C1023</td>
<td>0100H to 03FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Coil</strong></td>
<td>C0 to C255</td>
<td>0000H to 00FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>C256 to C1023</td>
<td>0100H to 03FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Data register</strong></td>
<td>D0 to D1023</td>
<td>0000H to 03FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>D1024 to D6143</td>
<td>0400H to 17FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>D9000 to D9255</td>
<td>2328H to 2427H</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>Link register</strong></td>
<td>W0 to W3FF</td>
<td>0000H to 03FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>W400 to WFFF</td>
<td>0400H to 0FFF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td><strong>File register</strong></td>
<td>R0 to R4095</td>
<td>0000H to 0FFF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>R4096 to R8191</td>
<td>1000H to 1FFF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
</tbody>
</table>

### Restriction

- Do not write data to the devices which cannot be written in the range of the special relays (M9000 to M9255) and special registers (D9000 to D9255). For details on the special relays and special registers, refer to manual of ACPU to be accessed.
- For L and S, perform accessing by specifying ‘M’ (For example, to access L100, specify M100.)
### List of devices (AnUCPU, QnACPU)

Specify the device within the range of AnACPU.

- Page 391 Considerations when reading/writing data to module other than ACPU module

**Accessible, ×: Not accessible, ---: No device**

<table>
<thead>
<tr>
<th>Device</th>
<th>Device range</th>
<th>Device number</th>
<th>A2US A2U</th>
<th>A2US-S1 A2USH-S1 A2U-S1</th>
<th>A3U A4U</th>
<th>Q2A Q2AS</th>
<th>Q2A-S1 Q2AS-S1 Q2ASH-S1</th>
<th>Q3A Q3A-Q4A Q4AR</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>X0 to X1FF</td>
<td>0000H to 01FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>X200 to X3FF</td>
<td>0200H to 03FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>X400 to X7FF</td>
<td>0400H to 07FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Y0 to Y1FF</td>
<td>0000H to 01FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Y200 to Y3FF</td>
<td>0200H to 03FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Y400 to Y7FF</td>
<td>0400H to 07FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Internal relay (including latch relay and step relay)</td>
<td>M0 to M8191</td>
<td>0000H to 1FFFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>M9000 to M9255</td>
<td>2328H to 2427H</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Annunciator</td>
<td>F0 to F2047</td>
<td>0000H to 07FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Link relay</td>
<td>B0 to BFFF</td>
<td>0000H to 0FFFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Timer</td>
<td>Current value</td>
<td>T0 to T2047</td>
<td>0000H to 07FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Contact</td>
<td>T0 to T2047</td>
<td>0000H to 07FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Coil</td>
<td>T0 to T2047</td>
<td>0000H to 07FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Counter</td>
<td>Current value</td>
<td>C0 to C1023</td>
<td>0000H to 03FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Contact</td>
<td>C0 to C1023</td>
<td>0000H to 03FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Coil</td>
<td>C0 to C1023</td>
<td>0000H to 03FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Data register</td>
<td>D0 to D6143</td>
<td>0000H to 17FFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>D9000 to D9255</td>
<td>2328H to 2427H</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Link register</td>
<td>W0 to WFFF</td>
<td>0000H to 0FFFH</td>
<td>○</td>
<td>○</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>File register</td>
<td>R0 to R8191</td>
<td>0000H to 1FFFH</td>
<td>○</td>
<td>×</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Restriction**

- Do not write data to the devices which cannot be written in the range of the special relays (M9000 to M9255) and special registers (D9000 to D9255). For details on the special relays and special registers, refer to the programming manual of ACPU.
- For L and S, perform accessing by specifying 'M' (For example, to access L100, specify M100.)
### Device list (QCPU, LCPU, safety CPU)
Specify the device within the range of AnACPU.

Considerations when reading/writing data to module other than ACPU module:
- ○: Accessible, ×: Not accessible, —: No device

<table>
<thead>
<tr>
<th>Device</th>
<th>Device range</th>
<th>Device number</th>
<th>Basic model QCPU Safety CPU</th>
<th>QCPU other than left LCPU</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input</td>
<td>X0 to X7FF</td>
<td>0000H to 07FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td>Output</td>
<td>Y0 to Y7FF</td>
<td>0000H to 07FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td>Internal relay</td>
<td>M0 to M8191</td>
<td>0000H to 1FFFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td></td>
<td>M9000 to M9255 (SM1000 to SM1255)</td>
<td>2328H to 2427H</td>
<td>—</td>
<td>○</td>
</tr>
<tr>
<td>Annunciator</td>
<td>F0 to F1023</td>
<td>0000H to 03FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td></td>
<td>F1024 to F2047</td>
<td>0400H to 07FFH</td>
<td>—</td>
<td>○</td>
</tr>
<tr>
<td>Link relay</td>
<td>B0 to B7FF</td>
<td>0000H to 07FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B800 to BFFF</td>
<td>0800H to 0FFFH</td>
<td>—</td>
<td>○</td>
</tr>
<tr>
<td>Timer</td>
<td>T0 to T511</td>
<td>0000H to 01FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td></td>
<td>T512 to T2047</td>
<td>0200H to 07FFH</td>
<td>—</td>
<td>○</td>
</tr>
<tr>
<td>Contact</td>
<td>T0 to T511</td>
<td>0000H to 01FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td></td>
<td>T512 to T2047</td>
<td>0200H to 07FFH</td>
<td>—</td>
<td>○</td>
</tr>
<tr>
<td>Coil</td>
<td>T0 to T511</td>
<td>0000H to 01FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td></td>
<td>T512 to T2047</td>
<td>0200H to 07FFH</td>
<td>—</td>
<td>○</td>
</tr>
<tr>
<td>Counter</td>
<td>C0 to C511</td>
<td>0000H to 01FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C512 to C1023</td>
<td>0200H to 03FFH</td>
<td>—</td>
<td>○</td>
</tr>
<tr>
<td>Contact</td>
<td>C0 to C511</td>
<td>0000H to 01FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C512 to C1023</td>
<td>0200H to 03FFH</td>
<td>—</td>
<td>○</td>
</tr>
<tr>
<td>Coil</td>
<td>C0 to C511</td>
<td>0000H to 01FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td></td>
<td>C512 to C1023</td>
<td>0200H to 03FFH</td>
<td>—</td>
<td>○</td>
</tr>
<tr>
<td>Data register</td>
<td>D0 to D6143</td>
<td>0000H to 17FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td></td>
<td>D9000 to D9255 (SD1000 to SD1255)</td>
<td>2328H to 2427H</td>
<td>—</td>
<td>○</td>
</tr>
<tr>
<td>Link register</td>
<td>W0 to W7FF</td>
<td>0000H to 07FFH</td>
<td>○</td>
<td></td>
</tr>
<tr>
<td></td>
<td>W800 to WFFF</td>
<td>0800H to 0FFFH</td>
<td>—</td>
<td>○</td>
</tr>
<tr>
<td>File register</td>
<td>R0 or more</td>
<td>0000H or more</td>
<td>×</td>
<td></td>
</tr>
</tbody>
</table>
Number of device points

Specify the number of device points to be read or written.
Specify the number of device points in one command within the device points that can be processed in one communication.

Page 459 Number of Processing per One Communication

Specify '00' for 256 points.

Data communication in ASCII code

Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.
Use capitalized code for alphabetical letter.

Data communication in binary code

Send 1-byte numerical value.

Ex.

5 points, 20 points, 256 points

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 points</td>
<td>05</td>
<td>00</td>
</tr>
<tr>
<td></td>
<td>305 350</td>
<td></td>
</tr>
<tr>
<td>20 points</td>
<td>14</td>
<td></td>
</tr>
<tr>
<td></td>
<td>311 340</td>
<td></td>
</tr>
<tr>
<td>256 points</td>
<td>00</td>
<td></td>
</tr>
<tr>
<td></td>
<td>300 300</td>
<td></td>
</tr>
</tbody>
</table>

Read data, write data

The read data is stored for reading, and the data to be written is stored for writing. The data order differs between bit units or word units.
Batch read in bit units (command: 00)

Read bit devices (X, Y, M, etc.) in 1-point units.

Message format

The following shows the message format of the request data and response data of the command.
Specify the command type by subheader. (Page 386 Subheader)

■Request data

<table>
<thead>
<tr>
<th>Head device</th>
<th>Number of device points</th>
<th>Fixed value</th>
</tr>
</thead>
</table>

■Response data

The data for the number of device points are stored.
(Page 396 Read data, write data)

For ASCII code, when the number of device points are specified in an odd number, one byte of dummy data (30H) will be added to the response data. For example, if a data for three points are read, data for four points is returned. The last byte will be a dummy data.

Data specified by request data

■Head device

Specify the head device number of bit devices to be read. (Page 391 Device codes and device numbers)

■Number of device points

Specify the number of the bit device points to be read.
Specify '00H' when the number of device points is to 256 points. (Page 396 Number of device points)

■Fixed value

Fixed to '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>00</td>
<td>00h</td>
</tr>
</tbody>
</table>
Communication example

Read the bit devices in the CPU module with E71 mounted under the following conditions.
- Head device: M100
- Number of device points: 12 points

Data communication in ASCII code
(Request data)

Head device | Number of device points
---|---
4 D 2 0 0 0 0 0 0 0 6 4 | 0 C 0 0

(Data communication in ASCII code
(Response data)

Data for the number of specified device points

1 0 1 0 1 0 1 0 1 0 1 0
(M100) to (M111)

Data communication in binary code
(Request data)

Head device | Number of device points
---|---
64 0 00 00 20 40 0 C 00

(Data communication in binary code
(Response data)

Data for the number of specified device points

1 0 1 0 1 0 1 0 1 0 1 0
(M100) to (M111)
### Batch read in word units (command: 01)

Reads bit devices (X, Y, M, etc.) in 16-point units.
Reads word devices (D, T, C, etc.) in 1-point units

#### Message format

The following shows the message format of the request data and response data of the command.

<table>
<thead>
<tr>
<th>Request data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Head device</td>
</tr>
</tbody>
</table>

| Response data |

The data for the number of device points are stored.
The order of data differs depending on the ASCII code or binary code. (Page 396 Read data, write data)

#### Data specified by request data

- **Head device**
  Specify the head device of the device to be read. (Page 391 Device codes and device numbers)

- **Number of device points**
  Specify the device number to be read.
  Specify '00H' when the number of device points is to 256 points. (Page 396 Number of device points)
  When specifying bit devices, set the head device No. in multiples of 16 (0, 16, ... in decimal notation).

- **Fixed value**
  Fixed to '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>00H</td>
</tr>
</tbody>
</table>
**Communication example**

Read the bit devices in the CPU module with E71 mounted under the following conditions.

- Head device: Y40
- Number of device points: 32 points (2 bytes)

**Data communication in ASCII code**

(Request data)

<table>
<thead>
<tr>
<th>Head device</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>Y40</td>
<td>32 points</td>
</tr>
</tbody>
</table>

(Response data)

- Head device
- Number of device points

**Data communication in binary code**

(Request data)

<table>
<thead>
<tr>
<th>Head device</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>Y40</td>
<td>32 points</td>
</tr>
</tbody>
</table>

(Response data)
Batch write in bit units (command: 02)

Write bit devices (X, Y, M, etc.) in 1-point units.

**Message format**
The following shows the message format of the request data and response data of the command.

- **Request data**
  
<table>
<thead>
<tr>
<th>Head device</th>
<th>Number of device points</th>
<th>Fixed value</th>
<th>Write data</th>
</tr>
</thead>
</table>

- **Response data**
  There is no response data for this command.

**Data specified by request data**

- **Head device**
  Specify the head device of the bit device to be written. (Page 391 Device codes and device numbers)

- **Fixed value**
  Fixed to '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>00</td>
<td>00h</td>
</tr>
</tbody>
</table>

- **Number of device points**
  Specify the bit device points to be written.
  Specify '00H' when the number of device points is to 256 points. (Page 396 Number of device points)

- **Write data**
  Stored data for the number of device points to be written.
  - 0 (30H): OFF
  - 1 (31H): ON
Communication example

Write the bit devices in the CPU module with E71 mounted under the following conditions.

- Head device: M50
- Number of device points: 12 points

■Data communication in ASCII code
(Request data)

<table>
<thead>
<tr>
<th>Head device</th>
<th>Number of device points</th>
<th>Data for the number of specified device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>4 4 2 0 0 0 0 0 0 3 2 0 3 0 0 1 1</td>
<td>0 1 1 0 0 0 0 0 0 0</td>
<td></td>
</tr>
</tbody>
</table>

(M50) to (M61)

■Data communication in binary code
(Request data)

<table>
<thead>
<tr>
<th>Head device</th>
<th>Data for the number of specified device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>32h 00h 00h 00h 20h 40h</td>
<td>01h 01h 01h 00h 00h 01h</td>
</tr>
</tbody>
</table>

(M50) to (M61)
Batch write in word units (command: 03)

Write bit devices (X, Y, M, etc.) in 16-point units.
Write word devices (D, T, C, etc.) in 1-point units.

Message format

The following shows the message format of the request data and response data of the command.

■ Request data

<table>
<thead>
<tr>
<th>Head device</th>
<th>Number of device points</th>
<th>Fixed value</th>
<th>Write data</th>
</tr>
</thead>
</table>

■ Response data

There is no response data for this command.

Data specified by request data

■ Head device

Specify the head device of the device to be written.

■ Number of device points

Specify the number of device points to be written.

Specify '00H' when the number of device points is to 256 points.

When specifying bit devices, set the head device No. in multiples of 16 (0, 16, ... in decimal notation).

■ Fixed value

Fixed to '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 30H</td>
<td>00H</td>
</tr>
</tbody>
</table>

■ Write data

Stored data for the number of device points to be written.

The order of data differs depending on the ASCII code or binary code. (Page 396 Read data, write data)

Communication example

Write the devices in the CPU module with E71 mounted under the following conditions.

• Head device: D100
• Number of device points: 3 points

■ Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Head device</th>
<th>Number of device points</th>
<th>Data for the number of specified device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>4 4 2 0 0 0 0 0 0 0 6 4 3 0 0</td>
<td>1 2 3 4 9 8 7 6 0 1 0 9</td>
<td></td>
</tr>
</tbody>
</table>

■ Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Head device</th>
<th>Number of device points</th>
<th>Data for the number of specified device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>64 00H 00H 00H 20H 44H</td>
<td>00H 13H 22H 36H</td>
<td></td>
</tr>
</tbody>
</table>
Test in bit units (random write) (command: 04)

Specify the devices and device numbers of bit devices (X, Y, M, etc.) in 1-point units randomly, and set/reset them.

Message format

The following shows the message format of the request data and response data of the command.

■Request data

There is no request data for this command.

<table>
<thead>
<tr>
<th>Number of device points (n points)</th>
<th>Fixed value</th>
<th>Specified device (first point)</th>
<th>ON/OFF specification (first point)</th>
<th>...</th>
<th>Specified device (nth point)</th>
<th>ON/OFF specification (nth point)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

■Response data

There is no response data for this command.

Data specified by request data

■Number of device points

Specify the number of points of the bit device to be set/reset. (Page 396 Number of device points)

■Fixed value

Fixed to '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>00</td>
</tr>
</tbody>
</table>

■Specified device

Specify the bit devices to be set/reset. (Page 391 Device codes and device numbers)

■ON/OFF specification

Specify set/reset.

<table>
<thead>
<tr>
<th>Processing</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reset</td>
<td>0 0 0</td>
<td>00</td>
</tr>
<tr>
<td>Set</td>
<td>0 1 0</td>
<td>01</td>
</tr>
</tbody>
</table>
Communication example

Set/reset the bit devices in CPU module with E71 mounted under the following conditions.

- Number of device points: 3 points
- Data for the number of specified device points: Specify Y94 to ON, M60 to OFF, and B26 to ON.

### Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>Specified device (first point)</th>
<th>ON/OFF specification (first point)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 3</td>
<td>0 0</td>
<td>5 9 2 0 0 0 0 0 0 9 4 0 1</td>
</tr>
</tbody>
</table>

(Y94)

<table>
<thead>
<tr>
<th>Specified device (second point)</th>
<th>ON/OFF specification (second point)</th>
</tr>
</thead>
<tbody>
<tr>
<td>4 D 2 0 0 0 0 0 0 0 0 3 C</td>
<td>0 0</td>
</tr>
</tbody>
</table>

(M60)

<table>
<thead>
<tr>
<th>Specified device (third point)</th>
<th>ON/OFF specification (third point)</th>
</tr>
</thead>
<tbody>
<tr>
<td>4 2 2 0 0 0 0 0 0 2 6 0 1</td>
<td></td>
</tr>
</tbody>
</table>

(B26)

### Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>Specified device (first point)</th>
<th>ON/OFF specification (first point)</th>
<th>Specified device (second point)</th>
<th>ON/OFF specification (second point)</th>
<th>Specified device (third point)</th>
<th>ON/OFF specification (third point)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0</td>
<td>94 00 00 00 00 00 00 00 00 00</td>
<td>0 1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Test in word units (random write) (command: 05)

Specify the devices and device numbers of bit devices (X, Y, M, etc.) in 16-point units randomly, and set/reset them.
Specify the devices and device numbers of word devices (D, T, C, etc.) in 1-point units randomly, and write them.

Message format

The following shows the message format of the request data and response data of the command.

<table>
<thead>
<tr>
<th>Request data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of device points (n points)</td>
</tr>
</tbody>
</table>

Response data

There is no response data for this command.

Data specified by request data

Number of device points

Specify the number of device points to be set/reset. (Page 396 Number of device points)
When specifying bit devices, set the head device No. in multiples of 16 (0, 16, ... in decimal notation).

Fixed value

Fixed to '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>00 30h, 30h</td>
<td>00h</td>
</tr>
</tbody>
</table>

Specified device

Specify the device to be set/reset. (Page 391 Device codes and device numbers)

ON/OFF specification

Store the data to be written.
Communication example

Set/reset the devices in the CPU module with E71 mounted under the following condition.

- Number of device points: 3 points
- Data for the number of specified device points: Specify Y80 to 8F to ON/OFF, W26 to '1234H', and the current value of C18 to '50H'.

**Data communication in ASCII code**
(Request data)

```
<table>
<thead>
<tr>
<th>Number of device points</th>
<th>Specified device (first point)</th>
<th>ON/OFF specification (first point)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>3</td>
<td>0 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>5 9 2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 0 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 0 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 0 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 0 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>7 8 2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 9</td>
</tr>
</tbody>
</table>
```

(Y80)

(Y8F) to (Y88)

(Y87) to (Y80)

**Data communication in binary code**
(Request data)

```
<table>
<thead>
<tr>
<th>Number of device points</th>
<th>Specified device (first point)</th>
<th>ON/OFF specification (first point)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>3</td>
<td>0 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>5 7 2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 0 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 0 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 0 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 0 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 0 0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 6</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 2 3 4</td>
</tr>
</tbody>
</table>
```

(W26)

(W87) to (Y80)

(W8F) to (Y88)

(Y87) to (Y80)

(Y88) to (Y88)
Monitor device memory (command: 06, 07, 08, 09)

The ON/OFF status or contents of devices in the CPU module can be monitored from an external device by registering the devices and device numbers to be monitored to E71 in advance and executing the monitor command from the external device.

When reading device memory in batch, the read device numbers will be consecutive. However, when reading them using the monitor command, the devices can be monitored randomly by specifying the arbitrary devices and device numbers.

For monitoring the extended file register, refer to the following section.

Page 419 Monitor extended file registers (command: 1A, 1B)

Procedure for monitoring

1. Register the devices to be monitored from the external device to E71 by registering monitor data.
2. Execute the read processing by a monitor command.
3. Process the data.
4. If do not change the devices to be monitored, return to step 2, and repeat the process.

- When monitoring data as the procedure shown above, the monitor data registration is required. If monitoring data without registering the data, a protocol error occurs.
- The content of registered monitor data is deleted when turning the power OFF or the resetting the CPU module.
- There are three types of commands for monitor data registration; expansion file register, device memory bit unit, and device memory word unit. The recently registered one command out of three types of commands can be registered to E71.
- When registering device memory of the CPU module as a monitoring data from more than one external devices on the same station, the recently registered device memory will be available since the registration data is overwritten.
**Register monitor data(command: 06, 07)**

Registers bit devices (X, Y, M, etc.) to be monitored in 1-point units. (Command: 06)
Registers bit devices (X, Y, M, etc.) to be monitored in 16-point units. (Command: 07)
Registers word devices (D, T, C, etc.) to be monitored in 1-point units. (Command: 07)

**Request data**

<table>
<thead>
<tr>
<th>Number of device points (n points)</th>
<th>Fixed value</th>
<th>Device number (first point)</th>
<th>...</th>
<th>Device number (nth point)</th>
</tr>
</thead>
</table>

- Number of device points: Specify the number of devices to be registered as a monitoring data. (Page 396 Number of device points)
- Fixed value: ‘0’.

**Response data**

There is no response data for this command.

**Communication example**

Register devices as a monitoring data in the CPU module with E71 mounted under the following conditions.

- Number of device points: 3 points
- Device number: Y46, M12, B2C

(Request data)

(ASCII code)

```
0 3
30x, 33x

5 9 2 0 0 0 0 0 0 0 0 4 6
35x, 39x, 32x, 30x, 30x, 30x, 30x, 30x, 30x, 30x, 34x, 36x
```

(Device code)

```
4 D 2 0 0 0 0 0 0 0 0 0 0 2 C
34x, 32x, 32x, 32x, 30x, 30x, 30x, 30x, 30x, 30x, 30x, 30x, 30x, 30x, 30x, 32x, 32x
```

(Binary code)

```
03x 00x 46x 00x 00x 00x 00x 00x 00x 00x 00x 00x 00x 00x 2C
```
Monitor in bit units (command: 08)

Monitor the bit devices for which monitor data is registered.

■ Request data
There is no request data for this command.

■ Response data
The value of the read device is stored in byte units.
The order of data differs depending on the ASCII code or binary code.

If the number of device points registered to be monitored is an odd number, dummy data 0 (30H) is added when the monitoring is executed. For example, if the number of device points registered to be monitored is three points, data for four points is returned. The last byte will be a dummy data.

■ Communication example
Monitor the devices registered with monitor data registration in the CPU module with E71 mounted under the following conditions.
- Number of registered device points: 3 points
- Number of registered device numbers: Y46, M12, B2C

(Response data)
(ASCII code)

(Response data)
(Binary code)
Monitor in word units (command: 09)

Monitor word devices and bit devices (16 point units) which are registered as a monitor data.

■ Request data
There is no request data for this command.

■ Response data
The value of the read device is stored in word units.
The order of data differs depending on the ASCII code or binary code.

■ Communication example
Monitor the devices registered with monitor data registration in the CPU module with E71 mounted under the following conditions.

- Number of registered device numbers: Y50 to 5F, D38, W1E

(Response data)

(ASCII code)

<table>
<thead>
<tr>
<th>Subheader</th>
<th>End code</th>
<th>Data for the number of specified device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>8 9 0 0</td>
<td>E 5 6 D 1 2 3 4 5 6 7 8</td>
<td>38h 39h 3Ah 3Bh 3Ch 3Dh 3Eh 3Fh</td>
</tr>
</tbody>
</table>

(Y5F) to (Y58)  (Y57) to (Y50)

(Binary code)

Subheader | End code | Data for the number of specified device points
-----------|----------|-----------------------------------------------|
89h 00h   | D38h     | 0110 0110 0110 0110 |

(Y57) to (Y50)  (Y5F) to (Y58)
18.5 Read and Write Extended File Register

The extended file register is a memory area that stores required data and operation result for various data processing and AnACPU and AnUSCPU extended file register dedicated instructions by using the software package for extended file register 'SWOGHP-UTLPC-FN1' or 'SW0SRX-FNUP' (hereinafter abbreviated to UTLP-FN1 and FNUP). The extended file register uses free area of user memory area in CPU module as a file register.

This section explains the commands for reading and writing extended file register.

For the message formats other than request data and response data, refer to the following sections.

Page 385 Message Format, Page 385 Detail of Setting Data

Restriction

For the considerations when reading and writing extended file register, refer to the following section.

Page 365 Considerations for reading and writing extended file register

For the specification method of the extended file register, refer to the following section.

Page 366 Specification method for extended file register

Data to be specified in command

<table>
<thead>
<tr>
<th>Block number</th>
</tr>
</thead>
<tbody>
<tr>
<td>Specify the block number of the extended file register.</td>
</tr>
</tbody>
</table>

- **Data communication in ASCII code**
  Convert the numerical value to 4-digit ASCII code (hexadecimal) and send it from upper digits.

- **Data communication in binary code**
  Send 2-byte numerical value.

<table>
<thead>
<tr>
<th>Device number</th>
</tr>
</thead>
<tbody>
<tr>
<td>Specify the device number of the extended file register.</td>
</tr>
</tbody>
</table>

When reading or writing (command: 3B, 3C) extended file register directly, refer to the following section.

Page 367 Device number (address) specification using AnA/AnUCPU common commands

- **Data communication in ASCII code**
  Convert the numerical value to 12-digit ASCII code (hexadecimal), and send it from the upper digits.

- **Data communication in binary code**
  Send 6-byte numerical value.
Batch read (command: 17)

Read extended file register (R) in 1-point units.

**Message format**

The following shows the message format of the request data and response data of the command.

- **Request data**
  (ASCII code)

<table>
<thead>
<tr>
<th>Block No.</th>
<th>Device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>0 0</td>
</tr>
</tbody>
</table>

  (Binary code)

<table>
<thead>
<tr>
<th>Device number</th>
<th>Block No.</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>00H</td>
</tr>
</tbody>
</table>

- **Response data**

  The data for the number of device points are stored.

  The order of data differs depending on the ASCII code or binary code. (Page 396 Read data, write data)

**Data specified by request data**

- **Device number**
  Specify the head device of the extended file register to be read. (Page 412 Device number)

- **Block number**
  Specify the block number of the extended file register to be read. (Page 412 Block number)

- **Number of device points**
  Specify the points of extended file register to be read.
  Specify '00H' when the number of device points is 256 points. (Page 396 Number of device points)
Communication example

Read the extended file registers in the CPU module with E71 mounted under the following conditions.

- Block number: No.2
- Device number: R70
- Number of device points: 3 points

■ Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Block No.</th>
<th>Device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 2</td>
<td>5 2 2 0</td>
<td>0 0 0 0 0 0 0 0 4 6</td>
</tr>
<tr>
<td>30h 30h</td>
<td>32h 32h</td>
<td>30h 30h 30h 30h 30h</td>
</tr>
</tbody>
</table>

(Response data)

Data for the number of specified device points

<table>
<thead>
<tr>
<th>1 2 3 4</th>
<th>8 7 6 5</th>
<th>0 1 3 F</th>
</tr>
</thead>
<tbody>
<tr>
<td>31h 32h</td>
<td>33h 34h</td>
<td>35h 36h</td>
</tr>
<tr>
<td>(R70 in No.2)</td>
<td>(R71 in No.2)</td>
<td>(R72 in No.2)</td>
</tr>
</tbody>
</table>

■ Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>Block No.</td>
</tr>
<tr>
<td>Device number</td>
</tr>
<tr>
<td>46h 00h 00h 00h 20h 52h</td>
</tr>
<tr>
<td>02h 00h 03h 00h</td>
</tr>
</tbody>
</table>

(Response data)

Data for the number of specified device points

<table>
<thead>
<tr>
<th>34h 12h</th>
</tr>
</thead>
<tbody>
<tr>
<td>65h 83h</td>
</tr>
<tr>
<td>3fn 01n</td>
</tr>
<tr>
<td>(R70 in No.2)</td>
</tr>
</tbody>
</table>
Batch write (command: 18)

Write to extended file register (R) in 1-point units.

Message format

The following shows the message format of the request data and response data of the command.

■ Request data

(ASCII code)

<table>
<thead>
<tr>
<th>Block No.</th>
<th>Device number</th>
<th>Number of device points</th>
<th>0</th>
<th>0</th>
<th>Data for the number of specified device points</th>
</tr>
</thead>
</table>

(Binary code)

| Device number | Block No. | Number of device points | 00H | Data for the number of specified device points |

■ Response data

There is no response data for this command.

Data specified by request data

■ Device number

Specify the head device number of the extended file register to be written. (Page 412 Device number)

■ Block number

Specify the block number of the extended file register to be written. (Page 412 Block number)

■ Number of device points

Specify the number of the data points to be write.
Specify '00H' when the number of device points is to 256 points. (Page 396 Number of device points)

■ Data for the number of specified device points

Store the data to be written to the extended file registers.
**Communication example**

Write data to extended file registers in the CPU module with E71 mounted under the following conditions.

- Block number: No.3
- Device number: R100
- Number of device points: 3 points

### Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Block No.</th>
<th>Device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 3</td>
<td>5 2 2 0</td>
<td>0 0 6 4</td>
</tr>
<tr>
<td>30h, 30h, 33h</td>
<td>35h, 32h, 32h</td>
<td>30h, 30h, 30h</td>
</tr>
</tbody>
</table>

Data for the number of specified device points

<table>
<thead>
<tr>
<th>0 1 0 9</th>
<th>9 8 7 6</th>
<th>1 2 3 4</th>
</tr>
</thead>
<tbody>
<tr>
<td>30h, 31h, 30h</td>
<td>33h, 37h</td>
<td>36h, 33h</td>
</tr>
</tbody>
</table>

(R100 in No.3) (R101 in No.3) (R102 in No.3)

### Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Device number</th>
<th>Block No.</th>
<th>Number of device points</th>
<th>Data for the number of specified device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>64h, 00h, 00h, 00h, 20h, 52h, 03h, 00h</td>
<td>0 0 0 9</td>
<td>01h, 01h</td>
<td>07h, 98h, 34h, 12h</td>
</tr>
</tbody>
</table>

(R100 in No.3) (R102 in No.3) (R101 in No.3)
Test (random write) (command: 19)

Specify the block numbers and device numbers in 1-point units and write them randomly to extended file register (R).

Message format

The following shows the message format of the request data and response data of the command.

■ Request data
(ASCII code)

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>0 0 30i 30i</th>
<th>Block No.</th>
<th>Device number</th>
<th>Write data</th>
</tr>
</thead>
</table>

(Binary code)

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>00i</th>
<th>Device number</th>
<th>Block No.</th>
<th>Write data</th>
</tr>
</thead>
</table>

■ Response data

There is no response data for this command.

Data specified by request data

■ Number of device points
Specify the number of points of the data to be written. (Page 396 Number of device points)

■ Device number
Specify the head device of the extended file register to be written. (Page 412 Device number)

■ Block number
Specify the block number of the extended file register to be written. (Page 412 Block number)

■ Write data

Store the data to be written to the extended file registers.
**Communication example**

Write data to extended file registers in the CPU module with E71 mounted under the following conditions.

- Data to be written: R26 in block number 2 and R19 in block number 3
- Number of device points: 2 points

### Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>Block No.</th>
<th>Device number</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2</td>
<td>0 0</td>
<td>0 0 0 2</td>
<td>5 2 2 0</td>
</tr>
<tr>
<td>0 0 0 2</td>
<td>30 30 30 30</td>
<td>35 35 35 35</td>
<td>31 31 31 31</td>
</tr>
<tr>
<td>5 2 2 0 0 0 0 0 0 0 1</td>
<td>31 31 31 31</td>
<td>31 31 31 31</td>
<td>31 31 31 31</td>
</tr>
<tr>
<td>0 0 0 3</td>
<td>30 30 30 30</td>
<td>35 35 35 35</td>
<td>31 31 31 31</td>
</tr>
<tr>
<td>0 0 0 3 5 2 2 0 0 0 0 0 0 0 0 0 1 3</td>
<td>0 1 0 9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0 0 0 3</td>
<td>30 30 30 30</td>
<td>35 35 35 35</td>
<td>31 31 31 31</td>
</tr>
</tbody>
</table>

(R26 in block No.2)  
(R19 in block No.3)

### Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>Device number</th>
<th>Block No.</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>02 00</td>
<td>34 20 00 20 52</td>
<td>02 00</td>
<td>34 12</td>
</tr>
<tr>
<td>02 00</td>
<td>13 00 00 20 52</td>
<td>03 00</td>
<td>09 01</td>
</tr>
</tbody>
</table>

(R26 in block No.2)  
(R19 in block No.3)
Monitor extended file registers (command: 1A, 1B)

The contents of extended file registers in the CPU module can be monitored from an external device by registering the block numbers and device numbers to be monitored to E71 in advance and executing the monitor command from the external device.

When reading extended file register in batch, the read device numbers will be consecutive. However, when reading them using the monitor command, the extended file registers can be read randomly by specifying the file registers of arbitrary block numbers and device numbers.

Procedure for monitoring

1. Register block numbers and device numbers of the extended file registers to be monitored to E71 by monitor data registration.
2. Execute read processing by monitoring.
3. Process the data.
4. If do not change the devices to be monitored, return to step 2, and repeat the process.

- When monitoring data as the procedure shown above, the monitor data registration is required. If monitoring data without registering the data, an error occurs (END code: 57H).
- The content of registered monitor data is deleted when turning the power OFF or the resetting the CPU module.
- There are three types of commands for monitor data registration; extended file register, device memory bit unit, and device memory word unit. The recently registered one command out of three types of commands can be registered to E71.
- When registering device memory of the CPU module as a monitoring data from more than one external devices on the same station, the recently registered device memory will be available since the registration data is overwritten.
Register monitor data (command: 1A)

Register device numbers to be monitored in 1-point units.

■ Request data

(ASCII code)

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>Block No.</th>
<th>Device number</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>2</td>
</tr>
</tbody>
</table>

(Binary code)

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>Device number</th>
<th>Block No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>2</td>
</tr>
</tbody>
</table>

- Number of device points: Specify the number of points of the extended file registers to be registered as a monitor data. (Page 396 Number of device points)
- Device number: Specify the extended file registers to be registered as a monitor data. (Page 412 Device number)
- Block number: Specify the block number of the extended file registers to be registered as a monitor data. (Page 412 Block number)

■ Response data

There is no response data for this command.

■ Communication example

Register devices as a monitoring data in the CPU module with E71 mounted under the following conditions.
- Data to be registered: R15 of block number 2 and R28 of block number 3

(Request data)

(ASCII code)

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>Block No.</th>
<th>Device number</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>2</td>
</tr>
</tbody>
</table>

(Binary code)

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>Device number</th>
<th>Block No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>2</td>
</tr>
</tbody>
</table>

(R15 in block No.2)

(R28 in block No.3)
Monitoring (command: 1B)
Monitor the extended file registers registered by monitor data registration.

■ Data specified by request data
There is no request data for this command.

■ Response data
Store the monitoring result.

■ Communication example
Monitor the following extended file registers registered by monitor data registration.
- Monitor data registration: R15 in block number 2 and R28 in block number 3

(Response data)
(ASCII code)

<table>
<thead>
<tr>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>45</td>
<td>35</td>
<td>36</td>
<td>46</td>
</tr>
</tbody>
</table>

(R15 in block No.2)  (R28 in block No.3)

(Binary code)

<table>
<thead>
<tr>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>65</td>
<td>E5</td>
<td>34</td>
<td>12</td>
</tr>
</tbody>
</table>

(R15 in block No.2)  (R28 in block No.3)
Direct read (command: 3B)

Read extended file register in 1-point (1 word) units by specifying the consecutive device numbers of extended file register. This command is a dedicated command for AnACPU. (The command is equivalent to AnA/AnUCPU common commands of 1C protocol.)

**Message format**

The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Device number</th>
<th>Number of device points</th>
<th>Fixed value</th>
</tr>
</thead>
</table>

**Response data**

The data for the number of device points are stored. (Page 396 Read data, write data)

**Data specified by request data**

**Device number**

Specify the start address of the extended file register to be read. (Page 412 Device number)

**Number of device points**

Specify the points of extended file register to be read. Specify '00H' when the number of device points is to 256 points. (Page 396 Number of device points)

**Fixed value**

Fixed to '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>00h</td>
</tr>
</tbody>
</table>
Communication example

Read the extended file registers directly in the CPU module with E71 mounted under the following conditions.

* Block number: No.0
* Device number: R70
* Number of device points: 4 points

Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Block No.</th>
<th>Device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 2</td>
<td>5 2 2 0</td>
<td>0 0 0 0 0 0 4 6</td>
</tr>
<tr>
<td>30h, 30h, 30h, 32h</td>
<td>35h, 32h, 32h, 30h</td>
<td>30h, 30h, 30h, 30h</td>
</tr>
</tbody>
</table>

(Response data)

Data for the number of specified device points

<table>
<thead>
<tr>
<th>1 2 3 4</th>
<th>8 7 6 5</th>
<th>0 1 3 F</th>
<th>0 0 2 0</th>
</tr>
</thead>
<tbody>
<tr>
<td>31h, 32h, 33h, 34h</td>
<td>35h, 37h, 36h, 35h</td>
<td>30h, 31h, 33h, 46h</td>
<td>30h, 30h, 32h, 30h</td>
</tr>
</tbody>
</table>

Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>46h, 00h, 00h, 00h</td>
<td>20h, 52h, 04h, 00h</td>
</tr>
</tbody>
</table>

(Response data)

Data for the number of specified device points

<table>
<thead>
<tr>
<th>34h, 12h</th>
<th>65h, 87h</th>
<th>3Fh, 01h</th>
<th>20h, 00h</th>
</tr>
</thead>
<tbody>
<tr>
<td>(R70 in No.0)</td>
<td>(R72 in No.0)</td>
<td>(R71 in No.0)</td>
<td>(R73 in No.0)</td>
</tr>
</tbody>
</table>
Direct write (command: 3C)

Write extended file register in 1-point (1 word) units by specifying the consecutive device number of extended file register. This command is a dedicated command for AnACPU. (The command is equivalent to AnA/AnUCPU common commands of 1C protocol.)

Message format
The following shows the message format of the request data and response data of the command.

- Request data

<table>
<thead>
<tr>
<th>Device number</th>
<th>Number of device points</th>
<th>Fixed value</th>
<th>Data for the number of specified device points</th>
</tr>
</thead>
</table>

- Response data
There is no response data for this command.

Data specified by request data

- Device number
Specify the start address of the extended file register to be written. (Page 412 Device number)

- Number of device points
Specify the number of extended file registers to be written. (Page 396 Number of device points)
Specify '00H' when the number of device points is to 256 points.

- Fixed value
Fixed to '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>(0)</td>
<td>(00)</td>
</tr>
</tbody>
</table>

- Data for the number of specified device points
Stored data for the number of device points to be written.
### Communication example

Write data to the extended file registers directly in the CPU module with E71 mounted under the following conditions.

- Block number: No.0
- Device number: R100
- Number of device points: 3 points

#### Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Device number</th>
<th>Number of device points</th>
<th>Data for the number of specified device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 2 2 0 0 0 0 0 6 4 0 3 0 0 0 1 0 9 9 8 7 6 1 2 3 4</td>
<td></td>
<td></td>
</tr>
<tr>
<td>35m 32m 32m 30m 30m 30m 30m 30m 30m 30m 30m 30m 30m 30m 31m 30m 39m 39m 39m 39m 39m 39m 39m 39m 39m 39m</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(R100 in No.0) (R101 in No.0) (R102 in No.0)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

#### Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Device number</th>
<th>Number of device points</th>
<th>Data for the number of specified device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>64m 00m 00m 00m 00m 52m 03m 09m 01m 76m 98m 34m 32m</td>
<td></td>
<td></td>
</tr>
<tr>
<td>(R100 in No.0) (R102 in No.0) (R101 in No.0)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

18.6 Read and Write Buffer Memory of Special Function Module

The section explains the commands that read/write data from/to buffer memory of MELSEC-A series special function module. For the message formats other than request data and response data, refer to the following sections.

Page 385 Message Format, Page 385 Detail of Setting Data

This command accesses in byte units.

Data to be specified in command

This section explains the contents and specification methods for data items which are set in each command related to the access to the special function module buffer memory.

Start address

Specify the start address of the buffer memory to be read/written. The value to specify is the same as 1C frame.

Page 378 Special function module No.

Data communication in ASCII code

Convert the numerical value to 6-digit ASCII code (hexadecimal), and send it from the upper digits.

Data communication in binary code

Send 3-byte numerical values from lower byte (L: bits 0 to 7).

Ex.
When the head area address is 1E1H

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 1 E 1</td>
<td>01 31 30 30</td>
</tr>
</tbody>
</table>

Ex.
When the head area address is 1E1H

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>E 1 0 0 0 0</td>
<td>0 0 31 30 30</td>
</tr>
</tbody>
</table>
### Byte length

Specify the byte length of the buffer memory to be read or written.

Specify '00' for 256 bytes.

- **Data communication in ASCII code**
  Convert the numerical value to 2-digit ASCII code (hexadecimal), and send it from the upper digits.

- **Data communication in binary code**
  Send 1-byte numerical value.

**Ex.**
For 5 bytes, 20 bytes, 256 bytes.

<table>
<thead>
<tr>
<th>Number of device points</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>5 bytes</td>
<td>0 5</td>
<td>05</td>
</tr>
<tr>
<td></td>
<td>30h, 35h</td>
<td></td>
</tr>
<tr>
<td>20 bytes</td>
<td>1 4</td>
<td>14h</td>
</tr>
<tr>
<td></td>
<td>31h, 34h</td>
<td></td>
</tr>
<tr>
<td>256 bytes</td>
<td>0 0</td>
<td>00h</td>
</tr>
<tr>
<td></td>
<td>30h, 30h</td>
<td></td>
</tr>
</tbody>
</table>

**Read data, write data**

The read buffer memory value is stored for reading, and the data to be written is stored for writing.

This function reads and writes data in byte units.

**Special function module No.**

Specify the last input/output signal (I/O address) of the special function module. (Specify the upper 2-digit of 3-digit representation.)

The value to specify is the same as 1C frame.

**Accessible modules**

Special function modules that can be accessed buffer memory are the same as 1C frame.
Batch read (command: 0E)

Read the buffer memory of a special function module.

Message format

The following shows the message format of the request data and response data of the command.

■ Request data

<table>
<thead>
<tr>
<th>Start address</th>
<th>Byte length</th>
<th>Special function module No.</th>
<th>Fixed value</th>
</tr>
</thead>
</table>

■ Response data

The data read from buffer memory is stored. (Page 427 Read data, write data)

Data specified by request data

■ Start address

Specify the buffer memory start address to be read. (Page 426 Start address)

■ Byte length

Specify the byte length of buffer memory to be read.
Specify '00H' when the number of device points is to 256 points. (Page 427 Byte length)

■ Special function module No.

Specify the special function module No. of the buffer memory to be read.

■ Fixed value

Fixed to '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>00h</td>
</tr>
</tbody>
</table>
### Communication example

Read the buffer memory of the special function module with E71 mounted in the same station under the following conditions.

- Special function module No.: 13H (buffer memory whose input/output signal is from 120H to 13FH)
- Start address: 7F0H
- Byte length: 4

#### Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Start address</th>
<th>Special function module No.</th>
<th>Byte length</th>
</tr>
</thead>
<tbody>
<tr>
<td>00 00 00 7F00</td>
<td>04 13 00 00</td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>Data read</th>
</tr>
</thead>
<tbody>
<tr>
<td>09 18 20 34</td>
</tr>
</tbody>
</table>

#### Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Head address</th>
<th>Special function module No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>F0 07 00 04 13 00</td>
<td></td>
</tr>
</tbody>
</table>

(Response data)

<table>
<thead>
<tr>
<th>Data read</th>
</tr>
</thead>
<tbody>
<tr>
<td>09 18 20 34</td>
</tr>
</tbody>
</table>
Batch write (command: 0F)

Write data to the buffer memory of a special function module.

**Message format**
The following shows the message format of the request data and response data of the command.

**Request data**

<table>
<thead>
<tr>
<th>Start address</th>
<th>Byte length</th>
<th>Special function module No.</th>
<th>Fixed value</th>
<th>Write data (for the length of specified bytes)</th>
</tr>
</thead>
</table>

**Response data**

There is no response data for this command.

**Data specified by request data**

- **Start address**
  Specify the buffer memory start address to be read. (Page 426 Start address)

- **Byte length**
  Specify the byte length of buffer memory to be read.
  Specify '00H' when the number of device points is to 256 points. (Page 427 Byte length)

- **Special function module No.**
  Specify the special function module No. of the buffer memory to be read.

- **Fixed value**
  Fixed to '0'.

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>00h</td>
</tr>
</tbody>
</table>

- **Write data**
  Store the data to be written in a buffer memory. (Page 427 Read data, write data)
Communication example

Write data to buffer the memory of the special function module with E71 mounted in the same station under the following conditions.

- Special function module No.: 13H (buffer memory whose input/output signal is from 120H to 13FH)
- Start address: 750H
- Byte length: 4

Data communication in ASCII code

(Request data)

<table>
<thead>
<tr>
<th>Start address</th>
<th>Byte length</th>
<th>Special function module No.</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 7 5 0</td>
<td>0 4 1 3 0 0</td>
<td>0 1 2 3 4 5 6 7</td>
<td>30h 30h 30h 30h 37h 35h 30h 30h</td>
</tr>
</tbody>
</table>

Data communication in binary code

(Request data)

<table>
<thead>
<tr>
<th>Start address</th>
<th>Byte length</th>
<th>Special function module No.</th>
<th>Write data</th>
</tr>
</thead>
<tbody>
<tr>
<td>50h 07h 00h</td>
<td>04h 13h 00h</td>
<td>01h 23h 45h 67h</td>
<td>(750h) (751h) (752h) (753h)</td>
</tr>
</tbody>
</table>
Appendix 1  Read/Write by Device Extension Specification

Accesses shown below are available by setting the subcommand in a request data to 008 or 00C0.

- Accessing link direct devices
- Accessing module access devices
- Accessing CPU buffer memory access devices
- Accessing by indexing network No. and the start input/output number
- Accessing by indexing the device number
- Accessing by specifying the device number with the value stored in word device with indirect specification

Device specification method for device extension specification

Replace the device portion in a message format of each command with a message format for extension specification described in this section when the extension is specified.

With commands which can specify more than one device, the devices listed in the following section can be accessed by specifying '0' for "Extension specification", "Extension specification modification", "Direct memory specification".

Page 66 Device code list
However, when 008 or 00C0 is specified by "Subcommand", specify the device in the message format shown in this section. Message formats with extension not specified and message formats with extension specified cannot coexist in the same message.
### Subcommands for device extension specification

Use the following subcommands for extension specification.

<table>
<thead>
<tr>
<th>Item</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>When accessing in word units</td>
<td>0 0 8 0</td>
</tr>
<tr>
<td></td>
<td>When accessing in bit units</td>
<td>0 0 8 1</td>
</tr>
<tr>
<td></td>
<td>When specifying monitor condition</td>
<td>0 0 C 0</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>When accessing in word units</td>
<td>0 0 8 2</td>
</tr>
<tr>
<td></td>
<td>When accessing in bit units</td>
<td>0 0 8 3</td>
</tr>
</tbody>
</table>
Accessing link direct devices

Access link devices of the network modules such as remote input (RX), remote output (RY), and link special relay (SB).

The following device access commands can be used for access.

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Batch read</td>
<td>0401</td>
<td>0080, 0081, 0082, 0083</td>
</tr>
<tr>
<td>Batch write</td>
<td>1401</td>
<td>0080, 0081, 0082, 0083</td>
</tr>
<tr>
<td>Random read</td>
<td>0403</td>
<td>0080, 0082, 00C0</td>
</tr>
<tr>
<td>Random write</td>
<td>1402</td>
<td>0080, 0081, 0082, 0083</td>
</tr>
<tr>
<td>Batch read multiple blocks</td>
<td>0406</td>
<td>0080, 0083</td>
</tr>
<tr>
<td>Batch write multiple blocks</td>
<td>1406</td>
<td>0080, 0082</td>
</tr>
<tr>
<td>Register monitor data</td>
<td>0801</td>
<td>0080, 0082, 00C0</td>
</tr>
</tbody>
</table>

Message format for device extension specification

Data communication in ASCII code

Subcommand type | ASCII code
--- | ---
For MELSEC-Q/L series | ![](image)
For MELSEC iQ-R series | ![](image)

Data communication in binary code

Subcommand type | Binary code
--- | ---
For MELSEC-Q/L series | ![](image)
For MELSEC iQ-R series | ![](image)
Data to be specified

■ Extension specification

Specify the access target network No. in hexadecimal.

- ASCII code: Specify J (4AH) at the head of data. Convert the numerical value to 3-digit ASCII code (hexadecimal), and send it from the upper digits.
- Binary code: Send 2-byte numerical values from the lower byte (L: bits 0 to 7).

Ex.
For network No. 8

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>J 0 0 8</td>
<td>0B 00</td>
</tr>
</tbody>
</table>

■ Device code and device number

Specify the following devices. (Page 63 Devices)

- Link input (X)
- Link output (Y)
- Link relay (B)
- Link special relay (SB)
- Link register (W)
- Link special register (SW)

For the values of device codes, refer to the following section.

Page 66 Device code list

Using the index register of CPU module, the access target network No. can be specified indirectly.

Page 440 Access to index the network No. and start input/output number

Point

Using the index register of CPU module, the access target device number can be specified indirectly.

Page 441 Access to index the device number

Device extension specification example

Access W100 (J1\W100) of network No. 1 by specifying subcommand 0080.

■ Data communication in ASCII code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Extension specification</th>
<th>Device code</th>
<th>Device number</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 8 0</td>
<td>30 30 30 30</td>
<td>0 0 0</td>
<td>0 0 0</td>
</tr>
<tr>
<td>0 0 0 1</td>
<td>44 30 30 30</td>
<td>0 0 0</td>
<td>W</td>
</tr>
<tr>
<td>0 0 0 1</td>
<td>52 2A 30 30</td>
<td>0 0 0 0</td>
<td>0 0 0 0</td>
</tr>
</tbody>
</table>

■ Data communication in binary code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device number</th>
<th>Device code</th>
<th>Extension specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>80 00</td>
<td>00 00</td>
<td>00 00</td>
<td>01 00 00</td>
</tr>
</tbody>
</table>
Accessing module access devices

Access buffer memory of an intelligent function module.

The following device access commands can be used for access.

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Batch read</td>
<td>0401</td>
<td>0080, 0082</td>
</tr>
<tr>
<td>Batch write</td>
<td>1401</td>
<td>0080, 0082</td>
</tr>
<tr>
<td>Random read</td>
<td>0403</td>
<td>0080, 0082, 00C0</td>
</tr>
<tr>
<td>Random write</td>
<td>1402</td>
<td>0080, 0082</td>
</tr>
<tr>
<td>Batch read multiple blocks</td>
<td>0406</td>
<td>0080, 0082</td>
</tr>
<tr>
<td>Batch write multiple blocks</td>
<td>1406</td>
<td>0080, 0082</td>
</tr>
<tr>
<td>Register monitor data</td>
<td>0801</td>
<td>0080, 0082, 00C0</td>
</tr>
</tbody>
</table>

Message format for device extension specification

Data communication in ASCII code

Subcommand type | ASCII code
--- | ---
For MELSEC-Q/L series

<table>
<thead>
<tr>
<th>Extension specification</th>
<th>Device code</th>
<th>Device number</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>U</td>
<td>30h 30h 55h</td>
</tr>
<tr>
<td>0 0</td>
<td>30h 30h 30h</td>
<td></td>
</tr>
<tr>
<td>0 0</td>
<td>30h 30h 30h</td>
<td></td>
</tr>
</tbody>
</table>

For MELSEC iQ-R series

<table>
<thead>
<tr>
<th>Extension specification</th>
<th>Device code</th>
<th>Device number</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0</td>
<td>U</td>
<td>30h 30h 55h</td>
</tr>
<tr>
<td>0 0 0</td>
<td>30h 30h 30h</td>
<td></td>
</tr>
<tr>
<td>0 0 0</td>
<td>30h 30h 30h</td>
<td></td>
</tr>
</tbody>
</table>

Data communication in binary code

Subcommand type | Binary code
--- | ---
For MELSEC-Q/L series

<table>
<thead>
<tr>
<th>Device number</th>
<th>Device code</th>
<th>Extension specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>00h 00h</td>
<td>00h 00h</td>
<td>F8h</td>
</tr>
<tr>
<td>(3 bytes)</td>
<td>(1 byte)</td>
<td></td>
</tr>
</tbody>
</table>

For MELSEC iQ-R series

<table>
<thead>
<tr>
<th>Device number</th>
<th>Device code</th>
<th>Extension specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>00h 00h</td>
<td>00h 00h</td>
<td>F8h</td>
</tr>
<tr>
<td>(4 bytes)</td>
<td>(2 bytes)</td>
<td></td>
</tr>
</tbody>
</table>
Data to be specified

■ Extension specification
Specify the value obtained by dividing the start input/output number of an intelligent function module by 16 in hexadecimal.

- ASCII code: Specify U (55H) at the head of data. Convert the numerical value to 3-digit ASCII code (hexadecimal), and send it from the upper digits.
- Binary code: Send 2-byte numerical values from the lower byte (L: bits 0 to 7).

Ex.
Start input/output number 0010H of a module

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>U 0 0 1</td>
<td>01 00</td>
</tr>
</tbody>
</table>

Point
Indirect specification of the start input/output number can also be performed by using the CPU module index register.
Page 440 Access to index the network No. and start input/output number

■ Device code and device number
Specify the following device. (Page 63 Devices)
- Module access device (G)
For the values of device codes, refer to the following section.
Page 66 Device code list

Point
Using the index register of CPU module, the access target device number can be specified indirectly.
Page 441 Access to index the device number

Device extension specification example
Access the buffer memory (address: 1) of intelligent function module whose start input/output number is 0030H by specifying subcommand 0080.

■ Data communication in ASCII code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Extension specification</th>
<th>Device code</th>
<th>Device number</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 8 0</td>
<td>0 0</td>
<td>U 0 0 3</td>
<td>G *</td>
</tr>
</tbody>
</table>

■ Data communication in binary code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device number</th>
<th>Device code</th>
<th>Extension specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>30H, 00H</td>
<td>00H, 00H, 00H</td>
<td>A8H</td>
<td>00H, 00H, 03H, 00H, F8H</td>
</tr>
</tbody>
</table>
Accessing CPU buffer memory access device

Access the buffer memory of RCPU.

The following device access commands can be used for access.

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Batch read</td>
<td>0401</td>
<td>0082</td>
</tr>
<tr>
<td>Batch write</td>
<td>1401</td>
<td>0082</td>
</tr>
<tr>
<td>Random read</td>
<td>0403</td>
<td>0082</td>
</tr>
<tr>
<td>Random write</td>
<td>1402</td>
<td>0082</td>
</tr>
<tr>
<td>Batch read multiple blocks</td>
<td>0406</td>
<td>0082</td>
</tr>
<tr>
<td>Batch write multiple blocks</td>
<td>1406</td>
<td>0082</td>
</tr>
<tr>
<td>Register monitor data</td>
<td>0801</td>
<td>0082</td>
</tr>
</tbody>
</table>

Message format for device extension specification

Data communication in ASCII code

Subcommand type | ASCII code
---|---
For MELSEC iQ-R series | Extension specification Device code Device number

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Batch read</td>
<td>0401</td>
<td>0082</td>
</tr>
<tr>
<td>Batch write</td>
<td>1401</td>
<td>0082</td>
</tr>
<tr>
<td>Random read</td>
<td>0403</td>
<td>0082</td>
</tr>
<tr>
<td>Random write</td>
<td>1402</td>
<td>0082</td>
</tr>
<tr>
<td>Batch read multiple blocks</td>
<td>0406</td>
<td>0082</td>
</tr>
<tr>
<td>Batch write multiple blocks</td>
<td>1406</td>
<td>0082</td>
</tr>
<tr>
<td>Register monitor data</td>
<td>0801</td>
<td>0082</td>
</tr>
</tbody>
</table>

Data communication in binary code

Subcommand type | Binary code
---|---
For MELSEC iQ-R series | Device number Device code Extension specification

Data to be specified

Extension specification

Specify the start input/output number of CPU module with the upper 3 digits of 4-digit in hexadecimal.

- ASCII code: Specify U (55H) at the head of data. Convert the numerical value to 3-digit ASCII code (hexadecimal), and send it from the upper digits.

- Binary code: Send 2-byte numerical values from the lower byte (L: bits 0 to 7).

The start input/output numbers of CPU modules to be specified are as shown below.

<table>
<thead>
<tr>
<th>CPU number</th>
<th>Start input/output number of CPU module</th>
<th>Value to be specified</th>
</tr>
</thead>
<tbody>
<tr>
<td>CPU No.1</td>
<td>3E00H</td>
<td>3E0H</td>
</tr>
<tr>
<td>CPU No.2</td>
<td>3E10H</td>
<td>3E1H</td>
</tr>
<tr>
<td>CPU No.3</td>
<td>3E20H</td>
<td>3E2H</td>
</tr>
<tr>
<td>CPU No.4</td>
<td>3E30H</td>
<td>3E3H</td>
</tr>
</tbody>
</table>
For CPU No.4 (start input/output number: 3E30H)

<table>
<thead>
<tr>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>U 3 E 3</td>
<td>E3 03</td>
</tr>
</tbody>
</table>

Indirect specification of the start input/output number of the CPU module can also be performed by using the CPU module index register.

***Device code and device number***
Specify the following devices. (Refer to Page 63 Devices)
- CPU buffer memory access device (G)
- CPU buffer memory access device (HG)

For the values of device codes, refer to the following section.

***Device extension specification example***
Access the buffer memory (address: 1) of the CPU No.1 (start input/output number: 03E0H) by specifying the subcommand 0082.

### Data communication in ASCII code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Extension specification</th>
<th>Device code</th>
<th>Device number</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 8 2</td>
<td>U 3 E 0</td>
<td>G</td>
<td>0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0</td>
</tr>
</tbody>
</table>

### Data communication in binary code

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device number</th>
<th>Device code</th>
<th>Extension specification</th>
</tr>
</thead>
</table>
Access for index modification

Index modification is the indirect specification using index registers.

Accesses shown below are available by setting the subcommand in a request data to 0080 or 00C0.

<table>
<thead>
<tr>
<th>Target data</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Network No. or start input/output number</td>
<td>Page 440 Access to index the network No. and start input/output number</td>
</tr>
<tr>
<td>Device number</td>
<td>Page 441 Access to index the device number</td>
</tr>
</tbody>
</table>

The following device access commands can be used for access.

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Random read</td>
<td>0403</td>
<td>0080, 0082, 00C0</td>
</tr>
<tr>
<td>Random write</td>
<td>1402</td>
<td>0080, 0081, 0082, 0083</td>
</tr>
<tr>
<td>Register monitor data</td>
<td>0801</td>
<td>0080, 0082, 00C0</td>
</tr>
</tbody>
</table>

Access to index the network No. and start input/output number

When accessing a link direct device, the access target network No. can be specified by the index register with indirect specification. Also, when accessing a module access device or a CPU buffer memory access device, the access target start input/output number can be specified by the index register with indirect specification.

The access target can be switched with one message, by changing the value of the index register in CPU module programs.

Ex.
The access target can be switched by changing the value of ‘Z0’, when multiple network modules are mounted onto the access target.
### Access to index the device number

When accessing a device, indirect specification of the device number can be performed using index register.

When accessing a device, indirect specification of the device number can be performed using index register.

The access target can be switched with one message, by changing the value of the index register in CPU module programs.

#### Ex
When accessing D4 by specifying D0 and Z0

Specify by the request data.

![Diagram of Device code and Device number](image)

Specify by the program of the CPU module.

![Diagram of Access to D4](image)

Similar to the way of access to D4 by the following program.

```
MOVP K4 Z0
```

#### Ex
When accessing M16 to M31 by specifying M0 and Z0 (Word units)

Specify this in request data.

![Diagram of Device code and Device number](image)

Specify this on the program of the CPU module.

![Diagram of Access to M16 to M31](image)

Similar to the way of access to M16 to M31 by the following program.

```
MOVP K16 Z0
```

```
Message format for device extension specification

Data communication in ASCII code

<table>
<thead>
<tr>
<th>0 0</th>
<th>Extension specification modification</th>
<th>Device code</th>
<th>Device number</th>
<th>Device modification</th>
</tr>
</thead>
</table>

Data communication in binary code

<table>
<thead>
<tr>
<th>000</th>
<th>Device number</th>
<th>Extension specification, Direct memory specification</th>
<th>Device code</th>
<th>Device number</th>
<th>Device code</th>
<th>Extension specification, Direct memory specification</th>
<th>Device number</th>
</tr>
</thead>
</table>

The following shows the correspondence of each data.

Extension specification, device code, and device number

Specify the access target network No. and the offset value of the start input/output number for extension specification. When indexing a network No. and start input/output number by "Extension specification modification", the values specified by "Extension specification" will be the offset value.

When indexing a device number by "Device modification", the values specified by "Device number" will be the offset value.

For the data to be specified for each access device, refer to the following table.

<table>
<thead>
<tr>
<th>Item</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Link direct device</td>
<td>Page 435 Data to be specified</td>
</tr>
<tr>
<td>Module access device</td>
<td>Page 437 Data to be specified</td>
</tr>
<tr>
<td>CPU buffer memory access device</td>
<td>Page 438 Data to be specified</td>
</tr>
</tbody>
</table>

Direct memory specification (only when communicating in binary code)

Specify the type of access device.

<table>
<thead>
<tr>
<th>Item</th>
<th>Value to be specified</th>
</tr>
</thead>
<tbody>
<tr>
<td>Link direct device</td>
<td>F9H</td>
</tr>
<tr>
<td>Module access device</td>
<td>F8H</td>
</tr>
<tr>
<td>CPU buffer memory access device</td>
<td>FAH</td>
</tr>
</tbody>
</table>

Specify '0' when accessing devices other than link direct device, module access device, and CPU buffer memory access device.

Binary code

Specify '0':

```
00 00
```
### Extension specification modification

Specify the index register to be used when indexing the value specified by 'Extension specification'.

<table>
<thead>
<tr>
<th>Access target</th>
<th>Devices to be used</th>
<th>ASCII code</th>
<th>Binary code</th>
<th>Fixed value</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC iQ-R series module</td>
<td>Index register</td>
<td>Specify 'Z' and space with 2-digit ASCII code.</td>
<td>Specify the device number in decimal (2-digit ASCII code). (Specification range: 0 to 24)</td>
<td>40H</td>
</tr>
<tr>
<td>MELSEC iQ-R series module</td>
<td>Long index register</td>
<td>Specify 'LZ' with 2-digit ASCII code.</td>
<td>Specify the device number in decimal (2-digit ASCII code). (Specification range: 0 to 12)</td>
<td>80H</td>
</tr>
<tr>
<td>MELSEC-Q/L series module</td>
<td>Index register</td>
<td>Specify 'Z' with 1-digit ASCII code.</td>
<td>Specify the device number in decimal (2-digit ASCII code). (Specification range: 0 to 15)</td>
<td>40H</td>
</tr>
</tbody>
</table>

### Index register (Z0)

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>5Az, 30z, 30z</td>
<td>00z, 04z</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>5Az, 30z, 30z, 30z</td>
<td>00z, 40z</td>
</tr>
</tbody>
</table>

### Long index register (LZ0)

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC iQ-R series</td>
<td>4Cz, 5Az, 30z, 30z</td>
<td>00z, 08z</td>
</tr>
</tbody>
</table>

When do not perform index modification, specify '0'.

### Device modification

Specify the number of index register when indexing device number. The data to be specified is the same as extension specification modification. (Page 443 Extension specification modification)
Communication example (indexing network No.)

Access W100 (J1Z0\W100) of network No.1 + Z0 by specifying subcommand 0080.

- **Data communication in ASCII code**

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Extension specification</th>
<th>Extension specification modification</th>
<th>Device code</th>
<th>Device number</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 8 0</td>
<td>0 0</td>
<td>J 0 0 1</td>
<td>Z 0 0</td>
<td>W *</td>
</tr>
<tr>
<td>30h, 30h, 38h, 30h</td>
<td>00h, 00h</td>
<td>30h, 30h, 31h, 30h</td>
<td>57h, 2Ah</td>
<td>30h, 30h, 30h, 30h</td>
</tr>
</tbody>
</table>

- **Data communication in binary code**

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device number</th>
<th>Device code</th>
<th>Extension specification</th>
<th>Extension specification modification</th>
<th>Direct memory specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>80h, 00h, 00h</td>
<td>00h, 01h, 00h</td>
<td>84h, 00h, 40h</td>
<td>01h, 00h, 00h</td>
<td>F9h</td>
<td></td>
</tr>
</tbody>
</table>

Device extension specification example (When indexing the device number)

Access D100Z4 by specifying subcommand 0080.

- **Data communication in ASCII code**

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Extension specification</th>
<th>Extension specification modification</th>
<th>Device code</th>
<th>Device number</th>
<th>Device modification</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 8 0</td>
<td>0 0</td>
<td>0 0 0 0</td>
<td>0 0 0</td>
<td>D *</td>
<td></td>
</tr>
<tr>
<td>30h, 30h, 38h, 30h</td>
<td>30h, 30h, 30h</td>
<td>30h, 30h, 30h, 30h</td>
<td>64h, 2Ah</td>
<td>30h, 30h, 30h, 30h, 30h, 30h</td>
<td></td>
</tr>
</tbody>
</table>

- **Data communication in binary code**

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Device modification</th>
<th>Device number</th>
<th>Device code</th>
<th>Extension specification</th>
<th>Extension specification modification</th>
<th>Direct memory specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>80h, 00h, 04h</td>
<td>04h, 40h</td>
<td>64h, 00h, 00h</td>
<td>0Ah</td>
<td>00h, 00h</td>
<td>00h, 00h</td>
<td>00h</td>
</tr>
</tbody>
</table>
Accessing devices for indirect specification

Access the device corresponding to the address stored in the word device (2 points).
Store the address of the access target device in the device for the indirect specification, and represent the data as '@ + device for indirect specification'.

For details on the indirect specification, refer to the following manual.
MELSEC iQ-R CPU Module User's Manual (Application)

The following device access commands can be used for access.

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
</tr>
</thead>
<tbody>
<tr>
<td>Random read</td>
<td>0403</td>
<td>0080, 0082, 00C0</td>
</tr>
<tr>
<td>Random write</td>
<td>1402</td>
<td>0080, 0082</td>
</tr>
<tr>
<td>Register monitor data</td>
<td>0801</td>
<td>0080, 0082, 00C0</td>
</tr>
</tbody>
</table>

Message format for device extension specification

Data communication in ASCII code

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0403 @ 0301</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0403 @ 0301</td>
</tr>
</tbody>
</table>

Data communication in binary code

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>0403 @ 0301</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>0403 @ 0301</td>
</tr>
</tbody>
</table>
Data to be specified

**Device code and device number**
Specify the devices for indirect specification. (Page 63 Devices)
Indirect specification can be used only for word devices.
When indexing a device number by "Device modification", the values specified by "Device number" will be the offset value.
For the values of device codes, refer to the following section.
Page 66 Device code list

**Device modification**
Specify the number of index register when the device number is indirectly specified with index register.

<table>
<thead>
<tr>
<th>Access target</th>
<th>Devices to be used</th>
<th>ASCII code</th>
<th>Device code</th>
<th>Device number</th>
<th>Binary code</th>
<th>Fixed value</th>
</tr>
</thead>
<tbody>
<tr>
<td>MELSEC iQ-R series module</td>
<td>Index register</td>
<td>Specify 'Z' and space with 2-digit ASCII code.</td>
<td>Specify the device number in decimal (2-digit ASCII code).</td>
<td>Specify in hexadecimal. (Specification range: 00H to 18H)</td>
<td></td>
<td>48H</td>
</tr>
<tr>
<td></td>
<td>Long index register</td>
<td>Specify 'LZ' with 2-digit ASCII code.</td>
<td>Specify the device number in decimal (2-digit ASCII code). (Specification range: 0 to 12)</td>
<td>Specify in hexadecimal. (Specification range: 00H to 0CH)</td>
<td></td>
<td>88H</td>
</tr>
<tr>
<td>MELSEC-Q/L series module</td>
<td>Index register</td>
<td>Specify 'Z' with 1-digit ASCII code.</td>
<td>Specify the device number in decimal (2-digit ASCII code). (Specification range: 0 to 15)</td>
<td>Specify in hexadecimal. (Specification range: 0 to F)</td>
<td></td>
<td>48H</td>
</tr>
</tbody>
</table>

**Ex**
Index register (Z0)

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>5Ah, 30h, 30h</td>
<td>00h, 48h</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>5Ah, 20h, 30h, 30h</td>
<td>00h, 48h</td>
</tr>
</tbody>
</table>

**Ex**
For long index register (LZ0)

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC iQ-R series</td>
<td>4Ch, 5Ah, 30h, 30h</td>
<td>00h, 88h</td>
</tr>
</tbody>
</table>

When do not perform index modification, specify the following.

<table>
<thead>
<tr>
<th>Subcommand type</th>
<th>ASCII code</th>
<th>Binary code</th>
</tr>
</thead>
<tbody>
<tr>
<td>For MELSEC-Q/L series</td>
<td>30h, 30h, 30h</td>
<td>00h, 08h</td>
</tr>
<tr>
<td>For MELSEC iQ-R series</td>
<td>30h, 30h, 30h, 30h</td>
<td>00h, 08h</td>
</tr>
</tbody>
</table>
Device extension specification example (when do not perform index modification)

Access D100 by specifying the subcommand 0080 and using devices for indirect specification '@D0'.
Store the address of D100 in D0 with a program before executing the command.

Specify by the request data.

Specify by the program of the CPU module.

Address of the access destination (D100) can be stored to D0 and D1 by the following program.

---

**Data communication in ASCII code**

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Indirect specification</th>
<th>Device code</th>
<th>Device number</th>
<th>Device modification</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 8 0 0 @ 0 0 0 0 0 0 0 0 * D</td>
<td>0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

**Data communication in binary code**


---

Device extension specification example (Index modification)

Access D100 by specifying subcommand 0080 and specify the index modified device for indirect specification @D0Z2.
Before executing the command, store the D100 address in D4 and '4' in Z2 with the program.

Specify by the request data.

Specify by the program of the CPU module.

Address of the access destination (D100) can be stored to D4 and D5 by the following program.

---

**Data communication in ASCII code**

<table>
<thead>
<tr>
<th>Subcommand</th>
<th>Indirect specification</th>
<th>Device code</th>
<th>Device number</th>
<th>Device modification</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 8 0 0 @ 0 0 0 0 0 0 0 0 * D</td>
<td>0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

**Data communication in binary code**


Appendix 2  Processing Time

Time chart and communication time of C24 transmission sequence

The following figure shows a communication time chart when accessing programmable controller from an external device via C24.

When accessing CPU module with C24 mounted from an external device

The following shows the time chart when the message wait time is specified.

For the number of scans required for processing a read/write request, refer to the following section.

Page 453 Number of scans required for processing

For the number of points processed per communication, refer to the following section.

Page 459 Number of Processing per One Communication

■ Reading data

![Diagram of reading data]

■ Writing data

![Diagram of writing data]

- The communication between C24 and CPU module is always performed after END. Therefore, the scan time becomes longer according to the communication time (the time to interrupt to the CPU module).
- The number of scans required for processing to request read/write operation to the CPU module differs depending on the content of the request. For example, when a read operation that requires a scan is requested, it takes an extra time of 1 scan + T2.
- The number of scans required for the processing varies depending on the Service Processing Setting. It can be set in the parameter settings of Engineering tool. For details of Service Processing Setting, refer to the user's manual of the CPU module used.
Transmission time of transmission sequence

The following explains the approximate time required from when external device starts data transmission to when C24 returns the result.

The average of the above approximate time is shown below for the estimation of the processing time.

- **When external device reads data from a programmable controller (unit: ms)**

  Communication time = Request message transmission time (T0) + [(T1 + (1.5 × scan time) + T2) or TW] + Response message transmission time (T4)
  
  (When the value exceeds TW)

- **When external device writes data to a programmable controller**

  Communication time = Request message transmission time (T0) + [(T1 + (1.5 × scan time) + T2 + T3 + T5) or TW] + Response message transmission time (T4)
  
  (When the value exceeds TW)

\[
T, T4 = \frac{1000}{\text{Transmission rate}} \times \text{number of bits for 1 byte at transmission (1 + 7/8 + 0/1 + 1/2) × number of bytes}
\]

- **Start bit**
- **Stop bit (1 or 2)**
- **Data length (7 or 8)**
- **Parity bit (0 or 1)**

\[
T1 = \text{C24 processing time}
\]

Depending on the access points (MIN to MAX), the following ranges.

<table>
<thead>
<tr>
<th>Access Point</th>
<th>Range</th>
</tr>
</thead>
<tbody>
<tr>
<td>RJ71C24(-R2/-R4)</td>
<td>12.0 to 45.0 ms</td>
</tr>
<tr>
<td>QJ71C24N(-R2/-R4), LJ71C24(-R2)</td>
<td>12.5 to 45.0 ms</td>
</tr>
<tr>
<td>QJ71C24(-R2)</td>
<td>13.0 to 70.0 ms</td>
</tr>
</tbody>
</table>

\[
T2, T3 = \text{CPU intervention time (0.07 to 13.1ms)}
\]

\[
T5 = \text{Scan time (For functions that can process one scan, T3 and T5 equal 0.)}
\]

\[
TW = \text{The set time when message wait time is set.}
\]
Transmission time when accessing other stations

This section explains the transmission time (T1) when accessing CC-Link IE, MELSECNET/H, or MELSECNET/10 on other station.

For details on the network systems, refer to the manual of each network system.

Transmittion time (T1) to access other station (CC-Link IE, PLC network)

The following formula is for calculating the transmission time of CC-Link IE, MELSECNET/H (PLC network), and MELSECNET/10 (PLC network).

\[
T_{\text{transmission}} = \frac{(\text{Transmission delay time} + 1 \text{ scan time of the station on which the C24/E71 is loaded or internal processing time}) \times (n + 1)}{\text{n} + 1} \\
\text{Internal processing time C24 : Approximately 50 ms, E71 : Approximately 30 ms}
\]

- Refer to the transmission delay time in the manual of the network system.
- \(n = 6\)
- When performing the initial communication to the relevant station after powering ON or resetting CPU
- When performing communication to stations excluding the currently communicated 16 stations
- When performing the second communication when the number of communication stations is 16 or less
- When performing the second communication to the 16 stations communicated last
- When online program change is disabled in C24/E71, '1 ' is added only when writing data from external device.

Transmission time calculation example

The following example shows when C24 is mounted on the station on CC-Link IE controller network, and the device memory of other station on the same network is read. (When the number of communication station is 8 stations, and the second communication is performed)

- **Processing times and settings**
  - \(S_T\): Scan time of transmission side 2 ms
  - \(S_R\): Scan time of reception side 1 ms
  - \(L_S\): Link scan time 2 ms
  - \(a_T\): Link refresh time of transmission side 1 ms
  - \(a_R\): Link refresh time of reception side 1 ms
  - Simultaneous transient request: 2
  - Maximum transient request: 1

**Ex**

Normal transmission delay time

\[
T_{\text{transmission}} = \frac{(2 + 1 + 1 + 1) \times 2 + 2 \times 4 + (2 / 1 - 1) \times 2 \times 2 + 50} \times 1 \\
(\text{LS }) \text{ (LS )}
\]

Simultaneous transient request
Maximum transient request
C24 internal processing time

**Ex**

Worst-case transmission delay time

\[
T_{\text{transmission}} = \frac{(2 + 1 + 1 + 1) \times 2 + 2 \times 6 + (2 / 1 - 1) \times 2 \times 2 + 50} \times 1 \\
(\text{LS }) \text{ (LS )}
\]

Simultaneous transient request
Maximum transient request
C24 internal processing time
Causes of transmission time (T1) delay

When a command that takes two scans to send is executed, the transmission time is twice the value obtained by the formula above.

When the access request is issued to the same station from multiple external devices simultaneously, refer to the precautions for data communication. (Page 21 When accessing CPU module)

Data transmission to the CPU module other than connected station (host station) on CC-Link IE, MELSECNET/H, or MELSECNET/10 may be delayed considerably depending on conditions. The transmission delay time can be shortened by limiting communication between an external device and the CPU module to the station with C24/E71 mounted, and communicating with programmable controllers on other stations by data link (LB, LW).
Transmission time (T1) to access other station (remote I/O net)

The following shows the transmission time for MELSECNET/H (remote I/O net) and MELSECNET/10 (remote I/O net).

**Restriction**

MELSEC iQ-R series and MELSEC-L series are not supported.

Transmission time (T1) = \( \frac{(\text{Transmission delay time} + \text{1 link scan time or internal processing time}) \times (n + 1)}{(n + 1)} \)  
(When this value is more than the internal processing time.)

- \( \text{Transmission delay time} \)
- \( n \): Number of communication stations
- \( \alpha_m \): Link refresh time of remote master station
- \( S_m \): Scan time of remote master station sequence program
- \( L \): Link scan time

\[ T1 = \left( \frac{(S_m + \alpha_m)}{101} \right) \times (n + 1) \times (n + 1) \]

\[ T1 = \left( \frac{(12 + 5) \times 3 + 50}{(12 + 5)} \right) \times 3 \times \left( \frac{101}{(12 + 5)} \right) \times (n + 1) \]

**Causes of transmission time (T1) delay**

When a command that takes two scans to send is executed, the transmission time is twice the value obtained by the formula above.

When the access request is issued to the same station from multiple external devices simultaneously, refer to the precautions for data communication. (Page 21 When accessing CPU module)

**Point**

Data transmission to the CPU module other than connected station (host station) on MELSECNET/H may be delayed considerably depending on conditions. The transmission delay time can be shortened by limiting communication between an external device and the CPU module to the station with C24/E71 mounted, and communicating with programmable controllers on other stations by data link (LB, LW).
# Number of scans required for processing

## When connected to C24/E71

### Basic model QCPU

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Number of scans required for processing</th>
<th>Online change is enabled</th>
<th>Online change is disabled</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Device access</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Batch read and write</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Batch read in word units</td>
<td>0401</td>
<td>0000</td>
<td>1</td>
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<td>0001</td>
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<td>0001</td>
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<td><strong>Batch read and write</strong></td>
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</tr>
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<td>Batch read</td>
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<td>0000</td>
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<td>2</td>
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<tr>
<td><strong>Module control</strong></td>
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</tr>
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<td>Remote control</td>
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### High performance model QCPU

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<th>Subcommand</th>
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<th>Online change is disabled</th>
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<td>Batch read in word units</td>
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<td>1</td>
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</tr>
<tr>
<td>Batch read in bit units</td>
<td></td>
<td>0001</td>
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<td></td>
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<tr>
<td>Batch write in word units</td>
<td>1401</td>
<td>0000</td>
<td>1</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td>Batch write in bit units</td>
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<td>0001</td>
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<td></td>
<td></td>
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<td><strong>Random read and write</strong></td>
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<td>Random read in word units</td>
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<td>0000</td>
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</tr>
<tr>
<td>Random write in word units</td>
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<td></td>
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</tr>
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<td>0001</td>
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<td></td>
<td></td>
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<tr>
<td>(test)</td>
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<td>0001</td>
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<td></td>
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<td><strong>Batch read and write</strong></td>
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</tr>
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<td><strong>Monitor device</strong></td>
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</tr>
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<td>memory</td>
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<td>0000</td>
<td>0</td>
<td>0</td>
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</tr>
<tr>
<td>Monitor</td>
<td>0802</td>
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<td>1</td>
<td></td>
</tr>
<tr>
<td><strong>Buffer memory access</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
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<tr>
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</tr>
<tr>
<td>Batch read</td>
<td>1601</td>
<td>0000</td>
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<td>1</td>
<td></td>
</tr>
<tr>
<td><strong>Module control</strong></td>
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<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Remote control</td>
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<td></td>
<td></td>
<td></td>
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</tr>
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<td><strong>File creation and deletion</strong></td>
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</tr>
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<td><strong>File modification</strong></td>
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</tr>
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<td>0</td>
<td>1</td>
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</tr>
<tr>
<td>Open file</td>
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<td>0</td>
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</tr>
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<td>Read file</td>
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</tr>
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<td>Close file</td>
<td>182A</td>
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</table>
## Universal model QCPU, LCPU, RCPU

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Number of scans required for processing</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
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<td>QCPU/ LCPU</td>
<td>Online change is enabled</td>
</tr>
<tr>
<td>Device access</td>
<td>Batch read and write</td>
<td>0401</td>
<td>0000 0002 1 1</td>
</tr>
<tr>
<td></td>
<td>Batch read in word units</td>
<td></td>
<td>0000 0002 1 1</td>
</tr>
<tr>
<td></td>
<td>Batch read in bit units</td>
<td></td>
<td>0001 0003 1 1</td>
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<tr>
<td></td>
<td>Batch write in word units</td>
<td>1401</td>
<td>0000 0002 1 2</td>
</tr>
<tr>
<td></td>
<td>Batch write in bit units</td>
<td>0001 0003 1 2</td>
<td></td>
</tr>
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<td>Random read and write</td>
<td>Random read in word units</td>
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<td>0000 0002 1 1</td>
</tr>
<tr>
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<td>Random write in word units (test)</td>
<td>1402</td>
<td>0000 0002 1 2</td>
</tr>
<tr>
<td></td>
<td>Random write in bit units (test)</td>
<td>0001 0003 1 2</td>
<td></td>
</tr>
<tr>
<td>Batch read and write multiple blocks</td>
<td>Batch read multiple blocks</td>
<td>0406</td>
<td>0000 0002 1 1</td>
</tr>
<tr>
<td></td>
<td>Batch write multiple blocks</td>
<td>1406</td>
<td>0000 0002 1 2</td>
</tr>
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<td>Register monitor data</td>
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<td>0000 0002 0 0</td>
</tr>
<tr>
<td></td>
<td>Monitor</td>
<td>0802</td>
<td>0000 1 1</td>
</tr>
<tr>
<td>Buffer memory access</td>
<td>Intelligent function module</td>
<td>0601</td>
<td>0000 1 1</td>
</tr>
<tr>
<td></td>
<td>Batch read</td>
<td>1801</td>
<td>0000 1 1</td>
</tr>
<tr>
<td></td>
<td>Batch write</td>
<td>1802</td>
<td>0000 1 2</td>
</tr>
<tr>
<td>Module control</td>
<td>Remote control</td>
<td>0101</td>
<td>0000 1 1</td>
</tr>
<tr>
<td>File control</td>
<td>File check</td>
<td>0401</td>
<td>0000 0040 1 1</td>
</tr>
<tr>
<td></td>
<td>Read directory/file information</td>
<td>1810</td>
<td>0000 0040 1 1</td>
</tr>
<tr>
<td></td>
<td>Search directory/file information</td>
<td>1811</td>
<td>0000 0040 1 1</td>
</tr>
<tr>
<td>File creation and deletion</td>
<td>Create new file</td>
<td>1820</td>
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<td></td>
<td>Delete file</td>
<td>1822</td>
<td>0000 0040 1 2</td>
</tr>
<tr>
<td></td>
<td>Copy file</td>
<td>1824</td>
<td>0000 0040 1 2</td>
</tr>
<tr>
<td>File modification</td>
<td>Modify file attribute</td>
<td>1825</td>
<td>0000 0040 1 2</td>
</tr>
<tr>
<td></td>
<td>Modify file creation date and time</td>
<td>1826</td>
<td>0000 0040 1 2</td>
</tr>
<tr>
<td></td>
<td>Open file</td>
<td>1827</td>
<td>0000 0040 1 2</td>
</tr>
<tr>
<td></td>
<td>Read file</td>
<td>1828</td>
<td>0000 0040 1 2</td>
</tr>
<tr>
<td></td>
<td>Write to file</td>
<td>1829</td>
<td>0000 0040 1 2</td>
</tr>
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<td></td>
<td>Close file</td>
<td>182A</td>
<td>0000 0040 1 2</td>
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### When serial communication function is used

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<tr>
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<th>Command</th>
<th>Subcommand</th>
<th>Number of scans required for processing</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>QCPU/ LCPU</td>
<td>Online change is enabled</td>
</tr>
<tr>
<td>Device access</td>
<td>Batch read and write</td>
<td>0401</td>
<td>0000 0002 3 3</td>
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<td></td>
<td>Batch read in word units</td>
<td></td>
<td>0000 0002 3 3</td>
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<tr>
<td></td>
<td>Batch read in bit units</td>
<td></td>
<td>0001 0003 3 3</td>
</tr>
<tr>
<td></td>
<td>Batch write in word units</td>
<td>1401</td>
<td>0000 0002 3 3</td>
</tr>
<tr>
<td></td>
<td>Batch write in bit units</td>
<td>0001 0003 3 3</td>
<td></td>
</tr>
<tr>
<td>Random read and write</td>
<td>Random read in word units</td>
<td>0403</td>
<td>0000 0002 3 3</td>
</tr>
<tr>
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<td>Random write in word units (test)</td>
<td>1402</td>
<td>0000 0002 3 3</td>
</tr>
<tr>
<td></td>
<td>Random write in bit units (test)</td>
<td>0001 0003 3 3</td>
<td></td>
</tr>
<tr>
<td>Monitor device memory</td>
<td>Register monitor data</td>
<td>0801</td>
<td>0000 0002 3 3</td>
</tr>
<tr>
<td></td>
<td>Monitor</td>
<td>0802</td>
<td>0000 3 3</td>
</tr>
</tbody>
</table>
Appendix 3  Compatibility with Multiple CPU Systems

This section explains data communication using MC protocol when CPU modules are configured in the multiple CPU system.

By setting routing parameters (communication route) in advance, accessing programmable controllers in the following network systems are available.

- CC-Link IE Controller Network
- CC-Link IE Field Network
- MELSECNET/H
- MELSECNET/10
- Ethernet

Up to 8 target networks (relay stations: 7 stations) can be accessed.

When RCPU is configured in the multiple CPU system

When using C24/E71 in the multiple CPU system of RCPU, refer to the following manual.
MELSEC iQ-R Module Configuration Manual

Accessing multiple CPU system on connected station (host station)

Accessing multiple CPU system on connected station (host station) from external devices

Control CPU (set with Engineering tool) and non-control CPU of C24 can be accessed.
The usable commands vary depending on the access target RCPU (control CPU, non-control CPU).

Accessing multiple CPU system on other station

Accessing multiple CPU system on the other station (access station)

Control CPU and non-control CPU of the network module connected to the relay station can be accessed.
The usable command vary depending on the access target RCPU (control CPU, non-control CPU).
The modules which can be accessed to other stations via network are as follows.

- CC-Link IE, MELSECNET/H, MELSECNET/10 Network Module
- C24
- E71

Point

Another station can be accessed whether the control CPU of the module acting as a relay is the same or different.

Point

Another station can be accessed whether the control CPU of the module acting as a relay is the same or different.

By setting routing parameters (communication route) in advance, accessing programmable controllers in the following network systems are available.

- CC-Link IE Controller Network
- CC-Link IE Field Network
- MELSECNET/H
- MELSECNET/10
- Ethernet

Up to 8 target networks (relay stations: 7 stations) can be accessed.
When QCPU is configured in the multiple CPU system

When using C24/E71 in the multiple CPU system of QCPU, refer to the following manual.
QCPU User's Manual (Multiple CPU System)

Accessing multiple CPU system on connected station (host station)

When using C24/E71 in the multiple CPU system
Use C24/E71 of which function version is B.

Accessing multiple CPU system on connected station (host station) from external devices
Control CPU (set with Engineering tool) and non-control CPU of C24/E71 can be accessed.
The usable commands vary depending on the access target QCPU (control CPU, non-control CPU).
Using C24/E71 of which function version is A is also possible. In this case, QCPU No.1 is the control CPU of C24/E71.
Only the control CPU of C24/E71 can be accessed when accessing QCPU on the connected station (host station) from
external devices.

Accessing multiple CPU system on other station

Use the modules of which function version is B for each station.
Use the modules of which function version is B for each station as shown below.

<table>
<thead>
<tr>
<th>Type</th>
<th>Module</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>Connected station</td>
<td>QCPU</td>
<td>—</td>
</tr>
<tr>
<td>(host station)</td>
<td>C24/E71 connected to external</td>
<td>Set the same control CPU for C24/E71 and network module.</td>
</tr>
<tr>
<td></td>
<td>device</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Network module connected to</td>
<td></td>
</tr>
<tr>
<td></td>
<td>relay station/access station</td>
<td></td>
</tr>
<tr>
<td>Relay station</td>
<td>QCPU</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>Two modules connecting the</td>
<td></td>
</tr>
<tr>
<td></td>
<td>network between the host</td>
<td></td>
</tr>
<tr>
<td></td>
<td>station side and the access</td>
<td></td>
</tr>
<tr>
<td></td>
<td>station side</td>
<td></td>
</tr>
<tr>
<td>Access station</td>
<td>QCPU</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>Network module connected to</td>
<td></td>
</tr>
<tr>
<td></td>
<td>relay station</td>
<td></td>
</tr>
</tbody>
</table>

Accessing multiple CPU system on the other station (access station)
Control CPU and non-control CPU of the network module connected to the relay station can be accessed.
The usable commands vary depending on the access target QCPU (control CPU, non-control CPU).
When accessing other stations from external devices, and any module of which function version is A is included in the above
modules of connected station (host station), relay station, or access station, only the control CPU of network module
connected to the relay station can be accessed. In addition, accessing other station via a module which is controlled by the
same control CPU is available.
The modules which can be accessed other stations via network are as follows.
• CC-Link IE, MELSECNET/H ,MELSECNET/10 Network module
• C24
• E71
Appendix 4  Applicable Commands for Online Program Change

This section explains the applicability of each command according to the STOP/RUN status of CPU module and the settings by supported devices.

In this section, the commands that cannot be executed while CPU module is in the RUN status and the commands to enable/disable the online change with Engineering tool are shown. The commands not listed in the following tables can be used regardless of the CPU STOP/RUN status.

Commands that cannot be executed during RUN

The following commands cannot be executed while the CPU module is in RUN.
Set the CPU module to STOP and perform the command.

File handling

The file operation to specify the following files cannot be performed during RUN.

<table>
<thead>
<tr>
<th>Type</th>
<th>Command</th>
<th>CPU module</th>
<th>Target file</th>
</tr>
</thead>
<tbody>
<tr>
<td>Write</td>
<td>• Copy file (command: 1824)</td>
<td>RCPU</td>
<td>Current execution file*1</td>
</tr>
<tr>
<td></td>
<td>• Modify file attribute (command: 1825)</td>
<td>Q/LCPU</td>
<td>• Parameter file (*.QPA)</td>
</tr>
<tr>
<td></td>
<td>• Modify file creation date and time (command: 1826)</td>
<td></td>
<td>• Current execution file of program memory (Drive name: 00H)</td>
</tr>
<tr>
<td></td>
<td>• Write to file (command: 1829)</td>
<td>QnACPU</td>
<td>• Parameter file (*.QPA)</td>
</tr>
<tr>
<td></td>
<td>• Write to file (command: 1203)</td>
<td></td>
<td>• Currently executing file in the built-in RAM (drive name: 00H)</td>
</tr>
<tr>
<td></td>
<td>• Copy file (command: 1206)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Modify file information (command: 1204)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Modify file name, attribute, file size (command: 1204)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Batch modify file information (command: 1204)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Deleting</td>
<td>• Delete file (command: 1822)</td>
<td>RCPU</td>
<td>Current execution file*1</td>
</tr>
<tr>
<td></td>
<td>• Delete file (command: 1205)</td>
<td>Q/LCPU</td>
<td>• Program file (*.QPG)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>QnACPU</td>
<td>• Parameter file (*.QPA)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Boot setting file (*.QBT)</td>
</tr>
</tbody>
</table>

*1 For details on the operations for the files of RCPU, refer to the following manual.
acional

Module control

<table>
<thead>
<tr>
<th>Type</th>
<th>Command</th>
<th>CPU module</th>
</tr>
</thead>
<tbody>
<tr>
<td>Remote control</td>
<td>• Remote latch clear (command: 1005)</td>
<td>RCPU</td>
</tr>
<tr>
<td></td>
<td>• Remote RESET (command: 1006)</td>
<td>Q/LCPU</td>
</tr>
<tr>
<td>Defragmentation of drive memory</td>
<td>• Defragment drive memory (command: 1207)</td>
<td>QnACPU</td>
</tr>
</tbody>
</table>

Commands that enable/disable online change

The following shows the commands which can be executed while the CPU module is in the RUN status only when the online change is set to be enabled.
○: Executable, ×:Not executable

<table>
<thead>
<tr>
<th>CPU state</th>
<th>STOP</th>
<th>RUN</th>
</tr>
</thead>
<tbody>
<tr>
<td>Setting of online change</td>
<td>Enable/Disable</td>
<td>Enable</td>
</tr>
<tr>
<td>Applicability of command execution</td>
<td>○</td>
<td>○</td>
</tr>
</tbody>
</table>
### Commands for 4C/3C/2C/4E/3E frame

<table>
<thead>
<tr>
<th>Type</th>
<th>Command</th>
<th>4C, 3C, 4E, 3E</th>
<th>2C</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device access</td>
<td>Batch write in word units</td>
<td>1401</td>
<td>4</td>
</tr>
<tr>
<td></td>
<td>Batch write in bit units</td>
<td></td>
<td>3</td>
</tr>
<tr>
<td></td>
<td>Random write in word units (test)</td>
<td>1402</td>
<td>7</td>
</tr>
<tr>
<td></td>
<td>Random write in bit units (test)</td>
<td></td>
<td>6</td>
</tr>
<tr>
<td></td>
<td>Batch write multiple blocks</td>
<td>1406</td>
<td></td>
</tr>
<tr>
<td>Label access</td>
<td>Batch write array type labels</td>
<td>141A</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Random write labels</td>
<td>141B</td>
<td></td>
</tr>
<tr>
<td>File control</td>
<td>Create new file</td>
<td>1820</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Delete file</td>
<td>1822</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Copy file&lt;sup&gt;1&lt;/sup&gt;</td>
<td>1824</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Modify file attribute</td>
<td>1825</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Modify file creation date and time</td>
<td>1826</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Write to file</td>
<td>1829</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Create new file</td>
<td>1202</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Write to file</td>
<td>1203</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Modify file information</td>
<td>1204</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Delete file</td>
<td>1205</td>
<td></td>
</tr>
</tbody>
</table>

<sup>1</sup> For E71, data can be copied even if Online program change function is set to prohibit.

### Commands for 1C/1E frame

<table>
<thead>
<tr>
<th>Type</th>
<th>Command</th>
<th>1C</th>
<th>1E</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device memory</td>
<td>Batch write</td>
<td></td>
<td>02H</td>
</tr>
<tr>
<td></td>
<td>Bit units</td>
<td>BW, JW</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>WW, QW</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Test (random write)</td>
<td></td>
<td>03H</td>
</tr>
<tr>
<td></td>
<td>Bit units</td>
<td>BT, JT</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>WT, QT</td>
<td></td>
</tr>
<tr>
<td>Extended file register</td>
<td>Batch write</td>
<td></td>
<td>18H</td>
</tr>
<tr>
<td></td>
<td>EW</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Test (random write)</td>
<td>ET</td>
<td>19H</td>
</tr>
<tr>
<td></td>
<td>Direct write</td>
<td>NW</td>
<td>3CH</td>
</tr>
<tr>
<td>Intelligent function module</td>
<td>Batch write</td>
<td>TW</td>
<td>0FH</td>
</tr>
</tbody>
</table>

### Setting method for writing data to CPU during RUN

The setting to allowed/prohibit of Online program change function can be performed on the following screen of Engineering tool.

For details of the setting, refer to the user's manual of the supported device (C24/E71) used.

**GX Works3**
- C24: "Module Parameter" screen (transmission setting)
- E71: "Module Parameter" screen (Own Node Settings)

**GX Works2**
- C24: "Switch Settings" screen of Intelligent functional module (Transmission setting)
- E71: "Ethernet Operation Setting" screen

**GX Developer**
- C24: "Switch Setting for I/O and Intelligent Function Module" screen (Switch 1, b6 of switch 3)
- E71: "Ethernet Operation Setting" screen
Appendix 5  Number of Processing per One Communication

The following shows the number of processing per one communication with each command.

Commands for 4C/3C/4E/3E frame

Device access

The letter in the column of 'Access target' indicates the following module:
- R/Q/L: MELSEC iQ-R series, MELSEC-Q series, or MELSEC-L series module
- QnA: MELSEC-QnA series and other station module via MELSEC-QnA series network module
- A: MELSEC-QnA series module

For the restrictions of access target for each command and subcommand type, refer to the following section.
Page 465 Accessible Modules for Each Command

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Condition</th>
<th>Number of points processed per communication</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>R/Q/L</td>
</tr>
<tr>
<td>Batch read and write</td>
<td>Batch read in word units</td>
<td>0401 0000 0002</td>
<td>Word device points</td>
<td>960 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Bit device points</td>
</tr>
<tr>
<td></td>
<td>Batch read in bit units</td>
<td>0001 0003</td>
<td>C24</td>
<td>7904 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>E71 (ASCII code)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>E71 (Binary code)</td>
</tr>
<tr>
<td></td>
<td>Batch write in word units</td>
<td>1401 0000 0002</td>
<td>Word device points</td>
<td>960 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Bit device points</td>
</tr>
<tr>
<td></td>
<td>Batch write in bit units</td>
<td>0001 0003</td>
<td>C24</td>
<td>7904 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>E71 (ASCII code)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>E71 (Binary code)</td>
</tr>
<tr>
<td>Random read and write</td>
<td>Random read in word units</td>
<td>0403 0000</td>
<td>Number of word access points + Number of double word access points</td>
<td>192 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0002 0080</td>
<td></td>
<td>192 points</td>
</tr>
<tr>
<td></td>
<td>Random write in word units (test)</td>
<td>1402 0000</td>
<td>(Number of word access points × 12) + (Number of double word access points × 14)</td>
<td>1920 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0002 0080</td>
<td></td>
<td>1920 points</td>
</tr>
<tr>
<td></td>
<td>Random write in bit units (test)</td>
<td>0001 0003</td>
<td>Number of bit access points</td>
<td>188 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0003 0080</td>
<td></td>
<td>188 points</td>
</tr>
<tr>
<td></td>
<td>Batch read and write multiple blocks</td>
<td>0406 0000</td>
<td>Number of word device blocks + Number of bit device blocks</td>
<td>120 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0002 0080</td>
<td></td>
<td>120 points</td>
</tr>
<tr>
<td></td>
<td>Batch write multiple blocks</td>
<td>1406 0000</td>
<td>Number of word access points</td>
<td>192 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0002 0080</td>
<td></td>
<td>192 points</td>
</tr>
<tr>
<td>Monitor device memory</td>
<td>Register monitor data</td>
<td>0801 0000</td>
<td>Number of word access points + Number of double word access points</td>
<td>192 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0002 0080</td>
<td></td>
<td>192 points</td>
</tr>
<tr>
<td></td>
<td>Monitor</td>
<td>0802 0000</td>
<td>Read data</td>
<td>(Number of registered points)</td>
</tr>
</tbody>
</table>
### Label access

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Number of points processed per communication</th>
</tr>
</thead>
<tbody>
<tr>
<td>Batch read and write</td>
<td>041A</td>
<td>0000</td>
<td>Depend on the label name length (total number of bytes are 1920 bytes or less)</td>
</tr>
<tr>
<td>Batch write array type labels</td>
<td>141A</td>
<td>0000</td>
<td></td>
</tr>
<tr>
<td>Random read and write</td>
<td>041C</td>
<td>0000</td>
<td></td>
</tr>
<tr>
<td>Random write labels</td>
<td>141B</td>
<td>0000</td>
<td></td>
</tr>
</tbody>
</table>

### Buffer memory access

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Number of points processed per communication</th>
</tr>
</thead>
<tbody>
<tr>
<td>Buffer memory</td>
<td>0613</td>
<td>0000</td>
<td>480 words (960 bytes)</td>
</tr>
<tr>
<td>Batch write</td>
<td>1613</td>
<td>0000</td>
<td></td>
</tr>
<tr>
<td>Intelligent function module</td>
<td>0601</td>
<td>0000</td>
<td>1920 bytes (960 words)</td>
</tr>
<tr>
<td>Batch write</td>
<td>1601</td>
<td>0000</td>
<td></td>
</tr>
</tbody>
</table>

### Module control

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Number of points processed per communication</th>
</tr>
</thead>
<tbody>
<tr>
<td>Remote control</td>
<td>1001</td>
<td>0000</td>
<td>(1 station)</td>
</tr>
<tr>
<td>Remote STOP</td>
<td>1002</td>
<td>0000</td>
<td>(1 station)</td>
</tr>
<tr>
<td>Remote PAUSE</td>
<td>1003</td>
<td>0000</td>
<td>(1 station)</td>
</tr>
<tr>
<td>Remote latch clear</td>
<td>1005</td>
<td>0000</td>
<td>(1 station)</td>
</tr>
<tr>
<td>Remote RESET</td>
<td>1006</td>
<td>0000</td>
<td>(1 station)</td>
</tr>
<tr>
<td>Read CPU model name</td>
<td>0101</td>
<td>0000</td>
<td>(1 station)</td>
</tr>
<tr>
<td>Remote password</td>
<td>1630</td>
<td>0000</td>
<td>—</td>
</tr>
<tr>
<td>Unlock</td>
<td>1631</td>
<td>0000</td>
<td>—</td>
</tr>
<tr>
<td>Loopback test</td>
<td>0619</td>
<td>0000</td>
<td>960 bytes (applicable only with a connected station)</td>
</tr>
<tr>
<td>Clear error information</td>
<td>1617</td>
<td>0000</td>
<td>(1 station)</td>
</tr>
</tbody>
</table>
## File control

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Number of points processed per communication</th>
</tr>
</thead>
<tbody>
<tr>
<td>Read directory/file information</td>
<td>1810</td>
<td>0000 0040</td>
<td>(for 36)</td>
</tr>
<tr>
<td>Search directory/file information</td>
<td>1811</td>
<td>0000 0040</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Create new file</td>
<td>1820</td>
<td>0000 0040</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Delete file</td>
<td>1822</td>
<td>0000 0004 0040</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Copy file</td>
<td>1824</td>
<td>0000 0004 0040</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Modify file attribute</td>
<td>1825</td>
<td>0000 0004 0040</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Modify file creation date and time</td>
<td>1826</td>
<td>0000 0040</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Open file</td>
<td>1827</td>
<td>0000 0004 0040</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Read file</td>
<td>1828</td>
<td>0000 0040</td>
<td>1920 bytes</td>
</tr>
<tr>
<td>Write to file</td>
<td>1829</td>
<td>0000 0040</td>
<td>1920 bytes</td>
</tr>
<tr>
<td>Close file</td>
<td>182A</td>
<td>0000 0040</td>
<td>(for 1)</td>
</tr>
</tbody>
</table>

## Serial communication module dedicated commands

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Number of points processed per communication</th>
</tr>
</thead>
<tbody>
<tr>
<td>Read registered data</td>
<td>0610</td>
<td>0000</td>
<td>80 bytes</td>
</tr>
<tr>
<td>Register data</td>
<td>1610</td>
<td>0000</td>
<td>(1 station)</td>
</tr>
<tr>
<td>Delete registered data</td>
<td></td>
<td>0001</td>
<td>(for 1 station/all stations)</td>
</tr>
<tr>
<td>1818</td>
<td></td>
<td>0000 0001</td>
<td>(for 1 station/all stations)</td>
</tr>
<tr>
<td>Initialize transmission sequence</td>
<td>1615</td>
<td>0000</td>
<td>(1 station)</td>
</tr>
<tr>
<td>Switch mode</td>
<td>1612</td>
<td>0000</td>
<td>(1 station)</td>
</tr>
<tr>
<td>Register</td>
<td>0630</td>
<td>0000</td>
<td>960 points</td>
</tr>
<tr>
<td>Deregister</td>
<td>0631</td>
<td>0000</td>
<td>—</td>
</tr>
<tr>
<td>On-demand</td>
<td>2101</td>
<td>—</td>
<td>(1 station)</td>
</tr>
<tr>
<td>Function</td>
<td>Command</td>
<td>Subcommand</td>
<td>Number of points processed per communication</td>
</tr>
<tr>
<td>----------------------------------</td>
<td>---------</td>
<td>------------</td>
<td>---------------------------------------------</td>
</tr>
<tr>
<td>Drive memory defragmentation</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Read memory usage status</td>
<td>0205</td>
<td>0000</td>
<td>(256 clusters)</td>
</tr>
<tr>
<td>Defragment memory</td>
<td>1207</td>
<td>0000</td>
<td>(1 station)</td>
</tr>
<tr>
<td>File control</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Read file information table</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Without header statement</td>
<td>0201</td>
<td>0000</td>
<td>(for 36)</td>
</tr>
<tr>
<td>With header statement</td>
<td>0202</td>
<td>0000</td>
<td>(for 16)</td>
</tr>
<tr>
<td>Read file presence (Search file)</td>
<td>0203</td>
<td>0000</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Read file No. usage status</td>
<td>0204</td>
<td>0000</td>
<td>(for 256)</td>
</tr>
<tr>
<td>Read file</td>
<td>0206</td>
<td>0000</td>
<td>960 bytes</td>
</tr>
<tr>
<td>Lock file</td>
<td>0808</td>
<td>0001</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Create new file (Register name)</td>
<td>1202</td>
<td>0000</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Write to file</td>
<td>1203</td>
<td>0000</td>
<td>960 bytes</td>
</tr>
<tr>
<td>Modify file information</td>
<td>1204</td>
<td>0000</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Delete file</td>
<td>1205</td>
<td>0000</td>
<td>(for 1)</td>
</tr>
<tr>
<td>Copy file</td>
<td>1206</td>
<td>0000</td>
<td>480 bytes</td>
</tr>
</tbody>
</table>
## Commands for 2C frame

Refer to the processing points of the corresponding commands for 4C/3C/4E/3E frame

### Commands for 1C frame

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Number of points processed per communication</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Device memory</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Batch read</td>
<td>Bit units</td>
<td>BR JR</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>WR QR</td>
</tr>
<tr>
<td></td>
<td></td>
<td>256 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Batch write</td>
<td>Bit units</td>
<td>BW JW</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>WW QW</td>
</tr>
<tr>
<td></td>
<td></td>
<td>160 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Test (random write)</td>
<td>Bit units</td>
<td>BT JT</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>WT QT</td>
</tr>
<tr>
<td></td>
<td></td>
<td>10 words (160 points)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Register monitor data</td>
<td>Bit units</td>
<td>BM JM</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>WM QM</td>
</tr>
<tr>
<td></td>
<td></td>
<td>40 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Number of points processed per communication</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Monitor</td>
<td>Bit units</td>
<td>MB MJ</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>MN MQ</td>
</tr>
<tr>
<td></td>
<td></td>
<td>20 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Number of registered points</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Extended file register</strong></td>
<td>Batch read</td>
<td>ER</td>
</tr>
<tr>
<td></td>
<td>Batch write</td>
<td>EW</td>
</tr>
<tr>
<td></td>
<td>Test (random write)</td>
<td>ET</td>
</tr>
<tr>
<td></td>
<td>Register monitor data</td>
<td>EM</td>
</tr>
<tr>
<td></td>
<td>Monitor</td>
<td>ME</td>
</tr>
<tr>
<td></td>
<td>Direct read</td>
<td>NR</td>
</tr>
<tr>
<td></td>
<td>Direct write</td>
<td>NW</td>
</tr>
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<td></td>
<td></td>
<td>64 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td>64 points</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Special function module</strong></td>
<td>Batch read</td>
<td>TR</td>
</tr>
<tr>
<td></td>
<td>Batch write</td>
<td>TW</td>
</tr>
<tr>
<td></td>
<td></td>
<td>128 bytes</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Loopback test</strong></td>
<td></td>
<td>TT</td>
</tr>
<tr>
<td></td>
<td></td>
<td>254 bytes</td>
</tr>
</tbody>
</table>

*1 For ACPU other than AnA/AnU, device X (input) has two processing points per point. When the X is included in the specified device, set the number of device points to meet the following.

\(((\text{Specified points for } X \times 2) + \text{Specified points for other devices}) \leq \text{Number of points processed per communication.} \)

If only X is specified, the number of points processed per one communication will be one half the value shown in the table.
## Commands for 1E frame

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Number of points processed per communication</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Device memory</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Batch read</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit units</td>
<td>00H</td>
<td>256 points</td>
</tr>
<tr>
<td>Word units Bit device</td>
<td>01H</td>
<td>128 words (2048 points)</td>
</tr>
<tr>
<td>Word device</td>
<td></td>
<td>256 points</td>
</tr>
<tr>
<td><strong>Batch write</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit units</td>
<td>02H</td>
<td>256 points</td>
</tr>
<tr>
<td>Word units Bit device</td>
<td>03H</td>
<td>40 words (640 points)</td>
</tr>
<tr>
<td>Word device</td>
<td></td>
<td>256 points</td>
</tr>
<tr>
<td><strong>Test (random write)</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit units</td>
<td>04H</td>
<td>80 points</td>
</tr>
<tr>
<td>Word units Bit device</td>
<td>05H</td>
<td>40 words (640 points)</td>
</tr>
<tr>
<td>Word device</td>
<td></td>
<td>40 points</td>
</tr>
<tr>
<td><strong>Register monitor data</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit units</td>
<td>06H</td>
<td>40 points*1</td>
</tr>
<tr>
<td>Word units Bit device</td>
<td>07H</td>
<td>20 words (320 points)*1</td>
</tr>
<tr>
<td>Word device</td>
<td></td>
<td>20 points</td>
</tr>
<tr>
<td><strong>Monitor</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit units</td>
<td>08H</td>
<td>Number of registered points</td>
</tr>
<tr>
<td>Word units</td>
<td>09H</td>
<td>Number of registered points</td>
</tr>
<tr>
<td><strong>Extended file register</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Batch read</td>
<td>17H</td>
<td>256 points</td>
</tr>
<tr>
<td>Batch write</td>
<td>18H</td>
<td>256 points</td>
</tr>
<tr>
<td>Test (random write)</td>
<td>19H</td>
<td>40 points</td>
</tr>
<tr>
<td>Register monitor data</td>
<td>1AH</td>
<td>20 points</td>
</tr>
<tr>
<td>Monitor</td>
<td>1BH</td>
<td>—</td>
</tr>
<tr>
<td>Direct read</td>
<td>3BH</td>
<td>256 points</td>
</tr>
<tr>
<td>Direct write</td>
<td>3CH</td>
<td>256 points</td>
</tr>
<tr>
<td><strong>Special function module</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Batch read</td>
<td>0EH</td>
<td>256 bytes (128 words)</td>
</tr>
<tr>
<td>Batch write</td>
<td>0FH</td>
<td>256 bytes (128 words)</td>
</tr>
</tbody>
</table>

*1 For ACPU other than AnA/AnU, device X (input) has two processing points per point. When the X is included in the specified device, set the number of device points to meet the following.

\[
((\text{Specified points for } X \times 2) + \text{Specified points for other devices}) \leq \text{Number of points processed per communication.}
\]

If only X is specified, the number of points processed per one communication will be one half the value shown in the table.
## Appendix 6 Accessible Modules for Each Command

The following shows the access target modules that can be specified by a request message. For the functions and commands which can be used for supported devices, refer to the user’s manual of each device.

### Access target modules

The character in the column of ‘Access target’ indicates the following module:

- R: MELSEC-iQ-R series CPU module and mounted intelligent function module
- Q/L: MELSEC-Q series or MELSEC-L series CPU module and the mounted intelligent functional module
- QnA: MELSEC-QnA series CPU module and mounted special function module
- A: MELSEC-A series CPU module and mounted special function module
- QS: Safety CPU module and the mounted intelligent functional module
- H: Module of MELSECNET/H remote station
- 10: Module of MELSECNET/10 remote station
- Head: Head module of CC-Link IE Field Network

### Commands for 4C/3C/4E/3E frame

#### Device access

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Access target</th>
<th>Remote I/O</th>
<th>Head</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>CPU module</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>R</td>
<td>L</td>
<td>Q</td>
<td>QnA</td>
</tr>
<tr>
<td>Batch read and write</td>
<td>0401</td>
<td>0000</td>
<td>○</td>
<td>○</td>
<td>○</td>
<td>○</td>
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<tr>
<td></td>
<td>0001</td>
<td>0000</td>
<td>○</td>
<td>○</td>
<td>○</td>
<td>○</td>
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<tr>
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<td>0000</td>
<td>○</td>
<td>○</td>
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<tr>
<td></td>
<td>1401</td>
<td>0000</td>
<td>○</td>
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<td></td>
<td>0001</td>
<td>0000</td>
<td>○</td>
<td>○</td>
<td>○</td>
<td>○</td>
</tr>
<tr>
<td></td>
<td>0002</td>
<td>0000</td>
<td>○</td>
<td>○</td>
<td>○</td>
<td>○</td>
</tr>
<tr>
<td>Random read and write</td>
<td>0403</td>
<td>0000</td>
<td>○</td>
<td>○</td>
<td>○</td>
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<td>○</td>
<td>○</td>
</tr>
<tr>
<td></td>
<td>0002</td>
<td>0000</td>
<td>○</td>
<td>○</td>
<td>○</td>
<td>○</td>
</tr>
<tr>
<td></td>
<td>1402</td>
<td>0000</td>
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<td></td>
<td>0002</td>
<td>0000</td>
<td>○</td>
<td>○</td>
<td>○</td>
<td>○</td>
</tr>
</tbody>
</table>
### Label access

The command can be used when both access target and connected station are MELSEC iQ-R series module.

![Page 119 LABEL ACCESS](image)

### Buffer memory access

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Access target</th>
<th>Remote I/O</th>
<th>Head</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>CPU module</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>R</td>
<td>L</td>
<td>Q</td>
<td>QnA</td>
</tr>
</tbody>
</table>

*1 Specify the device with the specification method of MELSEC-Q/L series. The added new devices for MELSEC iQ-R and their ranges cannot be specified.

*2 The command can be used when both access target and connected station are MELSEC iQ-R series module.

*3 The command can be specified when using Basic model QCPU, High Performance model QCPU, and Process CPU.

*4 QnACPU and Q2AS(H) CPU with the version 9707B or later can be used.

### Function

- **CPU module**: Executable, **△**: Executable (with restrictions), **X**: Not executable

---

*1 The command can only be used for C24 (including multidrop connection station) and E71 connected to the external device.
### Module control

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Access target</th>
<th>Remote I/O</th>
<th>Head</th>
</tr>
</thead>
<tbody>
<tr>
<td>Remote control</td>
<td>1001</td>
<td>0000</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1002</td>
<td>0000</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1003</td>
<td>0000</td>
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<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1005</td>
<td>0000</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1006</td>
<td>0000</td>
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<td></td>
</tr>
<tr>
<td></td>
<td>0101</td>
<td>0000</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td>Remote password</td>
<td>1630</td>
<td>0000</td>
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<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1631</td>
<td>0000</td>
<td>— ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td>Loopback test</td>
<td>0619</td>
<td>0000</td>
<td>— ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td>Clear error information</td>
<td>1617</td>
<td>0000</td>
<td>— ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
</tbody>
</table>

*1 The command can only be used for C24 (including multidrop connection station) and E71 connected to the external device.
*2 The command can only be used for E71 connected to an external device.

### File control

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Subcommand</th>
<th>Access target</th>
<th>Remote I/O</th>
<th>Head</th>
</tr>
</thead>
<tbody>
<tr>
<td>File check</td>
<td>1810</td>
<td>0000</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1811</td>
<td>0000</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td>File creation and deletion</td>
<td>1820</td>
<td>0000</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1822</td>
<td>0000</td>
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<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1824</td>
<td>0000</td>
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<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td></td>
<td>0004</td>
<td>0000</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td></td>
<td>0004</td>
<td>0040</td>
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<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
<tr>
<td></td>
<td>0040</td>
<td>0040</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td>☐ ☐ ☐ ☐ ☐ ☐ ☐</td>
<td></td>
</tr>
</tbody>
</table>

*1 The command can only be used for C24 (including multidrop connection station) and E71 connected to the external device.
*2 The command can only be used for E71 connected to an external device.
Appendix 6 Accessible Modules for Each Command

Serial communication dedicated commands

The command can only be used for C24 (including multidrop connection station) connected to the external device.

QnACPU dedicated commands

The QnACPU dedicated commands can only be executed when access target is QnACPU.

Commands for 2C frame

The command can only be used for C24 (including multidrop connection station) and its control CPU module connected to the external device.

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Access target</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Modify file</td>
<td>1825</td>
<td></td>
<td>Page 224 Modify file attribute (command: 1825)</td>
</tr>
<tr>
<td></td>
<td>1826</td>
<td></td>
<td>Page 227 Modify file creation date and time (command: 1826)</td>
</tr>
<tr>
<td></td>
<td>1827</td>
<td></td>
<td>Page 230 Open file (command: 1827)</td>
</tr>
<tr>
<td></td>
<td>1828</td>
<td></td>
<td>Page 234 Read file (command: 1828)</td>
</tr>
<tr>
<td></td>
<td>1829</td>
<td></td>
<td>Page 236 Write to file (command: 1829)</td>
</tr>
<tr>
<td></td>
<td>182A</td>
<td></td>
<td>Page 238 Close file (command: 182A)</td>
</tr>
</tbody>
</table>

*1 The command can be used when both access target and connected station are MELSEC iQ-R series module.
*2 It can be used when password is not set to the target file.
*3 The command can be used when both access target and connected station are MELSEC-L series module.

QnACPU dedicated commands

The QnACPU dedicated commands can only be executed when access target is QnACPU.

Commands for 2C frame

The command can only be used for C24 (including multidrop connection station) and its control CPU module connected to the external device.

Cannot be used via network.

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Access target</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device access</td>
<td>1</td>
<td>△ 1</td>
<td>Page 87 Batch read in bit units (command: 0401)</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>△ 1</td>
<td>Page 84 Batch read in word units (command: 0401)</td>
</tr>
<tr>
<td></td>
<td>3</td>
<td>△ 1</td>
<td>Page 92 Batch write in bit units (command: 1401)</td>
</tr>
<tr>
<td></td>
<td>4</td>
<td>△ 1</td>
<td>Page 89 Batch write in word units (command: 1401)</td>
</tr>
<tr>
<td></td>
<td>5</td>
<td>△ 1</td>
<td>Page 94 Random read in word units (command: 0403)</td>
</tr>
<tr>
<td></td>
<td>6</td>
<td>△ 1</td>
<td>Page 105 Random write in bit units (test) (command: 1402)</td>
</tr>
<tr>
<td></td>
<td>7</td>
<td>△ 1</td>
<td>Page 101 Random write in word units (test) (command: 1402)</td>
</tr>
<tr>
<td></td>
<td>8</td>
<td>△ 1</td>
<td>Page 115 Register monitor data (command: 0801)</td>
</tr>
<tr>
<td></td>
<td>9</td>
<td></td>
<td>Page 116 Monitor (command: 0802)</td>
</tr>
</tbody>
</table>

*1 Specify the device with the specification method of MELSEC-Q/L series. The added new devices their ranges cannot be specified.
### Commands for 1C frame

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Access target</th>
<th>Remote I/O</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CPU module</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit units</td>
<td>BR</td>
<td>□□□□□□□□□□□□□□□</td>
<td>□□□□□□□□□□□□□□□</td>
<td>Page 346 Batch read (bit units) (command: BR, JR)</td>
</tr>
<tr>
<td>WR</td>
<td>□□□□□□□□□□□□□□□</td>
<td>□□□□□□□□□□□□□□□</td>
<td>Page 350 Batch read (word units) (command: WR, QR)</td>
<td></td>
</tr>
<tr>
<td>Batch write</td>
<td>BW</td>
<td>□□□□□□□□□□□□□□□</td>
<td>□□□□□□□□□□□□□□□</td>
<td>Page 352 Batch write (bit units) (command: BW, JW)</td>
</tr>
<tr>
<td>WW</td>
<td>□□□□□□□□□□□□□□□</td>
<td>□□□□□□□□□□□□□□□</td>
<td>Page 354 Batch write (word units) (command: WW, QW)</td>
<td></td>
</tr>
<tr>
<td>Test (random write)</td>
<td>BT</td>
<td>□□□□□□□□□□□□□□□</td>
<td>□□□□□□□□□□□□□□□</td>
<td>Page 356 Test (random write) (bit units) (command: BT, JT)</td>
</tr>
<tr>
<td>Word units</td>
<td>WT</td>
<td>□□□□□□□□□□□□□□□</td>
<td>□□□□□□□□□□□□□□□</td>
<td>Page 358 Test (random write) (word units) (command: WT, QW)</td>
</tr>
<tr>
<td><strong>Register monitor data</strong></td>
<td>BM</td>
<td>□□□□□□□□□□□□□□□</td>
<td>□□□□□□□□□□□□□□□</td>
<td>Page 361 Register monitor data (bit units) (command: BM, JM)</td>
</tr>
<tr>
<td>WM</td>
<td>□□□□□□□□□□□□□□□</td>
<td>□□□□□□□□□□□□□□□</td>
<td>Page 362 Register monitor data (word units) (command: WM, QM)</td>
<td></td>
</tr>
<tr>
<td>Monitor</td>
<td>MB</td>
<td>□□□□□□□□□□□□□□□</td>
<td>□□□□□□□□□□□□□□□</td>
<td>Page 363 Monitor (bit units) (command: MB, MJ)</td>
</tr>
<tr>
<td>Word units</td>
<td>MN</td>
<td>□□□□□□□□□□□□□□□</td>
<td>□□□□□□□□□□□□□□□</td>
<td>Page 364 Monitor (word units) (command: MN, MQ)</td>
</tr>
<tr>
<td><strong>Extended file register</strong></td>
<td>ER</td>
<td>X X X X X X X X X</td>
<td>X X X</td>
<td>Page 369 Batch read (command: ER)</td>
</tr>
<tr>
<td>Batch write</td>
<td>EW</td>
<td>X X X X X X X X X</td>
<td>X X</td>
<td>Page 370 Batch write (command: EW)</td>
</tr>
<tr>
<td>Test (random write)</td>
<td>ET</td>
<td>X X X X X X X X X</td>
<td>X X</td>
<td>Page 371 Test (random write) (command: ET)</td>
</tr>
<tr>
<td>Register monitor data</td>
<td>EM</td>
<td>X X X X X X X X X</td>
<td>X X</td>
<td>Page 373 Register monitor data (command: EM)</td>
</tr>
<tr>
<td>Monitor</td>
<td>ME</td>
<td>X X X X X X X X X</td>
<td>X X</td>
<td>Page 374 Monitor (command: ME)</td>
</tr>
<tr>
<td>Direct read</td>
<td>NR</td>
<td>X X X X X X X X X</td>
<td>X X</td>
<td>Page 375 Direct read (command: NR)</td>
</tr>
<tr>
<td>Direct write</td>
<td>NW</td>
<td>X X X X X X X X X</td>
<td>X X</td>
<td>Page 376 Direct write (command: NW)</td>
</tr>
<tr>
<td><strong>Special function module</strong></td>
<td>TR</td>
<td>X X X X X X X X X</td>
<td>X X</td>
<td>Page 380 Batch read (command: TR)</td>
</tr>
<tr>
<td>Batch write</td>
<td>TW</td>
<td>X X X X X X X X X</td>
<td>X X</td>
<td>Page 382 Batch write (command: TW)</td>
</tr>
<tr>
<td>Loopback test</td>
<td>TT</td>
<td>—— ——</td>
<td></td>
<td>Page 383 Loopback test (Command: TT)</td>
</tr>
</tbody>
</table>

*1 When accessing Universal model QCPU, use the module with a serial number whose first five digits are ’10102’ or later. If using a module with a serial number whose first five digits are ’10101’ or earlier, access with 2C/3C/4C frame.

*2 Read/write the devices within the range of AnCPU, AnNCPU, AnACPU, or AnUCPU. The added new devices and their ranges cannot be specified.

*3 The command can only be used for C24 (including multidrop connection station) connected to the external device.
## Commands for 1E frame

○: Executable, ×: Not executable

<table>
<thead>
<tr>
<th>Function</th>
<th>Command</th>
<th>Access target</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>CPU module</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>L  Q&lt;sup&gt;1&lt;/sup&gt;  Qn  A  QS</td>
<td></td>
</tr>
<tr>
<td><strong>Device memory</strong></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Batch read</td>
<td>Bit units</td>
<td>00H □ □ □ □ □ □ □</td>
<td>Page 397 Batch read in bit units (command: 00)</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>01H □ □ □ □ □ □ □</td>
<td>Page 399 Batch read in word units (command: 01)</td>
</tr>
<tr>
<td>Batch write</td>
<td>Bit units</td>
<td>02H □ □ □ □ □ □ □</td>
<td>Page 401 Batch write in bit units (command: 02)</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>03H □ □ □ □ □ □ □</td>
<td>Page 403 Batch write in word units (command: 03)</td>
</tr>
<tr>
<td>Test (random write)</td>
<td>Bit units</td>
<td>04H □ □ □ □ □ □ □</td>
<td>Page 404 Test in bit units (random write) (command: 04)</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>05H □ □ □ □ □ □ □</td>
<td>Page 406 Test in word units (random write) (command: 05)</td>
</tr>
<tr>
<td>Register monitor data&lt;sup&gt;3&lt;/sup&gt;</td>
<td>Bit units</td>
<td>06H □ □ □ □ □ □ □</td>
<td>Page 409 Register monitor data (command: 06, 07)</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>07H □ □ □ □ □ □ □</td>
<td></td>
</tr>
<tr>
<td>Monitor</td>
<td>Bit units</td>
<td>08H □ □ □ □ □ □ □</td>
<td>Page 410 Monitor in bit units (command: 08)</td>
</tr>
<tr>
<td></td>
<td>Word units</td>
<td>09H □ □ □ □ □ □ □</td>
<td>Page 411 Monitor in word units (command: 09)</td>
</tr>
<tr>
<td><strong>Extended file register</strong></td>
<td>Batch read</td>
<td>17H × × × □ □ □ □</td>
<td>Page 413 Batch read (command: 17)</td>
</tr>
<tr>
<td></td>
<td>Batch write</td>
<td>18H × × × □ □ □ □</td>
<td>Page 415 Batch write (command: 18)</td>
</tr>
<tr>
<td></td>
<td>Test (random write)</td>
<td>19H × × × □ □ □ □</td>
<td>Page 417 Test (random write) (command: 19)</td>
</tr>
<tr>
<td></td>
<td>Register monitor data&lt;sup&gt;3&lt;/sup&gt;</td>
<td>1AH × × × □ □ □ □</td>
<td>Page 420 Register monitor data (command: 1A)</td>
</tr>
<tr>
<td></td>
<td>Monitor</td>
<td>1BH × × × □ □ □ □</td>
<td>Page 421 Monitoring (command: 1B)</td>
</tr>
<tr>
<td></td>
<td>Direct read</td>
<td>3BH × × × □ □ □ □</td>
<td>Page 422 Direct read (command: 3B)</td>
</tr>
<tr>
<td></td>
<td>Direct write</td>
<td>3CH × × × □ □ □ □</td>
<td>Page 424 Direct write (command: 3C)</td>
</tr>
<tr>
<td><strong>Special function module</strong></td>
<td>Batch read</td>
<td>0EH × × × □ □ □ □</td>
<td>Page 428 Batch read (command: 0E)</td>
</tr>
<tr>
<td></td>
<td>Batch write</td>
<td>0FH × × × □ □ □ □</td>
<td>Page 430 Batch write (command: 0F)</td>
</tr>
</tbody>
</table>

<sup>1</sup> When accessing Universal model QCPU, use the module with a serial number whose first five digits are ‘10102’ or later. If using a module with a serial number whose first five digits are ‘10101’ or earlier, access with 3E/4E frame.

<sup>2</sup> Read/write the devices within the range of AnACPU. The added new devices and their ranges cannot be specified.

<sup>3</sup> The devices that can be registered to E71 is for 1 command out of the three types of commands (06H, 07H, 1AH). The specified device recently used by any of the above commands is registered to E71.
Appendix 7 Setting Examples

This section explains the setting example of the message.

Setting examples of message for serial communication module

The following shows the setting example when using a command from a serial communication module.

Examples of device access in ASCII code (Format 1, 3C frame)

The following shows the setting example when using a command for format 1 and 3C frame.

Device reading

- Format 1 (sum check enabled), 3C frame
- Access target: QCPU of the connected station (host station)
- Command: Batch read in word units (command: 0401)
- Device: M100 to M131 (for 2 words)

1. Read values from devices.

Request message

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>ENQ</td>
<td>3C frame</td>
<td>Host station</td>
<td>F 9 0 0 0 0 F F 0 0</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>05H</td>
<td>46H 39H 30H 30H 30H 30H 46H 46H 30H 30H</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

The subtotal of the additional value of binary data = 22BH

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
<th>Sum check code*1</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 4 0 1 0 0 0 0 M *</td>
<td>0 0 0 1 0 0 0 2 0 A</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>30H 34H 30H 31H 30H 30H 30H 30H 4DH 2AH</td>
<td>30H 30H 30H 31H 30H 30H 30H 30H 30H 32H 30H 41H</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The subtotal of the additional value of binary data = 3DFH

*1 The addition result of the sum check range: 22BH + 3DF = 60AH

2. Receive the result.

Response message (Normal completion: Response data)

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>STX</td>
<td>3C frame</td>
<td>Host station</td>
<td>F 9 0 0 0 0 F F 0 0</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>02H</td>
<td>46H 39H 30H 30H 30H 30H 46H 46H 30H 30H</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

The subtotal of the additional value of binary data = 22BH

Response data (read data)*2

<table>
<thead>
<tr>
<th>Control code</th>
<th>Sum check code*1</th>
</tr>
</thead>
<tbody>
<tr>
<td>ETX</td>
<td>B A</td>
</tr>
<tr>
<td>31H 32H 33H 34H 30H 30H 32H 30H 30H 03H</td>
<td>42H 41H</td>
</tr>
</tbody>
</table>

The subtotal of the additional value of binary data = 18FH

*1 The addition result of the sum check range: 22BH + 18F = 3BAH

*2 The value of read data corresponds to the access target device as follows.
Device writing

- Format 1 (sum check enabled), 3C frame
- Access target: QCPU of the connected station (host station)
- Command: Batch write in word units (command: 1401)
- Device: M100 to M131 (for 2 words)

1. Write values to devices.

Request message

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>3C frame</td>
<td>Host station</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>ENQ</th>
<th>F</th>
<th>0</th>
<th>0</th>
<th>0</th>
<th>F</th>
<th>F</th>
<th>0</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>05H</td>
<td>46H</td>
<td>39H</td>
<td>30H</td>
<td>30H</td>
<td>30H</td>
<td>30H</td>
<td>46H</td>
<td>46H</td>
</tr>
</tbody>
</table>

The subtotal of the additional value of binary data = 22BH

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0</td>
<td>M</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>4</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
</tbody>
</table>

The subtotal of the additional value of binary data = 3E0H

Request data

Write data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>3</td>
<td>A</td>
<td>9</td>
<td>6</td>
</tr>
</tbody>
</table>

The subtotal of the additional value of binary data = 1C2H

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>32H</td>
<td>33H</td>
<td>34H</td>
<td>37H</td>
<td>41H</td>
</tr>
</tbody>
</table>

The subtotal of the additional value of binary data = 1C2H

2. Receive the result.

Response message (Normal completion: No response data)

<table>
<thead>
<tr>
<th>Control code</th>
<th>Frame ID No.</th>
<th>Access route</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>3C frame</td>
<td>Host station</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>ACK</th>
<th>F</th>
<th>0</th>
<th>0</th>
<th>0</th>
<th>F</th>
<th>F</th>
<th>0</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>06H</td>
<td>46H</td>
<td>39H</td>
<td>30H</td>
<td>30H</td>
<td>30H</td>
<td>30H</td>
<td>46H</td>
<td>46H</td>
</tr>
</tbody>
</table>

*1 The addition result of the sum check range: 22BH + 3E0H + 1C2H = 7CDH

*2 The value of write data corresponds to the access target device as follows.

The subtotal of the additional value of binary data = 1C2H
Examples of device access in binary code (Format 5, 4C frame)

The following shows the setting example when using a command for format 5 and 4C frame.

**Device reading**
- Format 5 (sum check enabled), 4C frame
- Access target: QCPU of the connected station (host station)
- Command: Batch read in word units (command: 0401)
- Device: M100 to M131 (for 2 words)

1. Read values from devices.  
Request message

<table>
<thead>
<tr>
<th>Control code</th>
<th>Number of data bytes</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Station No.</th>
<th>Network No.</th>
<th>PC No.</th>
<th>Request destination module I/O No.</th>
<th>Request destination module station No.</th>
<th>Self-Station No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>DLE STX</td>
<td>18 bytes</td>
<td>4C frame</td>
<td>Host station</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>10H 02H</td>
<td>12H 00H F8H 00H 00H FFH FFH 03H 00H 00H</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

* The subtotal of the additional value of binary data = 30BH

<table>
<thead>
<tr>
<th>Request data</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
<tbody>
<tr>
<td>Command</td>
<td>Subcommand</td>
<td>Head device number</td>
</tr>
<tr>
<td>0401</td>
<td>0000</td>
<td>100</td>
</tr>
<tr>
<td>01H 04H</td>
<td>00H 00H</td>
<td>64H 00H 00H 90H 02H 00H 10H 03H 30H 36H</td>
</tr>
</tbody>
</table>

*1 Frame ID No. (1 byte) + Access route (7 bytes) + Request data (10 bytes)
* The addition result of the sum check range: 30BH + FBH = 406H

2. Receive the result.  
Response message (Normal completion: Response data)

<table>
<thead>
<tr>
<th>Control code</th>
<th>Number of data bytes</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>Station No.</th>
<th>Network No.</th>
<th>PC No.</th>
<th>Request destination module I/O No.</th>
<th>Request destination module station No.</th>
<th>Self-Station No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>DLE STX</td>
<td>16 bytes</td>
<td>4C frame</td>
<td>Host station</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>10H 02H</td>
<td>10H 10H 00H F8H 00H 00H FFH FFH 03H 00H 00H</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

*2 The subtotal of the additional value of binary data = 309H

<table>
<thead>
<tr>
<th>Response ID code</th>
<th>Normal completion code</th>
<th>Response data (read data)</th>
<th>Control code</th>
<th>Sum check code</th>
</tr>
</thead>
<tbody>
<tr>
<td>FFFFH</td>
<td>0000H</td>
<td>M100 to M115 M116 to M131</td>
<td>DLE ETX 4</td>
<td>F</td>
</tr>
<tr>
<td>FFH</td>
<td>FFH 00H 00H 34H 12H 02H 00H 10H 03H 34H 46H</td>
<td>DLE ETX 0 6</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

*1 Frame ID No. (1 byte) + Access route (7 bytes) + Response ID code (2 bytes) + Normal completion code (2 bytes) + Response data (4 bytes)
*2 Additional code. Calculate the sum check code except for the additional code. (Page 33 Additional code (10H))
* The addition result of the sum check range: 309H + 246H = 54FH
* The value of read data corresponds to the access target device as follows.

```
<table>
<thead>
<tr>
<th>3</th>
<th>4</th>
<th>1</th>
<th>2</th>
<th>0</th>
<th>2</th>
<th>0</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>M107</td>
<td>to M100</td>
<td>M115</td>
<td>to M108</td>
<td>M123</td>
<td>to M116</td>
<td>M131</td>
<td>to M124</td>
</tr>
</tbody>
</table>
```

APPENDICES APPENDIX  
Appendix 7 Setting Examples 473
### Device writing

- Format 5 (sum check enabled), 4C frame
- Access target: QCPU of the connected station (host station)
- Command: Batch write in word units (command: 1401)
- Device: M100 to M131 (for 2 words)

#### 1. Write values to devices.

**Request message**

<table>
<thead>
<tr>
<th>Control code</th>
<th>Number of data bytes(^1)</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>PC No.</th>
<th>Request destination module I/O No.</th>
<th>Request destination module station No.</th>
<th>Self-station No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>DLE STX</td>
<td>22 bytes</td>
<td>4C frame</td>
<td>Host station</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>10H 02H</td>
<td>16H 00H</td>
<td>FBH</td>
<td>00H 00H</td>
<td>FFH</td>
<td>FFH 03H 00H</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

* The subtotal of the additional value of binary data = 30FH

#### Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Head device number</th>
<th>Device code</th>
<th>Number of device points</th>
<th>Write data(^3)</th>
<th>Control code</th>
<th>Sum check code(^2)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1401</td>
<td>0000</td>
<td>100</td>
<td>M</td>
<td>2</td>
<td>M100 to M115</td>
<td>DLE ETX</td>
<td>C 5</td>
</tr>
<tr>
<td>01H 14H</td>
<td>00H 00H</td>
<td>64H 00H 00H 90H</td>
<td>02H 00H 47H 23H 96H ABH</td>
<td>10H 03H 43H 35H</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The subtotal of the additional value of binary data = 2B6H

*1 Frame ID No. (1 byte) + Access route (7 bytes) + Request data (14 bytes)
*2 The addition result of the sum check range: 30FH + 2B6H = 5C5H
*3 The value of write data corresponds to the access target device as follows.

#### 2. Receive the result.

**Response message (Normal completion: No response data)**

<table>
<thead>
<tr>
<th>Control code</th>
<th>Number of data bytes(^1)</th>
<th>Frame ID No.</th>
<th>Access route</th>
<th>PC No.</th>
<th>Request destination module I/O No.</th>
<th>Request destination module station No.</th>
<th>Self-station No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>DLE STX</td>
<td>12 bytes</td>
<td>4C frame</td>
<td>Host station</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>10H 02H</td>
<td>0CH 00H</td>
<td>FBH</td>
<td>00H 00H</td>
<td>FFH</td>
<td>FFH 03H 00H</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

* The subtotal of the additional value of binary data = 305H

<table>
<thead>
<tr>
<th>Response ID code</th>
<th>Normal completion code</th>
<th>Control code</th>
<th>Sum check code(^2)</th>
</tr>
</thead>
<tbody>
<tr>
<td>FFFFH</td>
<td>0000H</td>
<td>DLE ETX</td>
<td>0 3</td>
</tr>
<tr>
<td>FFH FFH</td>
<td>00H 00H</td>
<td>10H 03H</td>
<td>30H 33H</td>
</tr>
</tbody>
</table>

The subtotal of the additional value of binary data = 1FEH

*1 Frame ID No. (1 byte) + Access route (7 bytes) + Response ID code (2 bytes) + Normal completion code (2 bytes)
*2 The addition result of the sum check range: 305H + 1FEH = 503H
Setting examples of message for Ethernet interface module

The following shows the setting example when using a command from an Ethernet interface module.

Examples of device access in ASCII code (3E frame)

The following shows the setting example when using a command for ASCII code and 3E frame.

Device reading

- ASCII code, 3E frame
- Access target: QCPU of the connected station (host station)
- Command: Batch read in word units (command: 0401)
- Device: M100 to M131 (for 2 words)

1. Read values from devices.

Request message

<table>
<thead>
<tr>
<th>Subheader</th>
<th>Access route</th>
<th>Request data length</th>
<th>Monitoring timer</th>
</tr>
</thead>
<tbody>
<tr>
<td>3E frame (request)</td>
<td>Host station</td>
<td>24</td>
<td>4 seconds</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>3E frame (request)</th>
<th>Host station</th>
<th>24</th>
<th>4 seconds</th>
</tr>
</thead>
<tbody>
<tr>
<td>35H</td>
<td>30H</td>
<td>30H</td>
<td>30H</td>
</tr>
</tbody>
</table>

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>00H</td>
<td>00H</td>
<td>00H</td>
<td>00H</td>
<td>00H</td>
</tr>
<tr>
<td>30H</td>
<td>34H</td>
<td>30H</td>
<td>31H</td>
<td>30H</td>
</tr>
</tbody>
</table>

1. Monitoring timer (4 bytes) + Request data (20 bytes)

2. Receive the result.

Response message (Normal completion: Response data)

<table>
<thead>
<tr>
<th>Subheader</th>
<th>Access route</th>
<th>Response data length</th>
<th>End code</th>
</tr>
</thead>
<tbody>
<tr>
<td>3E frame (response)</td>
<td>Host station</td>
<td>12</td>
<td>0000H</td>
</tr>
<tr>
<td>30H</td>
<td>30H</td>
<td>30H</td>
<td>30H</td>
</tr>
</tbody>
</table>

Response data (read data)

| 1 | 2 | 3 | 4 | 0 | 0 | 0 | 2 |
| 31H | 32H | 33H | 34H | 30H | 30H | 30H | 32H |

*1 End code (4 bytes) + Response data (8 bytes)
*2 The value of read data corresponds to the access target device as follows.
Device writing
- ASCII code, 3E frame
- Access target: QCPU of the connected station (host station)
- Command: Batch write in word units (command: 1401)
- Device: M100 to M131 (for 2 words)

1. Write values to devices.

Request message

<table>
<thead>
<tr>
<th>Subheader</th>
<th>Access route</th>
<th>Request data length</th>
<th>Monitoring timer</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Network No.</td>
<td>PC No.</td>
<td>Request destination module I/O No.</td>
</tr>
<tr>
<td>3E frame (request)</td>
<td>Host station</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3S</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>3OH</td>
<td>3OH</td>
<td>3OH</td>
<td>3OH</td>
</tr>
</tbody>
</table>

Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Device code</th>
<th>Head device number</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>4</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>31H</td>
<td>34H</td>
<td>3OH</td>
<td>31H</td>
<td>30H</td>
</tr>
</tbody>
</table>

Request data

Write data

| | | | | |
| 2 | 3 | 4 | 7 | A | B | 9 | 6 |
| 32H | 33H | 34H | 37H | 41H | 42H | 39H | 36H |

*1 Monitoring timer (4 bytes) + Request data (28 bytes)

*2 The value of write data corresponds to the access target device as follows.

![Diagram showing device connections and write data values]

2. Receive the result.

Response message (Normal completion: No response data)

<table>
<thead>
<tr>
<th>Subheader</th>
<th>Access route</th>
<th>Response data length</th>
<th>End code</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Network No.</td>
<td>PC No.</td>
<td>Request destination module I/O No.</td>
</tr>
<tr>
<td>3E frame (response)</td>
<td>Host station</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>44H</td>
<td>30H</td>
<td>30H</td>
<td>30H</td>
</tr>
</tbody>
</table>

*1 End code (4 bytes)
Examples of device access in binary code (3E frame)

The following shows the setting example when using a command for binary code and 3E frame.

### Device reading

- **Binary code, 3E frame**
- **Access target:** QCPU of the connected station (host station)
- **Command:** Batch read in word units (command: 0401)
- **Device:** M100 to M131 (for 2 words)

1. Read values from devices.

#### Request message

<table>
<thead>
<tr>
<th>Subheader</th>
<th>Access route</th>
<th>Request data</th>
<th>Monitoring timer</th>
</tr>
</thead>
<tbody>
<tr>
<td>3E frame (request)</td>
<td>Host station</td>
<td>12</td>
<td>4 seconds</td>
</tr>
<tr>
<td>50H 00H</td>
<td>00H FFH FFH 03H 00H</td>
<td>0CH 00H 10H 00H</td>
<td></td>
</tr>
</tbody>
</table>

#### Request data

<table>
<thead>
<tr>
<th>Command</th>
<th>Subcommand</th>
<th>Head device number</th>
<th>Device code</th>
<th>Number of device points</th>
</tr>
</thead>
<tbody>
<tr>
<td>0401</td>
<td>0000</td>
<td>100</td>
<td>M</td>
<td>2</td>
</tr>
<tr>
<td>01H 04H</td>
<td>00H 00H</td>
<td>64H 00H 00H</td>
<td>90H 02H 00H</td>
<td></td>
</tr>
</tbody>
</table>

*1 Monitoring timer (2 bytes) + Request data (10 bytes)

2. Receive the result.

#### Response message (Normal completion: Response data)

<table>
<thead>
<tr>
<th>Subheader</th>
<th>Access route</th>
<th>Response data</th>
<th>End code</th>
</tr>
</thead>
<tbody>
<tr>
<td>3E frame (response)</td>
<td>Host station</td>
<td>6 0000H</td>
<td>02H 00H</td>
</tr>
<tr>
<td>D0H 00H</td>
<td>00H FFH FFH 03H 00H</td>
<td>06H 00H 00H 00H</td>
<td></td>
</tr>
</tbody>
</table>

#### Response data (read data)*2

<table>
<thead>
<tr>
<th>M100 to M115</th>
<th>M116 to M131</th>
</tr>
</thead>
<tbody>
<tr>
<td>34H 12H 02H 00H</td>
<td></td>
</tr>
</tbody>
</table>

*1 End code (2 bytes) + Response data (4 bytes)

*2 The value of read data corresponds to the access target device as follows.
### Device writing

- Binary code, 3E frame
- Access target: QCPU of the connected station (host station)
- Command: batch write in word units (command: 1401)
- Device: M100 to M131 (for 2 words)

1. Write values to devices.

#### Request message

<table>
<thead>
<tr>
<th>Subheader</th>
<th>Access route</th>
<th>Request data</th>
<th>Monitoring timer</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Network No.</td>
<td>PC No.</td>
<td>Request destination module I/O No.</td>
</tr>
<tr>
<td>3E frame (request)</td>
<td>Host station</td>
<td></td>
<td>16</td>
</tr>
<tr>
<td>00H 00H</td>
<td>00H</td>
<td>FFH</td>
<td>FFH 03H 00H</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Request data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Command</td>
</tr>
<tr>
<td>1401</td>
</tr>
<tr>
<td>01H 14H</td>
</tr>
</tbody>
</table>

*1 Monitoring timer (2 bytes) + Request data (14 bytes)  
*2 The value of write data corresponds to the access target device as follows.

![Image of device writing with binary code and hexadecimal values]

2. Receive the result.

#### Response message (Normal completion: No response data)

<table>
<thead>
<tr>
<th>Subheader</th>
<th>Access route</th>
<th>Request data</th>
<th>End code</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Network No.</td>
<td>PC No.</td>
<td>Request destination module I/O No.</td>
</tr>
<tr>
<td>3E frame (response)</td>
<td>Host station</td>
<td></td>
<td>2</td>
</tr>
<tr>
<td>00H 00H</td>
<td>00H</td>
<td>FFH</td>
<td>FFH 03H 00H</td>
</tr>
</tbody>
</table>

*1 End code (2 bytes)
Setting examples of access route

The following shows the setting example of each access route for each frame. For the details of each setting item, refer to the following section.

Page 48 Detail of data to be set

When accessing the connected station (host station)

The following shows the setting example for accessing the connected station (host station).

![Diagram of connected station (host station) and access target station.]

--- Unnecessary

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Connected station (host station)</td>
<td>4C</td>
<td>00</td>
<td>00</td>
<td>FF</td>
<td>03FF</td>
<td>00</td>
<td>00</td>
</tr>
<tr>
<td></td>
<td>3C</td>
<td>00</td>
<td>00</td>
<td>FF</td>
<td>—</td>
<td>—</td>
<td>00</td>
</tr>
<tr>
<td></td>
<td>2C</td>
<td>00</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>00</td>
</tr>
<tr>
<td></td>
<td>1C</td>
<td>00</td>
<td>—</td>
<td>FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>4E/3E</td>
<td>—</td>
<td>00</td>
<td>FF</td>
<td>03FF</td>
<td>00</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>1E</td>
<td>—</td>
<td>—</td>
<td>FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>Multiple CPU system (Multiple CPU No.1)</td>
<td>4C</td>
<td>00</td>
<td>00</td>
<td>FF</td>
<td>03E0</td>
<td>00</td>
<td>00</td>
</tr>
<tr>
<td></td>
<td>4E/3E</td>
<td>—</td>
<td>00</td>
<td>FF</td>
<td>03E0</td>
<td>00</td>
<td>—</td>
</tr>
<tr>
<td>Redundant system (Control system CPU)</td>
<td>4C</td>
<td>00</td>
<td>00</td>
<td>FF</td>
<td>03D0</td>
<td>00</td>
<td>00</td>
</tr>
<tr>
<td></td>
<td>4E/3E</td>
<td>—</td>
<td>00</td>
<td>FF</td>
<td>03D0</td>
<td>00</td>
<td>—</td>
</tr>
</tbody>
</table>

Specify the CPU module of an access target in the request destination module I/O No.

Page 54 Accessing multiple CPU system, redundant system
When connecting with a multidrop connection

When accessing a multidrop connection station, specify the station No. of an access target to the station No.

When requiring to distinguish request sources in a m:n connection, specify the station No. of an external device to the self-station No.

The following shows setting examples for accessing a multidrop connection station.

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Multidrop connection station • Station No.1</td>
<td>4C</td>
<td>01</td>
<td>00</td>
<td>FF</td>
<td>03FF</td>
<td>00</td>
<td>00</td>
</tr>
<tr>
<td></td>
<td>3C</td>
<td>01</td>
<td>00</td>
<td>FF</td>
<td>—</td>
<td>—</td>
<td>00</td>
</tr>
<tr>
<td></td>
<td>2C</td>
<td>01</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td></td>
<td>1C</td>
<td>01</td>
<td>—</td>
<td>FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>All stations connected with a multidrop connection (Global function)</td>
<td>4C</td>
<td>FF</td>
<td>00</td>
<td>FF</td>
<td>03FF</td>
<td>00</td>
<td>00</td>
</tr>
<tr>
<td></td>
<td>3C</td>
<td>FF</td>
<td>00</td>
<td>FF</td>
<td>—</td>
<td>—</td>
<td>00</td>
</tr>
<tr>
<td></td>
<td>2C</td>
<td>FF</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>Multidrop connection station (At m:n connection) • Station No.1 • Station No.31 (1FH) of the external device</td>
<td>4C</td>
<td>01</td>
<td>00</td>
<td>FF</td>
<td>03FF</td>
<td>00</td>
<td>1F</td>
</tr>
<tr>
<td></td>
<td>3C</td>
<td>01</td>
<td>00</td>
<td>FF</td>
<td>—</td>
<td>—</td>
<td>1F</td>
</tr>
<tr>
<td></td>
<td>2C</td>
<td>01</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>1F</td>
</tr>
</tbody>
</table>
**When accessing from an Ethernet interface module**

When accessing a multidrop connection station with the frames (4E frame, 3E frame) for the Ethernet interface module, specify the start input/output number of a multidrop connection source module (relay station) and the station No. of an access target to the request destination I/O No. and the request destination module station No. For the request destination I/O No., specify the value obtained by dividing the start input/output number by 16 in 4 digits (hexadecimal).

The following shows the setting example of the cases below.

- Multidrop connection source module of the relay station: Start input/output number 0050H (request destination module I/O No. 0005H)
- Multidrop connection station of the access target: Station No. 1

---: Unnecessary

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Multidrop connection station</td>
<td>4E/3E</td>
<td>—</td>
<td>00</td>
<td>FF</td>
<td>0005</td>
<td>01</td>
<td>—</td>
</tr>
</tbody>
</table>

**When accessing via network**

When accessing other stations via network, specify the network No. and station No. of an access target network module to the network No. and PC No.

The following shows setting examples for accessing other stations via network (network No. 1, station No. 2) without a multidrop connection.

---: Unnecessary

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Other station via network</td>
<td>4C</td>
<td>00</td>
<td>01</td>
<td>02</td>
<td>03FF</td>
<td>00</td>
<td>00</td>
</tr>
<tr>
<td>• Network No.1</td>
<td>3C</td>
<td>00</td>
<td>01</td>
<td>02</td>
<td>—</td>
<td>—</td>
<td>00</td>
</tr>
<tr>
<td>• Station No.2</td>
<td>4E/3E</td>
<td>—</td>
<td>01</td>
<td>02</td>
<td>03FF</td>
<td>00</td>
<td>—</td>
</tr>
<tr>
<td>Other station accessed via the network module set in the “Valid Module During Other Station Access” setting.</td>
<td>4C</td>
<td>00</td>
<td>FE</td>
<td>02</td>
<td>03FF</td>
<td>00</td>
<td>00</td>
</tr>
<tr>
<td>• Station No.2</td>
<td>3C</td>
<td>00</td>
<td>FE</td>
<td>02</td>
<td>—</td>
<td>—</td>
<td>00</td>
</tr>
<tr>
<td>Others</td>
<td>1C</td>
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<td>02</td>
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</table>
When connecting with a multidrop link and via network

The following shows setting examples for connecting with a multidrop connection and via network.

■ Other stations via network from a multidrop connection

Specify the setting for a multidrop connection including the connected station (host station) and the setting for a connection via network each.

Specify the station No. of a multidrop connection station for a relay to the station No.
Specify the network No. and station No. of an access target to the network No. and PC No.

The following shows the setting example of the cases below.
• Multidrop connection station of the relay station: Station No.1
• Network module of the access target: Network No.1, station No.2

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■ Multidrop connection station via network

For accessing a multidrop connection station in the target via network, specify the start input/output number of a multidrop connection source module and the station No. of an access target to the request destination module I/O No. and the request destination module station No. For the request destination module I/O No., specify the value obtained by dividing the start input/output number by 16 in 4 digits (hexadecimal).

Specify the network No. and station No. of a network module for a relay station to the network No. and PC No.

The following shows the setting example of the cases below.
• Network module for the relay station: Network No.1, station No.2
• Multidrop connection source module of the relay station: Start input/output number 0050H (request destination module I/O No.0005H)
• Multidrop connection station of the access target: Station No.1

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**REVISIONS**

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<td>December 1999 to July 2013</td>
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| June 2014 | SH(NA)-080008-T | Complete revision (layout change)  
- Added models: RJ71C24, RJ71C24-R2, RJ71C24-R4 |
| July 2014 | SH(NA)-080008-U | Minor correction. |
| August 2015 | SH(NA)-080008-V |  
- Added or modified parts:  
  Section 6.2, Section 8.1, Section 8.2, Section 8.3, Section 8.4, Section 8.5, Chapter 9, Section 12.4, Appendix 7 |

Japanese manual number: SH-080003-AB

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MODEL CODE: 13JF89

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